# **Outlier Detection**

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#### INTRODUCTION

Data plays a very important role as it collects facts in different formats(words, numbers, text, etc..), which have been translated into forms that can be processed by computers and thus can help get insights and make decisions. Under such circumstance, data quality, which refers to the degree to which a set of characteristics of data fulfills requirements, is the key for performing further analysis of a data set. However, in most cases, a data set has different kinds of data quality issues, and one of the most common issues is the outliers. The definition of outliers of Grubbs [4] and quoted in Barnett & Lewis [2]: An outlying observation, or outlier, is one that appears to deviate markedly from other members of the sample in which it occurs. A further outlier definition from Barnett & Lewis [2] is: An observation (or subset of observations) which appears to be inconsistent with the remainder of that set of data.

There are many reasons that may cause outliers on a data set, such as:

- Data entry errors, which are caused by human errors.
- Measurement errors, which are caused by instrument errors.
- Experimental errors, which are caused by data extraction or experiment planning/executing errors.
- Data processing errors which are caused by data manipulation or data set unintended mutations.
- Sampling errors which are caused by extracting or mixing data from wrong or various sources

In addition, there are always entries with null values on a data set that may affect the analysis as well. Discovering these entries is one of the main job for data cleaning, and it is also widely used for different applications, such as fraud detection, which detects fraudulent applications for credit cards, state benefits or detects fraudulent usage of credit cards or mobile phones, loan application processing, which detects fraudulent applications or potentially problematical customers, intrusion detection, which detects unauthorized access in computer networks, etc[5].

If we can use efficient algorithms to find out outliers and null values at the very beginning of data processing, it can save a lot of time and give us more accurate results from data analysis.

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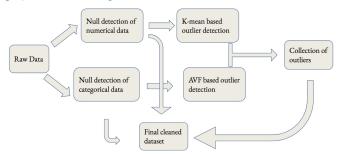
## 2 PROBLEM FORMULATION

Our goal for the project is to discover outliers from any given large data set. The problem we are interested in is how to implement some algorithms proposed in previous work and design or improve algorithms that can return more accurate results and achieve our goal in a more efficient way. Since there are different metrics to define outliers under different contexts, we focus on methods both for numerical variables and categorical variables.

## METHODS, ARCHITECTURE AND DESIGN

In this section we want to introduce some common and implements which we will use as baseline algorithms. Detecting outliers in the data is not as explicit as it sounds like. It is hard to define outlier for a single attribute. For instance, when it comes to the traffic sensor data, a speed of 60 mph may not be anomaly if the vehicle is on expressway but it is definitely strange if the car is running in a congested city like New York. In this case, volumn and speed should be considered at the same time.

The whole procedure of detecting null values and outliers in our project is as following:



## 3.1 Categorical data

Attribute value frequency(AVF) method There are various algorithms dealing with categorical data such as The Greedy Algorithm. However it is linear with respect to data size and it needs k-scans each time. The other models also exist which are based on frequent item set mining(FIM) need to create a large space to store item sets, and then search for these sets in each and every data point .These techniques can become very slow when we select low threshold value to find frequent item sets from dataset.

Intuitively, outliers are those points which are infrequent in the dataset. The infrequentness of an attribute value can be measured by computing the number of times this value is assumed by the corresponding attribute in the dataset.

Another simpler and faster approach to detect outliers that minimizes the scans over the data and does not need to create more space and more search for combinations of attribute values or item sets is Attribute Value Frequency (AVF) algorithm.

Assuming that a dataset contains n data points,  $x_i$ , i = 1, fi, n. If each data point has m attributes,  $x_i = [x_{i1}, ..., x_{ij}, ..., x_{im}]$ , where  $x_{ij}$  is the value of the j-th attribute of  $x_i$ .

An outlier point  $x_i$  is defined based on the AVF Score below:

$$AVFScore(x_i) = F_i = \frac{1}{m} \sum_{j=1}^{m} f(x_{ij})$$

where  $f(x_{ij})$  is the number of times the j-th attribute value of  $x_i$  appears in the dataset. Since we essentially have a sum of m positive numbers, the AVF score is minimized when each of the summation terms are individually minimized. Thus, the AVF score will be minimum for the ideal outlier.

Once we calculate the AVF score of all the points, we can define the k points with the smallest AVF scores as the k outliers. The complexity of AVF is  $O(n \times m)$  compared to Greedy's complexity,  $O(k \times n \times m)$  since AVF detects outlier after only one scan of the dataset rather than k scans, which is needed by Greedy Algorithm. Specifically, AVF exhibits the following advantages:

- AVF needs one dataset scan to detect the desired outliers. In addition, the number of data scans needed by AVF does not rely on the input number of target outliers *k*.
- A computational complexity of O(n × m), where n is the number of points in the data and m is the data dimensionality.
   It scales linearly with both n and m.
- The performance of AVF is independent on additional userentered parameters, such as minimum support.
- AVF runs significantly faster than the existing representative techniques, while maintaining comparable detection accuracy.

Input : Database  $\mathcal{D}$  (n points  $\times$  m attributes), Target number of outliers - k Output: k detected outliers

```
1 Label all data points as non-outliers;
2 foreach point \mathbf{x}_i, i = 1 \dots n do
       for each attribute l, l = 1 \dots m do
           Count frequency f(x_{il}) of attribute value x_{il};
5
       end
6 end
7 for
each point \mathbf{x}_i,\,i=1\dots n do
       foreach attribute l, l = 1...m do
           AVFScore(\mathbf{x}_i) += f(x_{il});
       end
10
11
       AVFScore(\mathbf{x}_i) /= m;
12 end
13 Return k outliers with min<sub>i</sub>(AVFScore);
```

Figure 1: AVF Algorithm

## 3.2 Numerical data

K-means method Data clustering is used to identify homogeneous groups or clusters from a set of objects. In other words, data clustering aims to divide a set of objects into groups or clusters such that objects in the same cluster are more similar to each other than to objects from other clusters[1]. As an unsupervised learning process, data clustering is often used as a preliminary step for data analytics. Among the many clustering algorithms have been developed in

the past years, the k-means algorithm is one of the oldest and commonly used clustering algorithms. In the k-means based outlier detection technique, the data are partitioned into k groups by assigning them to the closest cluster centers. Once assigned we can compute the distance or dissimilarity between each object and its cluster center, and pick those with largest distances as outliers. Although being used widely, the k-means algorithm has some drawbacks[3]. One of the drawbacks is that it is extremely sensitive to outliers, and such outliers may have a disproportionate impact on the final cluster configuration.

Figure 2: K-means Algorithm

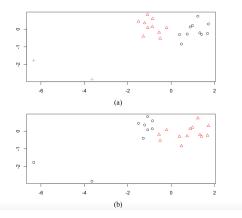


Figure 3: An illustration showing that the k-means algorithm is sensitive to outliers. (a) A data set with two clusters and two outliers. The two clusters are plotted by triangles and circles, respectively. The two outliers are denoted by plus signs. (b) Two clusters found by the k-means algorithm. The two found clusters are plotted by triangles and circles, respectively.

### 4 RESULTS

### 4.1 Standard AVF and Kmeans

We implemented these algorithms using PySpark on 50 datasets from NYC open data. We ran all our experiments on Dumbo - a

Hadoop Cluster provided by High Performance Computing(HPC) at NYU.

Both algorithms were applied on all datasets. Given an arbitrary dataset, we first classify each attributes as categorical or numerical. Then the algorithms are implemented on corresponding attributes(clustering on numerical data and AVF on categorical data).

The 50 datasets have various structures and sizes. The largest dataset has 63867610 rows and 3 attributes while the smallest dataset has only 3 rows for which there is no need to detect outliers.

Taking one dataset as example, this dataset contains both categorical and numeric data which is an ideal target to demonstrate our outliers detection method. The data includes counts settled, zip, business name, charge, city, latitude, industry, borough, unit type, certificate number, record id, unit, violation date, street, state, charge count, outcome, building number, longitude, counts guilty, description, street2, counts not guilty as attributes. After applying the AVF algorithm with k(the number of outliers) set to 10, we get result as following(shown partially):

```
([('business_name', 'PETROLITE INC.'), ('charge', 'NY Agri & Mixts \wideA7 183(2) = RRWYS EAAL WITHOUSTRY, 'Item of the Norwight, 'Outside NYC'), ('unit_type', 'RM'), ('certificate_number', '08379051'), ('record_id', '51350-2015-BHFO'), ('unit_type', 'RM'), ('certificate_number', '08379051'), ('record_id', '51350-2015-BHFO'), ('unit_type', 'Settlement (Pre-Hearing)'), ('building_number', '261'), ('description', ''), ('state', 'NL'), ('suctome', 'Settlement (Pre-Hearing)'), ('building_number', '261'), ('description', ''), ('state', 'NL'), ('suctome', 'NLE)ANDRO GARCIA'), ('charge', 'NTC Admin Code \wideA7 10-131(g)(1) - BUSINESS OR SET AGMIN AND BARRELS THAT WERE NOT PLUGGED WITH THE SAME MATERIAL THAT MAKES UP THE GUND AND/OR FAKE GUNS THAT DID N'), ('city', 'NNW YORK'), ('industry', 'Temporary Street Fair Vendor Permit - 111), ('bor ough', 'MANNATTAN'), ('unit_type', ''), ('certificate_number', '05381210'), ('record_id', '32854-2015'), ('outcome', 'Hearing Decision'), ('building_number', ''), ('description', 'NNEC'), ('street_2', 'SAST 10 STREET')), 18803
((('business_name', 'HAJOVSKY, MICHAEL'), ('charge', 'NYC Admin Code \wideA7 20-232 - NEWSTAND DOES STREET'), 18803
(INT STOKEN N), ('city', 'NEW YORK'), ('industry', 'Newsstand - 204'), ('borough', 'MANNATTAN'), ('unit_type', ''), ('certificate_number', '0538917'), ('record_id', '2227-2015-BNFO'), ('unit, ''), ('violation_adate', '2015-04-277080:80907'), ('street_2', 'MeST 46 STREET')), 91303
((('business_name', 'NEW YORK'), ('industry', 'Newsstand - 204'), ('borough', 'MANNATTAN'), ('unit_type', ''), ('certificate_number', ''), ('sescription', 'NAWAC'), ('street_2', 'MEST 46 STREET')), 95)
((('business_name', 'GHOUDHURY, FARDA A'), ('charge', 'MYC Admin Code \wideA7 20-231(b) - NEWSTAND DOES SELLS ITENS FOR $5.00 OR MORE. (1 count per type of item dissiplayed)'), ('city', 'NEW YORK'), ('industry', 'Newsstand - 204'), ('borough', 'MANNATTAN'), ('unit_type', ''), ('certificate_number', ''), ('description', 'NAWAC'), ('street_2', 'MEST 46 STREET')), 93
((('bus
```

Figure 4: AVF Result

ounts_se rd_id ur uilty			charge city			
-LEGL	1.0 33614.0   2016-08-31T00:00:00		\u00A7 2-2   TAMPA 1 Settlement			
	1.0 21702.0 ALBERTO  2015-07-16T00:00:00	DANIEL FL NYC Adm HARGETT LN MD	in Code \u FREDERICK  1 Settlement		ovement  Staten Isl 4820  0	
-ENFO null	null 10004.0 End to 9 2016-07-04T00:00:00		in Code \u   NEW YORK 25000		Other Manhat 42 null	
	1.0   7001.0   NATIONAL   2016-05-14T00:00:00	FENCE SY NYC Adm		0 Home Impr Pleaded	ovement  Staten Isl 1033  0	
LEGL	1.0   33614.0     2016-08-31T00:00:00		\u00A7 2-2   TAMPA 1 Settlement			
-LEGL	1.0   33614.0     2016-08-31T00:00:00		\u00A7 2-2  TAMPA 1 Settlement			
ENFO						
-LEGL			\u00A7 2-2   TAMPA 1 Settlement			

Figure 5: k-mean result

The AVF algorithm runs extremely fast on our dataset. However we can notice that it is difficult to decide which attributes contributes the most to our result according to the nature of the algorithm. The K-means algorithm also worked decently on the dataset as the number of numerical data columns and the size of the dataset are at sweet spot. However, since the scale of zip code is much larger than the other columns, it played a much larger role in determining the outliers.

## 4.2 Improved Kmeans

To achieve better performance, we also implemented improved K means algorithm. We preprocessed numerical features to normalize to mean 1 to balance the impact due to scale difference of features and reduce the excessive dimensionality by evaluating correlation among features and keep only principal ones. We got result as following:



Figure 6: improved k-mean result

Clearly, we can see that the improved algorithm find outliers that make more sense as the impact from zip code was reduced and other features contributed more to the selected data points.

### 5 TECHNICAL DEPTH AND INNOVATION

We implemented the most popular and quite powerful algorithms used in outlier detection for both numerical and categorical data. However, each of the algorithms has some drawbacks. From this point of view, our future work depends on how to improve these algorithms in terms of accuracy and time complexity.

## 5.1 Categorical data

## Normally Distributed Attribute value Frequency(NAVF) method

This model is defined as an optimal number of outliers in a single instance to get optimal precision in any classification model with good precision. This method calculates 'k' value itself based on the frequency instead of indicating 'k' manually. Taking the dataset 'D' with m attributes.  $k_N$  is the number of outliers which are normally distributed. If any object frequency is less than "mean-3 S.D" then this model treats those objects as outliers. This method uses AVF score formula to find AVF score but no k-value is required.

## 5.2 Numerical data

Since the k-means algorithm is extremely sensitive to outliers, there are some methods proposed to solve the problem by removing the outliers from the dataset before implementing k-means, or

```
Algorithm Input: Dataset – D, Output: Dataset – D, Output: K detected outliers.

Step 1: Read data set D Step 2: Label all the Data points as nonoutliers Step 3: calculate normalized frequency of each attribute value for each point x_i Step 4: calculate the frequency score of each record x_i as, Attribute Value Frequency of x_i is: AVF \ Score \ (x_i) = F_i = \frac{1}{m} \sum_{j=1}^m f(x_ij) Step 5: compute N-seed values a and b as b=mean (x_i), a=b-3*std (x_i), if max (F_i) > 3*std (F_i) Step 6: If F_i < a, then declare x_i as outlier Step 7: return K_N detected outliers.
```

Figure 7: The NAVF Algorithm

by choosing initial cluster centers that are not outliers, or doing clustering and outlier detection simultaneously.

### Improved K-means with Outlier Removal(KMOR) method

This method is designed to improve the k-means algorithm performance through reducing unnecessary dimensionality and balance scale difference between features and outlier detection simultaneously.

In the KMOR algorithm, the numerical features are all normalized to mean 1 to balance the impact due to scale difference of features and reduce the excessive dimensionality by evaluating correlation among features and keep only principal ones. The given the clustering centers, a data point that is at least  $\gamma \times d_{avg}$  away from all the cluster centers is considered as an outlier, where  $\gamma$  is a multiplier and  $d_{avg}$  is the average distance calculated dynamically during the clustering process. The KMOR algorithm has two main parameters:  $n_0$  and  $\gamma$ . The parameter n0 specifies the maximum number of outliers. The parameter  $\gamma$  specifies the multiplier of the average squared distance for outlier detection.

```
Algorithm 1: Pseudo-code of the KMOR algorithm, where \sigma and N_{max} are two parameters used to terminate the algorithm. Input: X, k_2, Y_0, g, \delta, N_{max} Output: Optimal values of U and Z Initialize Z^{(0)} = \{t_1^{(0)}, t_2^{(0)}, \dots, t_k^{(0)}\} by selecting k points from X randomly; 2 Update U^{(0)} by assigning \mathbf{x}_i to its nearest center for i=1,2,\dots,n; 3 s \leftarrow 0; 4 P^{(0)} \leftarrow 0; while Time do 6 Update U^{(s+1)} by minimizing Q(U,U^{(s)},Z^{(s)}) according to Theorem 1; 1 Update Z^{(s+1)} by minimizing Z^{(s+1)} according to Theorem 3; S \leftarrow S + 1; 9 Z^{(s+1)} \leftarrow P(U^{(s+1)},Z^{(s+1)}); 1 Z^{(s+1)} \leftarrow
```

Figure 8: The KMOR Algorithm

### 6 CODE REPOSITORY

**Repository URL**: https://github.com/KLiunyu/DS1004\_Project It includes our detection code, and also a README.txt file for instruction on running the outliers detection code.

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