

Algorithm Analysis
School of CSEE







Analyze Prim's algorithm by answering the following.

```
1 Q = V[G];
2 for each u \in Q key[u] = \infty; \pi[u] = NIL;
3
   key[r] = 0; \pi[r] = NULL;
   while (Q not empty)
5
       u = ExtractMin(Q);
6
       for each v \in Adi[u]
           if (v \in Q \text{ and } w(u,v) < key[v])
               \pi[V] = U; \qquad key[V] = W(U,V);
8
   What is the running time for lines 1-3?
   How many times 'while' loop at line 4 is executed?
3) What is the total running time?
```





Assuming, (binary) heap is used to implement PQ,

- What is the running time for lines 1-3?
 O(VlogV)
 or Θ(V) (since, all element has same value)
- 2) How many times 'while' loop at line 4 is executed? |V| times
- 3) What is the total running time?O(VlogV + ElogV) = O(ElogV)





- 1. Line 5 ExtractMin will take O(logV) times. Thus with while loop, it will take (VlogV)
- For loop in lines 6-7 is executed O(|E|) times. (not O(|V|*|E|) times)
 Increasing key value in line 8, will restructure heap which takes O(|logV|) times. → Thus, line 6-7 will take O(ElogV)
- 3. Thus it will takes O(VlogV + ElogV) = O(ElogV)



Question 2



Kruskal's algorithm can return different spanning trees for the same input graph G, depending on how it breaks ties when the edges are sorted in order.

- 1) In what condition, Kruskal's algorithm return same minimum spanning tree T of G with?
- 2) What is data structure used?
- 3) What is the time complexity of the algorithm?

Chapter 12



- Sort edges into nondecreasing order by w.
- The algorithm maintains A, a forest of trees.
- Repeatedly merges two components into one by choosing the light edge that connects them.

i.e.,

- 1. Choose the light edge crossing the cut between them.
- 2. (If it forms a cycle, the edge is discarded.)

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Ans) Stable sorting?



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- 2) What is data structure used?
- Ans) Usually, Disjoint set / Union-find



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i.e.,

- 1. Choose the light edge crossing the cut between them.
- 2. (If it forms a cycle, the edge is discarded.)
- 3) What is the time complexity of the algorithm?
 - Depending on data structure.
 - If disjoint-set data structure is used, it is safe to say O(ElogE).

Chapter 15





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What is the design strategy of Kruskal's algorithm and Prim's algorithm?

Ans) Greedy



MST applications



- Minimum spanning trees are used for network designs (i.e. telephone or cable networks). They are also used to find approximate solutions for complex mathematical problems like the <u>Traveling Salesman</u> <u>Problem</u>. Other, diverse applications include:
 - Cluster Analysis.
 - Real-time face tracking and verification (i.e. locating human faces in a video stream).
 - Protocols in computer science to avoid network cycles.
 - Entropy based image registration.
 - Max bottleneck paths.
 - Dithering (adding white noise to a digital recording in order to reduce distortion).
 From https://www.statisticshowto.com/

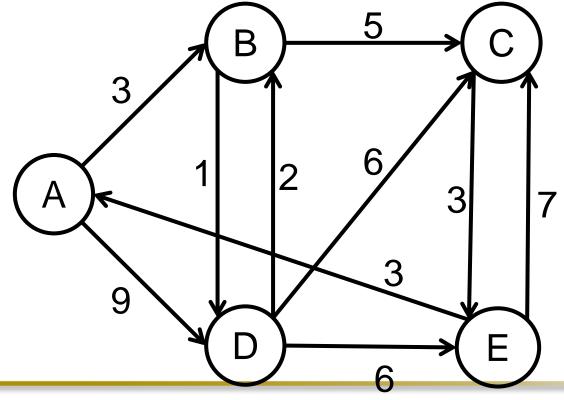






Run Dijkstra's algorithm on the following directed graph, using vertex *A* as the source. After vertex D is extracted from priority queue and all edges incident from vertex D are relaxed, what is the distance of vertex B, vertex C,

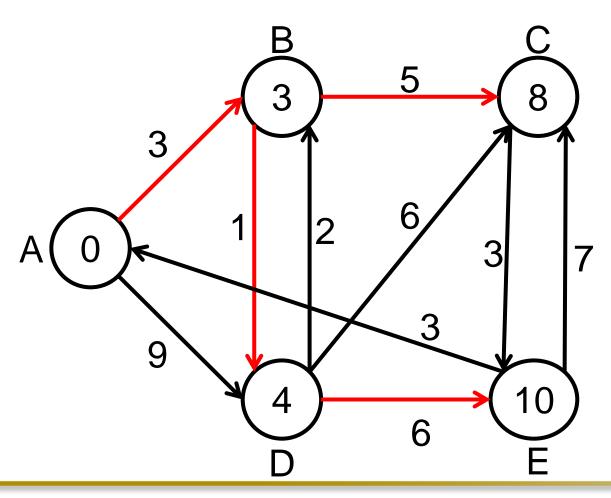
and vertex E?







Final result.







Order of relaxation: A, B, D, C, E

After vertex D is extracted from priority queue and all edges incident from vertex D are relaxed,

B: 3(A)

C: 8(B)

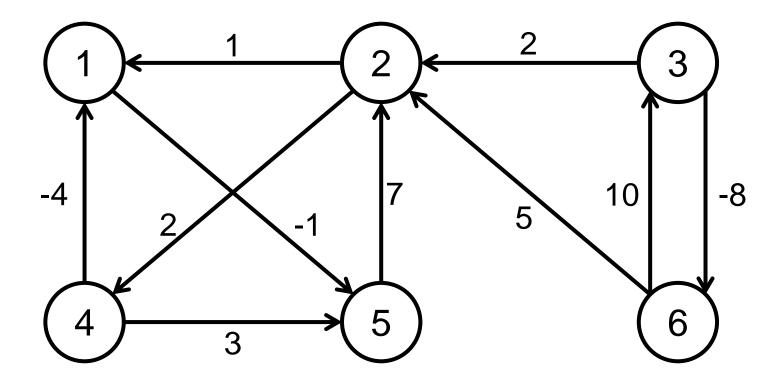
D: $9(A) \to 4(B)$

E: 10(D)





Run Floyd Warshall algorithm on the following weighted, directed graph. Show the last resulting matrix D.





A recursive solution



•
$$d_{ij}^{(k)} = \begin{cases} w_{ij} & \text{(if } k=0) \\ \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}) & \text{(if } k \ge 1) \end{cases}$$

• The Matrix $D^{(n)} = (d_{ij}^{(n)})$ gives the final answer: $d_{ij}^{(n)} = \delta(i,j)$ for all $i,j \in V$.





V2→V5: V2→V1→V5

$$D^{0} = \begin{bmatrix} 0 & \infty & \infty & \infty & -1 & \infty \\ 1 & 0 & \infty & 2 & \infty & \infty \\ \infty & 2 & 0 & \infty & \infty & -8 \\ -4 & \infty & \infty & 0 & 3 & \infty \\ \infty & 7 & \infty & \infty & 0 & \infty \\ \infty & 5 & 10 & \infty & \infty & 0 \end{bmatrix}$$





$$D^{1} = \begin{bmatrix} 0 & \infty & \infty & \infty & -1 & \infty \\ 1 & 0 & \infty & 2 & 0 & \infty \\ \infty & 2 & 0 & \infty & \infty & -8 \\ -4 & \infty & \infty & 0 & -5 & \infty \\ \infty & 7 & \infty & \infty & 0 & \infty \\ \infty & 5 & 10 & \infty & \infty & 0 \end{bmatrix}$$





$$D^{2} = \begin{bmatrix} 0 & \infty & \infty & \infty & -1 & \infty \\ 1 & 0 & \infty & 2 & 0 & \infty \\ 3 & 2 & 0 & 4 & 2 & -8 \\ -4 & \infty & \infty & 0 & -5 & \infty \\ 8 & 7 & \infty & 9 & 0 & \infty \\ 6 & 5 & 10 & 7 & 5 & 0 \end{bmatrix}$$





$$D^{6} = \begin{bmatrix} 0 & 6 & \infty & 8 & -1 & \infty \\ -2 & 0 & \infty & 2 & -3 & \infty \\ -5 & -3 & 0 & -1 & -6 & -8 \\ -4 & 2 & \infty & 0 & -5 & \infty \\ 5 & 7 & \infty & 9 & 0 & \infty \\ 3 & 5 & 10 & 7 & 2 & 0 \end{bmatrix}$$





a) What is the design strategy of Dijkstra's algorithm?

b) What is the design strategy of Floyd's algorithm?





Compare the time complexity of the following all-pair shortest paths.

- (1) Dijkstra's algorithm for nonnegative edge weights
- (2) Bellman-Ford for each vertex
- (3) Floyd-Warshall algorithm





Compare the time complexity of the following all-pair shortest paths.

- (1) Dijkstra's algorithm for nonnegative edge weights $\Theta(VE+ V^2|gV) = \Theta(V^3)$
- (2) Bellman-Ford for each vertex $\Theta(V^2E) = \Theta(V^4)$
- (3) Floyd-Warshall algorithm ⊖(V³)

Then, what is advantage of Floyd alg. Over Dijkstra's alg.? Ans) It can deal with negative edge.