## **ENGR 6928: Computer Aided Engineering**

# Tutorial- Setting up MatLab to achieve LAN/WLAN data communication

## 1. Establishing communication between two Matlab applications running on the same machine:

Network communication setup for Matlab programs running on the same machine using TCP protocol.

Machine1	Local IP	Irrelevant	Machine2	Local IP	Irrelevant
Application X	Local Port	9000	Application Y	Local Port	Any
	Remote IP	0.0.0.0		Remote IP	127.0.0.1
	Remote Port	Any		Remote Port	9000
	Protocol	TCP /Server		Protocol	TCP/Client

Run 2 matlab applications on the same machine. The following code would configure one matlab application as a server and the other as a client.

Server Application script	Client Application script
clear	clear
clc	clc
close all	instrreset % reset any connections of
	tis app if open
t =	close all
tcpip('0.0.0.0',4012,'NetworkRole',	
'server');	t =
	tcpip('127.0.0.1',4012,'NetworkRole',
fopen(t)	'client');
while(1)	
<pre>if (t.BytesAvailable&gt;0)</pre>	fopen(t)
data = fscanf(t)	pause (1)
end	<pre>fprintf(t,'testing')</pre>
end	
fclose(t)	fclose(t)
, ,	, ,

Network communication setup for Matlab programs running on the same machine using the UDP protocol.

Machine1	Local IP	192.168.1.1	Machine2	Local IP	192.168.1.8
Application X	Local Port	9000	Application Y	Local Port	12345
	Remote IP	127.0.0.1		Remote IP	127.0.0.1
	Remote Port	12345		Remote Port	9000
	Protocol	UDP		Protocol	UDP

### 2. Using the DSP system toolbox for UDP communication:

The above script is only possible with the Matlab instrument control toolbox which is currently not available @ MUN labs. If you are to implement this in the computers at the lab., Your only option is to use the DSP systems toolbox.

```
receiver Application script
                                            Sender Application script
clear
                                             clear
clc
                                            clc
close all
                                            close all
hudpr =
                                            hudps =
dsp.UDPReceiver('RemoteIPAddress','0.0.0
                                            dsp.UDPSender('LocalIPPortSource',
.0', 'LocalIPPort', 25000, 'MessageDataType
                                             'Auto', 'RemoteIPAddress', '127.0.0.1
','uint8')
                                             ', 'RemoteIPPort', 25000)
                                            data = uint8('testing...!');
string=[];
count=1;
                                             %convert the string to uint8
eof=0;
                                             for i=1:size(data,2)
while(~eof)
                                                step(hudps,data(i))
    dataReceived = step(hudpr);
                                                 %send the numbers 1 by 1
    if strcmp(char(dataReceived),'!')
                                            end
            eof=1; %! signified the end
    else
                                            release (hudps)
            string=[string
char(dataReceived)]; %fill the string
            count=count+1;
    end
end
                      %display the string
string
release(hudpr)
```

Notice that here the string is first converted to unsigned 8 bit integers, at the sender. At the receiver the data is then converted back to characters. This is because the 'MessageDataType' argument of the UDPReciever function does not allow char as a data type.

#### 3. Setting up a personal access point:

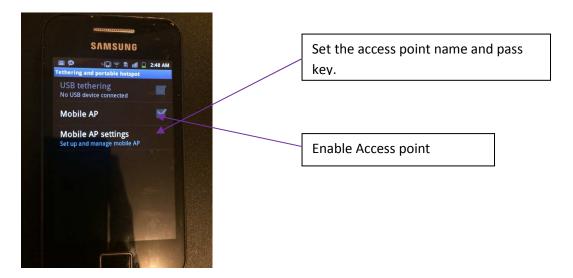
For communicating between two separate machines connected to a LAN, the windows firewall settings must be turned off. So it is not recommended to perform the connections that follows, while connected to the internet.

The recommended approach is to connect to a personal access point which is not connected to the internet, which would allow to perform the connections without unnecessary security risks.

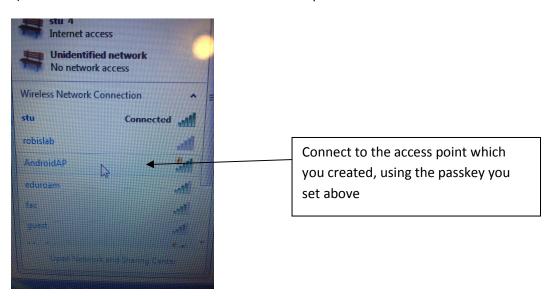
This capability is there on some laptops. And is there on Android devices. iOS devices tend to connect to the internet through a data network prior to setting up a hotspot, so this would still create security

issues. Following are some screenshots which guide you through setting up a access point on an Android device.

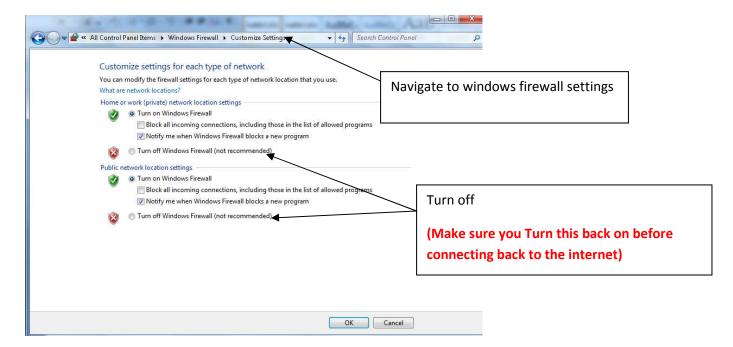
a) go to settings> Wireless & Networks > Tethering & portable hotspot. And turn on mobile AP.



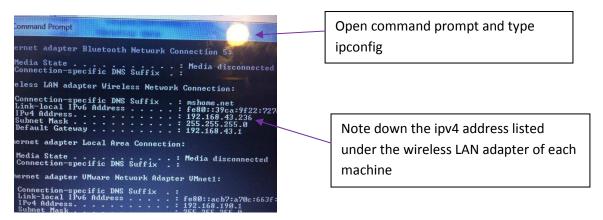
b) Each machine can connect to this mobile access point.



c) Turnoff windows firewall of each machine (be sure to turn it back on before connecting to the internet).



d) Note down the IP addresses of the machines, by using the ipconfig command typed on the command prompt.



For this example assume the IP address of machine 1 is :192.168.43.236 and the address of machine 2 is: 192.163.43.237.

### 4. Settings for communications between two different machines(hosts):

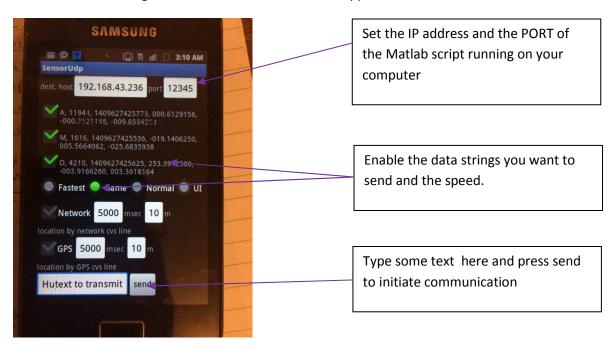
a) Network communication setup for Matlab programs on 2 different machines using TCP protocol.

Machine1	Local IP	192.168.43.236	Machine2	Local IP	192.163.43.237
Application X	Local Port	9000	Application Y	Local Port	Any
	Remote IP	0.0.0.0		Remote IP	192.163.43.236
	Remote Port	Any		Remote Port	9000
	Protocol	TCP /Server		Protocol	TCP/Client

Run Matlab on two machines connected to a mobile access point. An example of the configuration for communication is given above.

b) Network communication setup for UDP data reception from the sensor UDP app.

The sensorUDP app available for free, allows to send data to a UDP port. Following is an example communication setting to use to receive data from this App to matlab.



Machine1	Local IP	192.168.43.236	Android device	Local IP	(irrelevant)
MatLab	Local Port	12345	SensorUDP	Local Port	(irrelevant)
	Remote IP	(irrelevant)	Арр	Remote IP	192.168.43.236
	Remote Port	(irrelevant)		Remote Port	12345
	Protocol	UDP		Protocol	UDP

Following is a n example Matlab script which would plot the received data. Only the O (orientation ) data is enabled at the App.

```
instrreset
  clear
  clc
%Creating UDP object
  UDPComIn=udp('0.0.0.0','LocalPort',12345);
  set(UDPComIn,'DatagramTerminateMode','off')
%Creating bar plot for sensor visualization
  figure
  sensorbar=bar([0,0,0]);
  fopen(UDPComIn);
  longestLag=0;
while 1
  tic
```

```
csvdata=fscanf(UDPComIn);
    scandata=textscan(csvdata,'%s %f %f %f %f %f','Delimiter',',');
   data=[scandata{4},scandata{5},scandata{6}];
   if size(data,1)==1
     data(1) = data(1);
     set(sensorbar,'YData',data(1,:))
     axis([0.5, 3.5, -180, 180])
     pause(0.00001)
   end
 clc
 disp('Data received:')
 disp(data)
 disp('Longest Lag:')
 disp(longestLag)
 t=toc;
 longestLag=max(t,longestLag);
%Closing UDP communication
 fclose(UDPComIn);
%Deleting UDP communication
 delete(UDPComIn)
%CodeEnd-
```