### Rational Fractal Spline

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## Introduction to Fractal Interpolation

- Fractal interpolation is a modern technique in approximation theory used to fit and analyze scientific data.
- ► The graph of these FIF can be used to approximate image component such as the profiles of mountains ranges, the tops of clouds and horizons over forests.
- ► This method utilizes an iterated function system (IFS) with rational functions of the form  $\frac{p_i(x)}{q_i(x)}$ .
- ▶ Here,  $p_i(x)$  and  $q_i(x)$  are cubic polynomials that include two shape parameters.

## Advantages of Rational Cubic Fractal IFS

- ► The rational cubic IFS provides additional flexibility over classical rational cubic interpolants.
- ► This flexibility arises from the inclusion of scaling factors and shape parameters.
- Classical rational cubic functions are a special case of the proposed fractal interpolants.

## Shape Preservation

- ► The fractal interpolation scheme is computationally efficient and adaptable (local, moderately local, or global) based on scaling factors and shape parameters.
- ► Sufficient conditions on scaling factors and shape parameters ensure that the interpolation function preserves shape:
  - Monotonicity
  - Positivity
  - Convexity

#### Given Data and IFS

- Consider a data set  $\{(x_i, f_i), i = 1, 2, ..., n\}$ , where  $x_1 < x_2 < \cdots < x_n$ .
- Define the IFS  $I^* = \{\mathbb{R}^2; w_i(x, f) = (L_i(x), F_i(x, f)), i = 1, 2, ..., n 1\}.$
- Where:

$$L_i(x) = a_i x + b_i$$

 $ightharpoonup L_i(x)$  satisfies the condition

$$L_i(x_1) = x_i, L_i(x_n) = x_i + 1.$$

 $ightharpoonup F_i(x, f) = \alpha_i f + r_i(x)$ , where:

$$r_i(x) = \frac{p_i(x)}{q_i(x)}$$



▶  $p_i(x)$  and  $q_i(x)$  are cubic polynomials, and  $q_i(x) \neq 0 \quad \forall x \in [x_1, x_n].$ 

$$p_i(x) \equiv P_i(\theta) = U_i(1-\theta)^3 + M_i\theta(1-\theta)^2 + N_i\theta^2(1-\theta) + Z_i\theta^3,$$
  
$$q_i(x) \equiv Q_i(\theta) = (1-\theta)^3 + v_i\theta(1-\theta)^2 + w_i\theta^2(1-\theta) + \theta^3$$

▶ Where  $U_i$ ,  $M_i$ ,  $N_i$ , and  $Z_i$ , for i = 1, 2, ..., n - 1, are real parameters as follows:

$$U_{i} = f_{i} - \alpha_{i} f_{1},$$

$$Z_{i} = f_{i+1} - \alpha_{i} f_{n},$$

$$M_{i} = v_{i} f_{i} + h_{i} d_{i} - \alpha_{i} \left[ (x_{n} - x_{1}) d_{1} + f_{1} v_{i} \right],$$

$$N_{i} = w_{i} f_{i+1} - h_{i} d_{i+1} + \alpha_{i} \left[ (x_{n} - x_{1}) d_{n} - f_{n} w_{i} \right].$$

 $|\alpha_i| < a_i$ , for i = 1, 2, ..., n - 1.

#### **Derivative Conditions**

- Let  $F'_i(x, f) = \frac{\alpha_i f + r'_i(x)}{a_i}$ , where  $r'_i(x)$  is the derivative of  $r_i(x)$  with respect to x.
- Boundary conditions:

$$F_i(x_1, f_1) = f_i, \quad F_i(x_n, f_n) = f_{i+1}$$
  
 $F'_i(x_1, f_1) = d_i, \quad F'_i(x_n, f_n) = d_{i+1}$ 

- ▶ for i = 1, 2, ..., n 1.
- $h_i = x_{i+1} x_i$ ; i = 1 to n
- $ightharpoonup d_i \ (i=1,2,\ldots,n)$  be the derivative values at the knots.
- ▶ The value of ends points is given by:

$$d_1 = egin{cases} 0, & ext{if } \Delta_1 = 0, \ \Delta_1 + rac{(\Delta_1 - \Delta_2)h_1}{h_1 + h_2}, & ext{otherwise}. \end{cases}$$

 $\triangleright$  For  $d_n$ :

$$d_n = egin{cases} 0, & \text{if } \Delta_{n-1} = 0, \ \Delta_{n-1} + rac{(\Delta_{n-1} - \Delta_{n-2})h_{n-1}}{h_{n-1} + h_{n-2}}, & \text{otherwise.} \end{cases}$$



▶ The value of  $d_i$  for i = 2, 3, ..., n - 1 is given by:

$$d_i = egin{cases} 0, & ext{if } \Delta_{i-1} = 0 ext{ or } \Delta_i = 0, \ rac{\Delta_i h_{i-1} + \Delta_{i-1} h_i}{h_i + h_{i-1}}, & ext{otherwise}. \end{cases}$$

▶ The variable  $\theta$  is defined as:

$$\theta = \frac{x - x_1}{x_n - x_1}, \quad x \in [x_1, x_n].$$

Then the attractor of IFS is the graph of rational cubic FIF.

### Shape Preservation in Fractal Interpolation

#### **Problem:**

For an arbitrary selection of scaling factors and shape parameters, the rational cubic fractal interpolation function (FIF) may fail to maintain desired shape properties:

- ▶ Monotonicity: The curve may oscillate, even if the data is monotonic.
- Positivity: The interpolation could dip below zero, even if the data is positive.
- ► Convexity (Concavity): The curvature may not reflect the original data's convex or concave shape.

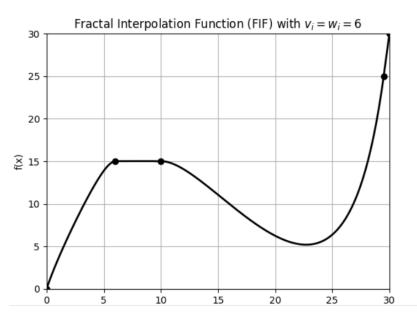
This is very similar to the ordinary spline schemes that do not provide the desired shape features of a data. Thus some mathematical treatment is required to achieve a monotonicity, positivity, and convexity (concavity) preserving rational cubic spline FIF for a given data

## Approach to solve the problem

#### There are two approach to address this:

- Trail and Error= Manually adjusting the scalling factor and shape parameter but it can work sometime usually not very efficient and precise.
- Automated Method= Develop automated process to compute the appropriate scalling factor and shape parameter that preserve desired shape properties

# Figure



## Sufficient conditions for monotonicity

#### Theorem:

Let  $\{(x_i, f_i, d_i), i = 1, 2, ..., n\}$  be a given monotonic data set. The derivative values must satisfy the necessary conditions for monotonicity:

- ▶  $d_i = d_{i+1} = 0$ , for  $\Delta_i = 0$ ;
- ▶  $\operatorname{sgn}(d_i) = \operatorname{sgn}(d_{i+1}) = \operatorname{sgn}(\Delta_i)$  for  $\Delta_i \neq 0$ .

Now, define the scaling factors  $\alpha_i$  for  $i=1,2,\ldots,n-1$  as:

$$\alpha_i \in \begin{cases} [0, \mu_i] & \text{if } \mu_i < a_i \\ [0, a_i) & \text{if } \mu_i \ge a_i \end{cases}$$

where  $\mu_i = \min\left\{\frac{a_id_i}{d_1}, \frac{a_id_{i+1}}{d_n}, \frac{f_{i+1}-f_i}{f_n-f_1}\right\}$ .

Additionally, the shape parameters  $v_i$  and  $w_i$  for i = 1, 2, ..., n - 1 are selected as:

#### ► Option 1:

$$v_i = l_i \cdot d_i^* \cdot i^*, \quad w_i = k_i \cdot d_{i+1}^* \cdot i^*, \quad l_i, k_i \in \mathbb{R}^+ \text{ such that } \frac{1}{l_i} + \frac{1}{k_i} \leq 1$$

#### ▶ Option 2:

$$v_i = \eta_i \cdot d_i^* \cdot d_{i+1}^* \cdot i^*, \quad w_i = \nu_i \cdot d_i^* \cdot d_{i+1}^* \cdot i^*$$

where 
$$\eta_i, \nu_i \geq 1$$
,  $d_i^* = d_i - \alpha_i \cdot \frac{d_1}{a_i}$ ,  $d_{i+1}^* = d_{i+1} - \alpha_i \cdot \frac{d_n}{a_i}$ , and  $i^* = i - \alpha_i \cdot \frac{f_n - f_1}{h_i}$ .

**Conclusion:** Form this theorem we find a way to choose scaling factors  $\alpha_i$ , shape parameters  $v_i$  and  $w_i$ , such monotonicity-preserving  $C^1$ -rational cubic FIF, whose graph is the attractor of the rational cubic IFS.

Thank you for your attention!