

Lattice Boltzmann and Finite Volume Large Eddy Simulations

This document describes two C# classes, `LatticeBoltzmannLES` and `LargeEddySim`, designed for large eddy simulation (LES) of estuarine circulation, incorporating river inflow, tidal forcing, and salinity-driven density variations. Both classes use the Smagorinsky model for subgrid-scale turbulence and provide graphical user interfaces (GUIs) for simulation control and visualization.

LatticeBoltzmannLES

The `LatticeBoltzmannLES` class implements a 2D lattice Boltzmann method (LBM) with the D2Q9 model to simulate estuarine hydrodynamics, capturing velocity, salinity, and turbulence quantities.

Core Components and Initialization

The class is initialized with:

- Grid size: $n_x = 200$, $n_y = 50$ (lattice points)
- Spatial step: $\Delta x = 50$ m
- Time step: $\Delta t = 0.1$ s (reserved for future scaling)
- River inflow: $u_{\text{river}} = 0.1$ m/s
- Tidal amplitude: $A_{\text{tidal}} = 1.0$ m, period: $T_{\text{tidal}} = 43200$ s
- Smagorinsky constant: $C_s = 0.1$
- Reynolds number: $Re = 1000$
- Salinity: $S_{\text{ocean}} = 35$ PSU, $S_{\text{river}} = 0$ PSU
- Ocean temperature: $T_{\text{ocean}} = 20$ °C

Arrays include:

- Density: $\rho(i, j)$
- Salinity: $S(i, j)$
- Velocity distribution functions: $f(i, j, k)$, equilibrium $f^{\text{eq}}(i, j, k)$ (D2Q9, $k = 0, \dots, 8$)
- Salinity distribution functions: $g(i, j, k)$, equilibrium $g^{\text{eq}}(i, j, k)$
- Velocities: $u(i, j)$, $v(i, j)$; time-averaged: $u_{\text{avg}}(i, j)$, $v_{\text{avg}}(i, j)$
- Vorticity or Q-criterion: $\omega(i, j)$
- Local Smagorinsky constant: $C_s(i, j)$
- Local spatial step: $\Delta x_{\text{local}}(i, j)$, relaxation times: $\tau(i, j)$, $\tau_S(i, j)$

The GUI allows users to adjust parameters and select visualization modes (velocity, salinity, time-averaged velocity), refinement modes (None, River, Tidal, Both), filter width (Lattice Spacing, Cell Area), and vortex visualization (Vorticity Magnitude, Q-Criterion).

Functioning Logic

The simulation follows the LBM algorithm:

1. **Streaming:** Propagate $f(i, j, k)$ and $g(i, j, k)$ along D2Q9 directions:

$$f(i + c_{k,x}, j + c_{k,y}, k) = f(i, j, k), \quad g(i + c_{k,x}, j + c_{k,y}, k) = g(i, j, k) \quad (1)$$

where $c_k = (c_{k,x}, c_{k,y})$ are lattice directions.

2. **Collision:** Update distributions using the Bhatnagar-Gross-Krook (BGK) model:

$$f(i, j, k) \leftarrow f(i, j, k) + \frac{f^{\text{eq}}(i, j, k) - f(i, j, k)}{\tau(i, j)} \quad (2)$$

$$g(i, j, k) \leftarrow g(i, j, k) + \frac{g^{\text{eq}}(i, j, k) - g(i, j, k)}{\tau_S(i, j)} \quad (3)$$

where equilibrium distributions are:

$$f^{\text{eq}}(i, j, k) = w_k \rho \left[1 + 3 \frac{\mathbf{u} \cdot \mathbf{c}_k \Delta x}{\Delta x_{\text{local}}} + 4.5 \left(\frac{\mathbf{u} \cdot \mathbf{c}_k \Delta x}{\Delta x_{\text{local}}} \right)^2 - 1.5 \frac{|\mathbf{u}|^2 \Delta x^2}{\Delta x_{\text{local}}^2} \right] \quad (4)$$

$$g^{\text{eq}}(i, j, k) = w_k S \rho \left[1 + 3 \frac{\mathbf{u} \cdot \mathbf{c}_k \Delta x}{\Delta x_{\text{local}}} + 4.5 \left(\frac{\mathbf{u} \cdot \mathbf{c}_k \Delta x}{\Delta x_{\text{local}}} \right)^2 - 1.5 \frac{|\mathbf{u}|^2 \Delta x^2}{\Delta x_{\text{local}}^2} \right] \quad (5)$$

with weights $w_k = \{4/9, 1/9, \dots, 1/36\}$.

3. **Macroscopic Variables:** Compute density, velocity, and salinity:

$$\rho(i, j) = \sum_{k=0}^8 f(i, j, k), \quad u(i, j) = \frac{1}{\rho} \sum_{k=0}^8 f(i, j, k) c_{k,x}, \quad v(i, j) = \frac{1}{\rho} \sum_{k=0}^8 f(i, j, k) c_{k,y}, \quad S(i, j) = \frac{1}{\rho} \sum_{k=0}^8 g(i, j, k) \quad (6)$$

4. **Turbulence Modeling:** Use Smagorinsky LES:

$$\nu_t = (C_s \Delta)^2 |\mathbf{S}|, \quad \tau(i, j) = 3(\nu + \nu_t) c_s^2 \frac{\Delta x}{\Delta x_{\text{local}}} + 0.5 \quad (7)$$

where Δ is the filter width (Δx_{local} or $\sqrt{\Delta x_{\text{local}}^2}$), $|\mathbf{S}|$ is the strain rate magnitude, and $c_s^2 = 1/3$.

5. **Vorticity/Q-Criterion:** Compute vorticity ($|\partial v / \partial x - \partial u / \partial y|$) or Q-criterion:

$$Q = \frac{1}{2} (\|\Omega\|^2 - \|\mathbf{S}\|^2), \quad \Omega_{xy} = \frac{1}{2} \left(\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right) \quad (8)$$

6. **Boundary Conditions:** Apply river inflow ($u = u_{\text{river}}, S = S_{\text{river}}$) at $x = 0$ and tidal velocity ($u = A_{\text{tidal}} \sin(2\pi t / T_{\text{tidal}}) / \Delta x, S = S_{\text{ocean}}$) at $x = n_x - 1$.

7. **Energy Spectrum:** Compute FFT of velocities at mid-y plane every 100 timesteps, outputting power spectral density to `energy_spectrum.txt`.

Visualization

The GUI displays:

- Velocity, salinity, or time-averaged velocity in a color-coded panel (red-blue gradient).
- Vorticity or Q-criterion isosurfaces in a separate panel, colored by velocity or vorticity.
- Console output with time, average velocity, salinity, TKE, dissipation, and vorticity.

LargeEddySim

The LargeEddySim class implements a 2D finite volume method for LES, solving Navier-Stokes equations with salinity and temperature effects.

Core Components and Initialization

The class is initialized with:

- Grid size: $n_x = 50, n_z = 20$
- Estuary dimensions: $L = 10000 \text{ m}, h = 10 \text{ m}$
- Spatial steps: $\Delta x = L/n_x, \Delta z = h/n_z$
- Time step: $\Delta t = 1.0 \text{ s}$ (adjusted by CFL condition)
- Smagorinsky constant: $C_s = 0.1$
- Kinematic viscosity: $\nu = 10^{-6} \text{ m}^2/\text{s}$
- River inflow: $Q_{\text{river}} = 0.1 \text{ m}^3/\text{s}$
- Tidal amplitude: $A_{\text{tidal}} = 1.0 \text{ m}$, period: $T_{\text{tidal}} = 43200 \text{ s}$
- Ocean salinity: $S_{\text{ocean}} = 35 \text{ PSU}$
- Ocean temperature: $T_{\text{ocean}} = 20 \text{ }^\circ\text{C}$

Arrays include:

- Velocities: $u(i, j), w(i, j)$
- Salinity: $S(i, j)$, temperature: $T(i, j)$
- Vorticity: $\omega(i, j)$
- Eddy viscosity: $\nu_e(i, j)$

The GUI allows parameter adjustments and selection of time integration schemes (RK4 or Crank-Nicolson).

Functioning Logic

The simulation follows:

1. **Density and Pressure Gradient:** Compute density using the equation of state:

$$\rho(i, j) = \text{EqOfState}(S(i, j), T(i, j), P), \quad P = \rho_0 g(h - j\Delta z)/10^4 \quad (9)$$

Pressure gradient: $\partial P/\partial x = g(\rho_{i+1,j} - \rho_{i-1,j})/(2\Delta x)$.

2. **Eddy Viscosity:** Use Smagorinsky model:

$$\nu_e = (C_s \Delta)^2 |\mathbf{S}|, \quad \Delta = \sqrt{\Delta x \Delta z}, \quad |\mathbf{S}| = \sqrt{2 \left(\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial w}{\partial z} \right)^2 \right) + \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)^2} \quad (10)$$

3. **Tendencies:** Compute time derivatives for velocity, salinity, and temperature:

$$\frac{\partial u}{\partial t} = - \left(u \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z} \right) + \frac{1}{\rho_0} \frac{\partial}{\partial x} \left(\nu_e \frac{\partial u}{\partial x} \right) + \frac{1}{\rho_0} \frac{\partial}{\partial z} \left(\nu_e \frac{\partial u}{\partial z} \right) - \frac{1}{\rho_0} \frac{\partial P}{\partial x} \quad (11)$$

$$\frac{\partial w}{\partial t} = - \left(u \frac{\partial w}{\partial x} + w \frac{\partial w}{\partial z} \right) + \frac{1}{\rho_0} \frac{\partial}{\partial x} \left(\nu_e \frac{\partial w}{\partial x} \right) + \frac{1}{\rho_0} \frac{\partial}{\partial z} \left(\nu_e \frac{\partial w}{\partial z} \right) \quad (12)$$

$$\frac{\partial S}{\partial t} = - \left(u \frac{\partial S}{\partial x} + w \frac{\partial S}{\partial z} \right) + \frac{\partial}{\partial x} \left(\nu_e \frac{\partial S}{\partial x} \right) + \frac{\partial}{\partial z} \left(\nu_e \frac{\partial S}{\partial z} \right) \quad (13)$$

$$\frac{\partial T}{\partial t} = - \left(u \frac{\partial T}{\partial x} + w \frac{\partial T}{\partial z} \right) + \frac{\partial}{\partial x} \left(\nu_e \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial z} \left(\nu_e \frac{\partial T}{\partial z} \right) \quad (14)$$

4. **Time Integration:** Use RK4 or Crank-Nicolson (CN):

- **RK4:** Four-stage explicit method:

$$\phi^{n+1} = \phi^n + \frac{\Delta t}{6} (k_1 + 2k_2 + 2k_3 + k_4) \quad (15)$$

- **CN:** Implicit for diffusion, explicit for advection, solved using tridiagonal matrix algorithm.

5. **Boundary Conditions:** River inflow ($u = Q_{\text{river}}/h, S = 0$) at $x = 0$, tidal velocity ($u = A_{\text{tidal}} \cos(2\pi t/T_{\text{tidal}})$) at $x = L$, no-slip at bottom, and free surface.

6. **Vorticity:** Compute as:

$$\omega = \frac{\partial w}{\partial x} - \frac{\partial u}{\partial z} \quad (16)$$

Visualization

The GUI displays:

- Vorticity field (blue-red gradient).
- Velocity vectors (black arrows).
- Status with simulation time, scheme, and Δt .

Comparison and Physical Models

Both classes model estuarine circulation with:

- **Navier-Stokes Equations:** Solved via LBM (D2Q9) in `LatticeBoltzmannLES` or finite volume in `LargeEddySim`.
- **Smagorinsky Model:** Eddy viscosity:

$$\nu_e = (C_s \Delta)^2 |\mathbf{S}| \quad (17)$$

- **Density:** $\rho = 1000(1 + 0.0008S - 0.00007(T - 20))$ in `LatticeBoltzmannLES`; custom `EqOfState` in `LargeEddySim`.
- **Boundary Conditions:** River inflow and tidal forcing drive the flow.

`LatticeBoltzmannLES` uses a lattice-based approach with adaptive grid refinement and energy spectrum output, while `LargeEddySim` uses a finite volume method with RK4 or Crank-Nicolson integration, suitable for structured grids.