Statistical Machine Learning

Summer Term 2021, Homework 1

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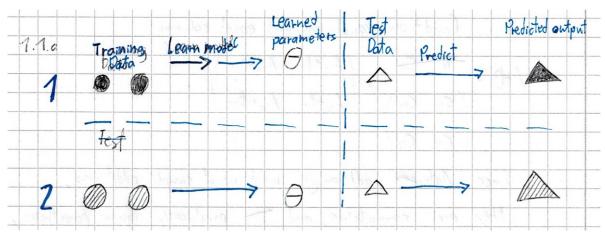
Total points: 80

Due date: 25. May 2018

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Problem 1.1 Machine Learning Introduction [6 Points]

a) Model Fitting [6 Points]



Model 1 is being trained on filled circles, and as such assumes that the triangle is also to be filled, coming to an incorrect result.

Model 2 is being trained on striped circles, and as such assumes that the triangle is also to be striped, coming to the correct conclusion.

Problem 1.2 Linear Algebra Refresher [20 Points]

- a) Matrix Properties [5 Points]
 - 1. Multiplication

$$A*B = \begin{pmatrix} A_{1,1}*B_{1,1} + A_{2,1}*B_{1,2} & A_{1,1}*B_{2,1} + A_{2,1}*B_{2,2} \\ A_{1,2}*B_{1,1} + A_{2,2}*B_{1,2} & A_{1,2}*B_{2,1} + A_{2,2}*B_{2,2} \end{pmatrix}$$

A*B is defined only when Columns of B equal rows of A.

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} * \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

BUT

$$\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} * \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

Matrixmultiplication is not Commutative.

A(B+C) = AB + AC

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} * \begin{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} * \begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 0 & 0 \end{pmatrix}$$

Matrixmultiplication is Distributive.

$$(A*B)*C = A*(B*C)$$

$$\left(\begin{pmatrix}0&1\\0&0\end{pmatrix}*\begin{pmatrix}0&0\\1&0\end{pmatrix}\right)*\begin{pmatrix}1&1\\1&1\end{pmatrix}=\begin{pmatrix}1&1\\0&0\right)$$

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} * \begin{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} * \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$$

2. Addition Since matrix-addition is made up of simple additions, they are commutative and practically ignore parentheses, so are also distributive and associative.

The condition for any matrix-addition is that the matrices have both equal rows and columns.

$$A_{2,2}+B_{2,2} = \begin{pmatrix} C_{1,1} & C_{2,1} \\ C_{1,2} & C_{2,2} \end{pmatrix} = \begin{pmatrix} A_{1,1}+B_{1,1} & A_{2,1}+B_{2,1} \\ A_{1,2}+B_{1,2} & A_{2,2}+B_{2,2} \end{pmatrix}$$

b) Matrix Inversion [7 Points]

$$A^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

...Via Gauß-Jordan. Under the condition that a=b=d=0; c=1

$$\begin{pmatrix} 2 & 2 & 3 \\ 0 & 1 & 0 \\ 8 & 3 & 12 \end{pmatrix}$$

Is not invertable, since it's Determinant Det = 0.

c) Matrix Pseudoinverse [3 Points]

Left:
$$A^{\#} * A = (A^{T} * A)^{-1} * A^{T}$$

Right:
$$A * A^{\#} = A * A^{T} (A * A^{T})^{-1}$$

Right: $A*A^{\#} = A*A^{T} (A*A^{T})^{-1}$ Since A_{2x3} has more rows than columns, the left Moore-Penrose exists. The equation is: $A_{3x2}^{\#}*A = (A_{3x2}^{T}*A_{2x3})_{2x2}^{-1}*A_{3x2}^{T}$

The equation is:
$$A_{3x2}^{\#} * A = (A_{3x2}^{T} * A_{2x3})_{2x2}^{-1} * A_{3x2}^{T}$$

d) Basis Transformation [5 Points]

Vector with new Basis $v^* = T^{-1} * v$

1)
$$T_v = E^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}; T_w = B^{-1} = \begin{pmatrix} 2 & -1.5 \\ -1 & 1 \end{pmatrix}$$

2)
$$2 * \begin{bmatrix} 2 \\ -1 \end{bmatrix} + 5 * \begin{bmatrix} -1, 5 \\ 1 \end{bmatrix} = \begin{bmatrix} -3, 5 \\ 3 \end{bmatrix} = v^*$$

Problem 1.3 Statistics Refreshner [29 Points]

- a) Expectation & Variance [8 Points]
 - 1. We can define the expectation by

$$E|f| = \sum_{w \in \Omega} P(w)f(w) \tag{18}$$

Which leads to the variance:

$$var[f] = E|f^2| - E[f]^2.$$
 (19)

If we have 2 random variables X,Y and Z=X+Y. Then is the expectation a linear function, since for any 2 points

$$E[Z] = \sum_{w \in \Omega} Z(w) P(w) = \sum_{w \in \Omega} (X(w) + Y(w)) P(w) = E[X] + E[Y]$$
(20)

applies. Since the variance of the sum of 2 random variables is

$$var\left[Z\right] = E\left[Z^2\right] - E\left[Z\right]^2 = var\left|X\right| + var\left[Y\right] + 2E\left[XY\right] - 2E\left[X\right]E\left[Y\right]isE\left[XY\right] \neq E\left[X\right]E\left[Y\right] \tag{21}$$

2. Unbiased estimator:

$$\overline{x} = \frac{1}{n} * \sum_{i=1}^{n} x_i \tag{23}$$

$$\overline{xA} = \frac{1}{6} * (1 + 5 + 6 + 3 + 2 + 1) = 3$$
 (24)

$$\overline{xB} = \frac{1}{6} * (6+1+1+4+1+5) = 3$$
 (25)

$$\overline{xC} = \frac{1}{6} * (3 + 2 + 3 + 3 + 4 + 3) = 3$$
 (26)

unbiased estimator for the variance

$$\overline{\sigma} = \frac{1}{n-1} * \sum_{i=1}^{n} x_i - \overline{x}^2 \tag{27}$$

$$\overline{\sigma A} = \frac{1}{5} * ((1-3)^2 + (5-3)^2 + (6-3)^2 + (3-3)^2 + (2-3)^2 + (1-3)^2) = \frac{22}{5} = 4,4$$
 (28)

$$\overline{\sigma B} = \frac{1}{5} * ((6-3)^2 + (1-3)^2 + (1-3)^2 + (4-3)^2 + (1-3)^2 + (5-3)^2) = \frac{26}{5} = 5, 2$$
 (29)

$$\overline{\sigma C} = \frac{1}{5} * ((3-3)^2 + (2-3)^2 + (3-3)^2 + (4-3)^2 + (3-3)^2 + (3-3)^2) = \frac{2}{5} = 0,4$$
 (30)

3.

$$KL: \sum_{x \in V} P(x) ln \frac{P(x)}{Q(x)}$$
(31)

$$KL(PA \parallel Q) = \frac{3}{6} * ln\left(\frac{\frac{3}{6}}{\frac{1}{6}}\right) + \frac{1}{6} * ln\left(\frac{\frac{1}{6}}{\frac{1}{6}}\right) + \frac{1}{6} * ln\left(\frac{\frac{1}{6}}{\frac{1}{6}}\right) + \frac{1}{6} * ln\left(\frac{\frac{1}{6}}{\frac{1}{6}}\right) + \frac{1}{6} * ln\left(\frac{\frac{1}{6}}{\frac{1}{6}}\right) = 3$$
(32)

$$KL(PB \parallel Q) = \frac{1}{6} * ln\left(\frac{\frac{1}{6}}{\frac{1}{6}}\right) + \frac{2}{6} * ln\left(\frac{\frac{2}{6}}{\frac{1}{6}}\right) + \frac{1}{6} * ln\left(\frac{\frac{1}{6}}{\frac{1}{6}}\right) + \frac{1}{6} * ln\left(\frac{\frac{1}{6}}{\frac{1}{6}}\right) = 1,52$$
(33)

$$KL(PC \parallel Q) = \frac{4}{6} * ln\left(\frac{\frac{4}{6}}{\frac{1}{6}}\right) + \frac{1}{6} * ln\left(\frac{\frac{1}{6}}{\frac{1}{6}}\right) + \frac{1}{6} * ln\left(\frac{\frac{1}{6}}{\frac{1}{6}}\right) = 2.38$$
 (34)

A has the biggest KL divergence, so it is the closest

b) It is a cold world [7 Points]

1.

$$a \in \{0, 1\}$$
: if apersonhasbackspin, with $1 = pain and 0 = nopain$ (43)

$$b \in \{0,1\}$$
: if a person has a cold, with $1 = pain and 0 = no cold$ (44)

2.

$$P(a=1 | b=1) = 0,25$$
 (45)

$$P(b=1) = 0.04 \tag{46}$$

$$P(a=1 | b=0) = 0,1$$
 (47)

3. Rule of Bayes

$$P(b=1 \mid a=1) = \frac{P(a=1 \mid b=1)P(b=1)}{P(b=1)}$$
(48)

$$\frac{P(a=1 \mid b=1)P(b=1)}{P(a=1 \mid b=1)P(b=1) + P(a=1 \mid b=0)P(b=0)}$$
(49)

Werteeinsetzen:
$$\frac{0,25*0,04}{0,25*0,04+0,10*(1-0,04)} = \frac{5}{53} \approx 0,094$$
 (50)

- c) Cure the virus [14 Points]
 - 1. Markov Chain

$$S_0 = \begin{pmatrix} 1\\0 \end{pmatrix} \tag{56}$$

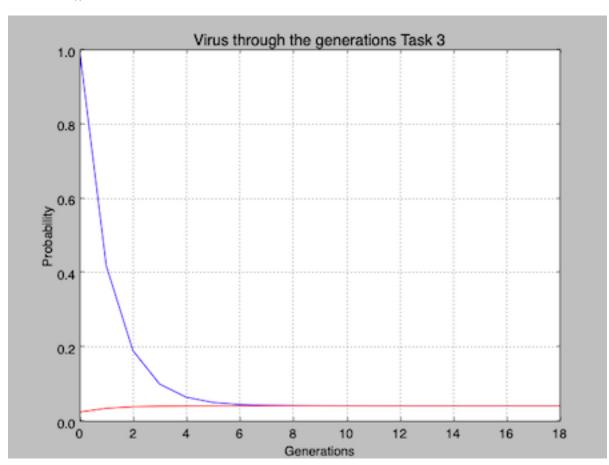
$$S_1 = \begin{pmatrix} 0,42\\0,58 \end{pmatrix} \tag{57}$$

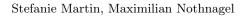
$$P = \begin{pmatrix} 0,42 & 0,974 \\ 0,58 & 0,026 \end{pmatrix} \tag{58}$$

$$S_1 = P * S_0 \longleftrightarrow \begin{pmatrix} 0,42\\0,58 \end{pmatrix} = \begin{pmatrix} 0,42 & 0,974\\0,58 & 0,026 \end{pmatrix} * \begin{pmatrix} 1\\0 \end{pmatrix}$$
 (59)

$$S_2 = P * S_1 \longleftrightarrow \begin{pmatrix} 0,741 \\ 0,394 \end{pmatrix} = \begin{pmatrix} 0,42 & 0,974 \\ 0,58 & 0,026 \end{pmatrix} * \begin{pmatrix} 0,42 \\ 0,58 \end{pmatrix}$$
 (60)

```
2. import numpy as np
  import matplotlib.pyplot as plt
  def markovChain(s0, p, g):
      s = s0.copy()
       result = np.zeros(g+1)
       result[0] = s[0]
       for i in range (1, g+1):
           s = s.dot(p)
           result[i]=s[0]
       return result
  s0 = np.array([1, 0])
  s1 = np.array([0.026, 0.974])
  p = np.array([[0.42, 0.58], [0.026, 0.974]])
  n = np.arange(0, 19, 1)
  gen18 = markovChain(s0, p, 18)
  gen18prog = markovChain(s1, p, 18)
  plt.plot(n, gen18, 'b')
  plt.plot(n, gen18prog, 'r')
plt.xlabel('Generations')
  plt.ylabel('Probability')
  plt.title('Virus_through_the_generations_Task_3')
  plt.grid(True)
  plt.show()
```





3.

Problem 1.4 Information Theory [5 Points]

- a) Entropy [5 Points]

2.

Problem 1.5 Bayesian Decision Theory [20 Points]

- a) Optimal Boundary [4 Points]
 - 1. Bayesian decision theory is a fundamental statistical approach to the problem of pattern classification based probabilities.
 - 2. The goal is to decide which class an example x most likely belongs to. This is done by comparing the class posterior probabilities $p(C_i | x)$, which can be calculated by Bayes' theorem:

$$p(C_i \mid x) = \frac{p(x \mid C_i)p(C_i)}{p(x)} \propto p(x \mid C_i)p(C_i)$$

- 3. The decision boundary of two classes C_1 and C_2 is given by $p(C_1 \mid x) = p(C_2 \mid x)$, where C_1 is chosen over C_2 if $p(C_1 \mid x) > p(C_2 \mid x)$.
- b) Decision Boundaries [8 Points]
- c) Different Misclassification Cost [8 Points]
 - 1.
 - 2.