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A Seminar Report on: "Transformers" Prepared by : Krunal Rajeshbhai Rank Roll. No. : U18CO081 Class : B.Tech –IV (Computer Engineering) 7 th Semester Year : 2021-22 Guided by : Shivangi Modi Department of Computer Engineering Sardar Vallabhbhai National Institute of Technology, Surat -395007 (Gujarat), India

Sardar Vallabhbhai National Institute of Technology, Surat -395007 (Gujarat), India CERTIFICATE This is to certify that the seminar report entitled Transformers is prepared and presented by Krunal Rajeshbhai Rank bearing Roll No.: U18CO081, 4 th Year of B. Tech (Computer Engineering) and his/her work is satisfactory. GUIDE JURY HOD (Shivangi Modi) COED i

Abstract The most prominent sequence to sequence machine learning models involve usage of com- plex convolutional networks as well as stacking them on top of recurrent neural networks that allow the input data to be processed considering the time frame in which the input data has been recorded. It was only recently that this idea was challenged by yet another machine learning concept presented by the researchers from Google Brain and University of Toronto. They presented a proposal of processing the sequential data into two phases, namely, encoding and decoding, which gave rise to Transformers. This seminar report highlights the limitations of the existing techniques which gave birth to transformers as well as some of the salient features and advantages of using transformers instead of the existing technology. The report also presents one of the several use cases o ered by trans- formers and how transformers are modi ed to achieve use case speci c goals and results. Keywords: Sequence to Sequence Machine Learning - Recurrent Neural Networks - Transformers - Speech to Text Recognition ii

Contents 1 Introduction 1 1.1 Application	ons	L 1.2 Motivation		
2 1.3 Objectives		bution		
3 1.5 Organization of Project		4 2.1 Recurrent Neural Network		
4 2.2 Gated Recurr	ent Networks	5 2.3 Long short Term Memory Network		
6 2.4 Transforn	ners: Attention is all you need	6 2.4.1 Model Architecture		
7 2.4.2 Attention	n	erature Review 9 3.1 ASR using		
Transformers	9 3.1.1 Preprocessing Audio Data			
Output Characters	10 3.1.3 Speech Embedding Layer	11 3.1.4 Encoder		
Layer	11 3.1.5 Token Embeddings			
11 3.1.7 Calc	ulating Loss	11 3.1.8 Conclusion		
11 3.2 BERT		uction		
12 3.2.2 Pre-training BERT	12 3.2.3 Fine-tuning BER	Γ13 3.2.4		
Conclusion	13 3.3 Extractive Summarization w	vith BERT		
Input and Output	14 3.3.2 Summarization Encoder	14 3.3.3 Fine		
tuning BERT for Summarization	15 3.3.4 Conclusion			
4 Conclusion 16 4.1 Conclusion		ture Prospects		
List of Figures 2.1 RNN Structure[1]				

Acronyms ASR Automatic Speech Recognition. 3, 9, 16 BERT Bidirectional Encoder Representations from Transformers. iii, v, 2, 3, 9, 12{14, 16 DNA Deoxyribose Nucleic Acid. 2 EOS End of Sentence. 10 GPU Graphics Processing Unit. 1 GRU Gated Recurrent Units. 1, 3, 5, 16, 19 LSTM Long Short Term Memory. 1, 3, 6, 16, 19 MHA Multi Head Attention. 1, 11 MLM Masked Language Model. 12, 13 NLP Natural Language Processing. 12, 13, 16 NSP Next Sentence Prediction. 12, 13 RNA Ribo Nucleic Acid. 2 RNN Recurrent Neural Network. 1, 3, 4, 16, 19 SOS Start of Sentence. 10 vi

Chapter 1 Introduction Recurrent Neural Network, Long Short Term Memory and Gated Recurrent Units were rmly established as the state of the art approaches in sequence to sequence machine learning and transduction problem domain such as automatic language translation and language modeling. There were many e orts made to push the boundaries of the available architectures[7][8][9]. The major drawback of RNN is the sequential nature of processing input data of a single RNN unit. This preludes the RNN's parallelization within the training examples. Recent work regarding the



factorisation techniques[10] and conditional computation[11] have achieved somewhat improvements as well an improvement in model performance but the drawback of sequential processing still remains the same. The paper on Transformers[3] presents a proposal of Self Attention and Multi Head Attention that allows modelling of dependencies without keeping in mind their distance in the input or output sequences. Transformer came out to be

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a model architecture that abandoned recurrence and completely relied on attention mechanisms to derive global dependencies between input and output. This allowed parallelization and allowed to reach new state of the art

results in various sequence to sequence learning tasks such as machine translation. 1.1

Applications With the emergence of Transformers, several use cases have achieved signi cant results which were exceedingly better than the previous existing benchmarks. Transformers allow parallel processing of the input data both in the encoder as well as the decoder section that makes the training process harness the capabilities of the current generation Graphics Processing Unit. Some of the areas where transformers are currently used are as follows: • Machine Translation: - With an availability of a large amount of data in more than one languages, it is now possible to train computers to translate a sequence of phrases and sentences from one language to another with the help of transformers. • Summarization: - Extractive Summarization, at the root, is an optimal subset problem, wherein, a subset of sentences from the given document need to be chosen that contains the maximum information. 1

• Speech to Text Recognition: - Speech to Text Recognition is one of the most impor- tant use cases when it comes to subtitle generation as well as recognizing valuable keywords from raw speech data. This has led to a rise in the number of Speech controlled Personal Assistants. Transformers play a crucial role in this domain. • Named Entity Recognition :- This problem pertains to recognizing proper nouns and names present in a given sentence or a document that helps in optimizing speci c search results in a search engine. • Biological Sequence Analysis: - It is the process of subjecting a DNA, RNA or pep-tide sequence to many analytical techniques to understand its functions, features, structures or evolution in general. This may only be some of the few most important use cases out of several others. Basically, transformer is a tool worth trying out for any observed sequential input data to extract the features and trends of the sequential data and put them into use. 1.2 Motivation The motivation behind choosing Transformers as a research topic lies behind the fact that technology has kept changing for the better and mankind has reached to a point where it is nally able to achieve results signi cantly closer to the ones obtained by human brain. Transformers have provided researchers and developers a new domain of Sequence to Sequence Machine Learning that can be explored even further than the current ndings. It required a lot of patience and persistence to reach the current position in this particular eld. The way transformers handle sequential data is something worth studying in a detailed manner. This has been the source of motivation. 1.3 Objectives The primary objective of this Seminar Report is to highlight the study and research based on the following topics: • Limitations of existing Sequence to Sequence Machine Learning Techniques • Self Attention • Transformers and parallel processing The secondary objective of this Seminar Report is to discuss a use case of Transformer as well as one of the improved transformers - Bidirectional Encoder Representations from Transformers. 2

1.4 Contribution To achieve required objectives, a thorough study of existing literature explaining the current Sequence to Sequence Machine Learning techniques such as RNN, LSTM, GRU as well as study of the literature explaining Transformers, Automatic Speech Recognition and BERT has been conducted. The report contains information based on all the referred literature. 1.5 Organization of Project Below are the descriptions of the contents presented in each of the chapters in this Project report. • Chapter 1: Presents a brief introduction on the Report, the applications of Trans- formers, motivation and objectives of the Report. • Chapter 2: Presents Background regarding the technology namely RNN, LSTM and Transformers. • Chapter 3: Presents one of the use cases of Transformers in the eld of Automatic Speech Recognition and one of the improved transformers - BERT. • Chapter 4: Concluding Remarks based on the study conducted 3

Chapter 2 Background This chapter presents an overview of the technologies dealing with sequential data as a part of sequence to sequence machine learning. Sequential data is quite di erent from the other kinds of data, such as those obtained from images or those that have distinct features. Sequential data, also known as time series data, consists of values for the same features at di erent time intervals or timestamps. It is usually of variable length. The problem of predicting the upcoming values in sequential data can not be solved seamlessly using conventional methods. Recurrent Neural Network have been proposed to solve this problem. 2.1 Recurrent Neural Network [12] Sequence-to-Sequence data cannot be handled by just standard Neural Networks due to two main reasons: a. Input and output length can be di erent in di erent training examples. b. Features are not shared across di erent positions of text. Recurrent Neural Network



hidden state h t by h t = (0; if t = 0 (h t\*1; x t); otherwise where is a nonlinear function like logistic sigmoid. Optionally, it may have an output y = (y 1; y 2; ...; y T) of any variable length. The update of the hidden state of RNN is implemented as: h t = g(Wx t + Uh t\*1) However, RNNs may not capture long term dependencies because the gradients tend to either vanish or explode. The exploding gradient problem is generally solved by meth- ods like gradient clipping, in which the gradient vector is clipped once it exceeds a certain threshold. However, solving vanishing gradients is much more di cult. 2.2 Gated Recurrent Networks [13] To solve the vanishing gradient problem, a variant of RNN having a more sophisticated activation function was introduced called Gated Recurrent Units (GRU). Each unit can capture dependencies of various time scales. It uses gates to modulate the ow of infor- mation inside the unit. Figure 2.2: GRU Structure[2] The activation function h t of GRU at time t is given by:

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 $h t = (1 * z t) h t*1 + z t \sim h t$  where z t decides how much

to update the activation function and  $\sim$  h t is the candidate activation function. The update gate is calculated using the formula below:  $z t = (W z x t + U z h t^*1) 5$ 

and the candidate activation is calculated similarly using:  $\sim h t = tanh(Wx t + U(r t h t*1))$  where indicates element-wise multiplication and r t is the reset gate. Similarly we can calculate the reset gate using the formula: r t = (W r x t + U r h t\*1) 2.3 Long Short Term Memory [13] To handle the vanishing gradient problem, another variant of RNN was introduced called LSTM. Each LSTM unit maintains a memory c t at time t. The output or the activation function of the LSTM h t is calculated using: h t = o t tanh(c t) where o t is the output gate which is calculated using o t = (W o x t + U o h t\*1 + V o c t) where is logistic sigmoid function. V o is a diagonal matrix. The memory cell c t is updated by partially forgetting existing memory and partially adding a new memory:  $c t = f i c t*1 + i t \sim c t$  where  $\sim c t$  is new memory content, f i is forget gate, i t is input gate. The forget gate manages the extent to which existing memory should be forgotten and the input gate manages the degree to which new memory content is added to memory cell. These gates are calculated using:

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ft = (W fx t + U fh t\*1 + V fc t\*1) it = (W ix t + U ih t\*1 +

Vict\*1) Simple RNNs just overwrite the content every time whereas LSTM can decide whether to keep memory or not. In the case where LSTM detects an important feature from input, it captures the information and use them later when needed. 2.4 Transformers: Attention is all you need [3] RNNs and LSTMs have certain limitations: • They are slow • They are sequential in nature Hence they don't utilize modern day parallel processing power of GPUs. Transformer is a network based solely on attention mechanisms to draw global dependencies between input and output. They allow parallelization of input sequence and take less time to train and hence they have made a signi cant impact on the development of sequence-to-sequence architectures. 6

Figure 2.3: Transformer Network[3] 2.4.1 Model Architecture The input to the transformer is a vector containing input embeddings. Then we perform positional encoding to the input embeddings which takes the positions into account and generates an output vector containing positional information. Transformer contains the following blocks: •

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Encoder: Encoder consists of a stack of N identical layers([3] suggests N = 6. Each layer has 2 sub-layers: 1. Multi head attention

layer 2. Feed forward neural network Each sub-layer is passed through layer normalization •



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Decoder: Decoder is also composed of a stack of N identical layers. In addition to the two sub-layers similar to encoder block, decoder inserts a new sublayer which performs multi-head attention over the output of the encoder stack.

The self- attention layer in the decoder block is

modi ed such that the subsequent positions after a position are masked. This ensures that the predictions for every position depend only on the positions before it. 7

2.4.2 Attention The Attention function for the transformer takes input in the form

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of queries and keys having dimension d k and values of dimension d v.

The queries, keys and values are packed into matrices Q, K and V and output attention function is calculated as follows:

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Attention(Q;K;V) = softmax(QKT = p d k)V

Instead of using a single attention function, we can linearly project queries, keys and values h times and

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then perform attention function in parallel yielding d v dimensional output values which are concatenated and projected again

as shown here:

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MultiHead(Q;K;V) = Concat(head 1;head 2;:::head h)W O where, head i = Attention(QW Q i;KW K i;V W V

i) Transformers can replace

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recurrent layers most commonly used in encoder-decoder architectures with multi-headed self attention. 8

Chapter 3 Literature Review This chapter presents one of the use cases of Transformers that is present in the industry currently as well as one of the improved versions of Transformers - Bidirectional Encoder Representations from Transformers. Automatic Speech Recognition requires us to process raw audio data which is in the form of waves and detect phrases and sentences out of this provided audio data. Later, the idea of Bidirectional Encoder Representations from Transformers is pre- sented as well as how BERT can be used for another one of the use cases, Text Summarization. 3.1 ASR using Transformers[4] Encoder - Decoder based Sequence to Sequence models have proved to be state of the art models in Automatic Speech Recognition for a long time. One of such techniques is described in this subsection. The model architecture proposed in the referred paper is described by the following diagram: 9

Figure 3.1: An Encoder - Decoder Transformer used to map Acoustic features from audio data to character level transcriptions[4] 3.1.1 Preprocessing Audio Data The audio data is preprocessed rst by converting raw waves into spectrograms that show frequency modi cations over time. This can be done by using Short Time Fourier Transform[14] to change audio data domain to time-frequency. Short Time Fourier Transform is actually obtained as a Complex number. However, we only require the magnitude of the value. The obtained data is then normalised using mean and standard



deviation. It is then padded to obtain an audio worth of 10 second duration. 3.1.2 Tokenizing Output Characters Output is processed character by character. 34 output characters are used as classes that include alphabetic characters, punctuation marks, unknown character markers and a Start of Sentence (SOS) and End of Sentence (EOS) marker. The Output characters are then vectorized using the same set of characters. 10

3.1.3 Speech Embedding Layer The speech embedding layer [15] is used to reduce dimensionality of the input data by using 1 Dimensional convolutional layers. This is identical to Down Sampling of given audio data. An embedding layer is used to create embeddings out of input vectors. 3.1.4 Encoder Layer The encoder layer rst normalises the created speech embeddings and then uses a Multi Head Attention (MHA) Layer. The Q,K,V vectors of the MHA layer are the normalised speech embeddings. The output of the MHA layer is then added to the residual input layer and normalised [16] similar to the one explained in the Residual Network layer. It is then passed through a feed forward network that is composed of a linear neural network and again added with the residual input and normalised. The normalised layers are also made available with dropout layers to prevent over t-ting of speech embeddings. 3.1.5 Token Embeddings Token Embeddings [17] are rst created using Output character vectors. These token embeddings are an addition of token vector embeddings and positional embeddings. These embeddings serve as an input for the Decoder. 3.1.6 Decoder Decoder masks the input Token embeddings and then passes it to the Decoder MHA Layer. Its output is then fed to the Source Attention MHA layer. The K,V vectors of Source Attention MHA Layer are the outputs from the encoder. The Q vector is the output of Decoder MHA Layer. The MHA Layer output is then added with residual input and normalised. It is then fed to a Feed Forward layer and again added with residual input and normalised. 3.1.7 Calculating Loss The model is trained using the preprocessed data, using Adam's optimizer [18] and a Learning Rate Schedule. The Decoder output is then passed to the character softmax and its loss is calculated using Categorical Cross Entropy. 3.1.8 Conclusion Mapping Acoustics directly to characters is actually a challenging task. The above pro- cedure successfully demonstrated how this challenging problem can be approached. 11

3.2 Bidirectional Encoder Representations from Trans- formers 3.2.1 Introduction Bidirectional Encoder Representations from Transformers is a language representation model that is trained on

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unlabeled text by jointly conditioning on both left and right context in all layers.

According to the authors[5], BERT is conceptually simple and em- pirically powerful, obtaining a state of the art result on Natural Language Processing tasks. There are two strategies employed to apply language representations to downstream tasks: • Feature Based Approach: - It uses task specild architectures that include pre-trained representations as additional features. Such an approach is explained as a part of ELMo. • Fine Tuning Approach: - It uses minimal task specild parameters and focuses on downstream tasks by simply tuning all pre-trained parameters. One such example for this approach is the Generative Pretrained Transformers by OpenAl. As far as BERT is concerned, there are two steps in the framework: • Pre-training • Fine-tuning Figure 3.2: BERT[5] 3.2.2 Pre-training BERT Pre-training BERT has two tasks: 1. Masked Language Model 2. Next Sentence Prediction 12

Masked Language Model A standard conditional language model can only be trained on left-to-right or right-to-left context or a shallow concatenation of both of these techniques. In order to train the deep bidirectional representations, some random tokens in the input are masked and those tokens are predicted. 15% of the tokens are masked in each sequence. Now this may lead to a problem in ne-tuning process where in the [MASK] token is not observed in ne-tuning process. Hence, out of the 15% masked tokens, 80% of these tokens are replaced with [MASK] token, 10% of these tokens are replaced with any random wordpiece and the rest are left unchanged. The other unmasked tokens are then used to predict the masked tokens using a cross entropy loss. Next Sentence Prediction Some of the NLP based

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tasks such as Question Answering and Natural Language Inference are based on understanding the relationship between sentences.

something which is not captured in language representations. In order to train a model that understands sentence relationships, a prediction task wherein the model is expected to predict whether the given sentences are actually consecutive sentences or not. Speci cally, two sentences are chosen at random by the generator with a 50% chance that



the sentence B is the next sentence for chosen sentence A. These two sentences are separated by [SEP] token. This task is somewhat similar to representation learning objectives[19]. 3.2.3 Fine-tuning BERT Fine-tuning BERT is simpler as compared to pre-training process. For every task, the input and output sequences are plugged into BERT and parameters are ne-tuned end- to-end. In pre-training stage, sentences A and B can be analogous to: • Sentence pairs in paraphrasing • Hypothesis Premise Pairs • Question Passage Pairs Compared to pre-training, ne tuning is relatively inexpensive and can be done pretty much faster. 3.2.4 Conclusion Recent improvements with the help of transfer learning with language models have demonstrated that rich, unsupervised pre-training is an important part of many lan- guage understanding systems. The major contribution of BERT is further general- izing these ndings to deep bidirectional architec- tures, which allows the same pre-trained model to suc- cessfully tackle numerous NLP tasks. 3.3 Extractive Summarization with BERT Summarization strategies are typically categorized as extractive, abstractive or mixed. 13

• Extractive strategies select the top K sentences that best represent the maximum information of the article.[6] • Abstractive summaries seek to reproduce the key points of the article in new words. [20] • Mixed strategies either produce an abstractive summary after identifying an ex-tractive intermediate state or they can choose which approach to use based on the particulars of the text. Extractive strategies are set up as binary classi cation problems where the goal is to identify the article sentences belonging to the summary. Extractive summarization is a challenging task that became practical only quite recently. The progress in this domain was due to the super embeddings o ered by BERT. BERT can parse meaning from all the nuances of language and steps such as stop word removal, stemming and lower-case transformations are purposely ignored. 3.3.1 Input and Output Figure 3.3: Original BERT architecture and modi ed BERT architecture for summariza- tion (BERTSUM)[6] The way in which BERTSUM is represented is guite di erent from the original BERT. The sentences are separated using [CLS] token and features from the previous sentence are collected and processed by BERTSUM to create features for the current sentence. Interval Embedding is also used to demarcate sentences at odd and even positions so that document representations are learned hierarchically where lower Transformer lay- ers represent adjacent sentences, while higher layers, in combination with self-attention, represent multi-sentence discourse. BERTSUM outputs a list of scores that show representiveness of sentences towards document. Hence, the higher the score is, the more prominent the sentence is. 3.3.2 Summarization Encoder Summarisation encoder represent individual sentences, by adding external [CLS] tokens at the beginning of each sentence. It collects features for the sentence preceding it. 14

Interval segment is used to distinguish multiple sentences within the document. For a particular sentence sent i we assign segment embedding E A or E B depending on whether i is odd or even. For example, for document [sent 1; sent 2; sent 3; sent 4; sent 5], we would assign embeddings [E A; E B; E A; E B; E A]. In this approach, document representations are learnt in a hierarchical manner, with lower Transformer layers representing neighbour- ing phrases and higher levels representing multi-sentence discourse when combined with self-attention. The original BERT model has a maximum length of 512 position embed- dings; we circumvent this constraint by adding additional position embeddings that are randomly started and ne tuned with other encoder settings. 3.3.3 Fine tuning BERT for Summarization Although BERT has been used to ne-tune a variety of NLP tasks, it is not as simple to apply to summarization. Because BERT is a masked-language model, the output masked vectors are limited to tokens rather than phrases, The majority of extractive summarization methods work with sentence-level representations. In BERT, segmenta- tion embeddings represent various sentences; however, they only apply to sentence pair inputs, but in summarization, multi-sentential inputs must be encoded and manipulated. So we modify our BERT architecture as shown above in the gure in order to summarise (which we call BERTSUM). 3.3.4 Conclusion BERTSUM Transformer was able to achieve a score of 43.25 ROUGE-1, 20.24 ROUGE-2 and 39.63 ROUGE-L on CNN/DailyMail dataset, which was found to be better than LEAD(an extractive baseline which uses the rst-3 sentences of the document as a sum- mary). 15

Chapter 4 Conclusion 4.1 Conclusion I was able to thoroughly study the concepts of Recurrent Neural Network and its limita- tions. The limitations of RNN are lled up by slightly modi ed versions of RNN - Gated Recurrent Units and Long Short Term Memory. These networks require sequential pro- cessing and thereby weren't able to utilise the modern day GPU Parallel Processing, which was overcome with the advent of another new architecture, Transformers. As I was able to study the above concepts, I also learnt a bit more on one of the use cases of Transformers, Automatic Speech Recognition and one of the improved versions of Transformers, Bidirectional Encoder Representations from Transformers. 4.2 Future Prospects With the advent of modi ed transformers like BERT, certain NLP tasks have taken a di erent turn. In case of summarization, the challenge has shifted from extractive summarization to abstractive summarization that completely changes the problem from choosing the given sentences to creating sentences and phrasings automatically provided the input text document. Even more advanced models are under research that have claimed to outperform BERT. 16



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# Hit and source - focused comparison, Side by Side

**Submitted text** As student entered the text in the submitted document.

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1/23 SUBMITTED TEXT 30 WORDS 42% MATCHING TEXT 30 WORDS

a model architecture that abandoned recurrence and completely relied on attention mechanisms to derive global dependencies between input and output. This allowed parallelization and allowed to reach new state of the art

a model architecture eschewing recurrence and instead relying entirely on an attention mechanism to draw global dependencies between input and output. The Transformer allows for significantly more parallelization and can reach a state of the art

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8/23 SUBMITTED TEXT 23 WORDS 65% MATCHING TEXT 23 WORDS

 $h t = (1 * z t) h t*1 + z t \sim h t$  where z t decides how much

h t = (1 " z t)\$  $^{\sim}$  h t + z t \$ h t"1 Hidden state 10 The update gate value z t indicates how much

W https://www.cs.utah.edu/docs/techreports/2020/pdf/UUCS-20-011.pdf

10/23 SUBMITTED TEXT 45 WORDS 59% MATCHING TEXT 45 WORDS

ft = (W fx t + U fh t\*1 + V fc t\*1) i t = (W i x t + U i h t\*1 $__$   $ft = \sigma \, g \, (\, W \, fx \, t + U \, fh \, t - 1 + b \, f) \, h \, t = ft \, \circ \, h \, t - 1 + (\, 1 - ft\,) \, \circ \, \sigma \, h \, (\, W \, h \, x \, t + U \, h \, (\, ft \, \circ \,$ 

https://en.wikipedia.org/wiki/Gated\_recurrent\_unit

2/23 SUBMITTED TEXT 22 WORDS 57% MATCHING TEXT 22 WORDS

Encoder: Encoder consists of a stack of N identical layers([3] suggests N=6. Each layer has 2 sub-layers: 1. Multi head attention

Encoder: The encoder is composed of a stack of N=6 identical layers. Each layer has two sub-layers. The first is a multi-head self-attention

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3/23 SUBMITTED TEXT 37 WORDS 73% MATCHING TEXT 37 WORDS

Decoder: Decoder is also composed of a stack of N identical layers. In addition to the two sub-layers similar to encoder block, decoder inserts a new sublayer which performs multi-head attention over the output of the encoder stack.

Decoder: The decoder is also composed of a stack of N=6 identical layers. In addition to the two sub-layers in each encoder layer, the decoder inserts a third sub-which performs multi-head attention over the output of the encoder stack.

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4/23 SUBMITTED TEXT 17 WORDS 89% MATCHING TEXT 17 WORDS

of queries and keys having dimension d k and values of dimension d v .

of queries and keys of dimension d k , and values of dimension d  $\nu$  .

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5/23 SUBMITTED TEXT 14 WORDS 100% MATCHING TEXT 14 WORDS

Attention(Q;K;V) = softmax(QKT = p d k)V

Attention(Q; K; V) = softmax(QK T p d k)V (1)

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**SUBMITTED TEXT** 18 WORDS **80% MATCHING TEXT** 18 WORDS

then perform attention function in parallel yielding d  $\nu$  dimensional output values which are concatenated and projected again

then perform the attention function in parallel, yielding d  ${\bf v}$  -dimensional output values. These are concatenated and once again

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7/23 SUBMITTED TEXT 21 WORDS 92% MATCHING TEXT 21 WORDS

MultiHead(Q;K;V) = Concat(head 1;head 2;:::head h)W O where, head i = Attention(QW Q i;KW K i;V W V

MultiHead(Q; K; V) = Concat( head 1; :::; head h) W O where head i = Attention(QW Q i; KW K i; V W V

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9/23 SUBMITTED TEXT 12 WORDS 100% MATCHING TEXT 12 WORDS

recurrent layers most commonly used in encoderdecoder architectures with multi-headed self attention. 8 recurrent layers most commonly used in encoderdecoder architectures with multi-headed self-attention.

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11/23 SUBMITTED TEXT 13 WORDS 100% MATCHING TEXT 13 WORDS

unlabeled text by jointly conditioning on both left and right context in all layers.

unlabeled text by jointly conditioning on both left and right context in all layers.

W https://journal-hnups.com.ua/index.php/soi/article/download/179/125/

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tasks such as Question Answering and Natural Language Inference are based on understanding the relationship between sentences, tasks, such as intelligent question answering (QA) and natural language inference (NLI), are based on understanding the connection between two sentences,

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16/23 SUBMITTED TEXT 24 WORDS 100% MATCHING TEXT 24 WORDS

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Google's neural machine translation system: Bridging the gap between human and machine translation.

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Kingma and Jimmy Ba. Adam: A method for stochastic			Kingma and Jimmy Ba. Adam: A met	thod for stochastic

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Kingma and Jimmy Ba. Adam: A method for stochastic optimization.

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