# **Number Systems**

## Introduction

A writing system for expressing numbers. Each number system defines a set of symbols that each represent a specific value.

## Base (or radix)

Number of symbols defined by a number system.

## **Commonly used number systems**

- Base 10 0 9
- Base 2 0,1
- Base 8 0 7
- Base 16 0 9, A F

## **⚠** Caution

These are required for s1:

- · Converting integers and floats between number systems
- Addition, subtraction, multiplication, division in base 2

But I don't know how to include it in a easy-to-understand way.

## (i) Confusion about unit prefixes

In computing, the prefix  $\it kilo$  —just like other prefixes— has been used to refer either  $2^{10}$  or  $10^3$  depending on the context.

- $10^3$  Marketing of disk capacities (by disk manufacturers)
- $oldsymbol{2^{10}}$  Memory capacities, and file sizes, disk capacities by operating systems

To avoid this confusion, 2 unit prefixes are used while measuring amounts of data.

- ullet SI prefixes Defined by ISO. Based on powers of  $10^3$  . Examples: kilo, mega, giga.
- ullet Binary prefixes Defined by IEC. Based on powers of  $\, 2^{10}$  . Examples: kibi, mebi, gibi.

## **One's & Two's Complement**

## One's complement

The ones' complement of a binary number is the value obtained by flipping all the bits in the binary representation of the number.

- If one's complement of a is b, then one's complement of b is a.
- Binary representation of a+b will include all 1 s.

## One's complement system

In which negative numbers are represented by the inverse of the binary representations of their corresponding positive numbers. First bit denotes the sign of the number.

- ullet Positive numbers are the denoted as basic binary numbers with 0 as the MSB.
- Negative values are denoted by the one's complement of their absolute value.

For example, to find the one's complement system representation of -7, one's complement of 7 must be found.  $7 = 0111_2$ . One's complement of -7 is 1000.

## Two's complement

In which negative numbers are represented using the MSB (sign bit).

#### If MSB is:

• 1 : negative

• 0 : positive

Positive numbers are represented as basic binary numbers with an additional 0 as the sign bit.

For example:

Following equation can be used to convert a number in two's complement form to decimal.

$$b = -2^{n-1}b_{n-1} + \sum_{k=0}^{n-2} 2^k b_k$$

### **Steps**

- 1. Starting with the absolute binary representation of the number
- 2. Add a leading 0 bit being a sign bit
- 3. Find the one's complement: flip all bits (which effectively subtracts the value from -1)
- 4. Add 1, ignoring any overflows

## **Floating-point Representation**

IEEE 754 standard.

2 types:

- · single precision
- double precision

## **Single precision**

Uses 32 bits.

- sign bit 1 bit
- exponent 8 bit
- mantissa 23 bit

### Sign bit

**0** if positive or zero. **1** if negative.

### **Exponent**

Exponent field range - [0, 255]. In this range [1, 254] is defined for normal numbers. 0 and 255 are reserved for subnormal, infinite, signed zeros and NaN.

To support negative exponents, we subtract 127 (half of 254) from this range. [-126, 127]. This range is the representable range.

#### Mantissa

In scientific notation, the part that doesn't contain the base and the power.

In binary scientific notation, there will always be exactly one  ${f 1}$  bit before the dot. So we don't include that one.

### (i) Example

#### Take **31.3125**.

• In binary:  $1111.0101_2$ 

• In binary scientific notation:  $1.1110101_2 imes 2^3$ 

- Add 127 to exponent: 130

- Convert exponent to binary  $\,10000010\,$ 

- Write the final result:  $0\ 10000010\ 000000000000001110101$ 

#### Take 0.125.

• In binary:  $-0.001_2$ 

• In binary scientific notation:  $-1.0_2 imes 2^{-3}$ 

- Add 127 to exponent: 124

- Convert exponent to binary 01111100

## **Double precision**

Uses 64 bits.

- ullet sign bit 1 bit
- exponent 11 bit
- mantissa **53** bit

### Sign bit

 $\mathbf{0}$  if positive or zero.  $\mathbf{1}$  if negative.

## **Exponent**

Exponent field range - [0, 2047]. In this range [1, 2046] is defined for normal numbers. 0 and 2047 are reserved for subnormal, infinite, signed zeros and NaN.

To support negative exponents, we subtract 1023 (half of 2046) from this range. [-1022, 1023]. This range is the representable range.

#### Mantissa

In scientific notation, the part that doesn't contain the base and the power.

In binary scientific notation, there will always be exactly one  ${\bf 1}$  bit before the dot. So we don't include that one.

### (i) Example

#### Take **31.3125**.

• In binary:  $1111.0101_2$ 

• In binary scientific notation:  $1.1110101_2 imes 2^3$ 

• Add 1023 to exponent: 1026

• Convert exponent to binary: 1000000010

· Write the final result:

#### Take 0.125.

• In binary:  $-0.001_2$ 

• In binary scientific notation:  $-1.0_2 imes 2^-3$ 

• Add **1023** to exponent: **1020** 

• Convert exponent to binary: 1111111100

· Write the final result:

# **String Representation**

A way of representing non-numerical data.

## **Commonly used encodings**

#### **ASCII**

Abbreviation for American Standard Code for Information Interchange. Uses 7 bits for letter representation and a parity bit (MSB). Can represent latin alphabet, digits, punctuations, and control characters.

Major limitation in ASCII is it can't support multiple languages.

#### Unicode

Uses 32 bits. Supports multiple languages and emojis. Characters are presented by code points. A code point is a integer (in base 16).

# **Data Types**

Data types can be grouped into 3 categories.

### **Primitive**

Data types that are directly supported by a programming languages.

Examples are:

- Boolean
- Characters
- Integers
- Floating-point numbers
- Memory pointers

## **Composite**

Data types that are built as

- structured collections of primitive types
- using other composite types already defined

Examples are:

- Array
- Record or Tuple
- Union

#### **Tuple**

Represents a finite ordered list of elements. Can contain different data types. Immutable. Tuple with length n is called as "n-tuple".

Some tuples have special names:

• length 0 : empty-tuple or null-tuple

• length 1 : singleton

• length 2 : couple

• length 3 : triple

### **Abstract**

Data types that are well defined in terms of properties and operations but not implementation.

### Examples:

- List
- Set
- Stack Last in; first out
- Queue First in; first out
- Tree
- Hash Table
- Graph

### (i) Note

Implementations of stacks, queues, and binary search trees are required in s1.

#### List

Represents a countable number of values where the same value can occur more than once.

Ordered. Can include different data types. Mutable. Aka. iterable collection.

Defined methods:

- isEmpty()
- prepend(item)
- append(item)
- head()
- get(i)
- set(i)
- tail()

## (i) Note

Lists in python can be considered as dynamically sized arrays. Methods other than abovementioned ones are implemented in python.

#### Set

Represents a collection of distinct objects. Unordered. Iterable. Mutable (but elements must be immutable). No duplicate elements.

#### **Dictionary**

Collection of key-value pairs. Unordered.

#### Tree

Holds a set of nodes. Each node holds a value. Each node can have child nodes.

#### **Binary Tree**

Tree with the restriction of at most 2 child nodes per node.

#### **Complete Binary Tree**

A binary tree in which every level, except possibly the last, is completely filled, and all nodes are as far left as possible.

#### **Binary Heap**

A binary heap is complete binary tree where items are stored in a way such that the value in a parent node is greater/smaller than values in its 2 children nodes. Can be represented by a binary tree or an array. 2 types:

- Max heap: when the parent node value is greater than its children nodes
- Min heap: when the parent node value is smaller than its children nodes

Can be represented by either an array or a binary tree.

### **Array representation**

If a parent node is stored at index i, the left child is stored at index 2i + 1 and the right child is stored at index 2i + 2 (assuming the indexing starts at 0).

Space efficient representation.

## **Algorithms**

An algorithm is a finite set of instructions, used to solve a problem.

(i) Note

In s1, only searching and sorting algorithms are discussed.

## 

Even though an implementation is provided for each algorithm below, the code might have issues.

## **Searching algorithms**

### Iterative sequential search

```
def iterative_sequential_search(a_list, item):
    for i in range(len(a_list)):
        if a_list[i] == item:
            return i
```

## Recursive sequential search

```
def recursive_sequential_search(a_list, item, offset = 0):
    if len(a_list) == 0:
        return False

if a_list[0] == item:
        return True

return recursive_sequential_search(a_list[1:], item)
```

## **Binary search**

```
def binary_search(a_list, item):
   first = 0
    last = len(a_list) - 1
    found = False
    while first <= last and not found:
        mid = (first + last) // 2
        if a_list[mid] == item:
            found = True
        else:
            if item < a_list[mid]:</pre>
                last = mid - 1 # search in first half
            else:
                first = mid + 1 # search in second half
    if found:
        return mid
    else:
        return -1
```

## **Time complexities**

Algorithms	Best	Average	Worst
Sequential search	O(1)	O(n)	O(n)
Binary search	O(1)	O(log n)	O(log n)

## Sorting algorithms

A sorting algorithm reorganizes a collection of items into some order as defined by values intrinsic to the items.

#### **Bubble sort**

Makes multiple passes through a collection and compare adjacent items to reorder those that are out of order.

Here is bubble sort algorithm that sorts a list of numbers in-place:

#### **Selection sort**

Keeps track of the position of the highest/smallest value encountered through a pass over the list and after completing the pass perform the swap operation to correctly place the item.

Here is selection sort algorithm that sorts a list of numbers in-place:

```
def selection_sort(arr):
    for current_starting_index in range(len(arr)):
        smallest_index = current_starting_index
        for i in range(current_starting_index + 1, len(arr)):
            if arr[i] < arr[smallest_index]:
                  smallest_index = i
            arr[smallest_index], arr[current_starting_index] = arr[current_starting_index], arr[smallest]</pre>
```

#### **Insertion sort**

Maintains a sorted sublist in the lower positions in the list. Each item picked from the unsorted sublist is inserted into the sorted sublist.

```
def insertion_sort(a_list):
```

```
for index in range(1, len(a_list)):
    current_value = a_list[index]
    pos = index
    while pos > 0 and a_list[pos - 1] > current_value:
        a_list[pos] = a_list[pos - 1]
        pos = pos - 1

a_list[pos] = current_value
```

#### **Shell sort**

Breaks the original list into a number of smaller sublists, each of which is sorted using an insertion sort.

```
def gap_insertion_sort(a_list, start, gap):
    for i in range(start + gap, len(a_list), gap):
        current_value = a_list[i]
        pos = i

    while pos >= gap and a_list[pos-gap] > current_value:
        a_list[pos] = a_list[pos - gap]
        pos = pos - gap

        a_list[pos] = current_value

def shell_sort(a_list):
        sublist_count = len(a_list) // 2

while sublist_count > 0:
        for start_pos in range(sublist_count):
            gap_insertion_sort(a_list, start_pos, sublist_count)

        print("After increments of size", sublist_count, "The list is", a_list)

sublist_count = sublist_count // 2
```

#### Merge sort

Recursive algorithm that continually splits a list in half.

- If the list is empty or has one item, it is sorted
- If the list has more elements, the list is split in the middle and merge sort is recursively used on those parts
- Once sorted, the halves are combined to create a new, sorted list

```
def merge_sort(a_list):
    if len(a_list) < 2:
        return
    print("Splitting ", a_list)
    mid = len(a_list) // 2
    left_half = a_list[:mid]
    right_half = a_list[mid:]
    merge_sort(left_half)
    merge_sort(right_half)
    i = 0; j = 0; k = 0
    while i < len(left_half) and j < len(right_half):
        if left_half[i] < right_half[j]:</pre>
            a_list[k] = left_half[i]
            i = i + 1
        else:
            a_list[k] = right_half[j]
            j = j + 1;
        k = k + 1
    while i < len(left_half):</pre>
        a_list[k] = left_half[i]
        i = i + 1; k = k + 1
   while j < len(right_half):</pre>
        a_list[k] = right_half[j]
        j = j + 1; k = k + 1
    print("Merging ", a_list)
```

### **Quick sort**

Recursive algorithm that use the divide and conquer strategy to continually split a list around a selected value called the split point.

- Selects a pivot (a value in the list)
- List is partitioned into 2 parts
  - With the elements lesser than the pivot
  - With the elements greater than the pivot
- The partitions are recursively sorted

```
def quick_sort(a_list, first, last):
    if first < last:</pre>
        split_point = partition(a_list, first, last)
        quick_sort(a_list, first, split_point - 1)
        quick_sort(a_list, split_point + 1, last)
def partition(a_list, first, last):
    pivot_value = a_list[first]
    left_mark = first + 1
    right_mark = last
    done = False
    while not done:
        while left_mark <= right_mark and a_list[left_mark] <= pivot_value:</pre>
        left_mark = left_mark + 1
        while a_list[right_mark] >= pivot_value and right_mark >= left_mark:
            right_mark = right_mark - 1 36 / 46
            if right_mark < left_mark:</pre>
                done = True
            else:
                temp = a_list[left_mark]
                a_list[left_mark] = a_list[right_mark]
                a_list[right_mark] = temp
    temp = a_list[first]
    a_list[first] = a_list[right_mark]
    a_list[right_mark] = temp
    return right_mark
```

#### **Heap sort**

Uses a binary heap.

Similar to selection sort where a search is done to find the item with the minimum value and this item is placed at the beginning of the list. The same process is repeated for remaining items.

#### Steps:

- 1. A max-heap is built from the input data
- 2. Largest item is stored at the root of the heap. Replace it with the last item of the heap.
- 3. Size of the heap is reduced by 1
- 4. Heapify the root of the tree
- 5. Repeat steps 2-4 until the size of the heap is greater than 1.

The heapify procedure can be applied to a node only if its children nodes are heapified. So the heapification must be performed in the bottom-up order.

```
# To heapify subtree rooted at index i. Heap size is n.
def heapify(a_list, n, i):
 largest = i # Initialize largest as root
  l = 2 * i + 1 # left = 2*i + 1
  r = 2 * i + 2 # right = 2*i + 2
  # See if left child of root exists and is > root
 if l < n and a_list[i] < a_list[l]:</pre>
    largest = 1
 # See if right child of root exists and is > root
  if r < n and a_list[largest] < a_list[r]:</pre>
    largest = r
  # Change root, if needed
  if largest != i:
    a_list[i],a_list[largest] = a_list[largest],a_list[i] # swap
    # Heapify the root.
    heapify(a_list, n, largest)
def heap_sort(a_list):
  n = len(a_list)
  # Build a maxheap. Since last parent will be
  # at ((n//2)-1) we can start at that location.
  for i in range(n // 2 - 1, -1, -1):
    heapify(a_list, n, i)
```

```
# One by one extract elements
for i in range(n-1, 0, -1):
   a_list[i], a_list[0] = a_list[0], a_list[i] # swap
   heapify(a_list, i, 0)
```

## **Time complexities**

Algorithms	Best	Average	Worst
Bubble sort	O(n)	O(n^2)	O(n^2)
Selection sort	O(n^2)	O(n^2)	O(n^2)
Insertion sort	O(n)	O(n^2)	O(n^2)
Shell sort	O(n)	O((n log n)^2)	O((n log n)^2)
Merge sort	O(n log n)	O(n log n)	O(n log n)
Quick sort	O(n log n)	O(n log n)	O(n^2)
Heap sort	O(n log n)	O(n log n)	O(n log n)

# **Software Engineering**

### **Software**

Refers to all the related things that are required to make a software system work.

### Includes:

- programs
- configuration files
- system and user documentation
- user support system
- bug fixes and updates

## Software engineering

An engineering discipline that is concerned with all aspects of software production. From the initial stage of writing the requirements to maintaining it while being used.

## Software process

Set of activities that are associated with the development of a software product.

Fundamental activities that are common to all types of software development processes:

- Specification defining the software to be produced and the runtime constraints
- Development design and development of the software
- Validation testing phase to check if the software meets the specifications
- Evolution software is modified to adapt to new specifications

#### Waterfall

All before-mentioned activities are done sequentially, as clear separate phases. One phase is completed before the next phase is started.

#### **Iterative & incremental**

System is developed in iteration. Smaller parts of the system is completed in each iteration, that includes:

- Small amount of requirements specification
- Design and development for the specification
- Validation for the developed parts

#### Component based

Existing components are combined to implement the system. Main concentration is on the integration of the components.

## **Quality of software**

Can be measured using these aspects:

- Maintainability how easy it is to making changes
- Dependability how secure, reliable it is to failures or other unusual activities
- Efficiency how efficiently hardware resources (such as memory, processor time, disk space) are used
- Usability how easy it is to use the software from user's perspective
- Robustness how resilient it is to invalid inputs

## Challenges in software engineering

- Complexity
  - o Essential inherent, difficult to overcome
  - o Accidental not inherent, can be overcome
- Conformity
- · Changeability expected to be changeable to greater extent
- Invisibility not visualizable
- Can't guarantee defect free software no amount of testing can prove absence of defects

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