

# Comprehensive Forcing Mechanism

## Core Components and Initialization

The `CompForcingMechanism` class, implemented in C#, provides a graphical interface for simulating estuarine circulation using three solver types: 1D Simplified, 2D Shallow Water, and 3D Navier-Stokes. The simulation domain is an estuary with length  $L = 10000$  m, width  $W = 2000$  m, and depth  $H = 10$  m, discretized into grids of  $n_x = 50$ ,  $n_y = 20$ , and  $n_z = 10$  for 3D, or  $n = 100$  for 1D. Key parameters include:

- River discharge:  $Q_r = 0.1 \text{ m}^3/\text{s}$
- Tidal amplitude:  $A_t = 1.0 \text{ m}$ , period:  $T_t = 43200 \text{ s}$
- Wind speed:  $U_w = 5.0 \text{ m/s}$ , direction:  $\theta_w = 0^\circ$
- Salinity gradient:  $\partial S/\partial x = 0.0035 \text{ PSU/m}$
- Wave height:  $H_w = 0.5 \text{ m}$ , period:  $T_w = 10 \text{ s}$
- Storm surge amplitude:  $A_s = 0.0 \text{ m}$
- Minimum depth for wetting/drying:  $h_{\min} = 0.01 \text{ m}$
- Gravitational acceleration:  $g = 9.81 \text{ m/s}^2$
- Freshwater density:  $\rho_0 = 1000 \text{ kg/m}^3$ , ocean density:  $\rho_{\text{ocean}} = 1025 \text{ kg/m}^3$
- Kinematic viscosity:  $\nu = 10^{-6} \text{ m}^2/\text{s}$
- Salinity diffusion coefficient:  $\kappa = 10^{-4} \text{ m}^2/\text{s}$
- Eddy viscosity:  $\nu_e = 0.01 \text{ m}^2/\text{s}$
- Coriolis parameter:  $f = 10^{-4} \text{ s}^{-1}$
- Friction coefficient:  $C_f = 0.0025$
- Atmospheric pressure gradient:  $\partial P_a/\partial x = 0.0001 \text{ Pa/m}$
- Seasonal salinity amplitude:  $S_a = 2.0 \text{ PSU}$

The class initializes a Windows Forms interface with input controls for parameters, a visualization panel, and an output console. It supports dynamic switching between solvers and optional wetting/drying algorithms.

## Functioning Logic

The `CompForcingMechanism` class manages:

1. **User Interface:** Allows input of physical parameters and solver selection (1D, 2D, or 3D).
2. **Simulation Initialization:** Sets up grids and initial conditions based on solver type.

3. **Time Stepping:** Uses a Courant-Friedrichs-Lewy (CFL) condition with  $C = 0.4$  to compute adaptive time steps  $\Delta t$ .
4. **Forcing Mechanisms:** Incorporates river discharge, tides, wind stress, waves, storm surge, baroclinic effects, Coriolis force, and friction.
5. **Numerical Solvers:** Updates velocity, salinity, water level, and temperature using explicit schemes with flux limiters.
6. **Visualization:** Plots velocity (blue), salinity (red), and water level (green) profiles.
7. **Stability Checks:** Detects numerical instabilities (NaN or Infinity) and stops the simulation if detected.

## Solver Initialization

The `InitializeSimulation` method configures the solver based on the selected type:

- **3D Navier-Stokes:** Initializes 3D arrays for velocity components ( $u, v, w$ ), pressure ( $p$ ), salinity ( $S$ ), and temperature ( $T$ ). Spatial steps are  $\Delta x = L/(n_x - 1)$ ,  $\Delta y = W/(n_y - 1)$ ,  $\Delta z = H/(n_z - 1)$ . Initial conditions:

$$u_{i,j,k} = Q_r/(WH), \quad v_{i,j,k} = w_{i,j,k} = 0 \quad (1)$$

$$p_{i,j,k} = \rho_0 g \eta (1 - k \Delta z / H), \quad \eta = A_t \sin(2\pi x / L) + A_s e^{-x/L} \quad (2)$$

$$S_{i,j,k} = (\partial S / \partial x) x, \quad T_{i,j,k} = 20^\circ \text{C} \quad (3)$$

- **2D Shallow Water:** Instantiates `ShallowWaterEq2D` with bathymetry  $h_{i,j} = H(1 - x/L)$  if wetting/drying is enabled, using `WetAndDryAlgo`.
- **1D Simplified:** Initializes arrays for velocity ( $u$ ), salinity ( $S$ ), and water level ( $\eta$ ) with  $\Delta x = L/(n - 1)$ :

$$u_i = Q_r/H, \quad S_i = (\partial S / \partial x) i \Delta x, \quad \eta_i = A_t \sin(2\pi x / L) \quad (4)$$

## CFL Time Step

The `ComputeCFLTimeStep` method ensures numerical stability:

- **3D:**  $\Delta t = C \min \left( \frac{\Delta x}{|u|_{\max}}, \frac{\Delta y}{|v|_{\max}}, \frac{\Delta z}{|w|_{\max}}, \frac{\Delta x^2}{2(\nu + \nu_e)}, \frac{\Delta y^2}{2(\nu + \nu_e)}, \frac{\Delta z^2}{2(\nu + \nu_e)} \right)$
- **2D:** Delegates to `ShallowWaterEq2D.ComputeCFLTimeStep`.
- **1D:**  $\Delta t = C \min \left( \frac{\Delta x}{|u|_{\max}}, \frac{\Delta x^2}{2(\nu + \nu_e)} \right)$

The time step is constrained to  $\Delta t \geq 0.01$  s.

## 3D Navier-Stokes Solver

The `UpdateSimulation` method for 3D solves:

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + (\nu + \nu_e) \nabla^2 u + f v - \frac{g}{\rho_0} \frac{\partial \rho}{\partial x} + F_u \quad (5)$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = -\frac{1}{\rho_0} \frac{\partial p}{\partial y} + (\nu + \nu_e) \nabla^2 v - f u + F_v \quad (6)$$

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = -\frac{1}{\rho_0} \frac{\partial p}{\partial z} + (\nu + \nu_e) \nabla^2 w - g \quad (7)$$

$$\frac{\partial S}{\partial t} + u \frac{\partial S}{\partial x} + v \frac{\partial S}{\partial y} + w \frac{\partial S}{\partial z} = \kappa \nabla^2 S + 0.1 \left| \frac{\partial u}{\partial x} \right| S \quad (8)$$

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} + w \frac{\partial T}{\partial z} = \kappa \nabla^2 T \quad (9)$$

where  $\rho = \rho_0 + S(\rho_{\text{ocean}} - \rho_0)/35 - 0.2(T - 20)$ , and forcing terms include:

- **Wind stress:**  $\tau_x = 0.001 \rho_0 U_w^2 \cos(\theta_w \pi / 180)$ ,  $\tau_y = 0.001 \rho_0 U_w^2 \sin(\theta_w \pi / 180)$
- **Wave velocity:**  $u_w = 0.5 H_w k \sqrt{g H}$ ,  $k = 2\pi / (L/10)$
- **Quadratic drag:**  $-C_f |u| u / H$
- **Atmospheric pressure gradient:**  $\partial P_a / \partial x / \rho_0$

Advection uses upwind schemes with a minmod flux limiter:

$$\phi_{\text{lim}} = \max(0, \min(1, r)), \quad r = \frac{\phi - \phi_{\text{upwind}}}{\phi_{\text{downwind}} - \phi + 10^{-10}} \quad (10)$$

Pressure is corrected iteratively to enforce incompressibility:

$$\nabla^2 p = \nabla \cdot \mathbf{u}, \quad p_{i,j,k} = \frac{p_{i+1,j,k} + p_{i-1,j,k} + p_{i,j+1,k} + p_{i,j-1,k} + p_{i,j,k+1} + p_{i,j,k-1} - \Delta x^2 (\nabla \cdot \mathbf{u})}{6} \quad (11)$$

Boundary conditions:

$$x = 0 : \quad u = Q_r / (WH), \quad v = w = 0, \quad S = 0, \quad T = 20 \quad (12)$$

$$x = L : \quad u = A_t (2\pi / T_t) \cos(2\pi t / T_t), \quad v = w = 0, \quad p = \rho_0 g (A_s e^{-t/86400} + 0.05 A_t A_s \sin(2\pi t / T_t)), \quad S \quad (13)$$

## 2D Shallow Water Solver

The `ShallowWaterEq2D` class updates velocity ( $u, v$ ), water level ( $\eta$ ), and salinity ( $S$ ) using shallow water equations, with optional wetting/drying via `WetAndDryAlgo`. Forcing includes wind, tides, waves, and storm surge.

## 1D Simplified Solver

The 1D solver updates velocity ( $u$ ), water level ( $\eta$ ), and salinity ( $S$ ):

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = -g \frac{\partial \eta}{\partial x} - \frac{g}{\rho_0} \frac{\partial \rho}{\partial x} + \frac{\tau_x}{\rho_0 H} + u_w + 0.05 A_t A_s \sin(2\pi t/T_t) - C_f |u| u / H + f u + \frac{\partial P_a / \partial x}{\rho_0} \quad (14)$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x} [(H + \eta)u] = A_t \sin(2\pi(t/T_t - x/\sqrt{gH})) - \epsilon \eta \quad (15)$$

$$\frac{\partial S}{\partial t} + u \frac{\partial S}{\partial x} = (\kappa + \nu_e) \frac{\partial^2 S}{\partial x^2} + 0.1 \left| \frac{\partial u}{\partial x} \right| S \quad (16)$$

Boundary conditions:

$$x = 0 : \quad u = Q_r/H, \quad S = 0 \quad (17)$$

$$x = L : \quad u = A_t(2\pi/T_t) \cos(2\pi t/T_t), \quad \eta = A_t \sin(2\pi t/T_t) + A_s e^{-t/86400}, \quad S = 35 + S_a \sin(2\pi t/(365 \cdot \dots)) \quad (18)$$

Advection uses upwind schemes with minmod flux limiter, and salinity is smoothed near boundaries.

## Visualization

The `visualizationPanel_Paint` method plots:

- Velocity (blue), salinity (red), and water level (green) as 1D profiles along the estuary length.
- For 3D, variables are averaged over  $y$  and  $z$ .
- For 2D, wet/dry cells are shown as light blue (wet) or tan (dry) backgrounds.

Values are scaled to the panel dimensions, with checks for NaN or Infinity.

## Physical and Mathematical Models

- **3D Navier-Stokes:**

$$\begin{aligned} \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} &= -\frac{1}{\rho_0} \nabla p + (\nu + \nu_e) \nabla^2 \mathbf{u} + \mathbf{f} \times \mathbf{u} - \frac{g}{\rho_0} \nabla \rho + \mathbf{F} \\ \nabla \cdot \mathbf{u} &= 0, \quad \frac{\partial S}{\partial t} + \mathbf{u} \cdot \nabla S = \kappa \nabla^2 S + 0.1 \left| \frac{\partial u}{\partial x} \right| S, \quad \frac{\partial T}{\partial t} + \mathbf{u} \cdot \nabla T = \kappa \nabla^2 T \end{aligned} \quad (19)$$

- **2D Shallow Water:** Handled by `ShallowWaterEq2D` with wetting/drying.
- **1D Simplified:**

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = -g \frac{\partial \eta}{\partial x} - \frac{g}{\rho_0} \frac{\partial \rho}{\partial x} + F_{\text{total}}, \quad \frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x} [(H + \eta)u] = F_\eta, \quad \frac{\partial S}{\partial t} + u \frac{\partial S}{\partial x} = (\kappa + \nu_e) \frac{\partial^2 S}{\partial x^2} + \dots \quad (21)$$

- **Forcing Terms:** Wind stress, wave velocity, tide-surge interaction, quadratic drag, Coriolis, atmospheric pressure gradient.
- **Numerical Methods:** Explicit time stepping, upwind advection with min-mod limiter, iterative pressure correction (3D), and boundary smoothing.

The model integrates multiple physical processes, ensuring robust simulation of estuarine dynamics with user-configurable parameters and real-time visualization.