Boundary Layer Schemes

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1 Functionalities

The Boundary Layer Schemes Window class provides the following functionalities:

- **Initialization**: Sets up a window for boundary layer schemes analysis, integrating with the model to access ocean and atmosphere temperatures and coupling parameters.
- **Simulation Control**: Allows users to start and stop a simulation, updating parameters (drag coefficient, sensible heat coefficient, boundary layer depth, KPP mixing coefficient) and selecting between Bulk and KPP schemes.
- **Visualization**: Displays a heatmap of heat flux (Bulk scheme) or diffusivity (KPP scheme) with annotations and a scatter plot of flux/diffusivity versus temperature gradient, updated in real-time via animation.
- **Parameter Input**: Enables users to input simulation parameters and select schemes, with validation to ensure physical constraints.
- Logging and Error Handling: Logs initialization, simulation control, and plot updates using the logging module, with exception handling to display errors via message boxes.

2 Simulation Logic

The simulation logic in BoundaryLayerSchemesWindow centers around managing boundary layer schemes analysis and visualization.

2.1 Initialization

- **Purpose**: Initializes the analysis window with model integration and visualization setup.
- · Process:

- Stores the model instance for access to ocean and atmosphere temperatures and coupling parameters.
- Sets up a window with a control panel for inputting drag coefficient, sensible heat coefficient, boundary layer depth, KPP mixing coefficient, and selecting Bulk/KPP schemes.
- Initializes a matplotlib figure with two subplots: one for a heatmap of heat flux or diffusivity with annotations, and one for a scatter plot of flux/diffusivity versus temperature gradient.
- Sets up a simulation grid (ny x nx) matching the model's ocean temperatures and initializes arrays for heat flux and diffusivity.
- Sets the time step $\Delta t = 1800\,\mathrm{s}$ to match the main simulation.
- Sets up a timer for animation updates every 100 ms and initializes the plot.
- Logs initialization details and handles exceptions, displaying errors via QMessageBox.

2.2 Simulation Control

• **Purpose**: Manages the start and stop of the boundary layer schemes simulation.

Process (Start):

- Validates inputs: drag coefficient (> 0), sensible heat coefficient (≥ 0), boundary layer depth (> 0), KPP mixing coefficient (> 0).
- Updates model parameters (model.coupling.drag_coeff).
- Resets simulation step, time steps, flux arrays, and diffusivity arrays.
- Starts a timer to trigger animation updates every 100 ms.
- Disables the start button and enables the stop button.

• Process (Stop):

- Stops the timer and animation.
- Enables the start button and disables the stop button.
- Logs actions and handles exceptions, displaying errors via QMessageBox.

2.3 Plot Update

• **Purpose**: Updates the visualization of heat flux or diffusivity and their relationship with temperature gradients.

• Process:

- Checks if the simulation should continue (current step < total_time/ Δt).
- Validates and updates parameters from user inputs and selected scheme.
- Computes heat flux (Bulk scheme) or diffusivity and heat flux (KPP scheme) based on ocean and atmosphere temperatures and wind speed.
- Stores flux and temperature gradient data for visualization.
- Updates plots: a heatmap of heat flux or diffusivity with sparse annotations, and a scatter plot of flux/diffusivity versus temperature gradient colored by time.
- Increments the simulation step and logs actions.

3 Physics and Mathematical Models

The Boundary Layer Schemes Window class implements models for boundary layer dynamics, comparing Bulk and KPP schemes.

3.1 Bulk Heat Flux (Bulk Scheme)

- Purpose: Computes sensible heat flux between ocean and atmosphere.
- Equation:

$$Q_b = \rho_{\text{air}} C_p^{\text{air}} C_h U(T_o - T_a),$$

where $\rho_{\rm air}=1.225\,{\rm kg/m^3}$, $C_p^{\rm air}=1005\,{\rm J/kg/K}$, C_h is the sensible heat coefficient (W/m²/K), U is wind speed (m/s), T_o is ocean temperature (K), and T_a is atmosphere temperature (K).

• Implementation: update_plot computes Q_b using user-input C_h and model temperature fields.

3.2 KPP Scheme

• **Purpose**: Computes turbulent diffusivity and heat flux using the K-Profile Parameterization (KPP) scheme.

Equations:

$$K(z) = k_m \left(1 - \frac{z}{h} \right)^2,$$
$$Q_{\text{KPP}} = -K(z) \frac{\partial T_o}{\partial y},$$

where k_m is the KPP mixing coefficient (m²/s), h is the boundary layer depth (m), $z \in [0,h]$, and $\frac{\partial T_o}{\partial y} \approx \frac{T_{o,i+1,j}-T_{o,i-1,j}}{2\Delta y}$. K(z) is clipped to $[0,k_m]$.

• Implementation: update_plot computes K(z) and Q_{KPP} using user-input k_m and h.

3.3 Temperature Gradient

- **Purpose**: Computes the temperature difference driving the heat flux.
- Equation:

$$\Delta T = T_o - T_a$$

where ΔT is the temperature gradient (K).

• Implementation: update_plot computes ΔT for scatter plot visualization.

4 Algorithms

4.1 Initialization Algorithm

- Input: Model instance (model).
- Steps:
 - 1. Log initialization.
 - 2. Store model as an instance variable.
 - 3. Set window title to "Boundary Layer Schemes Analysis" and size to 900×600 .
 - 4. Create a control panel with inputs for drag coefficient (model.coupling.drag_coesensible heat coefficient (10.0 W/m²/K), boundary layer depth (50.0 m), KPP mixing coefficient (0.01 m²/s), and a selector for Bulk/KPP schemes.
 - 5. Create start and stop buttons, with stop initially disabled.
 - 6. Initialize a matplotlib figure with two subplots: heatmap and scatter plot.

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- 7. Set up simulation grid (ny \times nx) from model's ocean temperatures and initialize arrays for heat flux and diffusivity.
- 8. Set $\Delta t = 1800 \, \text{s}$.
- 9. Initialize empty lists for time steps, bulk fluxes, KPP fluxes, and temperature gradients.
- 10. Set up a timer for 100 ms updates and call update_plot(0).
- 11. Log completion or errors, displaying critical errors via QMessageBox.

4.2 Start Simulation Algorithm (start_simulation)

- Input: None (uses input fields).
- Steps:
 - 1. Log start of simulation.
 - 2. Read and validate inputs: drag coefficient (> 0), sensible heat coefficient (≥ 0), boundary layer depth (> 0), KPP mixing coefficient (> 0).
 - 3. Update model.coupling.drag_coeff.
 - 4. Reset current_step, time_steps, bulk_fluxes, kpp_fluxes, temp_gradients, and heat flux/diffusivity arrays.
 - 5. Start timer (100 ms interval).
 - 6. Disable start button and enable stop button.
 - 7. Log completion or errors, displaying warnings or critical errors via QMessageBox.

4.3 Stop Simulation Algorithm (stop_simulation)

- Input: None.
- Steps:
 - 1. Log stop of simulation.
 - Stop timer and animation (anim.event_source.stop()).
 - 3. Set anim to None.
 - 4. Enable start button and disable stop button.
 - 5. Log completion or errors, displaying critical errors via QMessageBox.

4.4 Plot Update Algorithm (update_plot)

- Input: Frame number (unused directly, tracks via current_step).
- Steps:
 - 1. Log start of update at current_step.
 - 2. If current_step \geq total_time/ Δt or model is invalid, call stop_simulation.
 - 3. Validate and read inputs: drag coefficient, sensible heat coefficient, boundary layer depth, KPP mixing coefficient, and scheme.
 - 4. Compute Bulk heat flux: $Q_b = \rho_{air} C_p^{air} C_h U(T_o T_a)$.
 - 5. Compute KPP diffusivity and flux:

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, clipped to $[0,k_m]$.

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$$Q_{ ext{KPP}}=-Krac{\partial T_o}{\partial y}$$
, with $rac{\partial T_o}{\partial y}pproxrac{T_{o,i+1,j}-T_{o,i-1,j}}{2\Delta y}$.

- 6. Update fields: Q_b for Bulk scheme, K(z) for KPP scheme.
- 7. Store flattened Q_b , Q_{KPP} , and $\Delta T = T_o T_a$ for scatter plot.
- 8. Update plots:
 - Left: Heatmap of Q_b (Bulk, coolwarm) or K(z) (KPP, viridis) with annotations every ny/5 × nx/5.
 - Right: Scatter plot of Q_b or K(z) vs. ΔT , colored by time (plasma).
- 9. Increment current_step.
- 10. Log completion or errors, displaying warnings or critical errors via QMessageBox.