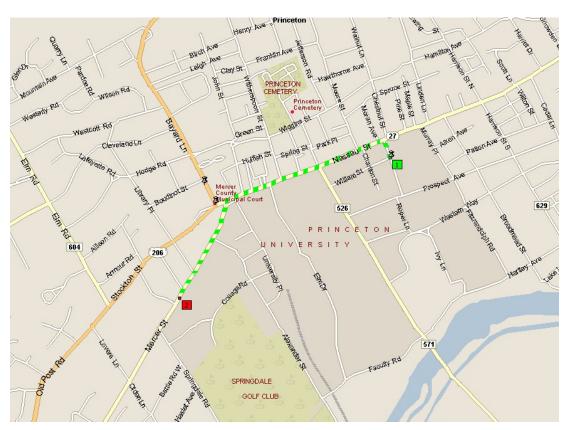
4.4 Shortest Paths in a Graph



shortest path from Princeton CS department to Einstein's house

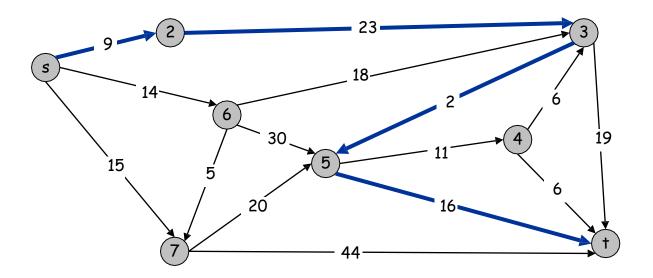
Shortest Path Problem

Shortest path network.

- Directed graph G = (V, E).
- Source s, destination t.
- Length ℓ_e = length of edge e.

Shortest path problem: find shortest directed path from s to t.

cost of path = sum of edge costs in path



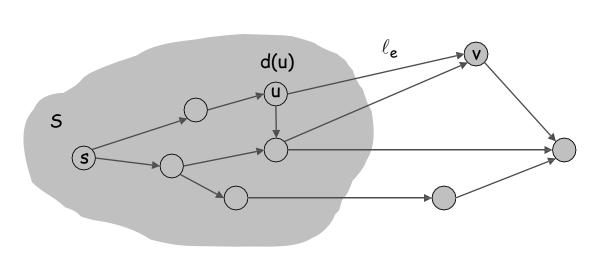
Cost of path s-2-3-5-t = 9 + 23 + 2 + 16 = 48.

Dijkstra's Algorithm

Dijkstra's algorithm.

- Maintain a set of explored nodes S for which we have determined the shortest path distance d(u) from s to u.
- Initialize $S = \{s\}, d(s) = 0$.
- Repeatedly choose unexplored node v which minimizes

$$\pi(v) = \min_{e = (u,v) : u \in S} d(u) + \ell_e,$$
 add v to S, and set d(v) = $\pi(v)$. shortest path to some u in explored part, followed by a single edge (u, v)







Invariant. For each node $u \in S$, d(u) is the length of the shortest s-u path.

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Pf. (by induction on |S|)

Base case: |S| = 1?

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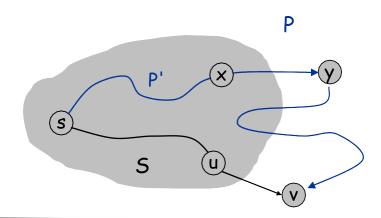
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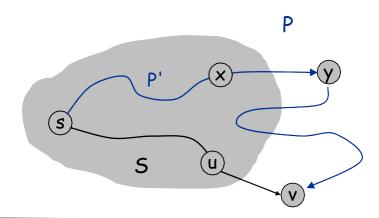
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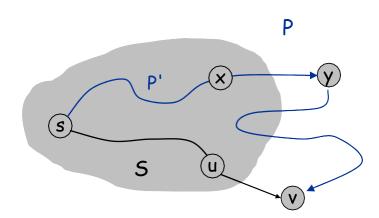
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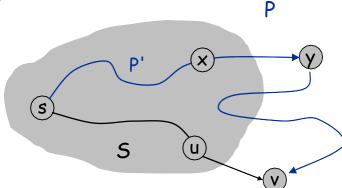
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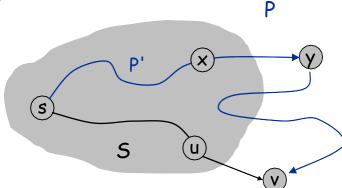
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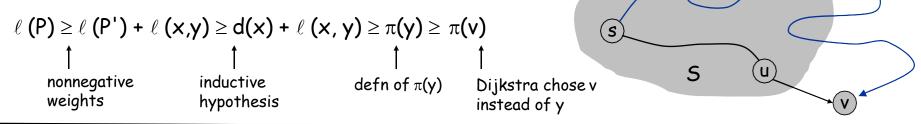
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Dijkstra's Algorithm: Implementation

For each unexplored node, explicitly maintain $\pi(v) = \min_{e = (u,v) : u \in S} d(u) + \ell_e$.

- Next node to explore = node with minimum $\pi(v)$.
- When exploring v, for each incident edge e = (v, w), update

$$\pi(w) = \min \left\{ \pi(w), \pi(v) + \ell_e \right\}.$$

Efficient implementation. Maintain a priority queue of unexplored nodes, prioritized by $\pi(v)$.

PQ Operation	Dijkstra	Array	Binary heap	d-way Heap	Fib heap†
Insert	n	n	log n	d log _d n	1
ExtractMin	n	n	log n	d log _d n	log n
ChangeKey	m	1	log n	log _d n	1
IsEmpty	n	1	1	1	1
Total		n ²	m log n	m log _{m/n} n	m + n log n

† Individual ops are amortized bounds