Metric Accuracy Testing

Processes

PIO	Arrival	Burst	Priorit-1	Turnaround =
P1	0	2	2	conplete - arsival
Pl	1	4	Ì	waiting =
РЗ	2	1	3	turnaround - basst
P4	3	2	Ч	respone =
			·	starttime - Arrival

FLFS	93 P4 L 3	ч	5	6	7	•	9			12
Pl	F	2		P3		РЧ		·	·	

Expected

PIO	Turnaround	na:ting	(esponse
P1	2	0	0
PZ	ς	1	
РЗ	5	Ч	4
P4	6	Ч	4

sim

PIO	Turnaround	ua:tino	Response
P1	2	0	0
PΣ	E	i	
РЗ	Z	4	4
P4	6	4	Ч

•	55F	2 ²³	१ ^५ 3 ५	5	6	7	5	9	10	п	12
	PI	P3	PЧ		P	2	· 				

Expected

PIO	Turansound	waiting	response
P1	2	0	0
Pl	8	4	4
РЗ	1	O	0
P4	2	0	0

Sin

PIO	Turnaround	wa:ting	response
P1	2	Ø	0
Pl	ъ	4	4
РЗ	l	0	0
P4	3	0	0

SRTF	2°, 3°4	 પ ક	 6 7	, , , q	10	 12
61	P3 P	4	P2			
Expec	ted		,			
PIO	Turantound	waiting	response			
P1	2	0	Ö			
PZ	Е	4	4			
P 3	l	0	0			
P4	2	0	0			

sim

PIO	Turnasand	w riting	response
P1	2	0	٥
PZ	ષ્ઠ	Ч	Ц
РЗ		O	0
Р4	2	0	Ò

priority	1 83 PH 2 3	ч	5	6	7	•	9	10	.,	12
٢,		P2-		P	3	94				

Expected

PIO	Turantound	waiting	response
P1	2	0	٥
PZ	5	1	
РЗ	5	4	4
P4	6	4	4

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PIO	Turnaround	waiting	Response
P1	2	O	O
PZ	S	1	1
РЗ	S	Ч	4
P4	6	4	4

Preemptive priority

27, 192 283 384 4 5 6 7 \$ 9 10 11 12

Pr P2 P1 P3 P4

PIO	Turnaround	waiting	response
P1	6	4	0
Pl	4	0	G
РЗ	S	ч	4
P 4	6	4	4

PIO Turnaround Waiting Response
P1 6 4 6
P2 4 0 0
P3 5 4 4

4

4

6

P 4

Round	robin	+	ine qu	antum	=	2		
61 182 3	?» 3 ^Р И 1	(9	6	7 \$	9	10	п	15
P1	PZ	Р3	P4	P2				

PIO	Turnaround	waiting	response
P1	2	0	0
PZ	4	4.	. l.
P 3	3	£	2
P 4	. 4	کی ا	2

5 · M				
PIO	Turneround	Ma:ting	Response	
P1	2	, O,	0	
PZ	ç	Ч	1	
РЗ	3	2	2	
P4	Ч	2	2	