

Software for Estuarine Circulation Modelling

The Estuarine Circulation Modeling software is a desktop software written to simulate and analyze estuarine hydrodynamics, stratification, turbulence, sediment transport, tidal dynamics, and wave-current interactions. It integrates numerical solvers, turbulence models, and visualization tools to model complex estuarine processes. The software supports both structured and unstructured grids, multiple coordinate systems (sigma and z-level), and advanced numerical schemes like Total Variation Diminishing (TVD).

Functionalities

1. Core Estuarine Model:

- Manages parameters: estuary length (1000 m), depth (10 m), tidal amplitude (1 m), tidal period (12 hours), salinity (river: 0 PSU, ocean: 35 PSU), temperature (river: 25°C, ocean: 20°C).
- Supports hydrostatic and non-hydrostatic modes with a Reynolds-Averaged Navier-Stokes (RANS) solver.
- Tracks salt wedge position and provides methods to retrieve salinity, temperature, and velocity profiles.

2. Hydrodynamic Solver:

- Solves 2D shallow water dynamics on a 100×100 grid for water level and velocities.
- Incorporates tidal forcing, wind stress, Coriolis force, and bottom friction.
- Applies river ($x=0$) and ocean ($x=1000$ m) boundary conditions.
- Handles wet/dry dynamics and wave-current interactions.

3. 2D Shallow Water Equations:

- Implements a 2D shallow water model with UI visualization of water level, velocity, and salinity.
- Allows control over tidal amplitude, period, wind speed, wind direction, wave height, and grid size.
- Supports wet/dry transitions and wave-enhanced friction.

4. Total Variation Diminishing:

- Uses TVD scheme with Harten-Lax-van Leer (HLL) flux to advect salinity, temperature, turbulent kinetic energy (k), and dissipation rate (ϵ) or specific dissipation rate (ω).
- Supports structured (200×100) and unstructured (triangular mesh, 40×25 nodes) grids with bathymetry (shallower near river, $x < 200$ m).

- Provides UI visualization: plan view, cross-section, contour, and quiver plots.
- Tracks fields: salinity, temperature, velocity, density, k , ϵ/ω , eddy viscosity, and diffusivity.

5. **Stratification:**

- Models 1D vertical stratification of density, salinity, temperature, and passive scalars on a 100-point grid.
- Computes gradient Richardson number and adjusts eddy viscosity using k - ϵ , k - ω , or constant turbulence models.
- UI controls mixing coefficient, critical Richardson number, and river scalar concentration.

6. **Baroclinic Flow:**

- Simulates buoyancy-driven flows due to density gradients.
- Updates velocity fields using finite differences, incorporating buoyancy effects.

7. **Passive Scalar Transport:**

- Solves 1D advection-diffusion for passive scalars (e.g., pollutants).
- Integrates with baroclinic flow for consistent transport.

8. **Comprehensive Forcing:**

- Combines tidal, wind, and wave forcing.
- UI adjusts tidal amplitude, wind speed, wave height, and visualizes velocity and water level fields.

9. **Wave-Current Interaction:**

- Computes Stokes drift velocities using linear wave theory.
- Calculates wave-enhanced bottom friction via a simplified Grant-Madsen model.
- Supports dynamic updates of wave height, direction, period, and depth.

10. **Wind Forcing:**

- Computes wind drag coefficient and stress components (τ_x, τ_y).
- Parameterizes drag coefficient based on wind speed and wave height.

11. **Wet & Dry Algorithm:**

- Manages wet/dry transitions for tidal flats using a minimum depth threshold (D_{\min}).
- Sets velocities, water level, and salinity to zero in dry cells.
- Ensures mass conservation via flux divergence corrections.

12. Simpson-Hunter Mechanism:

- Models tidal straining and internal tide effects in a sigma-coordinate system.
- Computes Stokes drift, vertical velocity, and turbulent kinetic energy (TKE) production.

13. Asymmetric Tidal Mixing:

- Simulates asymmetric tidal mixing effects on salinity and velocity fields.
- Uses a `Cell` class to manage local properties (salinity, velocity, TKE).

14. Bifurcated Estuary Model:

- Models circulation in bifurcated channels, accounting for branching flow dynamics.

15. Equations of State:

- Computes water density based on salinity and temperature.

16. Vertical Discretization (VerticalDiscretization):

- Supports sigma (terrain-following) and z-level (fixed layers) coordinate systems.
- Computes metric terms (z_ξ, z_η) for grid transformations.

17. Richardson Number and SSI Mixing:

- Computes gradient Richardson number and strain-induced mixing for turbulence closure.
- Supports $k-\epsilon$ and $k-\omega$ models.

18. Large Eddy Simulation:

- Implements LES with a Smagorinsky subgrid model.
- UI controls Smagorinsky coefficient and visualizes velocity/vorticity fields.

19. Lattice Boltzmann LES:

- Uses Lattice Boltzmann Method (LBM) with a D3Q19 lattice for LES.
- UI adjusts grid size and relaxation time, visualizing vorticity contours.

20. Spectral Analyzer:

- Performs spectral analysis (Welch's method) and EOF/POD analysis on variables like Richardson number, velocity, and salinity.
- UI controls variable selection, window type (Hanning, Hamming, Blackman, Rectangular), and visualization (PSD, heatmaps, modes).

21. Multi-Fraction Sediment Transport:

- Models bedload and suspended load for multiple grain sizes.

- UI adjusts sediment properties (grain size, settling velocity) and visualizes concentration profiles.

22. Adaptive Mesh Refinement:

- Refines grid based on velocity gradients or water level changes.
- Dynamically adjusts resolution to capture fine-scale features.

23. Visualization Renderer:

- Renders 2D visualizations of water level, salt wedge, salinity, temperature, passive scalar, and velocity profiles.

Simulation Logic

1. Grid and Field Initialization:

- Structured grids (e.g., 200×100 in `TotalVariationDiminishing`, 100×100 in `HydrodynamicSolver`) or unstructured triangular meshes (40×25 nodes).
- Sigma or z-level coordinates account for bathymetry (shallower near river, $x < 200$ m).
- Fields (salinity, temperature, velocity, density, TKE, ϵ/ω) initialized with profiles (e.g., salinity: 0 PSU at river to 35 PSU at ocean).

2. Forcing and Boundary Conditions:

- Tidal forcing via sinusoidal water level variations.
- Wind forcing (`WindForcing`) and wave-current interactions (`WaveCurrentInteractions`) add stresses.
- River ($x = 0$, low salinity/temperature) and ocean ($x = 1000$ m, high salinity/temperature) boundaries.

3. Numerical Solvers:

- `HydrodynamicSolver` and `ShallowWaterEq2D`: Semi-implicit finite differences for shallow water dynamics ($\Delta t = 0.1$ s).
- `TotalVariationDiminishing`: TVD scheme with HLL flux for stable advection.
- `LargeEddySim`: Smagorinsky subgrid model for LES.
- `LatticeBoltzmannLES`: LBM with D3Q19 lattice for turbulence.
- `PassiveScalarTransportEq` and `Stratification`: Finite differences for advection-diffusion.

4. Turbulence Modeling:

- $k-\epsilon$ and $k-\omega$ models compute TKE and dissipation/specific dissipation.

- Eddy viscosity modulated by gradient Richardson number.

5. Transport and Stratification:

- Scalars (e.g., pollutants) advected/diffused using velocity fields from BaroclinicFlow or HydrodynamicSolver.
- Density gradients drive baroclinic flows in BaroclinicFlow.

6. Wet/Dry Dynamics:

- WetAndDryAlgo updates cell status based on depth threshold (D_{\min}).
- Adjusts fluxes to prevent flow into dry cells and ensures mass conservation.

7. Visualization and Analysis:

- VisualizationRenderer plots plan views, cross-sections, contours, and quiver plots.
- SpectralAnalyzer computes PSD and EOF/POD modes.

8. Dynamic Updates:

- AdaptiveMeshRef refines grids based on gradients.
- User inputs (e.g., tidal period, wind speed) updated via UI or programmatic methods.

Algorithms

1. Initialization:

- Initialize grids: structured (200×100 or 100×100) or unstructured (40×25 nodes).
- Set bathymetry: shallower near river ($x < 200$ m).
- Initialize fields: salinity ($S(x) = 35 \cdot x/1000$), temperature ($T(x) = 25 - 5 \cdot x/1000$), velocity, TKE, ϵ/ω .

2. Hydrodynamic Solver:

- Solve continuity: $\frac{\partial \eta}{\partial t} + \frac{\partial(Hu)}{\partial x} = 0$.
- Solve momentum: $\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = -g \frac{\partial \eta}{\partial x} + \frac{1}{H} \frac{\partial(H\tau)}{\partial x} - \frac{C_f |u| u}{H} + F$.
- Apply boundaries: river ($u = Q_r/(BH)$), ocean ($\eta = A \sin(\omega t)$).
- Use semi-implicit finite differences, $\Delta t = 0.1$ s.

3. TVD Advection:

- Compute HLL flux: $F_{\text{HLL}} = \begin{cases} F_L, & s_L \geq 0 \\ F_R, & s_R \leq 0 \\ \frac{s_R F_L - s_L F_R + s_L s_R (U_R - U_L)}{s_R - s_L}, & \text{otherwise} \end{cases}$, where $s_L = \min(u_L - c_L, u_R - c_R, 0)$, $s_R = \max(u_L + c_L, u_R + c_R, 0)$.
- Apply Superbee limiter: $\psi(r) = \max(0, \min(2r, (1+r)/2, 2))$, $r = \frac{C_i - C_{i-1}}{C_{i+1} - C_i}$.
- Update salinity, temperature, k , ϵ/ω .

4. Turbulence Modeling:

- k - ϵ model:

$$\begin{aligned} - \frac{\partial k}{\partial t} + u \cdot \nabla k &= \nabla \cdot \left[\left(\nu + \frac{\nu_t}{\sigma_k} \right) \nabla k \right] + P_k - \epsilon. \\ - \frac{\partial \epsilon}{\partial t} + u \cdot \nabla \epsilon &= \nabla \cdot \left[\left(\nu + \frac{\nu_t}{\sigma_\epsilon} \right) \nabla \epsilon \right] + C_{1\epsilon} \frac{\epsilon}{k} P_k - C_{2\epsilon} \frac{\epsilon^2}{k}. \\ - \nu_t &= C_\mu \frac{k^2}{\epsilon}, \quad P_k = \nu_t \left(\frac{\partial u}{\partial x} \right)^2. \end{aligned}$$

- k - ω model:

$$\begin{aligned} - \frac{\partial k}{\partial t} + u \cdot \nabla k &= \nabla \cdot \left[\left(\nu + \frac{\nu_t}{\sigma_k} \right) \nabla k \right] + P_k - \beta^* k \omega. \\ - \frac{\partial \omega}{\partial t} + u \cdot \nabla \omega &= \nabla \cdot \left[\left(\nu + \frac{\nu_t}{\sigma_\omega} \right) \nabla \omega \right] + \alpha_\omega \frac{\omega}{k} P_k - \beta \omega^2. \\ - \nu_t &= \frac{k}{\omega}. \end{aligned}$$

- Richardson number: $Ri = \frac{N^2}{S^2}$, $N^2 = -\frac{g}{\rho_0} \frac{\partial \rho}{\partial z}$, $S^2 = \left(\frac{\partial u}{\partial z} \right)^2 + \left(\frac{\partial v}{\partial z} \right)^2$.
- Adjust ν_t : $\nu_t = \frac{\nu_0}{1+10Ri} (k-\epsilon)$ or $\nu_t = \nu_0 \frac{1+0.5 \min(Ri, Ri_{\text{crit}})}{1+Ri} (k-\omega)$.

5. Wet/Dry Algorithm:

- Check depth: cell is wet if $H = \eta + h \geq D_{\text{min}}$, else dry.
- Set dry cell values: $u = v = \eta = S = 0$.
- Limit fluxes: $u_{i,j} = \min(u_{i,j}, 0)$ if eastern neighbor is dry, etc.
- Update water level: $\Delta \eta = \frac{\text{Flux}_{\text{in}} - \text{Flux}_{\text{out}}}{\Delta x \Delta y}$.

6. Spectral Analysis:

- Welch's method for PSD:

- Window: Hanning ($w_i = 0.5(1 - \cos(2\pi i/(N-1)))$), Hamming, Blackman, or Rectangular.
- Segment: $\text{segmentData}_i = \text{data}_{\text{start}+i} \cdot w_i$.
- PSD: $\text{PSD}_i = \frac{1}{\text{windowPower} \cdot \text{samplingRate}} \cdot |\text{FFT}(\text{segmentData})_i|^2 / \text{numSegments}$.
- Frequencies: $f_i = \frac{i}{\text{samplingRate} \cdot \text{segmentLength}}$.

- EOF/POD via SVD:

- Data matrix: $\text{dataMatrix}_{s,t} = \text{data}_t[s, 0] - \text{mean}_t$.

- Power iteration: iterate $u_i = \sum_j \text{dataMatrix}_{i,j} v_j$, normalize u ; $v_j = \sum_i \text{dataMatrix}_{i,j} u_i$, normalize v .
- Singular value: $\sigma = \sqrt{\sum_i (\text{Av}_i)^2}$.
- Explained variance: $\text{variance}_m = \frac{\sigma_m^2}{\sum_i \sigma_i^2} \cdot 100$.

7. Sediment Transport:

- Update concentrations: $\frac{\partial C_f}{\partial t} = -u \frac{\partial C_f}{\partial x} + D_f \frac{\partial^2 C_f}{\partial x^2} - w_{s,f} C_f$.
- Compute bedload flux: $q_b = 8(\theta - \theta_c)^{1.5} \sqrt{\left(\frac{\rho_s}{\rho_0} - 1\right) g d^3}$ if $\theta > \theta_c$, else 0.

8. Adaptive Mesh Refinement:

- Compute gradients: $G_{i,j} = \sqrt{\sum (\frac{\partial \phi}{\partial x})^2 + (\frac{\partial \phi}{\partial z})^2}$ for $\phi = S, T, u$.
- Flag top 10% gradient cells.
- Initialize 2×2 subgrids with bilinear interpolation.

Physical and Mathematical Models

Shallow Water Dynamics

- Continuity:

$$\frac{\partial \eta}{\partial t} + \frac{\partial(Hu)}{\partial x} = 0 \quad (1)$$

- Momentum:

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = -g \frac{\partial \eta}{\partial x} + \frac{1}{H} \frac{\partial(H\tau)}{\partial x} - \frac{C_f |u| u}{H} + F \quad (2)$$

where η is water surface elevation, $H = h + \eta$, h is bathymetry, u is velocity, $\tau = \nu_{\text{eff}} \frac{\partial u}{\partial x}$, $C_f = 0.002 - 0.005$, F includes Coriolis, wind, and baroclinic terms.

Baroclinic Flow

- Density:

$$\rho = \rho_0 [1 - \alpha(T - T_0) + \beta_S(S - S_0)] \quad (3)$$

where $\rho_0 = 1000 \text{ kg/m}^3$, $\alpha = 2 \times 10^{-4} / ^\circ\text{C}$, $\beta_S = 8 \times 10^{-4} / \text{PSU}$, $T_0 = 20^\circ\text{C}$, $S_0 = 35 \text{ PSU}$.

- Baroclinic pressure gradient:

$$\frac{\partial p_b}{\partial x} = -g \int_{\eta}^{-h} \frac{\partial \rho}{\partial x} dz \quad (4)$$

Passive Scalar Transport

- Advection-diffusion:

$$\frac{\partial C}{\partial t} + u \frac{\partial C}{\partial x} = \frac{\partial}{\partial x} \left(K \frac{\partial C}{\partial x} \right) \quad (5)$$

where $K = K_m + \frac{\nu_t}{Sc_t}$, $K_m \approx 10^{-9} \text{ m}^2/\text{s}$, $Sc_t \approx 0.7$.

Turbulence Models

- k - ϵ model:

$$\frac{\partial k}{\partial t} + u \cdot \nabla k = \nabla \cdot \left[\left(\nu + \frac{\nu_t}{\sigma_k} \right) \nabla k \right] + P_k - \epsilon \quad (6)$$

$$\frac{\partial \epsilon}{\partial t} + u \cdot \nabla \epsilon = \nabla \cdot \left[\left(\nu + \frac{\nu_t}{\sigma_\epsilon} \right) \nabla \epsilon \right] + C_{1\epsilon} \frac{\epsilon}{k} P_k - C_{2\epsilon} \frac{\epsilon^2}{k} \quad (7)$$

where $\nu_t = C_\mu \frac{k^2}{\epsilon}$, $P_k = \nu_t \left(\frac{\partial u}{\partial x} \right)^2$, $C_\mu = 0.09$, $\sigma_k = 1.0$, $\sigma_\epsilon = 1.3$, $C_{1\epsilon} = 1.44$, $C_{2\epsilon} = 1.92$.

- k - ω model:

$$\frac{\partial k}{\partial t} + u \cdot \nabla k = \nabla \cdot \left[\left(\nu + \frac{\nu_t}{\sigma_k} \right) \nabla k \right] + P_k - \beta^* k \omega \quad (8)$$

$$\frac{\partial \omega}{\partial t} + u \cdot \nabla \omega = \nabla \cdot \left[\left(\nu + \frac{\nu_t}{\sigma_\omega} \right) \nabla \omega \right] + \alpha_\omega \frac{\omega}{k} P_k - \beta \omega^2 \quad (9)$$

where $\nu_t = \frac{k}{\omega}$.

Wave-Current Interaction

- Stokes drift:

$$u_s = \frac{a^2 \omega k \cosh(2kz)}{2 \sinh^2(kd)} \quad (10)$$

where $L = \sqrt{gd} \cdot T$, $k = \frac{2\pi}{L}$, $\omega = \frac{2\pi}{T}$.

- Wave-enhanced friction:

$$C_d = C_{d0}(1 + \beta U_b), \quad U_b = \frac{a\omega}{\sinh(kd)} \quad (11)$$

where $\beta = 0.2$, $C_{d0} = 0.0025$, $C_d \leq 0.01$.

Wind Forcing

- Drag coefficient:

$$C_d = (0.75 + 0.067U_{10} + 0.1H_s) \times 10^{-3}, \quad 0.001 \leq C_d \leq 0.003 \quad (12)$$

- Wind stress:

$$\tau_x = \rho_{\text{air}} C_d U_{10}^2 \cos(\theta), \quad \tau_y = \rho_{\text{air}} C_d U_{10}^2 \sin(\theta) \quad (13)$$

where $\rho_{\text{air}} = 1.225 \text{ kg/m}^3$.

Wet/Dry Algorithm

- Depth criterion: wet if $H = \eta + h \geq D_{\min}$, else dry.
- Flux limiting: $u_{i,j} = \min(u_{i,j}, 0)$ if eastern neighbor is dry, etc.
- Mass conservation:

$$\Delta\eta = \frac{\text{Flux}_{\text{in}} - \text{Flux}_{\text{out}}}{\Delta x \Delta y}, \quad \text{Flux}_u = u(\eta + h)\Delta y \Delta t \quad (14)$$

Simpson-Hunter Mechanism

- Stokes drift:

$$u_s = a\omega e^{-2kz} \sin(\theta) \quad (15)$$

- Internal tide:

$$N^2 = -\frac{g}{\rho_0} \frac{\partial \rho}{\partial z}, \quad w_{\text{tide}} = A \sin(\theta) \sqrt{N^2} \cos\left(\frac{2\pi z}{H}\right) \quad (16)$$

- Tidal straining:

$$\frac{\partial S}{\partial t} = -Cu \frac{\partial S}{\partial x} \quad (17)$$

Asymmetric Tidal Mixing

- Navier-Stokes with Boussinesq:

$$\frac{\partial u}{\partial t} + u \cdot \nabla u = -\frac{\nabla p}{\rho_0} + \nu \nabla^2 u + \frac{g(\rho - \rho_0)}{\rho_0} + f \times u - \frac{\tau_b}{\rho_0} \quad (18)$$

- Tidal asymmetry: flood factor 1.2, ebb factor 0.8.

Vertical Discretization

- Sigma coordinates: $z = \sigma H$, $\sigma \in [0, 1]$.
- Z-level: $\Delta z = H/(N_z - 1)$.
- Metric terms:

$$z_\xi \approx \frac{z_{i+1,j} - z_{i-1,j}}{2\Delta\xi}, \quad z_\eta \approx \frac{z_{i,j+1} - z_{i,j-1}}{2\Delta\eta} \quad (19)$$

Richardson Number and SSI Mixing

- Richardson number:

$$Ri = \frac{N^2}{S^2}, \quad N^2 = -\frac{g}{\rho_0} \frac{\partial \rho}{\partial z}, \quad S^2 = \left(\frac{\partial u}{\partial z}\right)^2 + \left(\frac{\partial v}{\partial z}\right)^2 \quad (20)$$

- Viscosity adjustment:

$$\nu_t = \frac{\nu_0}{1 + 10 Ri} \quad (\mathbf{k}\text{-}\epsilon), \quad \nu_t = \nu_0 \frac{1 + 0.5 \min(Ri, 0.25)}{1 + Ri} \quad (\mathbf{k}\text{-}\omega) \quad (21)$$

- TKE production:

$$P = \nu_t \left[\left(\frac{\partial u}{\partial z} \right)^2 + \left(\frac{\partial v}{\partial z} \right)^2 \right] \quad (22)$$

Lattice Boltzmann LES

- LBM:

$$f_i(x + c_i \Delta t, t + \Delta t) = f_i(x, t) + \frac{f_i^{\text{eq}}(x, t) - f_i(x, t)}{\tau} \quad (23)$$

- Smagorinsky:

$$\nu_t = (C_s \Delta)^2 \sqrt{2 S_{ij} S_{ij}}, \quad S_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \quad (24)$$

Spectral Analysis

- Synthetic data:

- Richardson number: Value = $0.5 + 0.3 \sin\left(\frac{2\pi t}{43200}\right) + 0.2 \sin\left(\frac{2\pi t}{17 \cdot 3600}\right) + \text{noise}$.
- Velocity: Value = $0.1 + 0.05 \sin\left(\frac{2\pi t}{43200}\right) + 0.02 \sin\left(\frac{2\pi t}{21600}\right) + \text{noise}$.
- Salinity: $S_{x,y} = (30 + 2 \sin\left(\frac{2\pi t}{44712}\right)) (1 - 0.1(x + y)) + \text{noise}$.

- Welch's PSD:

$$\text{PSD}_i = \frac{1}{\text{windowPower} \cdot \text{samplingRate}} \cdot \frac{|\text{FFT}(\text{segmentData})_i|^2}{\text{numSegments}} \quad (25)$$

- EOF/POD via SVD:

$$\text{dataMatrix}_{s,t} = \text{data}_t[s, 0] - \text{mean}_t \quad (26)$$

Sediment Transport

- Suspended load:

$$\frac{\partial C_f}{\partial t} = -u \frac{\partial C_f}{\partial x} + D_f \frac{\partial^2 C_f}{\partial x^2} - w_{s,f} C_f \quad (27)$$

- Bedload:

$$q_b = \begin{cases} 8 (\theta - \theta_c)^{1.5} \sqrt{\left(\frac{\rho_s}{\rho_0} - 1\right) g d^3}, & \theta > \theta_c \\ 0, & \text{otherwise} \end{cases} \quad (28)$$