# Data Mining

CS57300 Purdue University

Bruno Ribeiro

February 1st, 2018

### Exploratory Data Analysis & Feature Construction

- How to explore a dataset
  - Understanding the variables (values, ranges, and empirical distribution)
  - Finding easy relationships between variables
- Building features from data
  - How to better represent the data for various data mining tasks

Data exploration and visualization

#### Visualization

- Human eye/brain have evolved powerful methods to detect structure in nature
- Display data in ways that exploit human pattern recognition abilities
- Limitation: Can be difficult to apply if data size (number of dimensions or instances) is large

### Exploratory data analysis

- Data analysis approach that employs a number of (mostly graphical) techniques to:
  - Maximize insight into data
  - Uncover underlying structure
  - Identify important variables
  - Detect outliers and anomalies
  - Test underlying modeling assumptions
  - Develop parsimonious models
  - Generate hypotheses from data

### Visualizing/summarizing data

- Low-dimensional data
  - Summarizing data with simple statistics
  - Plotting raw data (1D, 2D, 3D)
- Higher-dimensional data
  - Principal component analysis
  - Multidimensional scaling

### Data summarization

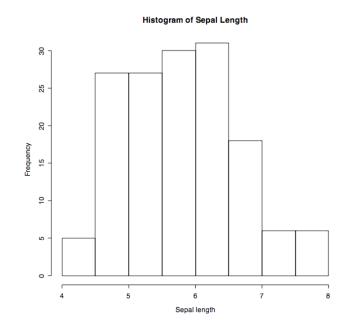
- Measures of location
  - Mean:  $\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} x(i)$
  - Median: value with 50% of points above and below
  - Quartile: value with 25% (75%) points above and below
  - Mode: most common value

### Data summarization

- Measures of dispersion or variability
  - Variance:  $\hat{\sigma}_k^2 = \frac{1}{n} \sum_{i=1}^n (x(i) \mu)^2$
  - Standard deviation:  $\hat{\sigma}_k = \sqrt{\frac{1}{n} \sum_{i=1}^n (x(i) \mu)^2}$
  - Range: difference between max and min point
  - Interquartile range: difference between 1st and 3rd Q
  - Skew:  $\frac{\sum_{i=1}^{n} (x(i) \hat{\mu})^3}{(\sum_{i=1}^{n} (x(i) \hat{\mu})^2)^{\frac{3}{2}}}$

### Histograms (1D)

- Most common plot for univariate data
- Split data range into equal-sized bins, count number of data points that fall into each bin
- Graphically shows:
  - Center (location)
  - Spread (scale)
  - Skew
  - Outliers
  - Multiple modes

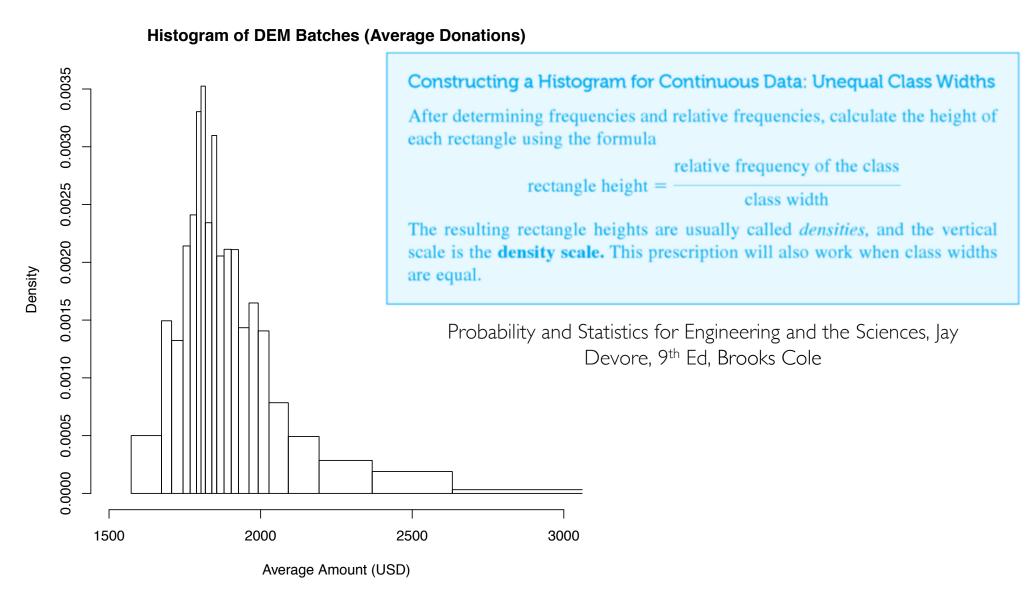


### Problem with Standard Histograms

- Test the following on R:
  - hist(c(0,0,0,2,3),breaks=c(0,1-1e-2,2,3))
  - hist(c(0,0,0,2,3),breaks=c(0,0.5,1-1e-2,2,3))
  - hist(c(0,0,0,2,3),breaks=c(0,0.5,1-1e-2,1.5,2,2.5,3))

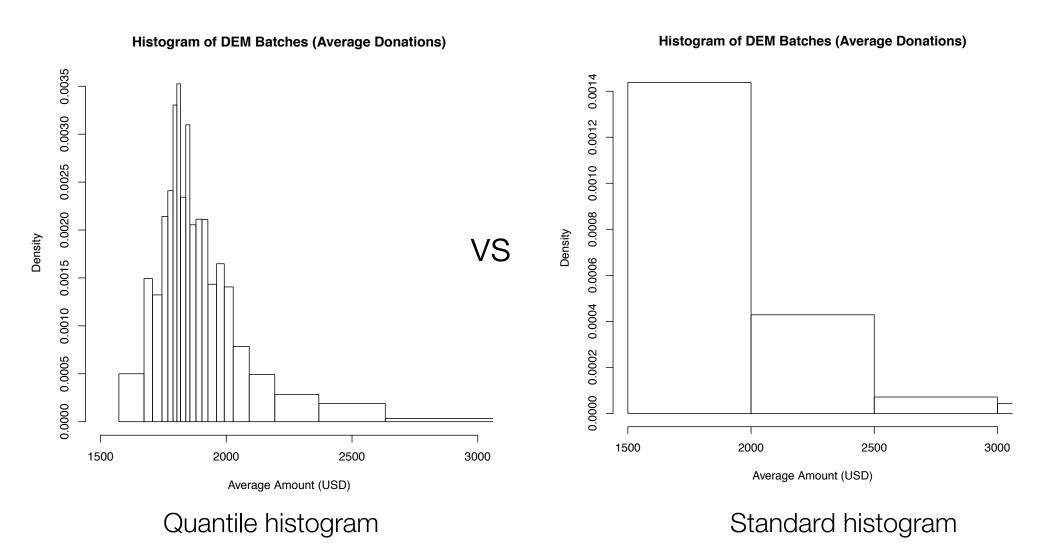
- Standard histograms give inconsistent results for continuous data
  - Visualization highly dependent on binning

## Quantile Histogram (better)



Each bin represents approximately the same number of data points

# Quantile Histogram (better)



### R code (of example)

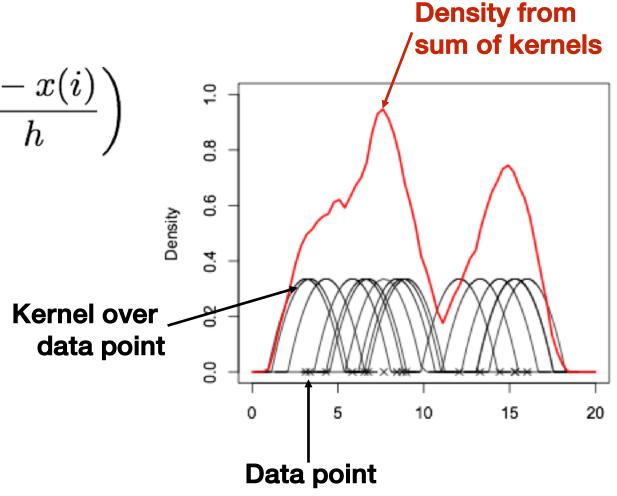
```
dem = read.csv("DEM donations 2012.csv", header=TRUE)
gop = read.csv("GOP donations 2012.csv",header=TRUE)
demdonations = as.matrix(dem$donation[dem$donation > 0])
gopdonations = as.matrix(gop$donation[gop$donation > 0])
N = round(nrow(demdonations)/200)
# randomly split DEMs into N groups of average length nrow(demdonations)/N
demsplit = as.list(split(demdonations, sample(1:N, nrow(demdonations), replace=T)))
# find average of each bin
dem bin averages = unlist(lapply(demsplit,mean))
# find 20 quantiles of each the batch averages
quantiles dem = quantile(dem bin averages, probs = seq(0, 1, 1/20))
# plot histogram
hist(dem bin averages, main="Histogram of DEM Batches (Average Donations)", freq=FALSE, breaks=quantiles dem, xlim=c(1500, 3000))
N = round(nrow(gopdonations)/200)
# randomly split GOP into N groups of average length nrow(demdonations)/N
gopsplit = split(gopdonations, sample(1:N, nrow(gopdonations), replace=T))
# find average of each bin
gop_bin_averages = unlist(lapply(gopsplit,mean))
# find 20 quantiles of each the batch averages
quantiles gop = quantile(gop bin averages, probs = seq(0, 1, 1/20))
# plot histogram
hist(gop bin averages, main="Histogram of GOP Batches (Average Donations)", freq=FALSE, breaks=quantiles gop, xlim=c(1500,3000))
```

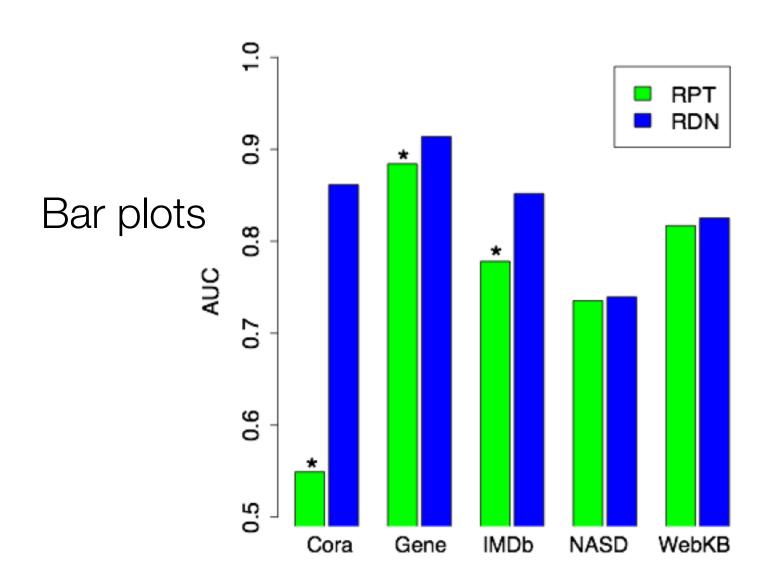
### Alternative to Histograms: Density plots

Estimated density is:

$$\hat{f}(x) = \frac{1}{n} \sum_{i=1}^{n} K\left(\frac{x - x(i)}{h}\right)$$

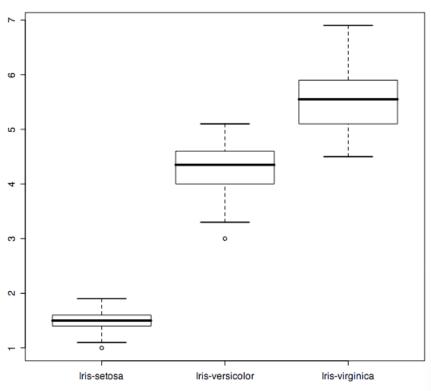
- Two parameters:
  - Kernel function K
     (e.g., Gaussian,
     Epanechnikov)
  - Bandwidth h



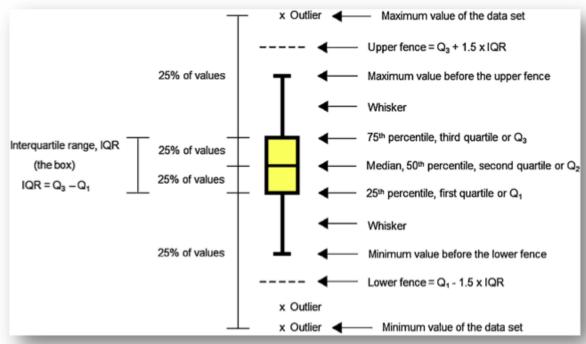


### Box plot (2D)

#### Box plot of petal length per class



- Display relationship between discrete and continuous variables
- For each discrete value X, calculate quartiles and range of associated Y values

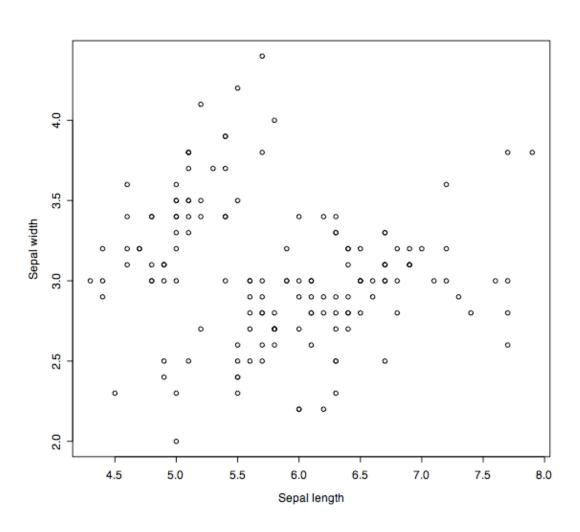


Ack: João Elias Vidueira Ferreira

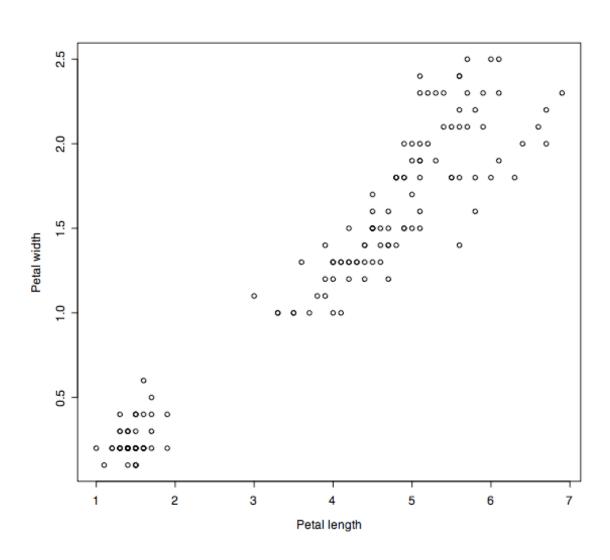
### Scatter plot (2D)

- Most common plot for bivariate data
  - Horizontal X axis: the suspected independent variable
  - Vertical Y axis: the suspected dependent variable
- Graphically shows:
  - If X and Y are related
  - Linear or non-linear relationship
  - If the variation in Y depends on X
  - Outliers

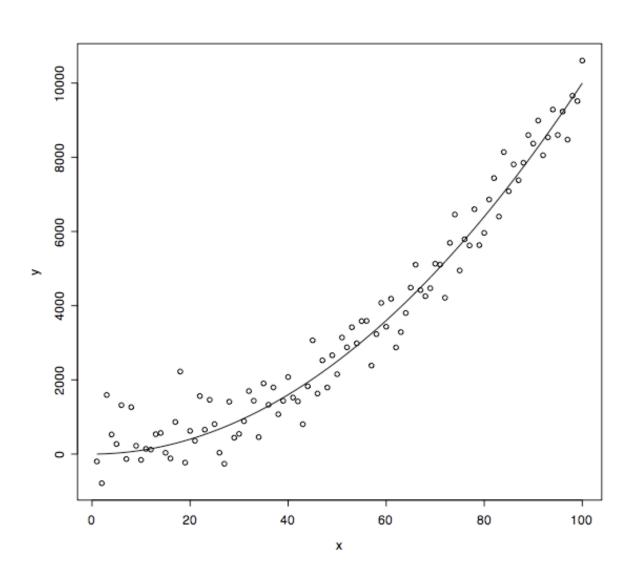
# No relationship



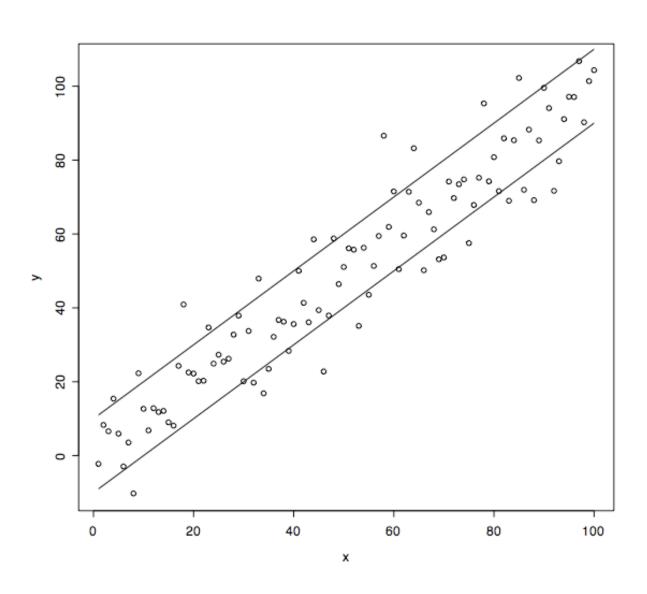
# Linear relationship



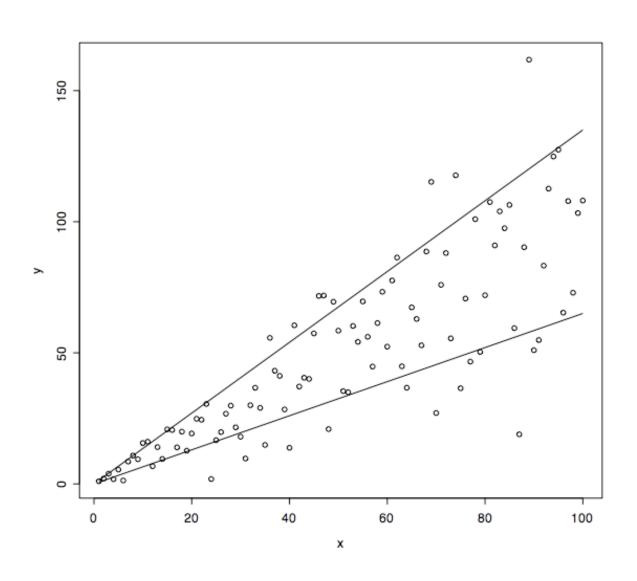
# Non-linear relationship



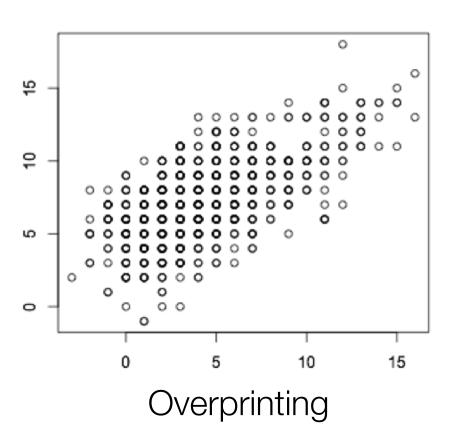
# Homoskedastic (equal variance)

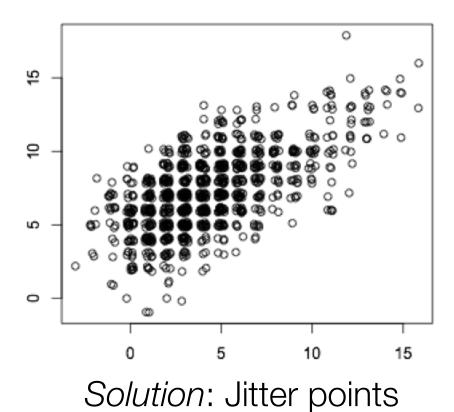


# Heteroskedastic (unequal variance)



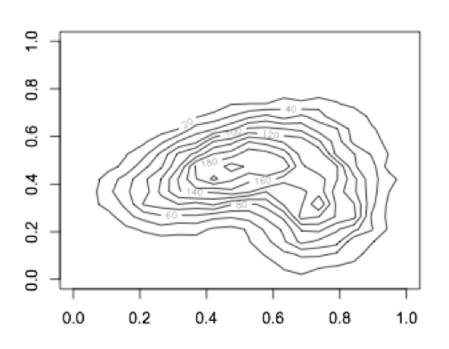
### Scatterplot limitations



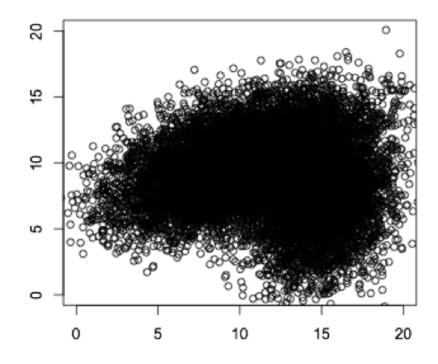


## Contour plot (3D)

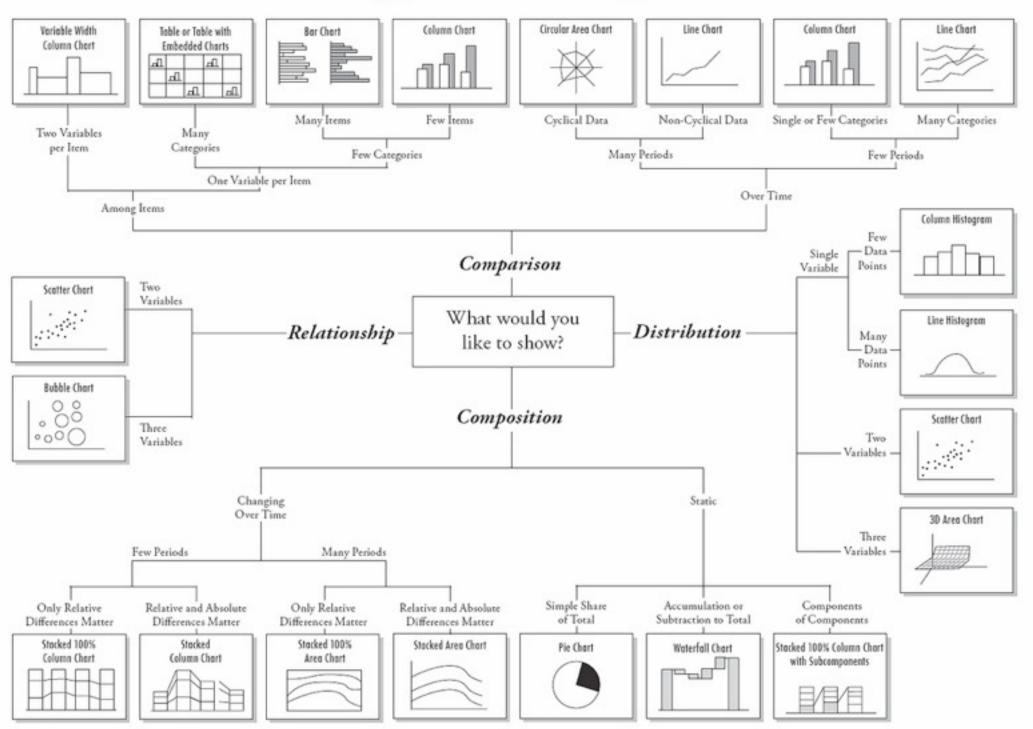
 Represents a 3D surface by plotting constant z slices (contours) in a 2D format



 Can overcome some limitations of 2D scatterplot (e.g., when there is too much data to discern relationship)



### Chart Suggestions—A Thought-Starter



Constructing Features from Data

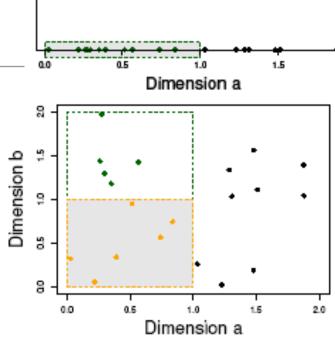
### Whitening (Normalization)

- For numerical features (not categorical)
  - It is common to whiten each feature by subtracting its mean and dividing by its variance

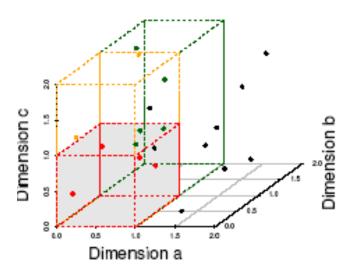
• For regularization, this helps all the features be penalized in the same units, that is, we are assuming they have the same variance  $\sigma^2$ 

### The Curse of Dimensionality

- Data in only one dimension is relatively packed
- Adding a dimension "stretches" the points across that dimension, making them further apart
- Adding more dimensions will make the points further apart—high dimensional data is extremely sparse
- Distance measure becomes meaningless



(b) 6 Objects in One Unit Bin

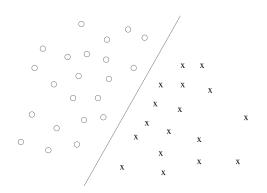


(c) 4 Objects in One Unit Bin

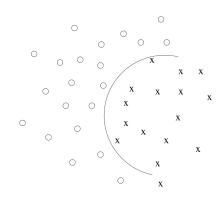
#### Kernels

- A kernel K is a form of similarity function
  - K(u,v) > 0 is the similarity between vectors  $u, v \in X$

- Mercer's theorem: For every continuous symmetric positive semi-definite kernel K there is a feature vector function  $\phi$  such that
  - $K(u,v) = \phi(u) \phi(v)$



Linear separator in the feature  $\phi$ -space



Non-linear separator in the original x-space

Fig ack Tommi Jaakkola

#### Some Common Kernels

Polynomials of degree up to d

$$K(u,v) = (u^T v + c)^d$$

 Gaussian/Radial kernels (polynomials of all orders –projected space has infinite dimension)

$$K(u,v) = \exp\left(-\frac{\|u-v\|^2}{2\sigma^2}\right)$$

Sigmoid

$$K(u,v) = \tanh\left(au^T v + c\right)$$

## Other Forms of Dimensionality Reduction

- Dataset X consisting of n points in a d-dimensional space
- Data point  $x_i \in \mathbb{R}^d$  (d-dimensional real vector):

$$x_i = [x_{i1}, x_{i2}, ..., x_{id}]$$

- Dimensionality reduction methods:
  - Feature selection: choose a subset of the features
  - Feature extraction: create new features by combining new ones

### Dimensionality reduction

- Dimensionality reduction methods:
  - Feature selection: choose a subset of the features
  - Feature extraction: create new features by combining new ones
- Both methods map vector  $\mathbf{x_i} \in \mathbf{R^d}$ , to vector  $\mathbf{y_i} \in \mathbf{R^k}$ , (k<<d)
- $F: \mathbb{R}^d \rightarrow \mathbb{R}^k$

### Random Projections

- It is also possible to learn models & classifiers over random projections of the data
- Johnson-Lindenstrauss Lemma
  - A given a set  $S \in \mathbb{R}^n$ , if we perform an orthogonal projection of those points onto a random d-dimensional subspace, then  $d = O(\gamma^{-2} \log |S|)$  is sufficient so that with high probability all pairwise distances are preserved up to  $1 \pm \gamma$

## Finding random projections

- Vectors  $\mathbf{x_i} \in \mathbf{R^d}$ , are projected onto a **k**-dimensional space (**k<<d**)
- Random projections can be represented by linear transformation matrix R

• 
$$y_i = R x_i$$

What is the matrix R?

## Finding matrix R

- Elements R<sub>i,j</sub> can be Gaussian distributed
- Achlioptas\* has shown that the Gaussian distribution can be replaced by

$$R(i, j) = \begin{cases} +1 \text{ with prob } \frac{1}{6} \\ 0 \text{ with prob } \frac{2}{3} \\ -1 \text{ with prob } \frac{1}{6} \end{cases}$$

 All zero mean, unit variance distributions for R<sub>i,j</sub> would give a mapping that satisfies the Johnson-Lindenstrauss lemma