

# MATLAB Tutorial

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# Variables and Assignments

- To store a value, use a *variable*
- One way to put a value(s) in a variable is with an *assignment statement*
- General form:

*variable = expression*

```
% variable = expression  
a1 = 3  
a2 = 5
```

Name	Value
a1	3
a2	5

- The order is important
  - Variable name on the left
  - Assignment operator “=” (Note: this does NOT mean equality)
  - Expression on the right

# Variable names

- Names **must** begin with a letter of the alphabet
- After that names can contain letters, digits, and **the underscore character(\_)**
- You cannot use other character except for '\_'
- MATLAB is **case-sensitive**
- Names should be **mnemonic** (they should make sense!)
- Use a workspace browser rather than type these command
- **clear** clears out variables and also functions

## Example: Variable names

```
8val = 10; % error: must begin with a letter of the alphabet  
  
_col = 0 ; % error: must begin with a letter of the alphabet  
  
row_3_ = 1; % no error  
  
row@3 = 10; % error: cannot contain characters other than underscore  
  
col-03 = 10; % error: cannot contain characters other than underscore  
  
% Following scripts have no error but the names should be mnemonic  
asdf1 = 100; % no error  
love = 10; % no error  
aaaa3 = 10; % no error
```

```
% define a variable of 'gal'  
gal = 100
```

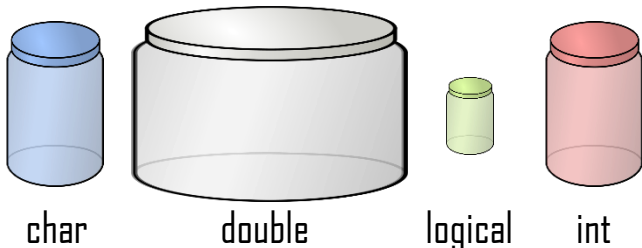
Q: What value is in 'Ga1' ?

# Data Types

- Every expression and variable has an associated *type*, or *class*
  - Real numbers: **single**, **double**
  - Integer types: numbers in the names are the number of bits used to store a value of that type
    - Signed integers: **int8**, **int16**, **int32**, **int64**
    - Unsigned integers: **uint8**, **uint16**, **uint32**, **uint64**
  - Single characters and character vectors: **char**
  - Strings of characters: **string**
  - True/false: **logical**

The default type for numbers in MATLAB is **double**

## Container



## Example

- 2.145, 0.15893, 3.0, 2.45
- 10, 11, 24, 30, 400
- 'a', 'b', 'A', 'c'
- 0, 1

# Constants

- In programming, variables are used for values that **could change**, or **are not known** in advance
- **Constants** are used when the value is known and is not updated in the program.
- Examples in MATLAB (these are actually functions that return constant values)
  - **pi**      3.14159....
  - **i, j**    imaginary number
  - **inf**     infinity
  - **NaN**    stands for “not a number”; e.g. the result of 0/0

## Example: Arithmetic Operation in MATLAB

If the car has a mass of 300kg and you push the car with an acceleration of 5 , compute the force that is generated from the car in newton

```
% MATLAB as a calculator  
300*5*0.0254
```

Name	Value
ans	38.1

```
% MATLAB as programming tool  
  
inch2m = 0.0254; % inch to m  
mass = 300; % kg  
accel = 5; % inch/s/s  
  
% force = mass(kg) * acceleration (m/s/s)  
force = mass * accel * inch2m;
```

Name	Value
inch2m	0.0254
mass	300
accel	5
force	38.1

# Operator Precedence

- A symbol that perform specific mathematical or logical manipulations.
- Precedence list (highest to lowest) so far:
  - ( ) parentheses
  - ^ exponentiation
  - negation
  - \*, /, \ all multiplication and division
  - +, - addition and subtraction
- **Nested parentheses: expressions in inner parentheses are evaluated first**

```
val1 = (5 + 1)*2;  
val2 = 10^2*3;  
val3 = 10^(2+3) ;  
val4 = 4-3*2;  
val5 = 3*((4+3)*2) ;
```

Name	Value
val1	12
val2	300
val3	100000
val4	-2
val5	42



# Relational Operator

- The relational operators in MATLAB are:

> greater than  
< less than  
>= greater than or equals  
<= less than or equals  
== equality  
~= inequality



- The resulting type is **logical 1** for true or 0 for false

```
% relation operator  
ro1 = 3 < 4;  
ro2 = 3 > 5;  
ro3 = 3 == 5;  
ro4 = 3 ~= 7;  
ro5 = 3 <= 3;  
ro6 = 3 >= 3;
```

Name	Value
ro1	1
ro2	0
ro3	0
ro4	1
ro5	1
ro6	1

# Logical Operator



- The logical operators are:
  - `||` or for scalars
  - `&&` and for scalars
  - `~` not
- Also, **`xor`** function which returns true if only one of the arguments is true
- Note that the logical operators are commutative
  - (e.g., `x || y` is equivalent to `y || x`)
- The resulting type is **logical 1** for true or **0** for false

x	y
true	true
true	false
false	false



<code>~x</code>	<code>x    y</code>	<code>x &amp;&amp; y</code>	<code>xor(x,y)</code>
false	true	true	false
false	true	false	true
true	false	false	false

# Operator Precedence

Parentheses ( )

Transpose (.'), power (.^), complex conjugate transpose ('), matrix power (^)

Multiplication (.\*), right division (./), left division (.\), matrix multiplication (\*), matrix right division (/), matrix left division (\)

Addition (+), subtraction (-)

Colon operator ( : )

Less than (<), less than or equal to (<=), greater than (>), greater than or equal to (>=), equal to (==), not equal to (~=)

Short-circuit AND (&&)

Short-circuit OR (||)

```
lg1 = (3 < 4) < 4;  
lg2 = 3 < (4 < 5);  
lg3 = (3 > 5) + 3;  
lg4 = (10 > 4) && (4 > 1);  
lg5 = (10 < 4) && (4 < 1);  
lg6 = ~( (10 < 4) && (4 < 1) );  
lg7 = 2 < 3 + 4;
```

Name	Value
lg1	1
lg2	0
lg3	3
lg4	1
lg5	0
lg6	1
lg7	1

## Example2: Operator Precedence



How to write a code to check if x lies in between 5 and 10. If yes, 1 and otherwise 0.

```
x1 = 6;  
x2 = 11;  
  
lg1 = (5<=x1) && (x1<=10)  
lg2 = 5 <= x1 <=10;  
lg3 = (5 <= x1) <=10;  
  
lg4 = (5<=x2) && (x2<=10)  
lg5 = 5<= x2 <=10;  
lg6 = (5 <= x2) <=10;
```

Name	Value
x1	6
x2	11
lg1	0
lg2	1
lg3	1
lg4	0
lg5	1
lg6	1

# Array Operations

Array operations on two matrices A and B:

- These are applied term-by-term, or element-by-element
- The matrices must have the same dimensions (no! after R2016)
- In MATLAB:
  - addition/subtraction:  $A + B$ ,  $A - B$
  - array multiplication:  $A .* B$
  - array division:  $A ./ B$ ,  $A ./ B$
  - array exponentiation  $A.^2$
- Matrix multiplication: NOT an array operation

```
A = [2 2 2; 4 4 4; 6 6 6];
```

```
B = [1 1 1; 2 2 2; 3 3 3];
```

```
AmB = A.*B;
```

```
AdB = A./B;
```

2	2	2
4	4	4
6	6	6

A

1	1	1
2	2	2
3	3	3

B

2	2	2
8	8	8
18	18	18

AmB

2	2	2
2	2	2
2	2	2

AdB

# Matrix Multiplication: Dimensions

- **Matrix multiplication** is not an array operation
  - It does not mean multiplying term by term
- In MATLAB, the multiplication **operator** `*` performs matrix multiplication
- In order to be able to multiply a matrix A by a matrix B, the number of columns of A must be the same as the number of rows of B
- If the matrix A has dimensions  $m \times n$ , that means that matrix B must have dimensions  $n \times \text{something}$ ; we will call it  $p$ 
  - In mathematical notation,  $[A]_{m \times n} [B]_{n \times p}$
  - We say that the **inner dimensions** must be the same
- The resulting matrix C has the same number of rows as A and the same number of columns as B
  - in other words, the **outer dimensions**  $m \times p$
  - In mathematical notation,  $[A]_{m \times n} [B]_{n \times p} = [C]_{m \times p}$ .
  - This only defines the size of C

## Matrix Times a Vector

A linear system of equations with coefficient matrix  $A$ , variable vector  $\vec{x}$  and constant term vector  $\vec{b}$ , can be expressed as

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

$$\begin{matrix} \text{matrix} & \text{vector} & \text{vector} \\ (m \times n) & (n \times 1) & = (m \times 1) \end{matrix}$$

**Compatibility** – the number of columns in the matrix **must** equal the number of rows in the vector.

## Example: Matrix Times a Vector

```
m1 = [1 1 1; 2 2 2; 3 3 3];
```

```
v1 = [2 2 2]';
```

```
c1 = m1*v1;
```

```
c21 = m1(1,:) * v1;
```

```
c22 = m1(2,:) * v1;
```

```
c23 = m1(3,:) * v1;
```

```
c2 = [c21; c22; c23];
```

1	1	1		2		6
2	2	2	*	2	=	12
3	3	3		2		18

m1 \* v1 = c1

				2		
1	1	1	*	2	=	6
				2		

m1(1,:) \* v1 = c21

				2		
2	2	2	*	2	=	12
				2		

m1(2,:) \* v1 = c22

				2		
3	3	3	*	2	=	18
				2		

m1(3,:) \* v1 = c23



# Matrix Times a Matrix

Matrix multiplication is an extension of matrix and vector multiplication.

Consider the product of an  $m \times n$  matrix  $A$ , and an  $n \times p$  matrix  $B$ :

$$AB = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ b_{31} & b_{32} & \cdots & b_{3p} \\ \vdots & \vdots & & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{bmatrix}$$

$$\begin{matrix} \text{matrix} & \text{matrix} & \text{matrix} \\ (m \times n) & (n \times p) & = (m \times p) \end{matrix}$$

**Compatibility** – the number of columns in the first matrix **must** equal the number of rows in the second matrix.

## Example: Matrix Times a Matrix

```
m1 = [1 2;3 4];
```

```
m2 = [1 2;2 1];
```

```
m3 = m1*m2;
```

```
m411 = m1(1,:) * m2(:,1);
```

```
m421 = m1(2,:) * m2(:,1);
```

```
m412 = m1(1,:) * m2(:,2);
```

```
m422 = m1(2,:) * m2(:,2);
```

```
m4 = [m411 m412;m421 m422];
```

$$\begin{bmatrix} 3 & 4 \end{bmatrix} * \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 11 \end{bmatrix}$$

$$m1(1,:) * m2(:,2) = m412$$

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} * \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 5 & 4 \\ 11 & 10 \end{bmatrix}$$

$$m1 * m2 = m3$$

$$\begin{bmatrix} 1 & 2 \end{bmatrix} * \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \end{bmatrix}$$

$$m1(1,:) * m2(:,1) = m411$$

$$\begin{bmatrix} 1 & 2 \end{bmatrix} * \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \end{bmatrix}$$

$$m1(1,:) * m2(:,2) = m412$$

$$\begin{bmatrix} 3 & 4 \end{bmatrix} * \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 10 \end{bmatrix}$$

$$m1(2,:) * m2(:,2) = m422$$

## Example: Swapping Columns

Swap the 2<sup>nd</sup> and 3<sup>rd</sup> columns in `mat1`

1	2	3
4	5	6
7	8	9

1	3	2
4	6	5
7	9	8

```
mat1 = [1 2 3; 4 5 6; 7 8 9];
```

```
mat1(:, [3 2]) = ...
```

```
mat1(:, [2 3]);
```

## Quiz

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \\ a_{41} & a_{42} & a_{43} \end{pmatrix}$$

**A**

$$\begin{pmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \end{pmatrix}$$

**B**

$$(r_1 \quad r_2 \quad r_3 \quad r_4)$$

**r**

$$\begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{pmatrix}$$

**c**

`vec_c =`

$$\begin{pmatrix} a_{11} r_1 + a_{21} r_2 + a_{31} r_3 + a_{41} r_4 \\ a_{12} r_1 + a_{22} r_2 + a_{32} r_3 + a_{42} r_4 \\ a_{13} r_1 + a_{23} r_2 + a_{33} r_3 + a_{43} r_4 \end{pmatrix}$$

`mat_f =`

$$\begin{pmatrix} a_{11} c_1 + a_{12} c_2 + a_{13} c_3 \\ a_{21} c_1 + a_{22} c_2 + a_{23} c_3 \\ a_{31} c_1 + a_{32} c_2 + a_{33} c_3 \\ a_{41} c_1 + a_{42} c_2 + a_{43} c_3 \end{pmatrix}$$

`mat_g =`

$$\begin{pmatrix} a_{11} b_{11} + a_{12} b_{21} & a_{11} b_{12} + a_{12} b_{22} \\ a_{21} b_{11} + a_{22} b_{21} & a_{21} b_{12} + a_{22} b_{22} \end{pmatrix}$$

# Linear Indexing

Linear indexing: only using one index into a matrix (MATLAB will unwind it column-by-column)

A

1	5	9	5
12	3	4	14
3	17	6	1
4	1	7	2

A(1)	1
A(2,3)	4
A(10)	3
A([10 12])	[4 7]
A(1:4)	[1 12 3 4]'
A([1:4:13])	[1 5 9 5]

Linear index of  
each cell in A

1	5	9	13
2	6	10	14
3	7	11	15
4	8	12	16

m1 = [1 2;3 4];
m2 = [1 2;3 4];
m1(1,1) = 3; % m2(1) = 3;
m1(1,:) = [3 4 5 6];
% m1([1 5 9 13]) = [3 4 5 6];

# If-Statement

- The **if** statement is used to determine whether or not a statement or group of statements is to be executed
- General form:

```
if condition
    action
end
```
- the *condition* is any relational expression (True or False)
- the *action* is any number of valid statements (including, possibly, just one)
- If the condition is true, the action is executed – otherwise, it is skipped entirely

## Example 1: If-Statement

**abs (x)**

Finds the absolute value of **x**

**abs (-3)**

**3**

**abs (2)**

**2**

```
x1 = -3
xsign = 1;

if x1<0
    xsign = -1;
end

x1_abs = xsign*x1;
```

```
x1 = 3
xsign = 1;

if x1<0
    xsign = -1;
end

x1_abs = xsign*x1;
```

Name	Value
x1	-3
x1_abs	3
xsign	-1

Name	Value
x1	3
x1_abs	3
xsign	1

## Example 2: If-Statement

<b>sign(x)</b>	Return <b>-1</b> if <b>x</b> is less than zero, a value of <b>0</b> if <b>x</b> equals zero, and a value of <b>1</b> if <b>x</b> is greater than zero.	<b>sign(-5)</b> <b>sign(3)</b> <b>sign(0)</b>	<b>-1</b> <b>1</b> <b>0</b>
----------------	--	---	-----------------------------------

```
x1 = -3
xsign = 0;

if x1<0
    xsign = -1;
end

if x1>0
    xsign = 1;
end
```

Name	Value
x1	-3
xsign	-1

```
x1 = 3
xsign = 0;

if x1<0
    xsign = -1;
end

if x1>0
    xsign = 1;
end
```

Name	Value
x1	3
x1_abs	1



# If-else Statement

- The **if-else** statement chooses between two actions
- General form:

```
if condition
    action1
else
    action2
end
```

- Only one action is executed; which one depends on the value of the condition (`action1` if it is logical true or `action2` if it is false)

## Example 1: If-else Statement

**abs (x)**

Finds the absolute value of **x**

**abs (-3)**

**3**

**abs (2)**

**2**

```
x1 = -3;  
xsign = 1;  
  
if x1<0  
    xsign = -1;  
end  
  
x1_abs = xsign*x1;
```

```
x1=-3;  
  
if x1 < 3  
    x1_abs = -1*x1;  
else  
    x1_abs = x1;  
end
```

Name	Value
x1	-3
x1_abs	3
xsign	-1

Name	Value
x1	-3
x1_abs	3

# Nested if-else Statements

- To choose from more than two actions, ***nested if-else*** statements can be used (an **if** or **if-else** statement as the action of another)
- General form:

```
if condition1
    action1
else
    if condition2
        action2
    else
        action3
    end
end
```

## Example: Nested if-else Statements

Q: If 'scalar1' is larger than 0 and less than 50, assign 10 to 'out1'. Otherwise, assign 5 to 'out1'.

```
scalar1 = 20;

if scalar1 > 0
    if scalar1 < 50
        out1 = 10;
    else
        out1 = 5;
    end
end
```

```
scalar1 = 20;

if (scalar1 > 0) && (scalar1 < 50)
    out1 = 10;
else
    out1 = 5;
end
```

# if, if-else, if-elseif, if-elseif-else

if condition1

action1

end

if condition1

action1

else

action2

end

if condition1

action1

elseif condition2

action2

end

if condition1

action1

elseif condition2

action2

else

action3

end

# For-Loop Statement

- Used as a counted loop (We know how many times are repeated)
- **Repeats an action** a specified number of times
- An **iterator** or loop variable specifies how many times to repeat the action
- General form:

```
for loopvar = range
    action
end
```
- The range is specified by **a vector**.
- The action is repeated for every value of `loopvar` in the specified vector
- If it is desired to repeat the process of prompting the user and reading input a specified number of times (N), a for loop is used:

```
for ii = 1:N
    % do something with it!
end
```

## Example1: How For-Loop Works

```
1 sumv = 0;  
2 for ii=1:3  
3     sumv = sumv + ii;  
4 end  
5
```

Step	Operation	Workspace
1	line1: assign 0 to sumv	sumv → 0
2	line2: ii becomes 1	sumv → 0, ii → 1
3	line3: add sumv and ii, and assign the value to sumv	sumv → 1, ii → 1
4	line4: end	sumv → 1, ii → 1
5	go to line2 and ii becomes 2	sumv → 1, ii → 2
6	line3: add sum and ii, and assign the value to sumv	sumv → 3, ii → 2
7	line4: end	sumv → 3, ii → 2
8	go to line2 and ii becomes 3	sumv → 3, ii → 3
9	line3: add sum and ii, and assign the value to sumv	sumv → 6, ii → 3
10	line4: end	sumv → 6, ii → 3
11	no more value in range, and go to line5	sumv → 6, ii → 3

## Example2: Summation Using For-Loop (continue)

Sum all values in a vector named 'vec' and assign the value to 'sumv'

1	vec = [1 3 7 11];
2	sumv = 0;
3	for ii=1:4
4	sumv = sumv + vec(ii);
5	end

1	vec = [1 3 7 11];
2	sumv = 0;
3	for ii=vec
4	sumv = sumv + ii;
5	end

```
for ii = 1:N
    % do something!
end
```

```
for loopvar = range
    action
end
```



## Nested For-Loop Statement

- A nested **for** loop is one inside of ( as the action of) another **for** loop
- General form of a nested **for** loop:

```
for loopvar1 = range1
    action1
    for loopvar2 = range2
        action2
    end
end
```
- The inner loop action is executed in its entirety for every value of the outer loop variable

## Example1: How Nested For-Loop Works

```
1 mat1 = [1 2 3;4 5 6];
2 sumv = 0;
3 for ii=1:2
4     for jj=1:3
5         sumv = sumv + mat1(ii,jj);
6     end
7 end
```

mat1

1	2	3
4	5	6

Step	Operation	Workspace
1	line1: assign values to mat1	mat1 → [1 2 3;4 5 6]
2	line2: assign 0 to sumv	mat1 → [1 2 3;4 5 6], sumv → 0
3	line3: ii becomes 1	ii → 1, mat1 → [1 2 3;4 5 6], sumv → 0
4	line4: jj becomes 1	ii → 1, jj → 1, mat1 → [1 2 3;4 5 6], sumv → 0
5	line5: read a value at 1 row and 1 column in mat1, and add the value to sumv	ii → 1, jj → 1, mat1 → [1 2 3;4 5 6], sumv → 1
6	line6: end	ii → 1, jj → 1, mat1 → [1 2 3;4 5 6], sumv → 1
7	line4: jj becomes 2	ii → 1, jj → 2, mat1 → [1 2 3;4 5 6], sumv → 1

## Example1: How Nested For-Loop Works

```

1  mat1 = [1 2 3;4 5 6];
2  sumv = 0;
3  for ii=1:2
4      for jj=1:3
5          sumv = sumv + mat1(ii,jj);
6      end
7  end

```

mat1

1	2	3
4	5	6

Step	Operation	Workspace
7	line5: read a value at 1 row and 2 column in mat1, and add the value to sumv	ii → 1, jj → 2, mat1 → [1 2 3;4 5 6], sumv → 3
8	line6: end	ii → 1, jj → 2, mat1 → [1 2 3;4 5 6], sumv → 3
9	line4: jj becomes 3	ii → 1, jj → 3, mat1 → [1 2 3;4 5 6], sumv → 3
10	line5: read a value at 1 row and 3 column in mat1, and add the value to sumv	ii → 1, jj → 3, mat1 → [1 2 3;4 5 6], sumv → 6
11	line6: end and line7: end	ii → 1, jj → 3, mat1 → [1 2 3;4 5 6], sumv → 6
12	line3: ii becomes 2	ii → 2, jj → 3, mat1 → [1 2 3;4 5 6], sumv → 6
13	line4: jj becomes 1	ii → 2, jj → 1, mat1 → [1 2 3;4 5 6], sumv → 6

## Example1: How Nested For-Loop Works

```
1  mat1 = [1 2 3;4 5 6];
2  sumv = 0;
3  for ii=1:2
4      for jj=1:3
5          sumv = sumv + mat1(ii,jj);
6      end
7  end
```

mat1

1	2	3
4	5	6

Step	Operation	Workspace
14	line5: read a value at 1 row and 2 column in mat1, and add the value to sumv	ii → 2, jj → 1, mat1 → [1 2 3;4 5 6], sumv → 10
15	line6: end	ii → 2, jj → 1, mat1 → [1 2 3;4 5 6], sumv → 10
16	line4: jj becomes 2	ii → 2, jj → 2, mat1 → [1 2 3;4 5 6], sumv → 10
17	line5: read a value at 1 row and 3 column in mat1, and add the value to sumv	ii → 2, jj → 2, mat1 → [1 2 3;4 5 6], sumv → 15
18	line6: end	ii → 2, jj → 2, mat1 → [1 2 3;4 5 6], sumv → 15
19	line4: jj becomes 3	ii → 2, jj → 3, mat1 → [1 2 3;4 5 6], sumv → 15

# MATLAB Operator

Symbol	Role
+	Addition
-	Subtraction
*	Multiplication
/	Division
^	Matrix power
./	Element-wise right division
.*	Element-wise multiplication
.^	Element-wise power
'	Transpose

Symbol	Role
==	Equal to
~=	Not equal to
>	Greater than
>=	Greater than or equal to
<	Less than
<=	Less than or equal to
&&	Logical AND (scalar logical)
	Logical OR (scalar logical)
~	Logical NOT
&	Logical AND (array)
	Logical OR (array)

## Assign Value(s) to a Variable

*variable = expression*

```
val2 = 2; % scalar value  
vec1 = [1 2 3 4]; % vector  
vec3 = vec1-val2
```

- Conduct a 'minus' operation between a vector of 'vec1' and a scalar value 'val2'. This operation subtract 2 from each element in [1 2 3 4]. A resulting vector is [-1 0 1 2].
- Assign a resulting vector to 'vec3'. 'vec3' contains [-1 0 1 2].

Q: Matrix multiplication ?

# MATLAB Operator

```
val1 = 10; % scalar value
val2 = 2; % scalar value

vec1 = [1 2 3 4]; % vector

mat1 = [1 2; 3 4]; % matrix
mat2 = [5 6; 7 8]; % matrix
```

1	2
3	4

mat1

5	6
7	8

mat2

1	2	3	4
---	---	---	---

vec1

Operator

+

-

\*

/

^

./

Scalar ★ Scalar

Vector ★ Scalar

Matrix ★ Scalar

Vector ★ Vector

Matrix ★ Matrix

★: Operator

val1 + val2	12
val1 * val2	20
val1 / val2	5
val1^val2	100
vec1*val1	[10 20 30 40]
vec1/val2	[0.5 1 1.5 2]
vec1 + val2	[3 4 5 6]
vec1 - val2	[-1 0 1 2]
mat1*val2	[2 4; 6 8]
mat1/val2	[0.5 1; 1.5 2]
mat1 + val2	[3 4; 5 6]
mat1 - val2	[-1 0; 1 2]
mat1 + mat2	[6 8; 10 12]
mat1 - mat2	[-4 -4; -4 -4]

# MATLAB Operator

```
vec1 = [1 2]; % vector
vec2 = [1; 0]; % vector
```

```
mat1 = [1 2; 3 4]; % matrix
mat2 = [1 0; 0 1]; % matrix
```

1	2
3	4

mat1

1	0
0	1

mat2

1	2
---	---

vec1

1
0

vec2

Operator

+

-

\*

/

^

./

.\*

.^

\

Scalar ★ Scalar

Vector ★ Scalar

Matrix ★ Scalar

Vector ★ Vector

Matrix ★ Matrix

★: Operator

```
mat1*vec1
mat1*vec2
vec1*mat1
vec2*mat1
```

*error*

[1; 3]

[7 10]

*error*

```
mat1*mat2
```

[1 2;3 4]

```
mat1*mat1
```

[7 10;15 22]

```
mat1^2
```

[7 10;15 22]

```
vec1.* vec2'
```

[1 0]

```
mat1.*mat2
```

[1 0;0 4]

```
mat2./mat1
```

[1 0;0 0.25]

```
mat1.^2
```

[1 4;9 16]

```
mat1.*vec2
```

[1 2;0 0]

```
mat1.*vec1
```

[1 4;3 8]



# Q. How to Change the Matrix A

1	2	3
4	5	6
7	8	9

A



8	2	3
4	8	6
7	8	8

A

1	2	8
4	8	6
8	8	9

?

1	2	3
4	5	6
7	8	9

A



5	4	3
20	10	6
35	16	9

A

# MATLAB Implicitly Expands Element-wise Operations (Changed After R2016b)

Two inputs which are exactly the same size.

A: 2-by-2


B: 2-by-2


Result: 2-by-2


One input is a matrix, and the other is a column vector with the same number of rows.

A: 4-by-2


B: 4-by-1


Result: 4-by-2


1	2
3	4
5	6

.\*

1
1
2

?

# MATLAB Operator

```
val1 = 1; % scalar value
val2 = 2; % scalar value
```

```
vec1 = [1 2 3 4]; % vector
vec2 = [1 0 1 4]; % vector
```

```
mat1 = [1 2; 3 4]; % matrix
mat2 = [1 0; 5 4]; % matrix
```

Symbol	Role
==	Equal to
~=	Not equal to
>	Greater than
>=	Greater than or equal to
<	Less than
<=	Less than or equal to

1	2
3	4

mat1

1	0
0	1

mat2

1	2	3	4
1	0	1	4

vec1

vec2

vec1 == val1	[1 0 0 0]
vec1 <= val2	[1 1 0 0]
vec1 ~= val2	[1 0 1 1]
vec1 == vec2	[1 0 0 1]
vec1 >= vec2	[1 1 1 1]
vec1 < vec2	[0 0 0 0]
mat1 == val1	[1 0; 0 0]
mat1 ~= val2	[1 0; 1 1]
mat1 == mat2	[1 0; 0 1]
mat1 ~= mat2	[0 1; 1 0]
mat1 >= mat2	[1 1; 0 1]
mat1 == [1 2]	[1 1; 0 0]
mat1 == [1; 2]	[1 0; 0 0]
mat1 > [1 2]	[0 0; 1 1]

# MATLAB Operator

```
val1 = 1; val2 = 0;

vec1 = [1 0]; vec2 = [0 0];

mat1 = [1 1; 0 0];
mat2 = [1 0; 0 1];
```

Symbol	Role
&&	Logical AND (scalar logical)
	Logical OR (scalar logical)
~	Logical NOT
&	Logical AND (array)
	Logical OR (array)

1	1
0	0

mat1

1	0
0	1

mat2

1	0
0	0

vec1

0	0
---	---

vec2

```
val1 && val1      1
val2 && val2      0
val1 || val2      1

val2 || val2      0
~ val1            0
~ val2            1

vec1 && val1      error
vec1 & val1       [1 0]
vec1 & val2       [0 0]
vec1 | val2       [1 0]
vec2 | val1       [1 1]

vec2 | vec1       [1 0]
vec2 & vec1       [0 0]

mat1 | mat2       [1 1;0 1]
mat1 & mat2       [1 0;0 0]
mat1 & vec1       [1 0;0 0]
mat1 | vec2       [1 1;0 0]
```

# Value Replacement

If values in 'vec1' are larger than 0 and less than 50, replace the values to 10. Otherwise, replace them to 5.

```
vec1 = [1 10 70 80 2];

for ii=1:numel(vec1)
    testv = vec1(ii);
    if testv > 0
        if testv < 50
            replv = 10;
        else
            replv = 5;
        end
    else
        replv = 5;
    end
    vec1(ii) = replv;
end
```

```
vec1 = [1 10 70 80 2]
```

```
vec1 = [1 10 70 80 2];




logi10 = and(vec1>0, vec1<50);

vec1(logi10) = 10;
vec1(~logi10) = 5;
```

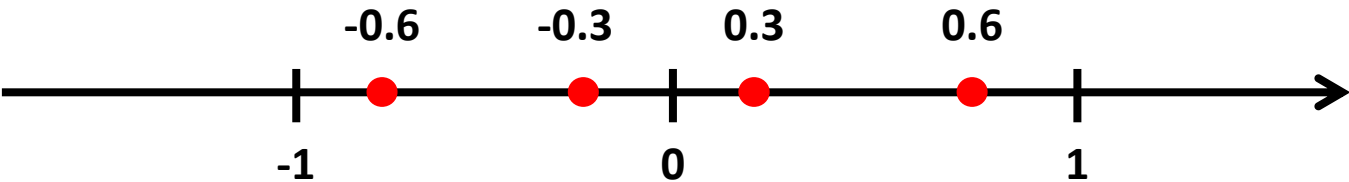
**'vec1' becomes**

```
vec1 = [10 10 5 5 10]
```

# Rounding Functions

Function	Description	Note
<code>round(x)</code>	Rounds <b>x</b> to the nearest integer	
<code>fix (x)</code>	Truncates <b>x</b> to the nearest integer toward zero.	
<code>floor(x)</code>	Rounds <b>x</b> to the nearest integer toward negative infinity.	
<code>ceil(x)</code>	Rounds <b>x</b> to the nearest integer toward positive infinity.	

# Rounding Functions (Example 1)



	round	ceil	fix	floor
0.3	0	1	0	0
0.6	1	1	0	0
-0.3	0	0	0	-1
-0.6	-1	0	0	-1

## Rounding Functions (Example 2)

```
x1 = -0.6;  
x2 = -0.3;  
x3 = 0.3;  
x4 = 0.6;  
  
x = [x1 x2 x3 x4];  
  
x_ce = ceil(x);  
x_fi = fix(x);  
x_fl = floor(x);  
x_ro = round(x);
```

Name	Value
x1	-0.6
x2	-0.3
x3	0.3
x4	0.3
x	[-0.6 -0.3 0.3 0.6]
x_ce	[0 0 1 1]
x_fi	[0 0 0 0]
x_fl	[-1 -1 0 0]
x_ro	[-1 0 0 1]



# Array Operations

- **reshape** changes dimensions of a matrix to any matrix with the same number of elements
- **diag** create diagonal matrix or get diagonal elements of matrix
- **rot90** rotates a matrix 90 degrees counter-clockwise
- **fliplr** flips columns of a matrix from left to right
- **flipud** flips rows of a matrix up to down
- **flip** flips a row vector left to right, column vector or matrix up to down
- **repmat** replicates an entire matrix; it creates  $m \times n$  copies of the matrix
- **repelem** replicates each element from a matrix in the dimensions specified

## Example: Create and Index Arrays

```
mat1 = zeros(3,3)
mat2 = ones(3,3)

mat4 = ones(6,6);
mat5 = repmat(mat2, 2, 2);

mat6 = eye(3,3);
mat7 = diag(ones(3,1));
```

```
mat1 = 3×3
    0    0    0
    0    0    0
    0    0    0

mat2 = 3×3
    1    1    1
    1    1    1
    1    1    1

mat4 = 6×6
    1    1    1    1    1    1
    1    1    1    1    1    1
    1    1    1    1    1    1
    1    1    1    1    1    1
    1    1    1    1    1    1
    1    1    1    1    1    1
```

```
mat5 = 6×6
    1    1    1    1    1    1
    1    1    1    1    1    1
    1    1    1    1    1    1
    1    1    1    1    1    1
    1    1    1    1    1    1
    1    1    1    1    1    1

mat6 = 3×3
    1    0    0
    0    1    0
    0    0    1

mat7 = 3×3
    1    0    0
    0    1    0
    0    0    1
```

## Example: Combine and Transform Array (horcat, vertcat, cat)

```
mat01 = reshape(1:9, 3, 3);  
mat02 = horzcat(mat01, mat01);  
mat03 = cat(2, mat01, mat01);  
  
mat05 = vertcat(mat01, mat01);  
mat06 = cat(1, mat01, mat01);
```

mat01 = 3×3

1	4	7
2	5	8
3	6	9

mat02 = 3×6

1	4	7	1	4	7
2	5	8	2	5	8
3	6	9	3	6	9

mat03 = 3×6

1	4	7	1	4	7
2	5	8	2	5	8
3	6	9	3	6	9

mat05 = 6×3

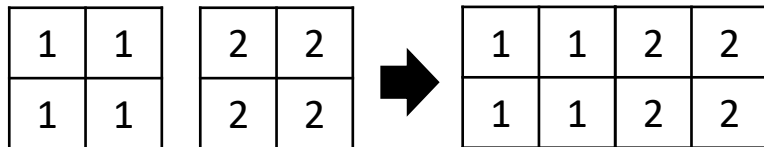
1	4	7
2	5	8
3	6	9
1	4	7
2	5	8
3	6	9

mat06 = 6×3

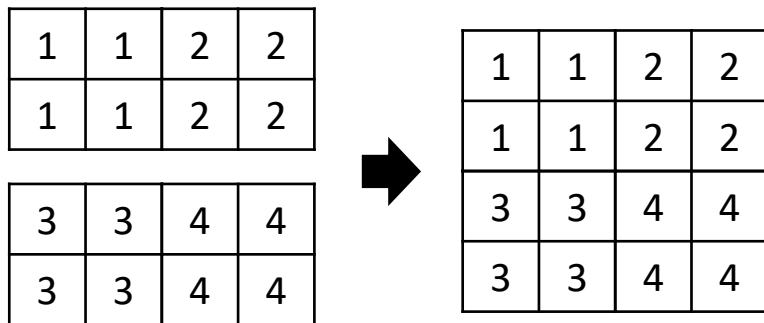
1	4	7
2	5	8
3	6	9
1	4	7
2	5	8
3	6	9

## Example: Combine and Transform Array (repelem)

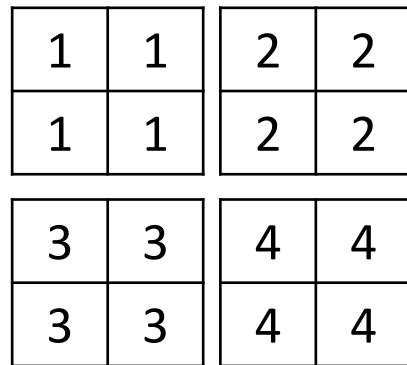
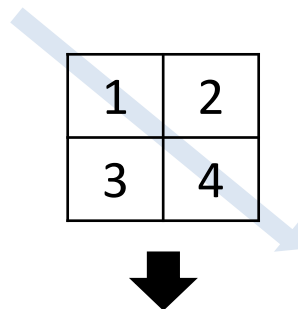
```
mat08 = cat(2, ones(2,2), ones(2,2)+1);  
mat09 = cat(1, mat08, mat08+2);  
mat10 = repelem([1 2;3 4], 2, 2);
```



mat08



mat09



mat10

## Example: Combine and Transform Array

```
mat1 = reshape(1:9, 3, 3)
mat2 = flip(mat1, 1)
mat3 = flipud(mat1)

mat4 = flip(mat1, 2)
mat5 = fliplr(mat1)

mat6 = transpose(mat1)
mat7 = mat1'
mat8 = flipud(rot90(mat1))
```

1	4	7
2	5	8
3	6	9

mat1

3	6	9
2	5	8
1	4	7

mat2

3	6	9
2	5	8
1	4	7

mat3

7	4	1
8	5	2
9	6	3

mat4

7	4	1
8	5	2
9	6	3

mat5

1	2	3
4	5	6
7	8	9

mat6

1	2	3
4	5	6
7	8	9

mat7

1	2	3
4	5	6
7	8	9

mat8

# Cell Array

- A **cell array** is a type of data structure that can store different types of values in its elements
- A cell array could be a vector (row or column) or a matrix
- It is an array, so indices are used to refer to the elements

e.g., Store multiple values in different types or matrix in a single variable

## Cell Array

- The syntax used to create a cell array is curly braces { } instead of [ ]
- The **direct method** is to put values in the row(s) separated by commas or spaces, and to separate the rows with semicolons (so, same as other arrays) – the difference is using { } instead of [ ]
- The cell function can also be used to preallocate by passing the dimensions of the cell array, e.g.
- `cell(4,2)`

## Example: Containing Multiple Data Types

```
temp_st1 = [10 11; 12 15; 9 7];  
temp_st2 = [12 13];  
temp_st3 = [8 9; 11 12];
```

```
num_st1 = 3;  
num_st2 = 1;  
num_st3 = 2;
```

```
name_st1 = 'Kitchener';  
name_st2 = 'Waterloo';  
name_st3 = 'Guelph';
```

```
data_st{1,1} = [10 11; 12 15; 9 7];  
data_st{2,1} = [12 13];  
data_st{3,1} = [8 9; 11 12];
```

```
data_st{1,2} = 3;  
data_st{2,2} = 1;  
data_st{3,2} = 2;
```

```
data_st{1,3} = 'Kitchener';  
data_st{2,3} = 'Waterloo';  
data_st{3,3} = 'Guelph';
```

```
find([data_st{:,2}] == 2)  
find(strcmp(data_st(:,3), 'Waterloo'))
```

3  
2

**Other benefit?**



# Structure Variables

- Structures store values of different types, in fields
- Fields are given names; they are referred to as
- **structurename.fieldname** using the dot operator
- Structure variables can be initialized using the `struct` function, which takes pairs of arguments (field name as a string followed by the value for that field)
- To print, `disp` will display all fields; `fprintf` can only print individual fields

## Example: Containing Multiple Data Types

```
temp_st1 = [10 11; 12 15; 9 7];  
temp_st2 = [12 13];  
temp_st3 = [8 9; 11 12];
```

```
num_st1 = 3;  
num_st2 = 1;  
num_st3 = 2;
```

```
name_st1 = 'Kitchener';  
name_st2 = 'Waterloo';  
name_st3 = 'Guelph';
```

```
temp_st{1} = [10 11; 12 15; 9 7];  
temp_st{2} = [12 13];  
temp_st{3} = [8 9; 11 12];
```

```
num_st = [3 1 2];
```

```
name_st{1} = 'Kitchener';  
name_st{2} = 'Waterloo';  
name_st{3} = 'Guelph';
```

```
data_st.temp_st = temp_st;  
data_st.num_st = num_st;  
data_st.name_st = name_st;
```

# Cell Arrays vs Structures

- Cell arrays are arrays, so they are indexed
  - That means that you can loop through the elements in a cell array – or have MATLAB do that for you by using a vectorized code
- Structs are not indexed, so you cannot loop
  - However, the field names are mnemonic so it is more clear what is being stored in a struct
- For example:
  - `variable{1}` vs. `variable.weight`: which is more mnemonic?

# Cell Arrays vs Structures

- Cell arrays are arrays, so they are indexed
  - That means that you can loop through the elements in a cell array – or have MATLAB do that for you by using vectorized code
- Structs are not indexed, so you cannot loop
  - However, the field names are mnemonic so it is more clear what is being stored in a struct
- For example:
  - `variable{1}` vs. `variable.weight`: which is more mnemonic?

# Numerical Technique

- Algorithms that are used to obtain numerical solutions of a mathematical problem
- It is useful when no analytical solution exists or analytical solution is difficult to obtain.

$$f(x) = 2x + 3$$

$$f'(3)$$

$$f(x) = \log(x) * 2x + e^{3x} * x^{2/3}$$

$$f'(3)$$

# Theory: Differentiation

The derivative is a measure of the rate at which a function is changing

The derivative of  $f(x)$  at  $x = a$  can be defined using limits as:

$$f'(a) = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{x - a}$$

With a small change in notation, we can write that:

$$f'(a) = \lim_{h \rightarrow 0} \frac{f(a + h) - f(a)}{h}$$

Instead of finding a derivative at every point in a function, we can find the derivative for a function  $f(x)$ .

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x + h) - f(x)}{h} \text{ can be written as } f'(x) = \frac{d}{dx} f(x) = \frac{dy}{dx}$$



**For one point**



**For a function**

# Theory: Tangent Lines

We can find the equation of a tangent line to  $f(x)$  at point  $(a, f(x))$ .

Recall the general equation of a line  $y = mx + b$

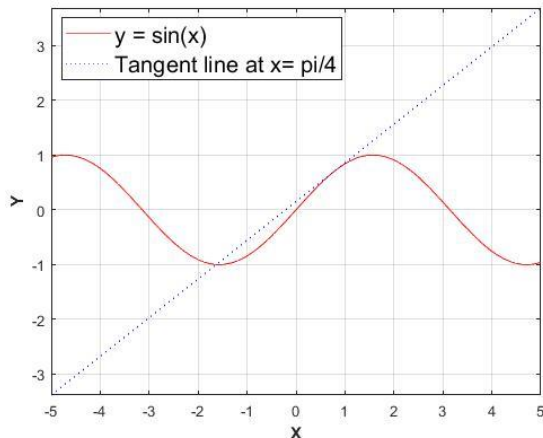
where  $m$  is the slope and  $b$  is the y-intercept. The slope of the tangent line found by  $m = f'(a)$

Given two points on a line, the slope can be found using:

$$\text{Slope} = \frac{y_2 - y_1}{x_2 - x_1}$$

From there, the equation of a line can be found using:

$$y - y_1 = m(x - x_1)$$



# Theory: Differentiation 1 – Symbolic Way

**Example: Find the derivative of:**

$$f(x) = \sqrt{x^2 + 1}$$

$$\triangleright f(x) = \sqrt{u} \rightarrow u = x^2 + 1$$

$$\triangleright f'(x) = \frac{1}{2}u^{\frac{1}{2}} * (2x)$$

$$\triangleright f'(x) = \frac{2x}{2\sqrt{u}} = \frac{x}{\sqrt{x^2+1}}$$

```
syms x
fx = sqrt(x^2 + 1);
fxp = diff(fx);

fxp
fxp_2 = subs(fxp, x, 2)
double(fxp_2)
```

fxp =

$$\frac{x}{\sqrt{x^2 + 1}}$$

fxp\_2 =

$$\frac{2\sqrt{5}}{5}$$

ans = 0.8944

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$



# Theory: Differentiation 1 – Numerical Way

**Example: Find the derivative of:**

$$f(x) = \sqrt{x^2 + 1}$$

›  $f(x) = \sqrt{u} \rightarrow u = x^2 + 1$

›  $f'(x) = \frac{1}{2}u^{\frac{1}{2}} * (2x)$

›  $f'(x) = \frac{2x}{2\sqrt{u}} = \frac{x}{\sqrt{x^2+1}}$

```
h = 0.000000001;  
x = 2;  
(diff_ex1(x+h) - diff_ex1(x))/h
```

ans = 0.8944

```
function fx = diff_ex1(x)  
  
fx = sqrt(x^2 + 1);  
  
end
```

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

# Theory: L'Hôpital's Rule

L'Hôpital's Rule is a way of solving certain limits of an **indeterminant** form.

In order to apply L'Hôpital's rule the limit must be:

1. A ratio, like  $\frac{f(x)}{g(x)}$
2. Indeterminate

So, L'Hôpital's rule can be applied to limits of the form  $\frac{0}{0}$  or  $\frac{\infty}{\infty}$ .

If  $f(x)$  and  $g(x)$  are different functions and if  $\lim_{x \rightarrow a} \frac{f(x)}{g(x)}$  is indeterminate, then

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$$

## Example: L'Hôpital's Rule

**Example: Find the following using L'Hôpital's rule**

$$1. \lim_{x \rightarrow 1} \frac{\ln(x)}{x-1} \Rightarrow \frac{0}{0}$$

$$\text{Using L'Hôpital's rule} = \lim_{x \rightarrow 1} \frac{\frac{1}{x}}{1} = 1$$

$$2. \lim_{x \rightarrow \infty} \frac{e^x}{x^2} \Rightarrow \frac{0}{0}$$

$$\text{Using L'Hôpital's rule} = \lim_{x \rightarrow \infty} \frac{e^x}{2x} = \lim_{x \rightarrow \infty} \frac{e^x}{2} = \infty$$

## Example: L'Hopitals Rule (Script)

```
tol = 10^-4;  
x = 10;  
val1 = sin(x)/x
```

```
val1 = -0.0544
```

```
x = 10;  
if abs(x)<tol  
    x = tol;  
end  
val2 = sin(x)/x
```

```
val2 = -0.0544
```

```
x = 0;  
if abs(x)<tol  
    x = tol;  
end  
val3 = sin(x)/x
```

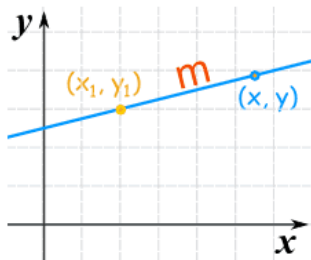
```
val3 = 1.0000
```

```
x = 0;  
val4 = cos(x)
```

```
val4 = 1
```

# Theory: Point-Slope Equation of a Line

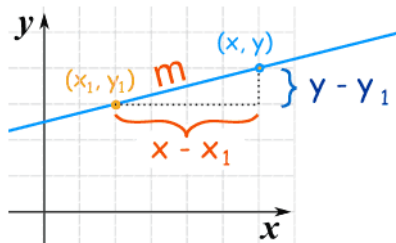
$$y - y_1 = m(x - x_1)$$



$(x_1, y_1)$  is a **known** point

$m$  is the **slope** of the line

$(x, y)$  is any other point on the line



Slope  $m = \frac{\text{change in } y}{\text{change in } x} = \frac{y - y_1}{x - x_1}$

Starting with the slope:  $\frac{y - y_1}{x - x_1} = m$

we rearrange it like this:

$$\frac{y - y_1}{x - x_1} = m(x - x_1)$$

to get this:

$$y - y_1 = m(x - x_1)$$

<https://www.mathsisfun.com/algebra/line-equation-point-slope.html>

# Theory: Newton's Method

Newton's Method is a way successively finding better and better approximations to the roots of a function.

The slope of tangent line L is  $f'(x)$  so its equation is:

$$y - f(x_1) = f'(x_1)(x - x_1)$$

To find the roots, we need to find the x-intercepts where  $y = 0$ ,

so we assume  $x_L$  is where  $y = 0$ ,

$$0 - f(x_1) = f'(x_1)(x_2 - x_1)$$

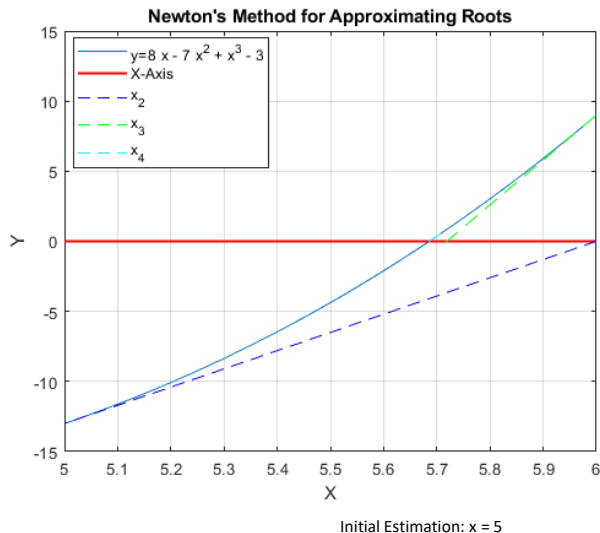
$$x_2 = x_1 - \frac{f(x_1)}{f'(x_1)}$$

We call  $x_2$  the second approximation to  $r$ , but what if we want  $x_2$  to be even more accurate?

This process can be repeated for  $x_1, x_2, x_3 \dots$

In general, if the  $n^{th}$  approximation is  $x_n$  and  $f'(x_n) \neq 0$ , then the next approximation  $x_{n+1}$  is:

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$



## Example: Newton's Method 1

Example: Use Newton's Method to find a root:

$$f(x) = x^6 - 2$$

$$f'(x) = 6x^5$$

We can apply Newton's method to solve for the root  $y = 0$ .  $x_1 = 1$   
(Initial Guess)

$$\triangleright x_2 = 1 - \frac{f(1)}{f'(1)} = 1 - \frac{1^6 - 2}{6(1^5)} \approx 1.16666667$$

$$\triangleright x_3 = x_2 - \frac{f(x_2)}{f'(x_2)} \approx 1.12644368$$

$$\triangleright x_4 = x_3 - \frac{f(x_3)}{f'(x_3)} \approx 1.12249707$$

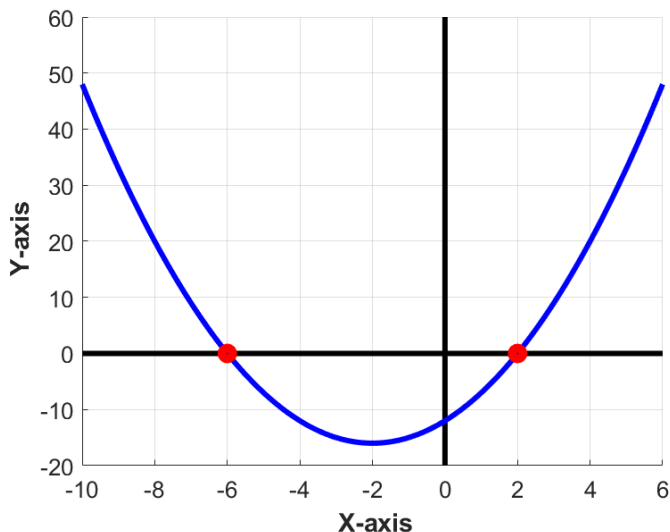
$$\triangleright x_5 = x_4 - \frac{f(x_4)}{f'(x_4)} \approx 1.12246205$$

$$\triangleright x_6 = x_5 - \frac{f(x_5)}{f'(x_5)} \approx 1.12246205$$

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

## Example: Root Finding 1

$$f(x) = (x - 2)(x - 6) \\ = x^2 - 4x - 12$$



```
% plot a graph
x = -10:0.01:6;
y = (x-2) .* (x + 6);

figure(1);
line([0 0 ], [-20 60], 'color', ...
      'k', 'LineWidth', 3); hold on; % y-axis
line([min(x) max(x)], [0 0 ], 'color', ...
      'k', 'LineWidth', 3); % x-axis
plot(x, y, 'b', 'LineWidth',3); % graph
plot(2, 0, 'or', 'LineWidth',5);
plot(-6, 0, 'or', 'LineWidth',5); hold off
xlabel('\bf X-axis')
ylabel('\bf Y-axis')
xticks(-10:2:6);
xticklabels({'-10', '-8', '-6', '-4', ...
            '-2', '0', '2', '4', '6'})
set(gca, 'fontsize', 13)
xlim([-10 6])
grid on;
```



## Example: Root Finding 1 (Simulation)

```
x1 = 5;  
x2 = x1 - myfun(x1)/myfunp(x1)  
x3 = x2 - myfun(x2)/myfunp(x2)  
x4 = x3 - myfun(x3)/myfunp(x3)  
x5 = x4 - myfun(x4)/myfunp(x4)
```

```
function fx = myfun(x)
```

```
fx = (x-2) .* (x + 6);
```

```
end
```

```
function fxp = myfunp(x)
```

```
fxp = 2*x + 4;
```

```
end
```

$$f(x) = x^2 - 4x - 12$$

$$f'(x) = 2x - 4$$

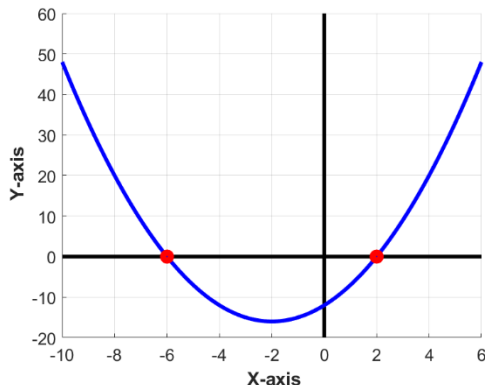
$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

$$x_2 = 2.6429$$

$$x_3 = 2.0445$$

$$x_4 = 2.0002$$

$$x_5 = 2.0000$$



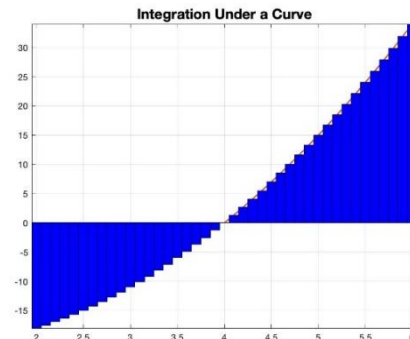
# Theory: Integral

Integration is the technique of determining the **area under a curve**. This process is **opposite the process of differentiation**.

To find the area under a curve, we divide the curve into many equal segments of equal width. Each rectangle is multiplied by its corresponding y-value to get the area of that rectangle. The rectangle's areas are summed for the total area under that curve segment:

- Left endpoints can be used so that the rectangular segments give an underestimation
- Right endpoints can be used so that the rectangular segments give an overestimation
- Center endpoints can be used to try and balance the error from overestimations and underestimations

How can you make your estimation even more accurate?  
Take smaller segments!



# Theory: Integral

## The Definite Integral

If  $f$  is defined for  $a \leq x \leq b$ , we divide the interval  $[a, b]$  into  $n$  segments of equal width  $\Delta x = \frac{b-a}{n}$ .

We let  $x_0 = a, x_1, x_2, \dots, x_n = b$  be the endpoints of these segments and let  $x_1^*, x_2^*, x_3^*, \dots, x_n^*$  be sample points in these segments such that  $x_i^*$  lies in the  $i^{th}$  segment. This means that the definite integral from  $a$  to  $b$  is:

$$\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*) \Delta x$$

Recall that,

$$\sum_{i=1}^n i = \frac{n(n+1)}{2} \text{ and } \sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6} \text{ and } \sum_{i=1}^n i^3 = \frac{n^2(n+1)^2}{4}$$

## Example: Definite Integral

Solve the following definite integral using the definition of the definite integral:

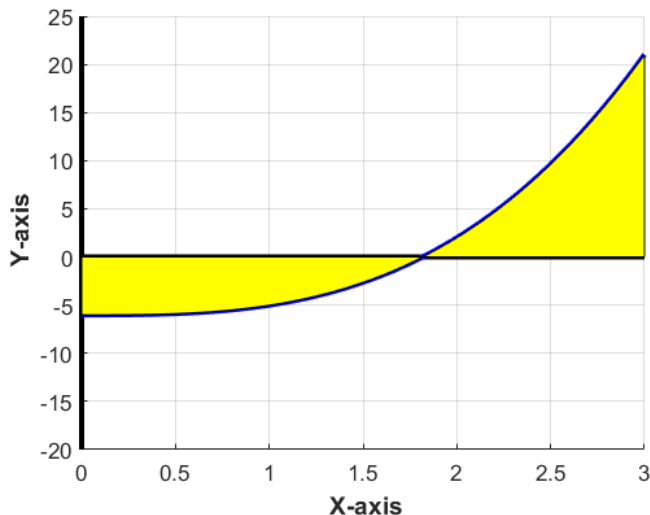
$$\int_0^3 (x^3 - 6x) dx$$

$$\int_0^3 (x^3 - 6x) dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i) \Delta x$$
$$\Delta x = \frac{3}{n}, x_i = \frac{3i}{n}$$

$$\begin{aligned} & \triangleright = \lim_{n \rightarrow \infty} \sum_{i=1}^n f\left(\frac{3i}{n}\right) \frac{3}{n} \\ & \triangleright = \lim_{n \rightarrow \infty} \frac{3}{n} \sum_{i=1}^n \left[ \left(\frac{3i}{n}\right)^3 - 6\left(\frac{3i}{n}\right) \right] \\ & \triangleright = \lim_{n \rightarrow \infty} \frac{3}{n} \sum_{i=1}^n \left[ \frac{27i^3}{n^3} - \frac{18i}{n} \right] \\ & \triangleright = \lim_{n \rightarrow \infty} \left[ \left(\frac{81}{n^4}\right) \sum_{i=1}^n i^3 - \frac{54}{n^2} \sum_{i=1}^n i \right] \\ & \triangleright = \lim_{n \rightarrow \infty} \left[ \left(\frac{81}{n^4}\right) \left(\frac{n(n+1)}{2}\right)^2 - \frac{54}{n^2} \left(\frac{n(n+1)}{2}\right) \right] \\ & \triangleright = \lim_{n \rightarrow \infty} \left[ \left(\frac{81}{n^4}\right) \left(\frac{n^2+n}{2}\right)^2 - \frac{54}{n^2} \left(\frac{n^2+n}{2}\right) \right] \\ & \triangleright = \lim_{n \rightarrow \infty} \left[ \left(\frac{81}{n^4}\right) \left(\frac{n^4+2n^3+n^2}{4}\right) - \frac{54}{n^2} \left(\frac{n^2+n}{2}\right) \right] \\ & \triangleright = \frac{81}{4} - \frac{54}{2} = \frac{-27}{4} \end{aligned}$$

## Example: Integral (graph)

$$f(x) = x^3 - 6x$$



```
% plot a graph
x = 0:0.01:3;
y = x.^3 - 6;

figure(1);
line([0 0 ], [-20 25], 'color', ...
      'k', 'Linewidth', 3); hold on; % y-axis
line([min(x) max(x)], [0 0 ], 'color', ...
      'k', 'Linewidth', 3); % x-axis
plot(x, y, 'b', 'Linewidth',3); % graph
area(x, y, 'FaceColor','y'); % filled area
xlabel('\bf X-axis')
ylabel('\bf Y-axis')
xticks(0:0.5:3);
xticklabels({'0','0.5','1','1.5', '2', '2.5', '3'})
set(gca, 'fontsize', 13)
xlim([0 3]);
ylim([-20 25])
grid on;
```

## Example: Integral (Symbolic)

```
syms x
y = x^3 - 6*x;
int_y_ab = int(y, 0, 3)
double(int_y_ab)
```

int\_y\_ab =

$$-\frac{27}{4}$$

ans = -6.7500

## Example: Integral (Numeric 1)

```
1  n = 10000;  
2  a = 0;  
3  b = 3;  
4  del_x = (b-a)/n;  
5  
6  area_fx = 0;  
7  for ii=1:n  
8      x_star = a + del_x*ii;  
9      area_fx = area_fx + myfun(x_star)*del_x;  
10 end  
11 area_fx  
12  
13 error_est = area_fx - (-27/4)
```

```
function fx = myfun(x)
```

```
fx = x^3 - 6*x;
```

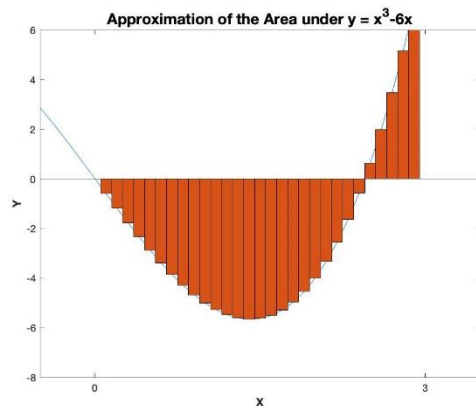
```
end
```

$$f(x) = x^3 - 6x$$

area\_fx = -6.7486

error\_est = 0.0014

$$\int_a^b f(x)dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*) \Delta x$$



## Example: Integral (Numeric 2)

```
1  n = 10000;  
2  a = 0;  
3  b = 3;  
4  del_x = (b-a)/n;  
5  
6  area_fx = 0;  
7  for ii=1:n-1  
8      x_star1 = a + del_x*ii;  
9      x_star2 = a + del_x*(ii+1);  
10     area_fx = area_fx + (myfun(x_star2)+myfun(x_star1))/2*del_x;  
11 end  
12 area_fx  
13  
14 error_est = area_fx - (-27/4)
```

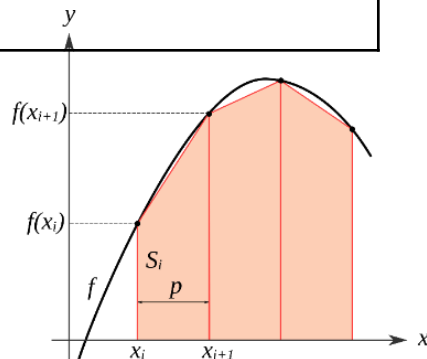
```
function fx = myfun(x)
```

```
fx = x^3 - 6*x;
```

```
end
```

```
area_fx = -6.7500
```

```
error_est = 4.7250e-07
```





## Example: Integral (Numeric 1 vs Numeric 2)

```
1  n = 10000;
2  a = 0;
3  b = 3;
4  del_x = (b-a)/n;
5
6  area_fx1 = 0;
7  for ii=1:n
8      x_star = a + del_x*ii;
9      area_fx1 = area_fx1 + myfun(x_star)*del_x;
10 end
11
12 area_fx2 = 0;
13 for ii=1:n-1
14     x_star1 = a + del_x*ii;
15     x_star2 = a + del_x*(ii+1);
16     area_fx2 = area_fx2 + (myfun(x_star2)+myfun(x_star1))/2*del_x;
17 end
18
19 area_fx1
20 area_fx2
21
22 error_est1 = area_fx1 - (-27/4)
23 error_est2 = area_fx2 - (-27/4)
24
```

```
function fx = myfun(x)

fx = x^3 - 6*x;

end
```

```
area_fx1 = -6.7486
area_fx2 = -6.7500

error_est1 = 0.0014
error_est2 = 4.7250e-07
```