

Channel Capacity Allocation & Convex Optimization

Lightning Day
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Sharif University of Technology

Kasra Khoshjoo



Presentation Overview

1. Preliminaries
2. Convexity in our setting
3. Solving a convex bandit problem

1. Preliminaries

- 2. Convexity in our setting
- 3. Solving a convex bandit problem

Problem Setting

- The Topology of the network is fixed
- Predetermined Budget : $\sum c(e_i) \leq B$
- for each pair (s, t) the amount of each transaction is an independent variable
- Light-tailed Distribution
- Higher probability near zero

A potential Solution

Stochastic convex optimization with bandit feedback
(Agarwal et al., 2011)

Convex Optimization

consider the following bandit problem:

- arms are vectors from the convex set \mathcal{X}
- the feedback for each arm x has the same distribution as $f(x) + \epsilon$
- f is a 1-Lipschitz convex function
- ϵ is sub-gaussian. i.e. $\forall x > 0 : \mathbb{P}[|\epsilon| > x] \leq 2e^{-\frac{x^2}{2\sigma^2}}$

the algorithm is guaranteed to have a regret in $\tilde{O}\left(\text{poly}(d)\sqrt{T}\right)$

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Convexity in our setting

Does our problem satisfy these criteria?

Convexity

- convexity of the feasible set is straightforward
- consider the expected reward of each transaction:

$$F(C) \triangleq \sum_{s,t} \mathbb{P}[S = s, T = t] \mathbf{1}_{\{v \text{ is in the shortest path of } (s,t)\}} \int_0^\infty \underbrace{\mathbb{P}_{s,t}[\text{amount} = \tau]}_{?} \mathbf{1}_{\{\tau < C(e_s), \tau < C(e_t)\}} \text{reward}(\tau) d\tau$$

Convexity

$$F(C) =$$

$$\sum_{s,t} \mathbb{P}[S = s, T = t] \mathbb{1}_{\{v \text{ is in } SP(s,t)\}} \left[\int_0^{\min\{C(e_s), C(e_t)\}} \mathbb{P}_{s,t}[\tau] \text{reward}(\tau) d\tau \right]$$

Exponential Distribution

$$\mathbb{P}_{s,t}[\tau] \triangleq \lambda_{s,t} e^{-\lambda_{s,t}\tau}$$

we have :

$$\frac{d^2}{dx^2} \int_0^x \lambda e^{-\lambda \tau} \tau d\tau = \lambda e^{-\lambda x} [-\lambda x + 1]$$

given that $\lambda_{s,t} \min\{C(e_s), C(e_t)\} > 1$, F as a function of capacities is concave

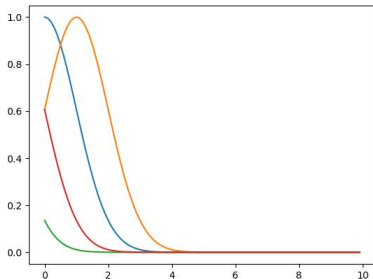
Exponential Distribution

✓ convexity

✗ concentration of measure

Case 2 : Truncated Normal Distribution

$$\mathbb{P}_{s,t}[\tau] = \frac{e^{-\frac{(\tau+\epsilon_{s,t})^2}{2\sigma_{s,t}^2}}}{\underbrace{\sigma_{s,t}\sqrt{2\pi} \cdot \phi(-\epsilon_{s,t})}_{\text{normalizing constant}}}$$



Convexity

define :

$$l(x) = \int_0^x \mathbb{P}_{s,t}[x] \cdot x \, dx$$

we have:

$$\frac{d^2}{dx^2} l(x) = \mathcal{C}_{s,t} e^{-\frac{(x+\epsilon)^2}{2\sigma^2}} [\sigma^2 - x^2 - \epsilon x]$$

the function $l(x)$ is concave if $x \in [\tau_0, \infty)$ and $\epsilon \geq \frac{\sigma^2}{\tau_0} - \tau_0$.

which means $F(C)$ is concave if $C(e_i) \geq \tau_0$:

$$\int_0^{\min\{C(e_s), C(e_t)\}} \mathbb{P}_{s,t}[\tau] (\alpha\tau + \beta) \, d\tau =$$

$$\alpha \overbrace{l(\min\{C(e_s), C(e_t)\})}^{\text{concave}} + \beta \mathcal{C}'_{s,t} \left[\phi\left(\frac{\overbrace{\min\{C(e_s), C(e_t)\} + \epsilon}^{\text{concave}}}{\sigma_{s,t}^2}\right) - \phi\left(\frac{\epsilon}{\sigma^2}\right) \right]$$

Truncated Normal Distribution

- ✓ convexity
- ✓ concentration of measure
- ? approximation of real world data

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one-dimensional case

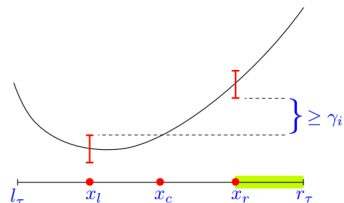
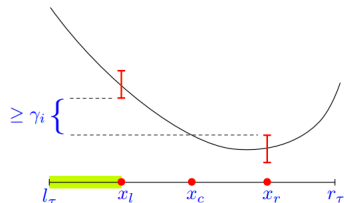


Figure 1: Two possible configurations when the algorithm enters case 1.

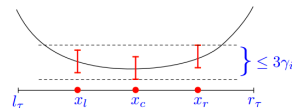
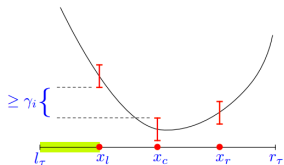


Figure 2: One of the possible configurations when

Figure 2: Configuration of the confidence intervals

Algorithm 1 One-dimensional stochastic convex bandit algorithm

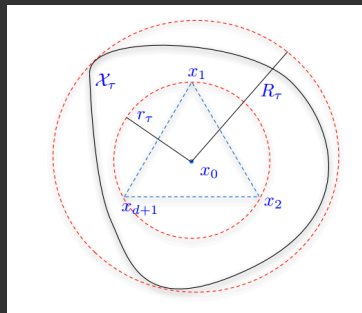
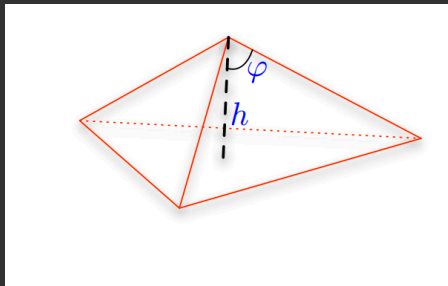
input noisy black-box access to $f: [0, 1] \rightarrow \mathbb{R}$, total number of queries allowed T .

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1: Let  $l_1 := 0$  and  $r_1 := 1$ .
2: for epoch  $\tau = 1, 2, \dots$  do
3:   Let  $w_\tau := r_\tau - l_\tau$ .
4:   Let  $x_l := l_\tau + w_\tau/4$ ,  $x_c := l_\tau + w_\tau/2$ , and  $x_r := l_\tau + 3w_\tau/4$ .
5:   for round  $i = 1, 2, \dots$  do
6:     Let  $\gamma_i := 2^{-i}$ .
7:     For each  $x \in \{x_l, x_c, x_r\}$ , query  $f(x)$   $\frac{2\sigma}{\gamma_i^2} \log T$  times. sampling
8:     if  $\max\{\text{LB}_{\gamma_i}(x_l), \text{LB}_{\gamma_i}(x_r)\} \geq \min\{\text{UB}_{\gamma_i}(x_l), \text{UB}_{\gamma_i}(x_r)\} + \gamma_i$  then
9:       {Case 1: CI's at  $x_l$  and  $x_r$  are  $\gamma_i$  separated}
10:      if  $\text{LB}_{\gamma_i}(x_l) \geq \text{LB}_{\gamma_i}(x_r)$  then let  $l_{\tau+1} := x_l$  and  $r_{\tau+1} := r_\tau$ .
11:      if  $\text{LB}_{\gamma_i}(x_l) < \text{LB}_{\gamma_i}(x_r)$  then let  $l_{\tau+1} := l_\tau$  and  $r_{\tau+1} := x_r$ .
12:      Continue to epoch  $\tau + 1$ .
13:    else if  $\max\{\text{LB}_{\gamma_i}(x_l), \text{LB}_{\gamma_i}(x_r)\} \geq \text{UB}_{\gamma_i}(x_c) + \gamma_i$  then
14:      {Case 2: CI's at  $x_c$  and  $x_l$  or  $x_r$  are  $\gamma_i$  separated}
15:      if  $\text{LB}_{\gamma_i}(x_l) \geq \text{LB}_{\gamma_i}(x_r)$  then let  $l_{\tau+1} := x_l$  and  $r_{\tau+1} := r_\tau$ .
16:      if  $\text{LB}_{\gamma_i}(x_l) < \text{LB}_{\gamma_i}(x_r)$  then let  $l_{\tau+1} := l_\tau$  and  $r_{\tau+1} := x_r$ .
17:      Continue to epoch  $\tau + 1$ .
18:    end if
19:  end for
20: end for

```

Higher Dimensions



- smallest euclidian ball containing \mathcal{X}_τ has radius R_τ
- $r_\tau \triangleq \frac{R_\tau}{c_1 \cdot d}$, $\mathcal{B}(r_\tau)$ is an euclidian ball of radius r_τ where $\mathcal{B}(r_\tau) \subseteq \mathcal{X}_\tau$

Cone Cutting

Algorithm 3 CONE-CUTTING

input pyramid Π with apex y , (rounded) feasible region \mathcal{X}_τ for epoch τ , enclosing ball \mathcal{B}_τ

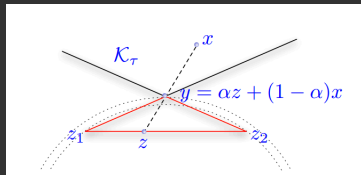
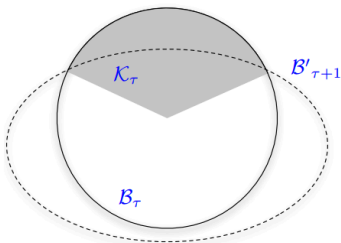
- 1: Let z_1, \dots, z_d be the vertices of the base of Π , and $\bar{\varphi}$ the angle at its apex.
- 2: Define the cone

$$\mathcal{K}_\tau = \{x \mid \exists \lambda > 0, \alpha_1, \dots, \alpha_d > 0, \sum_{i=1}^d \alpha_i = 1 : x = y - \lambda \sum_{i=1}^d \alpha_i (z_i - y)\}$$

- 3: Set $\mathcal{B}'_{\tau+1}$ to be the min. volume ellipsoid containing $\mathcal{B}_\tau \setminus \mathcal{K}_\tau$.

- 4: Set $\mathcal{X}_{\tau+1} = \mathcal{X}_\tau \cap \mathcal{B}'_{\tau+1}$.

output new feasible region $\mathcal{X}_{\tau+1}$ and enclosing ellipsoid $\mathcal{B}'_{\tau+1}$.



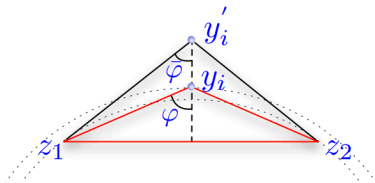
Hat Raising

Algorithm 4 HAT-RAISING

input pyramid Π with apex y , (rounded) feasible region \mathcal{X}_τ for epoch τ , enclosing ball \mathcal{B}_τ .

- 1: Let CENTER be the center of Π .
- 2: Set $y' = y + (y - \text{CENTER})$.
- 3: Set Π' to be the pyramid with apex y' and same base as Π .
- 4: Set $(\mathcal{X}_{\tau+1}, \mathcal{B}'_{\tau+1}) = \text{CONE-CUTTING}(\Pi', \mathcal{X}_\tau, \mathcal{B}_\tau)$.

output new feasible region $\mathcal{X}_{\tau+1}$ and enclosing ellipsoid $\mathcal{B}'_{\tau+1}$.



Algorithm for Higher Dimensions

