# **KOALA:** A new paradigm for election coverage

An opinion poll based "now-cast" of probabilities of events in multi-party electoral systems

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DAGStat | March 20, 2019 | Munich

Alexander Bauer 1 / 17



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Alexander Bauer 1 / 17



#### Collaborators

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Alexander Bauer 1 / 17

## **Outline**

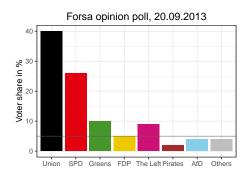
- 1. Motivation
- 2. Methods
- 3. Technical implementation
- 4. Results & Outlook

Alexander Bauer 2 / 17

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Alexander Bauer 2 / 17



#### Questions of interest

- Which parties will pass the 5% hurdle and enter the parliament?
- Which parties will form the governing coalition?
- Which party will have the third largest share of votes?

Alexander Bauer 3 / 1'

### Reported voter shares

| Union | SPD | Greens | FDP | The Left | Pirates | AfD | Others |
|-------|-----|--------|-----|----------|---------|-----|--------|
| 40%   | 26% | 10%    | 5%  | 9%       | 2%      | 4%  | 5%     |

### Redistributed voter shares (based on 5% hurdle)

| Union  | SPD    | Greens | FDP   | The Left | Pirates | AfD | Others |
|--------|--------|--------|-------|----------|---------|-----|--------|
| 44.44% | 28.89% | 11.11% | 5.56% | 10.00%   | -       | -   | -      |

- Union-FDP have a joint seat share of exactly 50%
- Stating that Union-FDP would thus miss a joint majority would neglect sample uncertainty

⇒ We calculate event probabilities that fully reflect sample uncertainty

Alexander Bauer 3 / 1

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# Motivation

## We aim to do now-casting

- We incorporate the uncertainty as reported by the polling agencies
- · Potential house biases or an industry bias are not accounted for

#### We do not aim to do for-casting

- Our approach simply communicates sample uncertainty in a novel way
- Also, a relevant share of voters is still undecided shortly before election day (Küchenhoff et al., 2018)

Alexander Bauer 4 / 17

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Alexander Bauer 4 / 17

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Alexander Bauer 5 / 17



## Estimating probabilities of events (POEs)

Given one opinion poll with sample size n:

$$\mathbf{X} = (X_1, \dots, X_P)^T \sim Multinomial(n, \theta_1, \dots, \theta_P),$$

with voter counts  $X_j$  and the true percentage of voters  $\theta_j$  per party j (assuming a simple random sample, ignoring a possible bias)

Using an uninformative Dirichlet prior (Gelman et al., 2013)

$$heta=( heta_1,\ldots, heta_P)^{\mathsf{T}}\sim extit{Dirichlet}(lpha_1,\ldots,lpha_P),$$
 with  $lpha_1=\ldots=lpha_P=rac{1}{2},$ 

the resulting posterior distribution of  $\theta | x$  is again Dirichlet:

$$\theta | \mathbf{x} \sim Dirichlet(x_1 + 1/2, ..., x_P + 1/2).$$

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## 2 Methods

## Estimating probabilities of events (POEs)

Given the posterior distribution of voter shares we can use **Monte Carlo simulations** to estimate POEs:

- 1. Simulate 10 000 election outcomes from the posterior
- 2. If necessary: Redistribute voter shares to get obtained seats in parliament
- 3. POE = Percentage of simulations where event of interest occurred

#### **Example**

Given the Forsa poll, the coalition of Union-FDP obtained a majority of seats in 2 633 of 10 000 simulations

 $\Rightarrow$  POF  $\approx 26\%$ 

Alexander Bauer 7 / 17



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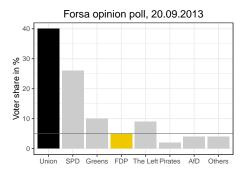
#### **Example**

Given the Forsa poll, the coalition of Union-FDP obtained a majority of seats in 2633 of 10000 simulations

 $\Rightarrow$  POE  $\approx$  26%

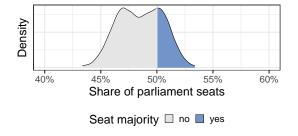
Alexander Bauer 7 / 17

#### Voter shares



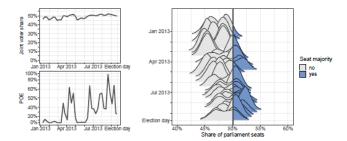
Alexander Bauer 8 / 17

#### Posterior distribution of joint CDU-FDP seat share



 $\Rightarrow$  POE  $\approx$  26%

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#### Plan:

- 1. Als Motivationsbeispiel die frueheste gepoolte Umfrage im 2013er Ridgeline Plot nehmen
- 2. Erstmal nur Ridgeline zeigen und Zeitverlauf animieren
- 3. Bei erster richtiger Bimodalitaet Animation anhalten und kurz daneben Unionund FDP-Stimmanteil-Zeitverlauf einblenden
- 4. Animation fertig laufen lassen (Union und FDP dabei wieder ausgeblendet)
- 5. Am Ende links den redistributed joint voter share und die POE-W'keiten einblenden

Alexander Bauer 10 / 1



#### **Pooling**

We aggregate multiple polls to reduce sample uncertainty. In case of multiple random samples:

$$\left(\sum_{i} X_{i1}, \dots, \sum_{i} X_{iP}\right)^{T} \sim Multinomial\left(\sum_{i} n_{i}, \theta_{1}, \dots, \theta_{P}\right).$$

We account for correlations between polling agencies by using an **effective sample size** (Hanley et al., 2003).

 $\Rightarrow$  **Example:** Pooling two polls with 1500 and 2000 respondents (where the strongest party obtained 40%), we get a conservative effective sample size of  $n_{\text{eff}} = 2341$ .

Alexander Bauer 11 / 17



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#### Pooling in practice

- We only pool surveys published in the last 14 days
- We only include one survey per polling agency

Correction of rounding errors

Party shares are only published with a certain accuracy. We add **uniformly distributed random noise** to avoid potential biases.

Alexander Bauer 12 / 17



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Alexander Bauer 12 / 17

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# **2** Technical implementation

## R package coalitions



... Code example: More on GitHub

Alexander Bauer 14 / 17

# **2** Technical implementation

#### Web-Interface

- koala.stat.uni-muenchen.de
- Blog
- @koala\_lmu
- based on Shiny
- automatic update scraping data from wahlrecht.de

Alexander Bauer 15 / 1

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Alexander Bauer 17 / 17

#### References

#### **Topic**

**Doe J, Mustermann M (2019)** This is the paper title. Journal, 19(2-3), 1-19 **Doe J, Mustermann M (2019)** This is the paper title. Journal, 19(2-3), 1-19

#### **Another topic**

**Doe J, Mustermann M (2019)** This is the paper title. Journal, 19(2-3), 1-19 Hanley et al., 2003

Alexander Bauer 17 / 17

## References

## One more topic

Doe J, Mustermann M (2019) This is the paper title. Journal, 19(2-3), 1-19

Alexander Bauer 17 / 17