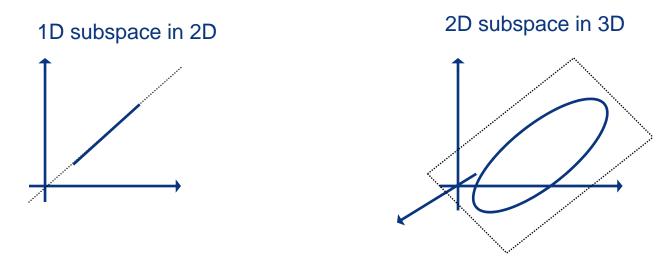
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▶ basic idea:

 if the data lives in a subspace, it is going to look very flat when viewed from the full space, e.g.



 this means that if we fit a Gaussian to the data the equiprobability contours are going to be highly skewed ellipsoids

The role of the mean

- ▶ note that the mean of the entire data is a function of the coordinate system
 - if X has mean μ then X μ has mean 0
- we can always make the data have zero mean by centering

if

$$X = \begin{bmatrix} 1 & & & \\ x_1 & \dots & x_n \\ & & & \end{bmatrix}$$

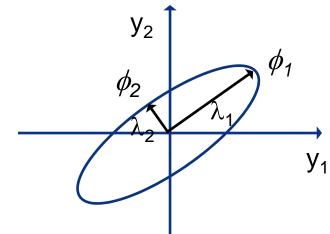
and

$$\boldsymbol{X}_{c}^{T} = \left(\boldsymbol{I} - \frac{1}{n} \boldsymbol{1} \boldsymbol{1}^{T}\right) \boldsymbol{X}^{T}$$

- then X_c has zero mean
- ▶ can assume that X is zero mean without loss of generality

- ▶ If y is Gaussian with covariance Σ
- ▶ the equiprobability contours

$$y^T \Sigma^{-1} y = K$$



- ► are the ellipses whose
 - principal components φ_{i} are the eigenvectors of Σ
 - principal lengths λ_i are the eigenvalues of Σ
- by detecting small eigenvalues we can eliminate dimensions that have little variance
- ▶ this is PCA

PCA by SVD

- computation of PCA by SVD
- ▶ given X with one example per column
 - 1) create the centered data-matrix

$$\boldsymbol{X}_{c}^{T} = \left(\boldsymbol{I} - \frac{1}{n} \boldsymbol{1} \boldsymbol{1}^{T}\right) \boldsymbol{X}^{T}$$

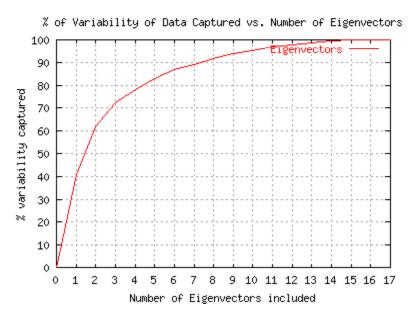
• 2) compute its SVD

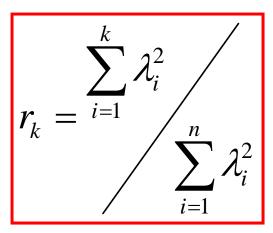
$$X_c^T = M\Pi N^T$$

• 3) principal components are columns of N, eigenvalues are

$$\lambda_i = \pi_i^2 / n$$

- a natural measure is to pick the eigenvectors that explain p % of the data variability
 - can be done by plotting the ratio r_k as a function of k





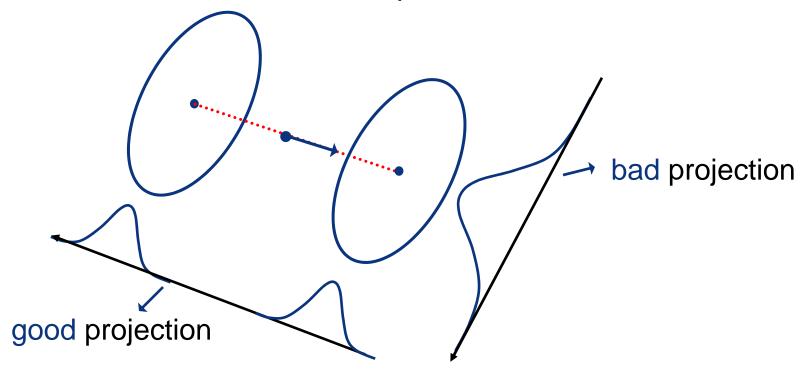
 e.g. we need 3 eigenvectors to cover 70% of the variability of this dataset

Limitations of PCA

- ▶ PCA is not optimal for classification
 - note that there is no mention of the class label in the definition of PCA
 - keeping the dimensions of largest energy (variance) is a good idea, but not always enough
 - certainly improves the density estimation, since space has smaller dimension
 - but could be unwise from a classification point of view
 - the discriminant dimensions could be thrown out
- ▶ it is not hard to construct examples where PCA is the worst possible thing we could do

Fischer's linear discriminant

▶ find the line $z = w^T x$ that best separates the two classes



$$w^* = \max_{w} \frac{\left(E_{Z|Y}[Z \mid Y = 1] - E_{Z|Y}[Z \mid Y = 0]\right)^2}{\text{var}[Z \mid Y = 1] + \text{var}[Z \mid Y = 0]}$$

Linear discriminant analysis

this can be written as

$$J(w) = \frac{w^T S_B w}{w^T S_W w}$$

between class scatter $J(w) = \frac{w^{T} S_{B} w}{w^{T} S_{W} w} \qquad S_{B} = (\mu_{1} - \mu_{0}) (\mu_{1} - \mu_{0})^{T}$ $S_{W} = (\Sigma_{1} + \Sigma_{0})$

within class scatter

optimal solution is

$$w^* = S_W^{-1}(\mu_1 - \mu_0) = (\Sigma_1 + \Sigma_0)^{-1}(\mu_1 - \mu_0)$$

- ▶ BDR after projection on z is equivalent to BDR on x if
 - the two classes are Gaussian and have equal covariance
- otherwise, LDA leads to a sub-optimal classifier

▶ it turns out that the maximization of the Rayleigh quotient

$$J(w) = \frac{w^T S_B w}{w^T S_W w}$$

$$J(w) = \frac{w^{T} S_{B} w}{w^{T} S_{W} w}$$

$$S_{B}, S_{W}, symmetric$$

$$positive semidefinite$$

appears in many problems in engineering and pattern recognition

we have already seen that this is equivalent to

$$\max_{w} w^{T} S_{B} w \quad \text{subject to} \quad w^{T} S_{W} w = K$$

and can be solved using Lagrange multipliers

define the Lagrangian

$$L = w^T S_B w - \lambda (w^T S_W w - K)$$

► maximize with respect to w

$$\nabla_{w} L = 2(S_B - \lambda S_W) w = 0$$

▶ to obtain the solution

$$S_B w = \lambda S_W w$$

- this is a generalized eigenvalue problem that you can solve using any eigenvalue routine
- which eigenvalue?

recall that we want

$$\max_{w} w^{T} S_{B} w \quad \text{subject to} \quad w^{T} S_{W} w = K$$

and the optimal w satisfies

$$S_B w = \lambda S_W w$$

hence

$$(w^*)^T S_B w^* = \lambda (w^*)^T S_W w^* = \lambda K$$

which is maximum for the largest eigenvalue

▶ in summary, we need the generalized eigenvector $S_R w = \lambda S_W w$ of largest eigenvalue

- ► case 1: S_w invertible
 - simplifies to a standard eigenvalue problem

$$S_W^{-1} S_B w = \lambda w$$

- w is the largest eigenvalue of S_w⁻¹S_B
- ► case 2: S_w not invertible
 - this is case is more problematic
 - in fact the cost can be unbounded
 - consider $w = w_r + w_n$, w_r in the row space of S_w and w_n in the null space

$$w^{T} S_{W} w = (w_{r} + w_{n})^{T} S_{W} (w_{r} + w_{n}) = (w_{r} + w_{n})^{T} S_{W} w_{r}$$
$$= w_{r}^{T} S_{W} (w_{r} + w_{n}) = w_{r}^{T} S_{W} w_{r}$$

and

$$w^{T} S_{B} w = (w_{r} + w_{n})^{T} S_{B} (w_{r} + w_{n})$$

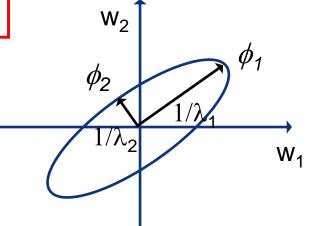
$$= w_{r}^{T} S_{B} w_{r} + 2w_{r}^{T} S_{B} w_{n} + \underbrace{w_{n}^{T} S_{B} w_{n}}_{\geq 0}$$

- ▶ hence, if there is a (w_r, w_n) such that $w_r^T S_B w_n \ge 0$,
 - we can make the cost arbitrarily large
 - by simply scaling up the null space component w_n
- ▶ this can also be seen geometrically

recall that

$$w^T S_W w = K \text{ with } S_W = \Phi \Lambda \Phi^T$$

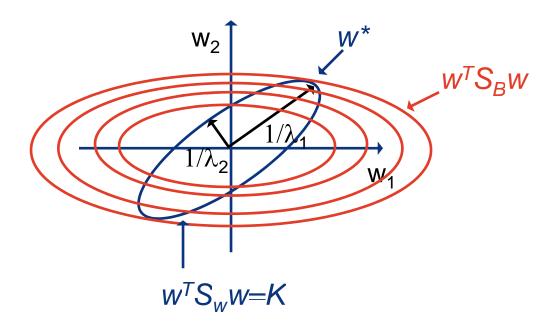
- ► are the ellipses whose
 - principal components ϕ_i are the eigenvectors of S_w
 - principal lengths are 1/λ_i



- ▶ when the eigenvalues go to zero, the ellipses blow up
- consider the picture of the optimization problem

$$\max_{w} w^{T} S_{B} w \quad \text{subject to} \quad w^{T} S_{W} w = K$$

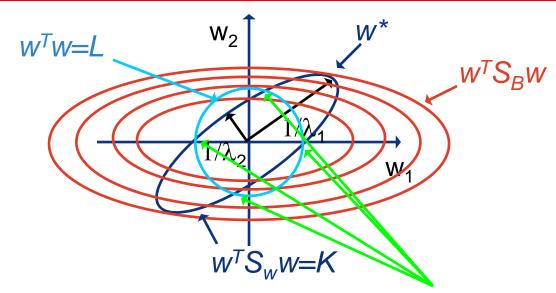
 $\max_{w} w^{T} S_{B} w \quad \text{subject to} \quad w^{T} S_{W} w = K$



- ▶ the optimal solution is where the outer red ellipse (cost) touches the blue ellipse (constraint)
 - in this example, as λ_1 goes to 0, $||w^*||$ and the cost go to infinity

- ▶ how do we avoid this problem?
 - we introduce another constraint

$$\max_{w} w^{T} S_{B} w \quad \text{subject to} \quad w^{T} S_{W} w = K, \quad ||w|| = L$$



 restricts the set of possible solutions to these points (surfaces in high dimensional case)

▶ the Lagrangian is now

$$L = w^{T} S_{B} w - \lambda (w^{T} S_{W} w - K) - \beta (w^{T} w - L)$$

and the solution satisfies

$$\nabla_{w}L = 2(S_{B} - \lambda S_{W} - \beta I)w = 0$$

or

$$(S_B - \lambda [S_W + \gamma I])w = 0, \quad \gamma = \beta / \lambda$$

▶ but this is exactly the solution of the original problem with $S_w + \gamma I$ instead of S_w

$$\max_{w} w^{T} S_{B} w \quad \text{subject to} \quad w^{T} [S_{W} + \gamma I] w = K$$

adding the constraint is equivalent to maximizing the regularized Rayleigh quotient

$$J(w) = \frac{w^T S_B w}{w^T [S_W + \gamma I] w}$$

$$J(w) = \frac{w^{T} S_{B} w}{w^{T} [S_{W} + \gamma I] w}$$

$$S_{B}, S_{W}, symmetric$$

$$positive semidefinite$$

- what does this accomplish?
 - note that

$$S_{W} = \Phi \Lambda \Phi^{T} \Rightarrow S_{W} + \gamma I = \Phi \Lambda \Phi^{T} + \gamma \Phi I \Phi^{T}$$
$$= \Phi \left[\Lambda + \gamma I \right] \Phi^{T}$$

- this makes all eigenvalues positive
- the matrix is no longer non-invertible

▶ in summary

$$\max_{w} \frac{w^{T} S_{B} w}{w^{T} S_{W} w}$$

 $S_B, S_W, symmetric$ positive semidefinite

▶ 1) S_w invertible

- w* is the eigenvector of largest eigenvalue of S_w⁻¹S_B
- the max value is λK , where λ is the largest eigenvalue

▶ 2) S_w not invertible

- regularize: $S_w -> S_w + \gamma I$
- w* is the eigenvector of largest eigenvalue of [S_w + γI]⁻¹S_B
- the max value is λK , where λ is the largest eigenvalue

Regularized discriminant analysis

- back to LDA:
 - when the within scatter matrix is non-invertible, instead of

$$J(w) = \frac{w^T S_B w}{w^T S_W w}$$

$$J(w) = \frac{w^{T} S_{B} w}{w^{T} S_{W} w}$$

$$S_{B} = (\mu_{1} - \mu_{0})(\mu_{1} - \mu_{0})^{T}$$

$$S_{W} = (\Sigma_{1} + \Sigma_{0})$$

within class scatter

between class scatter

we use

$$J(w) = \frac{w^T S_B w}{w^T S_W w}$$

$$J(w) = \frac{w^T S_B w}{w^T S_W w}$$
$$S_B = (\mu_1 - \mu_0)(\mu_1 - \mu_0)^T$$
$$S_W = (\Sigma_1 + \Sigma_0 + \gamma I)$$

regularized within class scatter

Regularized discriminant analysis

- ▶ this is called regularized discriminant analysis (RDA)
- noting that

$$S_W = \Sigma_1 + \Sigma_0 + \gamma I$$

= \Sigma_1 + \gamma_1 I + \Sigma_0 + \gamma_0 I

$$\gamma_1 + \gamma_0 = \gamma$$

- this can also be seen as regularizing each covariance matrix individually
- the regularization parameters γ_i are determined by cross-validation
 - more on this later
 - basically means that we try several possibilities and keep the best

- ▶ back to PCA: given X with one example per column
 - 1) create the centered data-matrix

$$\boldsymbol{X}_{c}^{T} = \left(\boldsymbol{I} - \frac{1}{n} \boldsymbol{1} \boldsymbol{1}^{T}\right) \boldsymbol{X}^{T}$$

this has one point per row

$$X_c^T = \begin{bmatrix} x_1^T - \mu^T \\ \vdots \\ x_n^T - \mu^T \end{bmatrix}$$

• note that the projection of all points on principal component ϕ is

$$z = X_c^T \phi$$

$$\begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix} = \begin{bmatrix} (x_1 - \mu)^T \phi \\ \vdots \\ (x_n - \mu)^T \phi \end{bmatrix}$$

▶ and, since

$$\frac{1}{n}\sum_{i} z_{i} = \frac{1}{n}\sum_{i} \left(x_{i} - \mu\right)^{T} \phi = \left(\frac{1}{n}\sum_{i} x_{i} - \mu\right)^{T} \phi = 0$$

▶ the sample variance of Z is given by its norm

$$var(z) = \frac{1}{n} \sum_{i} z_{i}^{2} = ||z||^{2}$$

► recall that PCA looks for the largest variance component

$$\max_{\phi} \|z\|^{2} = \max_{\phi} \|X_{c}^{T} \phi\|^{2} = \max_{\phi} (X_{c}^{T} \phi)^{T} X_{c}^{T} \phi = \max_{\phi} \phi^{T} X_{c} X_{c}^{T} \phi$$

recall that the sample covariance is

$$\Sigma = \frac{1}{n} \sum_{i} (x_{i} - \mu)(x_{i} - \mu)^{T} = \frac{1}{n} \sum_{i} x_{i}^{c} (x_{i}^{c})^{T}$$

where x_i^c is the ith column of X_c

▶ this can be written as

$$\Sigma = \frac{1}{n} \begin{bmatrix} | & & | \\ x_1^c & \dots & x_n^c \\ | & | \end{bmatrix} \begin{bmatrix} - & x_1^c & - \\ & \vdots & \\ - & x_n^c & - \end{bmatrix} = \frac{1}{n} X_c X_c^T$$

▶ hence the PCA problem is

$$\max_{\phi} \phi^T X_c X_c^T \phi = \max_{\phi} \phi^T \Sigma \phi$$

- \blacktriangleright as in LDA, this can be made arbitrarily large by simply scaling ϕ
- \blacktriangleright to normalize we constrain ϕ to have unit norm

$$\max_{\phi} \phi^T \Sigma \phi \quad \text{subject to} \quad \|\phi\| = 1$$

which is equivalent to

$$\max_{\phi} \frac{\phi^T \Sigma \phi}{\phi^T \phi}$$

► shows that PCA = maximization of a Rayleigh quotient

▶ in this case

$$\max_{w} \frac{w^{T} S_{B} w}{w^{T} S_{W} w}$$

 S_{B}, S_{W} , symmetric positive semidefinite

- ▶ with $S_B = \Sigma$ and $S_w = I$
- \triangleright S_w is clearly invertible
 - no regularization problems
 - w* is the eigenvector of largest eigenvalue of S_w-1S_B
 - this is just the largest eigenvector of the covariance Σ
 - the max value is λ , where λ is the largest eigenvalue

The Rayleigh quotient dual

- let's assume, for a moment, that the solution is of the form $w = X_c \alpha$
 - i.e. a linear combination of the centered datapoints
- hence the problem is equivalent to

$$\max_{\alpha} \frac{\alpha^{T} X_{c}^{T} S_{B} X_{c} \alpha}{\alpha^{T} X_{c}^{T} S_{W} X_{c} \alpha}$$

- ▶ this does not change its form, the solution is
 - α* is the eigenvector of largest eigenvalue of (X_c^TS_wX_c)-1X_c^TS_BX_c
 - the max value is λK , where λ is the largest eigenvalue

The Rayleigh quotient dual

► for PCA

- $S_w = I$ and $S_B = \Sigma = 1/n X_c X_c^T$
- the solution satisfies

$$S_{B}W = \lambda S_{W}^{-1}W \Leftrightarrow \frac{1}{n}X_{c}X_{c}^{T}W = \lambda W \Leftrightarrow W = X_{c}\frac{1}{n\lambda}X_{c}^{T}W$$

- and, therefore, we have
 - w* eigenvalue of $S_B = X_c X_c^T$
 - α^* eigenvalue of $(X_c^T S_w X_c)^{-1} X_c^T S_B X_c = (X_c^T X_c)^{-1} X_c^T X_c X_c^T X_c = X_c^T X_c$
- i.e. we have two alternative manners in which to compute PCA

primal

- assemble matrix
- $\Sigma = X_c X_c^T$
- compute eigenvectors ϕ_i
- these are the principal components

dual

- assemble matrix
- $K = X_c^T X_c$
- compute eigenvectors α_i
- the principal components are
- $\phi_i = X_c \alpha_i$
- ▶ in both cases we have an eigenvalue problem
 - primal on the sum of outer products

$$\Sigma = \sum_{i} X_{i}^{c} \left(X_{i}^{c} \right)^{T}$$

dual on the matrix of inner products

$$K_{ij} = \left(X_i^c\right)^T X_j^c$$

- this is a property that holds for many Rayleigh quotient problems
 - the primal solution is a linear combination of datapoints
 - the dual solution only depends on dot-products of the datapoints

whenever both of these hold

- the problem can be kernelized
- this has various interesting properties
- we will talk about them

many examples

kernel PCA, kernel LDA, manifold learning, etc.

