

```

In[311]:= pppp = Table[0, {i, 5}]
           |tabela
pppm = Table[0, {i, 5}]
           |tabela
ppmm = Table[0, {i, 5}]
           |tabela
pmmm = Table[0, {i, 5}]
           |tabela
mmmm = Table[0, {i, 5}]
           |tabela

pppp[[1]] := 1
pppm[[2]] := 1
ppmm[[3]] := 1
pmmm[[4]] := 1
mmmm[[5]] := 1

Jp = Table[0, {i, 5}, {k, 5}]
    |tabela
Jm = Table[0, {i, 5}, {k, 5}]
    |tabela

Jx = Table[0, {i, 5}, {k, 5}]
    |tabela
Jy = Table[0, {i, 5}, {k, 5}]
    |tabela
Jz = Table[0, {i, 5}, {k, 5}]
    |tabela

Jp[[1, 2]] := Sqrt[4]
            |pierwiastek kwadratowy
Jp[[2, 3]] := Sqrt[6]
            |pierwiastek kwadratowy
Jp[[3, 4]] := Sqrt[6]
            |pierwiastek kwadratowy
Jp[[4, 5]] := Sqrt[4]
            |pierwiastek kwadratowy
MatrixForm[Jp]
|postać macierzy
Jm[[2, 1]] := Sqrt[4]
            |pierwiastek kwadratowy
Jm[[3, 2]] := Sqrt[6]
            |pierwiastek kwadratowy
Jm[[4, 3]] := Sqrt[6]
            |pierwiastek kwadratowy
Jm[[5, 4]] := Sqrt[4]
            |pierwiastek kwadratowy
MatrixForm[Jm]
|postać macierzy
Jx = (Jp + Jm) / 2
"Macierz Jx"

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MatrixForm[Jx]
|postać macierzy
Jy = i * (-Jp + Jm) / 2
"Macierz Jy"
MatrixForm[Jy]
|postać macierzy
Jz = i * (-Jx.Jy + Jy.Jx)
"Macierz Jz"
MatrixForm[Jz]
|postać macierzy
Eigenvectors[Jx]
|wektory własne
MatrixForm[Eigenvalues[Jx]]
|postać macie... |wartości własne macierzy
Eigenvectors[Jy]
|wektory własne
MatrixForm[Eigenvalues[Jy]]
|postać macie... |wartości własne macierzy
Eigenvectors[Jz]
|wektory własne
MatrixForm[Eigenvalues[Jz]]
|postać macie... |wartości własne macierzy
"Macierz obrotu o kat T"
R = FullSimplify[MatrixExp[- i T Jy]]
|uprość pełniej |eksponenta macierzy
MatrixForm[R]
|postać macierzy
"Wektory macierzy dij"
R1 = R[[All, 1]]
|wszystko
R2 = R[[All, 2]]
|wszystko
R3 = R[[All, 3]]
|wszystko
R4 = R[[All, 4]]
|wszystko
R5 = R[[All, 5]]
|wszystko
MatrixForm[R1]
|postać macierzy
MatrixForm[R2]
|postać macierzy
MatrixForm[R3]
|postać macierzy
MatrixForm[R4]
|postać macierzy
MatrixForm[R5]
|postać macierzy
"Orthogonality"
Simplify[R1[[1]] * R2[[1]] + R1[[2]] * R2[[2]] +
|uprość

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[\\_uproszcz](#)

$R1[[3]] * R2[[3]] + R1[[4]] * R2[[4]] + R1[[5]] * R2[[5]]]$   
 $\text{Simplify}[R1[[1]] * R3[[1]] + R1[[2]] * R3[[2]] + R1[[3]] * R3[[3]] +$   
[\\_uproszcz](#)

$R1[[4]] * R3[[4]] + R1[[5]] * R3[[5]]]$   
 $\text{Simplify}[R1[[1]] * R4[[1]] + R1[[2]] * R4[[2]] + R1[[3]] * R4[[3]] +$   
[\\_uproszcz](#)

$R1[[4]] * R4[[4]] + R1[[5]] * R4[[5]]]$   
 $\text{Simplify}[R1[[1]] * R5[[1]] + R1[[2]] * R5[[2]] + R1[[3]] * R5[[3]] +$   
[\\_uproszcz](#)

$R1[[4]] * R5[[4]] + R1[[5]] * R5[[5]]]$   
 $\text{Simplify}[R2[[1]] * R3[[1]] + R2[[2]] * R3[[2]] + R2[[3]] * R3[[3]] +$   
[\\_uproszcz](#)

$R2[[4]] * R3[[4]] + R2[[5]] * R3[[5]]]$   
 $\text{Simplify}[R2[[1]] * R4[[1]] + R2[[2]] * R4[[2]] + R2[[3]] * R4[[3]] +$   
[\\_uproszcz](#)

$R2[[4]] * R4[[4]] + R2[[5]] * R4[[5]]]$   
 $\text{Simplify}[R2[[1]] * R5[[1]] + R2[[2]] * R5[[2]] + R2[[3]] * R5[[3]] +$   
[\\_uproszcz](#)

$R2[[4]] * R5[[4]] + R2[[5]] * R5[[5]]]$   
 $\text{Simplify}[R3[[1]] * R4[[1]] + R3[[2]] * R4[[2]] + R3[[3]] * R4[[3]] +$   
[\\_uproszcz](#)

$R3[[4]] * R4[[4]] + R3[[5]] * R4[[5]]]$   
 $\text{Simplify}[R3[[1]] * R5[[1]] + R3[[2]] * R5[[2]] + R3[[3]] * R5[[3]] +$   
[\\_uproszcz](#)

$R3[[4]] * R5[[4]] + R3[[5]] * R5[[5]]]$   
 $\text{Simplify}[R4[[1]] * R5[[1]] + R4[[2]] * R5[[2]] + R4[[3]] * R5[[3]] +$   
[\\_uproszcz](#)

$R4[[4]] * R5[[4]] + R4[[5]] * R5[[5]]]$

"Orthonormal"

$\text{Simplify}[R1[[1]] * R1[[1]] + R1[[2]] * R1[[2]] +$

[\\_uproszcz](#)

$R1[[3]] * R1[[3]] + R1[[4]] * R1[[4]] + R1[[5]] * R1[[5]]]$   
 $\text{Simplify}[R2[[1]] * R2[[1]] + R2[[2]] * R2[[2]] + R2[[3]] * R2[[3]] +$   
[\\_uproszcz](#)

$R2[[4]] * R2[[4]] + R2[[5]] * R2[[5]]]$   
 $\text{Simplify}[R3[[1]] * R3[[1]] + R3[[2]] * R3[[2]] + R3[[3]] * R3[[3]] +$   
[\\_uproszcz](#)

$R3[[4]] * R3[[4]] + R3[[5]] * R3[[5]]]$   
 $\text{Simplify}[R4[[1]] * R4[[1]] + R4[[2]] * R4[[2]] + R4[[3]] * R4[[3]] +$   
[\\_uproszcz](#)

$R4[[4]] * R4[[4]] + R4[[5]] * R4[[5]]]$   
 $\text{Simplify}[R5[[1]] * R5[[1]] + R5[[2]] * R5[[2]] + R5[[3]] * R5[[3]] +$   
[\\_uproszcz](#)

$R5[[4]] * R5[[4]] + R5[[5]] * R5[[5]]]$

"Wartości  $d_{ij} * d_{ij}$ "

$\int_0^\pi R[[1, 1]] R[[1, 1]] \text{Sin}[T] / 2 \, dT$   
[\\_sinus](#)

For[i = 1;

dla

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t = x, i < 6, i++, t =  $\int_0^\pi R[[1, i]] R[[1, i]] \sin[T] / 2 dT$ ;
Print[t]
For[i = 1;
t = x, i < 6, i++, t =  $\int_0^\pi R[[2, i]] R[[2, i]] \sin[T] / 2 dT$ ;
Print[t]
For[i = 1;
t = x, i < 6, i++, t =  $\int_0^\pi R[[3, i]] R[[3, i]] \sin[T] / 2 dT$ ;
Print[t]
For[i = 1;
t = x, i < 6, i++, t =  $\int_0^\pi R[[4, i]] R[[4, i]] \sin[T] / 2 dT$ ;
Print[t]
For[i = 1;
t = x, i < 6, i++, t =  $\int_0^\pi R[[5, i]] R[[5, i]] \sin[T] / 2 dT$ ;
Print[t]
"Równania Maxwella"
M = Sin[T] * Jx + Cos[T] * Jz
MatrixForm[M]
eigenvectorQ[matrix_, vector_] := MatrixRank[{matrix.vector, vector}] == 1
"Sprawdzanie czy wektor jest wektorem własnym danej macierzy"
eigenvectorQ[M, R1]
eigenvectorQ[M, R2]
eigenvectorQ[M, R3]
eigenvectorQ[M, R4]
eigenvectorQ[M, R5]

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MatrixForm[Eigenvalues[M]]
      |wartości własne macierzy
FullSimplify[MatrixForm[M.R1 - 2 R1]]
      |postać macierzy
FullSimplify[MatrixForm[M.R2 - R2]]
      |postać macierzy
FullSimplify[MatrixForm[M.R3]]
      |postać macierzy
FullSimplify[MatrixForm[M.R4 + R4]]
      |postać macierzy
FullSimplify[MatrixForm[M.R5 + 2 R5]]
      |postać macierzy
"Czyli wartości własne to kolejno[ 2,1,0,-1,-2]"
"..."
"Pchnięcia Y"
PAY = FullSimplify[MatrixExp[w Jy]]
      |uprosć pełniej |eksponenta macierzy
MatrixForm[PAY]
      |postać macierzy
"Kolumny macierzy obrotu o Y"
PAY1 = PAY[[All, 1]]
      |wszystko
PAY2 = PAY[[All, 2]]
      |wszystko
PAY3 = PAY[[All, 3]]
      |wszystko
PAY4 = PAY[[All, 4]]
      |wszystko
PAY5 = PAY[[All, 5]]
      |wszystko
"Ortogonalność"
Simplify[PAY1[[1]] * PAY2[[5]] - PAY1[[2]] * PAY2[[4]] +
      |uprosć
      PAY1[[3]] * PAY2[[3]] - PAY1[[4]] * PAY2[[2]] + PAY1[[5]] * PAY2[[1]]]
Simplify[PAY1[[1]] * PAY3[[5]] - PAY1[[2]] * PAY3[[4]] +
      |uprosć
      PAY1[[3]] * PAY3[[3]] - PAY1[[4]] * PAY3[[2]] + PAY1[[5]] * PAY3[[1]]]
Simplify[PAY1[[1]] * PAY4[[5]] - PAY1[[2]] * PAY4[[4]] +
      |uprosć
      PAY1[[3]] * PAY4[[3]] - PAY1[[4]] * PAY4[[2]] + PAY1[[5]] * PAY4[[1]]]
Simplify[PAY1[[1]] * PAY5[[5]] - PAY1[[2]] * PAY5[[4]] +
      |uprosć
      PAY1[[3]] * PAY5[[3]] - PAY1[[4]] * PAY5[[2]] + PAY1[[5]] * PAY5[[1]]]
Simplify[PAY2[[1]] * PAY3[[5]] - PAY2[[2]] * PAY3[[4]] +
      |uprosć
      PAY2[[3]] * PAY3[[3]] - PAY2[[4]] * PAY3[[2]] + PAY2[[5]] * PAY3[[1]]]
Simplify[PAY2[[1]] * PAY4[[5]] - PAY2[[2]] * PAY4[[4]] +
      |uprosć
      PAY2[[3]] * PAY4[[3]] - PAY2[[4]] * PAY4[[2]] + PAY2[[5]] * PAY4[[1]]]
Simplify[PAY2[[1]] * PAY5[[5]] - PAY2[[2]] * PAY5[[4]] +
      |uprosć
      PAY2[[3]] * PAY5[[3]] - PAY2[[4]] * PAY5[[2]] + PAY2[[5]] * PAY5[[1]]]

```

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$$\text{PAY2}[[3]] * \text{PAY5}[[3]] - \text{PAY2}[[4]] * \text{PAY5}[[2]] + \text{PAY2}[[5]] * \text{PAY5}[[1]]$$

Simplify[PAY3[[1]] * PAY4[[5]] - PAY3[[2]] * PAY4[[4]] +

$$\text{PAY3}[[3]] * \text{PAY4}[[3]] - \text{PAY3}[[4]] * \text{PAY4}[[2]] + \text{PAY3}[[5]] * \text{PAY4}[[1]]$$

Simplify[PAY3[[1]] * PAY5[[5]] - PAY3[[2]] * PAY5[[4]] +

$$\text{PAY3}[[3]] * \text{PAY5}[[3]] - \text{PAY3}[[4]] * \text{PAY5}[[2]] + \text{PAY3}[[5]] * \text{PAY5}[[1]]$$

Simplify[PAY4[[1]] * PAY5[[5]] - PAY4[[2]] * PAY5[[4]] +

$$\text{PAY4}[[3]] * \text{PAY5}[[3]] - \text{PAY4}[[4]] * \text{PAY5}[[2]] + \text{PAY4}[[5]] * \text{PAY5}[[1]]$$

"Normalizacja"
Simplify[PAY1[[1]] * PAY1[[1]] + PAY1[[2]] * PAY1[[2]] +

$$\text{PAY1}[[3]] * \text{PAY1}[[3]] + \text{PAY1}[[4]] * \text{PAY1}[[4]] + \text{PAY1}[[5]] * \text{PAY1}[[5]]$$

Simplify[PAY2[[1]] * PAY2[[1]] + PAY2[[2]] * PAY2[[2]] +

$$\text{PAY2}[[3]] * \text{PAY2}[[3]] + \text{PAY2}[[4]] * \text{PAY2}[[4]] + \text{PAY2}[[5]] * \text{PAY2}[[5]]$$

Simplify[PAY3[[1]] * PAY3[[1]] + PAY3[[2]] * PAY3[[2]] +

$$\text{PAY3}[[3]] * \text{PAY3}[[3]] + \text{PAY3}[[4]] * \text{PAY3}[[4]] + \text{PAY3}[[5]] * \text{PAY3}[[5]]$$

Simplify[PAY4[[1]] * PAY4[[1]] + PAY4[[2]] * PAY4[[2]] +

$$\text{PAY4}[[3]] * \text{PAY4}[[3]] + \text{PAY4}[[4]] * \text{PAY4}[[4]] + \text{PAY4}[[5]] * \text{PAY4}[[5]]$$

Simplify[PAY5[[1]] * PAY5[[1]] + PAY5[[2]] * PAY5[[2]] +

$$\text{PAY5}[[3]] * \text{PAY5}[[3]] + \text{PAY5}[[4]] * \text{PAY5}[[4]] + \text{PAY5}[[5]] * \text{PAY5}[[5]]$$

"Macierz stworzona z iloczynu wektorów"
LAY = Table[0, {i, 5}, {k, 5}]

$$\text{LAY}[[1, 5]] := 1$$


$$\text{LAY}[[5, 1]] := 1$$


$$\text{LAY}[[4, 2]] := -1$$


$$\text{LAY}[[2, 4]] := -1$$

MatrixForm[LAY]
"Pchniecie znalezionej macierzy Y i X"
MatrixForm[PAY.LAY]
MatrixForm[PAX.LAY]
"Пchnięcia X"
PAX = FullSimplify[MatrixExp[w Jx]]
MatrixForm[PAY.Eigenvectors[LAY]]
MatrixForm[PAX.Eigenvectors[LAY]]

```

Ustalać macierzy

"Kolumny macierzy obrotu o X"

PAX1 = PAX[[A11, 1]]  
 [wszystko]

PAX2 = PAX[[A11, 2]]  
 [wszystko]

PAX3 = PAX[[A11, 3]]  
 [wszystko]

PAX4 = PAX[[A11, 4]]  
 [wszystko]

PAX5 = PAX[[A11, 5]]  
 [wszystko]

"Ortogonalność"

Simplify[PAX1[[1]] \* PAX2[[5]] - PAX1[[2]] \* PAX2[[4]] +  
 [uprość

PAX1[[3]] \* PAX2[[3]] - PAX1[[4]] \* PAX2[[2]] + PAX1[[5]] \* PAX2[[1]]]

Simplify[PAX1[[1]] \* PAX3[[5]] - PAX1[[2]] \* PAX3[[4]] +  
 [uprość

PAX1[[3]] \* PAX3[[3]] - PAX1[[4]] \* PAX3[[2]] + PAX1[[5]] \* PAX3[[1]]]

Simplify[PAX1[[1]] \* PAX4[[5]] - PAX1[[2]] \* PAX4[[4]] +  
 [uprość

PAX1[[3]] \* PAX4[[3]] - PAX1[[4]] \* PAX4[[2]] + PAX1[[5]] \* PAX4[[1]]]

Simplify[PAX1[[1]] \* PAX5[[5]] - PAX1[[2]] \* PAX5[[4]] +  
 [uprość

PAX1[[3]] \* PAX5[[3]] - PAX1[[4]] \* PAX5[[2]] + PAX1[[5]] \* PAX5[[1]]]

Simplify[PAX2[[1]] \* PAX3[[5]] - PAX2[[2]] \* PAX3[[4]] +  
 [uprość

PAX2[[3]] \* PAX3[[3]] - PAX2[[4]] \* PAX3[[2]] + PAX2[[5]] \* PAX3[[1]]]

Simplify[PAX2[[1]] \* PAX4[[5]] - PAX2[[2]] \* PAX4[[4]] +  
 [uprość

PAX2[[3]] \* PAX4[[3]] - PAX2[[4]] \* PAX4[[2]] + PAX2[[5]] \* PAX4[[1]]]

Simplify[PAX2[[1]] \* PAX5[[5]] - PAX2[[2]] \* PAX5[[4]] +  
 [uprość

PAX2[[3]] \* PAX5[[3]] - PAX2[[4]] \* PAX5[[2]] + PAX2[[5]] \* PAX5[[1]]]

Simplify[PAX3[[1]] \* PAX4[[5]] - PAX3[[2]] \* PAX4[[4]] +  
 [uprość

PAX3[[3]] \* PAX4[[3]] - PAX3[[4]] \* PAX4[[2]] + PAX3[[5]] \* PAX4[[1]]]

Simplify[PAX3[[1]] \* PAX5[[5]] - PAX3[[2]] \* PAX5[[4]] +  
 [uprość

PAX3[[3]] \* PAX5[[3]] - PAX3[[4]] \* PAX5[[2]] + PAX3[[5]] \* PAX5[[1]]]

Simplify[PAX4[[1]] \* PAX5[[5]] - PAX4[[2]] \* PAX5[[4]] +  
 [uprość

PAX4[[3]] \* PAX5[[3]] - PAX4[[4]] \* PAX5[[2]] + PAX4[[5]] \* PAX5[[1]]]

"Sprawdzenie czy dla pchnięcia w X była by taka sama macierz, jak widać TAK"

Out[311]= {0, 0, 0, 0, 0}

Out[312]= {0, 0, 0, 0, 0}

Out[313]= {0, 0, 0, 0, 0}

Out[314]= {0, 0, 0, 0, 0}

Out[315]=  $\{0, 0, 0, 0, 0\}$

Out[321]=  $\{\{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}\}$

Out[322]=  $\{\{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}\}$

Out[323]=  $\{\{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}\}$

Out[324]=  $\{\{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}\}$

Out[325]=  $\{\{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, 0, 0\}\}$

Out[330]//MatrixForm=

$$\begin{pmatrix} 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & \sqrt{6} & 0 & 0 \\ 0 & 0 & 0 & \sqrt{6} & 0 \\ 0 & 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Out[335]//MatrixForm=

$$\begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 2 & 0 & 0 & 0 & 0 \\ 0 & \sqrt{6} & 0 & 0 & 0 \\ 0 & 0 & \sqrt{6} & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 \end{pmatrix}$$

Out[336]=  $\{\{0, 1, 0, 0, 0\}, \{1, 0, \sqrt{\frac{3}{2}}, 0, 0\}, \{0, \sqrt{\frac{3}{2}}, 0, \sqrt{\frac{3}{2}}, 0\}, \{0, 0, \sqrt{\frac{3}{2}}, 0, 1\}, \{0, 0, 0, 1, 0\}\}$

Out[337]= **Macierz Jx**

Out[338]//MatrixForm=

$$\begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & \sqrt{\frac{3}{2}} & 0 & 0 \\ 0 & \sqrt{\frac{3}{2}} & 0 & \sqrt{\frac{3}{2}} & 0 \\ 0 & 0 & \sqrt{\frac{3}{2}} & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

Out[339]=  $\{\{0, -i, 0, 0, 0\}, \{i, 0, -i\sqrt{\frac{3}{2}}, 0, 0\},$   
 $\{0, i\sqrt{\frac{3}{2}}, 0, -i\sqrt{\frac{3}{2}}, 0\}, \{0, 0, i\sqrt{\frac{3}{2}}, 0, -i\}, \{0, 0, 0, i, 0\}\}$

Out[340]= **Macierz Jy**



Out[341]//MatrixForm=

$$\begin{pmatrix} 0 & -i & 0 & 0 & 0 \\ i & 0 & -i\sqrt{\frac{3}{2}} & 0 & 0 \\ 0 & i\sqrt{\frac{3}{2}} & 0 & -i\sqrt{\frac{3}{2}} & 0 \\ 0 & 0 & i\sqrt{\frac{3}{2}} & 0 & -i \\ 0 & 0 & 0 & i & 0 \end{pmatrix}$$

Out[342]=  $\{\{2, 0, 0, 0, 0\}, \{0, 1, 0, 0, 0\}, \{0, 0, 0, 0, 0\}, \{0, 0, 0, -1, 0\}, \{0, 0, 0, 0, -2\}\}$ Out[343]= **Macierz Jz**

Out[344]//MatrixForm=

$$\begin{pmatrix} 2 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & -2 \end{pmatrix}$$

Out[345]=  $\{\{1, -2, \sqrt{6}, -2, 1\}, \{1, 2, \sqrt{6}, 2, 1\},$   
 $\{-1, 1, 0, -1, 1\}, \{-1, -1, 0, 1, 1\}, \{1, 0, -\sqrt{\frac{2}{3}}, 0, 1\}\}$

Out[346]//MatrixForm=

$$\begin{pmatrix} -2 \\ 2 \\ -1 \\ 1 \\ 0 \end{pmatrix}$$

Out[347]=  $\{\{1, -2i, -\sqrt{6}, 2i, 1\}, \{1, 2i, -\sqrt{6}, -2i, 1\},$   
 $\{-1, i, 0, i, 1\}, \{-1, -i, 0, -i, 1\}, \{1, 0, \sqrt{\frac{2}{3}}, 0, 1\}\}$

Out[348]//MatrixForm=

$$\begin{pmatrix} -2 \\ 2 \\ -1 \\ 1 \\ 0 \end{pmatrix}$$

Out[349]=  $\{\{0, 0, 0, 0, 1\}, \{1, 0, 0, 0, 0\}, \{0, 0, 0, 1, 0\}, \{0, 1, 0, 0, 0\}, \{0, 0, 1, 0, 0\}\}$ 

Out[350]//MatrixForm=

$$\begin{pmatrix} -2 \\ 2 \\ -1 \\ 1 \\ 0 \end{pmatrix}$$

Out[351]= **Macierz obrotu o kat T**

$$\begin{aligned}
\text{Out[352]} = & \left\{ \left\{ \cos\left[\frac{T}{2}\right]^4, -2 \cos\left[\frac{T}{2}\right]^3 \sin\left[\frac{T}{2}\right], \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2, -\sin\left[\frac{T}{2}\right]^2 \sin[T], \sin\left[\frac{T}{2}\right]^4 \right\}, \right. \\
& \left\{ \frac{1}{2} (1 + \cos[T]) \sin[T], \frac{1}{2} (\cos[T] + \cos[2T]), -\sqrt{\frac{3}{2}} \cos[T] \sin[T], \right. \\
& \frac{1}{2} (\cos[T] - \cos[2T]), -\sin\left[\frac{T}{2}\right]^2 \sin[T] \}, \left\{ \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2, \sqrt{\frac{3}{2}} \cos[T] \sin[T], \right. \\
& \frac{1}{4} (1 + 3 \cos[2T]), -\sqrt{\frac{3}{2}} \cos[T] \sin[T], \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 \}, \left\{ \sin\left[\frac{T}{2}\right]^2 \sin[T], \right. \\
& \frac{1}{2} (\cos[T] - \cos[2T]), \sqrt{\frac{3}{2}} \cos[T] \sin[T], \frac{1}{2} (\cos[T] + \cos[2T]), -2 \cos\left[\frac{T}{2}\right]^3 \sin\left[\frac{T}{2}\right] \}, \\
& \left. \left. \left\{ \sin\left[\frac{T}{2}\right]^4, \sin\left[\frac{T}{2}\right]^2 \sin[T], \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2, \frac{1}{2} (1 + \cos[T]) \sin[T], \cos\left[\frac{T}{2}\right]^4 \right\} \right\} \right\}
\end{aligned}$$

Out[353]//MatrixForm=

$$\begin{pmatrix}
\cos\left[\frac{T}{2}\right]^4 & -2 \cos\left[\frac{T}{2}\right]^3 \sin\left[\frac{T}{2}\right] & \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 & -\sin\left[\frac{T}{2}\right]^2 \sin[T] & \sin\left[\frac{T}{2}\right]^4 \\
\frac{1}{2} (1 + \cos[T]) \sin[T] & \frac{1}{2} (\cos[T] + \cos[2T]) & -\sqrt{\frac{3}{2}} \cos[T] \sin[T] & \frac{1}{2} (\cos[T] - \cos[2T]) & -\sin\left[\frac{T}{2}\right]^2 \sin[T] \\
\frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 & \sqrt{\frac{3}{2}} \cos[T] \sin[T] & \frac{1}{4} (1 + 3 \cos[2T]) & -\sqrt{\frac{3}{2}} \cos[T] \sin[T] & \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 \\
\sin\left[\frac{T}{2}\right]^2 \sin[T] & \frac{1}{2} (\cos[T] - \cos[2T]) & \sqrt{\frac{3}{2}} \cos[T] \sin[T] & \frac{1}{2} (\cos[T] + \cos[2T]) & -2 \cos\left[\frac{T}{2}\right]^3 \sin\left[\frac{T}{2}\right] \\
\sin\left[\frac{T}{2}\right]^4 & \sin\left[\frac{T}{2}\right]^2 \sin[T] & \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 & \frac{1}{2} (1 + \cos[T]) \sin[T] & \cos\left[\frac{T}{2}\right]^4
\end{pmatrix}$$

Out[354]= Wektory macierzy dij

$$\text{Out[355]} = \left\{ \cos\left[\frac{T}{2}\right]^4, \frac{1}{2} (1 + \cos[T]) \sin[T], \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2, \sin\left[\frac{T}{2}\right]^2 \sin[T], \sin\left[\frac{T}{2}\right]^4 \right\}$$

$$\text{Out[356]} = \left\{ -2 \cos\left[\frac{T}{2}\right]^3 \sin\left[\frac{T}{2}\right], \frac{1}{2} (\cos[T] + \cos[2T]), \right.$$

$$\left. \sqrt{\frac{3}{2}} \cos[T] \sin[T], \frac{1}{2} (\cos[T] - \cos[2T]), \sin\left[\frac{T}{2}\right]^2 \sin[T] \right\}$$

$$\text{Out[357]} = \left\{ \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2, -\sqrt{\frac{3}{2}} \cos[T] \sin[T], \frac{1}{4} (1 + 3 \cos[2T]), \sqrt{\frac{3}{2}} \cos[T] \sin[T], \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 \right\}$$

$$\text{Out[358]} = \left\{ -\sin\left[\frac{T}{2}\right]^2 \sin[T], \frac{1}{2} (\cos[T] - \cos[2T]), \right. \\ \left. -\sqrt{\frac{3}{2}} \cos[T] \sin[T], \frac{1}{2} (\cos[T] + \cos[2T]), \frac{1}{2} (1 + \cos[T]) \sin[T] \right\}$$

$$\text{Out[359]} = \left\{ \sin\left[\frac{T}{2}\right]^4, -\sin\left[\frac{T}{2}\right]^2 \sin[T], \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2, -2 \cos\left[\frac{T}{2}\right]^3 \sin\left[\frac{T}{2}\right], \cos\left[\frac{T}{2}\right]^4 \right\}$$

Out[360]//MatrixForm=

$$\begin{pmatrix} \cos\left[\frac{T}{2}\right]^4 \\ \frac{1}{2} (1 + \cos[T]) \sin[T] \\ \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 \\ \sin\left[\frac{T}{2}\right]^2 \sin[T] \\ \sin\left[\frac{T}{2}\right]^4 \end{pmatrix}$$

Out[361]//MatrixForm=

$$\begin{pmatrix} -2 \cos\left[\frac{T}{2}\right]^3 \sin\left[\frac{T}{2}\right] \\ \frac{1}{2} (\cos[T] + \cos[2T]) \\ \sqrt{\frac{3}{2}} \cos[T] \sin[T] \\ \frac{1}{2} (\cos[T] - \cos[2T]) \\ \sin\left[\frac{T}{2}\right]^2 \sin[T] \end{pmatrix}$$

Out[362]//MatrixForm=

$$\begin{pmatrix} \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 \\ -\sqrt{\frac{3}{2}} \cos[T] \sin[T] \\ \frac{1}{4} (1 + 3 \cos[2T]) \\ \sqrt{\frac{3}{2}} \cos[T] \sin[T] \\ \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 \end{pmatrix}$$

Out[363]//MatrixForm=

$$\begin{pmatrix} -\sin\left[\frac{T}{2}\right]^2 \sin[T] \\ \frac{1}{2} (\cos[T] - \cos[2T]) \\ -\sqrt{\frac{3}{2}} \cos[T] \sin[T] \\ \frac{1}{2} (\cos[T] + \cos[2T]) \\ \frac{1}{2} (1 + \cos[T]) \sin[T] \end{pmatrix}$$

Out[364]//MatrixForm=

$$\begin{pmatrix} \sin\left[\frac{T}{2}\right]^4 \\ -\sin\left[\frac{T}{2}\right]^2 \sin[T] \\ \frac{1}{2} \sqrt{\frac{3}{2}} \sin[T]^2 \\ -2 \cos\left[\frac{T}{2}\right]^3 \sin\left[\frac{T}{2}\right] \\ \cos\left[\frac{T}{2}\right]^4 \end{pmatrix}$$

Out[365]= Orthogonality

Out[366]= 0

Out[367]= 0

Out[368]= 0

Out[369]= 0

Out[370]= 0

Out[371]= 0

Out[372]= 0

Out[373]= 0

Out[374]= 0

Out[375]= 0

Out[376]= Orthonormal

Out[377]= 1

Out[378]= 1

Out[379]= 1

Out[380]= 1

Out[381]= 1

Out[382]= Wartości  $d_{ij} \cdot d_{ij}$ Out[383]=  $\frac{1}{5}$  $\frac{1}{5}$  $\frac{1}{5}$  $\frac{1}{5}$  $\frac{1}{5}$



Out[390]=  $\left\{ \{2 \cos[T], \sin[T], 0, 0, 0\}, \right.$   
 $\left. \{ \sin[T], \cos[T], \sqrt{\frac{3}{2}} \sin[T], 0, 0\}, \{0, \sqrt{\frac{3}{2}} \sin[T], 0, \sqrt{\frac{3}{2}} \sin[T], 0\}, \right.$   
 $\left. \{0, 0, \sqrt{\frac{3}{2}} \sin[T], -\cos[T], \sin[T]\}, \{0, 0, 0, \sin[T], -2 \cos[T]\} \right\}$

Out[391]/MatrixForm=

$$\begin{pmatrix} 2 \cos[T] & \sin[T] & 0 & 0 & 0 \\ \sin[T] & \cos[T] & \sqrt{\frac{3}{2}} \sin[T] & 0 & 0 \\ 0 & \sqrt{\frac{3}{2}} \sin[T] & 0 & \sqrt{\frac{3}{2}} \sin[T] & 0 \\ 0 & 0 & \sqrt{\frac{3}{2}} \sin[T] & -\cos[T] & \sin[T] \\ 0 & 0 & 0 & \sin[T] & -2 \cos[T] \end{pmatrix}$$

Out[393]= Sprawdzenie czy wektor jest wektorem własnym danej macierzy

Out[394]= True

Out[395]= True

Out[396]= True

Out[397]= True

Out[398]= True

Out[399]/MatrixForm=

$$\begin{pmatrix} -2 \\ 2 \\ -1 \\ 1 \\ 0 \end{pmatrix}$$

Out[400]/MatrixForm=

$$\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Out[401]/MatrixForm=

$$\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Out[402]/MatrixForm=

$$\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Out[403]//MatrixForm=

$$\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Out[404]//MatrixForm=

$$\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Out[405]= Czyli wartości własne to kolejno [ 2,1,0,-1,-2]

Out[406]= ...

Out[407]= Pchnięcia Y

$$\begin{aligned} \text{Out[408]} = & \left\{ \left\{ \cosh\left[\frac{w}{2}\right]^4, -\frac{1}{2} i (1 + \cosh[w]) \sinh[w], -\frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2, i \sinh\left[\frac{w}{2}\right]^2 \sinh[w], \sinh\left[\frac{w}{2}\right]^4 \right\}, \right. \\ & \left\{ \frac{1}{2} i (1 + \cosh[w]) \sinh[w], \frac{1}{2} (\cosh[w] + \cosh[2w]), \right. \\ & \left. -i \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \frac{1}{2} (\cosh[w] - \cosh[2w]), i \sinh\left[\frac{w}{2}\right]^2 \sinh[w] \right\}, \\ & \left\{ -\frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2, i \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \frac{1}{4} (1 + 3 \cosh[2w]), -i \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \right. \\ & \left. -\frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 \right\}, \left\{ -i \sinh\left[\frac{w}{2}\right]^2 \sinh[w], \frac{1}{2} (\cosh[w] - \cosh[2w]), \right. \\ & \left. i \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \frac{1}{2} (\cosh[w] + \cosh[2w]), -\frac{1}{2} i (1 + \cosh[w]) \sinh[w] \right\}, \\ & \left. \left\{ \sinh\left[\frac{w}{2}\right]^4, -i \sinh\left[\frac{w}{2}\right]^2 \sinh[w], -\frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2, \frac{1}{2} i (1 + \cosh[w]) \sinh[w], \cosh\left[\frac{w}{2}\right]^4 \right\} \right\} \end{aligned}$$

Out[409]//MatrixForm=

$$\begin{pmatrix} \cosh\left[\frac{w}{2}\right]^4 & -\frac{1}{2}i(1+\cosh[w])\sinh[w] & -\frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 & i\sinh\left[\frac{w}{2}\right]^2\sinh[w] \\ \frac{1}{2}i(1+\cosh[w])\sinh[w] & \frac{1}{2}(\cosh[w]+\cosh[2w]) & -i\sqrt{\frac{3}{2}}\cosh[w]\sinh[w] & \frac{1}{2}(\cosh[w]-\cosh[2w]) \\ -\frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 & i\sqrt{\frac{3}{2}}\cosh[w]\sinh[w] & \frac{1}{4}(1+3\cosh[2w]) & -i\sqrt{\frac{3}{2}}\cosh[w] \\ -i\sinh\left[\frac{w}{2}\right]^2\sinh[w] & \frac{1}{2}(\cosh[w]-\cosh[2w]) & i\sqrt{\frac{3}{2}}\cosh[w]\sinh[w] & \frac{1}{2}(\cosh[w]+\cosh[2w]) \\ \sinh\left[\frac{w}{2}\right]^4 & -i\sinh\left[\frac{w}{2}\right]^2\sinh[w] & -\frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 & \frac{1}{2}i(1+\cosh[w]) \end{pmatrix}$$

Out[410]= Kolumny macierzy obrotu o Y

$$\text{Out[411]} = \left\{ \cosh\left[\frac{w}{2}\right]^4, \frac{1}{2}i(1+\cosh[w])\sinh[w], -\frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2, -i\sinh\left[\frac{w}{2}\right]^2\sinh[w], \sinh\left[\frac{w}{2}\right]^4 \right\}$$

$$\text{Out[412]} = \left\{ -\frac{1}{2}i(1+\cosh[w])\sinh[w], \frac{1}{2}(\cosh[w]+\cosh[2w]), i\sqrt{\frac{3}{2}}\cosh[w]\sinh[w], \frac{1}{2}(\cosh[w]-\cosh[2w]), -i\sinh\left[\frac{w}{2}\right]^2\sinh[w] \right\}$$

$$\text{Out[413]} = \left\{ -\frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2, -i\sqrt{\frac{3}{2}}\cosh[w]\sinh[w], \frac{1}{4}(1+3\cosh[2w]), i\sqrt{\frac{3}{2}}\cosh[w]\sinh[w], -\frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 \right\}$$

$$\text{Out[414]} = \left\{ i\sinh\left[\frac{w}{2}\right]^2\sinh[w], \frac{1}{2}(\cosh[w]-\cosh[2w]), -i\sqrt{\frac{3}{2}}\cosh[w]\sinh[w], \frac{1}{2}(\cosh[w]+\cosh[2w]), \frac{1}{2}i(1+\cosh[w])\sinh[w] \right\}$$

$$\text{Out[415]} = \left\{ \sinh\left[\frac{w}{2}\right]^4, i\sinh\left[\frac{w}{2}\right]^2\sinh[w], -\frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2, -\frac{1}{2}i(1+\cosh[w])\sinh[w], \cosh\left[\frac{w}{2}\right]^4 \right\}$$

Out[416]= Ortogonalność

Out[417]= 0

Out[418]= 0

Out[419]= 0

Out[420]= 1



Out[421]= 0

Out[422]= -1

Out[423]= 0

Out[424]= 0

Out[425]= 0

Out[426]= 0

Out[427]= Normalizacja

Out[428]= 1

Out[429]= 1

Out[430]= 1

Out[431]= 1

Out[432]= 1

Out[433]= Macierz stworzona z iloczynu wektorów

Out[434]= {{0, 0, 0, 0, 0}, {0, 0, 0, 0, 0}, {0, 0, 0, 0, 0}, {0, 0, 0, 0, 0}, {0, 0, 0, 0, 0}}

Out[439]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Out[440]= Pchniecie znalezionej macierzy Y i X

Out[441]/MatrixForm=

$$\begin{pmatrix} \sinh\left[\frac{w}{2}\right]^4 & -i \sinh\left[\frac{w}{2}\right]^2 \sinh[w] & 0 & \frac{1}{2} i (1 + \cosh[w]) \sinh[w] & \cosh\left[\frac{w}{2}\right]^4 \\ i \sinh\left[\frac{w}{2}\right]^2 \sinh[w] & \frac{1}{2} (-\cosh[w] + \cosh[2w]) & 0 & \frac{1}{2} (-\cosh[w] - \cosh[2w]) & \frac{1}{2} i (1 + \cosh[w]) \sinh[w] \\ -\frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 & i \sqrt{\frac{3}{2}} \cosh[w] \sinh[w] & 0 & -i \sqrt{\frac{3}{2}} \cosh[w] \sinh[w] & -\frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 \\ -\frac{1}{2} i (1 + \cosh[w]) \sinh[w] & \frac{1}{2} (-\cosh[w] - \cosh[2w]) & 0 & \frac{1}{2} (-\cosh[w] + \cosh[2w]) & -i \sinh\left[\frac{w}{2}\right]^2 \sinh[w] \\ \cosh\left[\frac{w}{2}\right]^4 & -\frac{1}{2} i (1 + \cosh[w]) \sinh[w] & 0 & i \sinh\left[\frac{w}{2}\right]^2 \sinh[w] & \sinh\left[\frac{w}{2}\right]^4 \end{pmatrix}$$

Out[442]/MatrixForm=

$$\begin{pmatrix} \sinh\left[\frac{w}{2}\right]^4 & -\sinh\left[\frac{w}{2}\right]^2 \sinh[w] & 0 & -\frac{1}{2} (1 + \cosh[w]) \sinh[w] & \cosh\left[\frac{w}{2}\right]^4 \\ \sinh\left[\frac{w}{2}\right]^2 \sinh[w] & \frac{1}{2} (\cosh[w] - \cosh[2w]) & 0 & \frac{1}{2} (-\cosh[w] - \cosh[2w]) & \frac{1}{2} (1 + \cosh[w]) \sinh[w] \\ \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 & -\sqrt{\frac{3}{2}} \cosh[w] \sinh[w] & 0 & -\sqrt{\frac{3}{2}} \cosh[w] \sinh[w] & \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 \\ \frac{1}{2} (1 + \cosh[w]) \sinh[w] & \frac{1}{2} (-\cosh[w] - \cosh[2w]) & 0 & \frac{1}{2} (\cosh[w] - \cosh[2w]) & \sinh\left[\frac{w}{2}\right]^2 \sinh[w] \\ \cosh\left[\frac{w}{2}\right]^4 & -\frac{1}{2} (1 + \cosh[w]) \sinh[w] & 0 & -\sinh\left[\frac{w}{2}\right]^2 \sinh[w] & \sinh\left[\frac{w}{2}\right]^4 \end{pmatrix}$$

Out[443]= Pchniecie wektorów własnych znalezionej macierzy Y i X

Out[444]//MatrixForm=

$$\begin{pmatrix} -\cosh\left[\frac{w}{2}\right]^4 - \frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 & -\frac{1}{2}\mathfrak{i}\left(1+\cosh[w]\right)\sinh[w] - \mathfrak{i}\sinh\left[\frac{w}{2}\right]^2\sinh[w] \\ -\mathfrak{i}\sqrt{\frac{3}{2}}\cosh[w]\sinh[w] - \frac{1}{2}\mathfrak{i}\left(1+\cosh[w]\right)\sinh[w] & \frac{1}{2}\left(-\cosh[w]+\cosh[2w]\right) + \frac{1}{2}\left(\cosh[w]+\cosh[2w]\right) \\ \frac{1}{4}\left(1+3\cosh[2w]\right) + \frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 & \mathfrak{i}\sqrt{6}\cosh[w]\sinh[w] \\ \mathfrak{i}\sqrt{\frac{3}{2}}\cosh[w]\sinh[w] + \mathfrak{i}\sinh\left[\frac{w}{2}\right]^2\sinh[w] & \frac{1}{2}\left(-\cosh[w]-\cosh[2w]\right) + \frac{1}{2}\left(\cosh[w]-\cosh[2w]\right) \\ -\sinh\left[\frac{w}{2}\right]^4 - \frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 & -\frac{1}{2}\mathfrak{i}\left(1+\cosh[w]\right)\sinh[w] - \mathfrak{i}\sinh\left[\frac{w}{2}\right]^2\sinh[w] \end{pmatrix}$$

Out[445]//MatrixForm=

$$\begin{pmatrix} -\cosh\left[\frac{w}{2}\right]^4 + \frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 & \frac{1}{2}\left(1+\cosh[w]\right)\sinh[w] - \sinh\left[\frac{w}{2}\right]^2\sinh[w] \\ \sqrt{\frac{3}{2}}\cosh[w]\sinh[w] - \frac{1}{2}\left(1+\cosh[w]\right)\sinh[w] & \frac{1}{2}\left(\cosh[w]-\cosh[2w]\right) + \frac{1}{2}\left(\cosh[w]+\cosh[2w]\right) \\ \frac{1}{4}\left(1+3\cosh[2w]\right) - \frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 & 0 \\ \sqrt{\frac{3}{2}}\cosh[w]\sinh[w] - \sinh\left[\frac{w}{2}\right]^2\sinh[w] & \frac{1}{2}\left(-\cosh[w]-\cosh[2w]\right) + \frac{1}{2}\left(-\cosh[w]+\cosh[2w]\right) \\ -\sinh\left[\frac{w}{2}\right]^4 + \frac{1}{2}\sqrt{\frac{3}{2}}\sinh[w]^2 & -\frac{1}{2}\left(1+\cosh[w]\right)\sinh[w] + \sinh\left[\frac{w}{2}\right]^2\sinh[w] \end{pmatrix}$$

Out[446]= Pchnięcia X

$$\begin{aligned}
\text{Out[447]} = & \left\{ \left\{ \cosh\left[\frac{w}{2}\right]^4, \frac{1}{2} (1 + \cosh[w]) \sinh[w], \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2, \sinh\left[\frac{w}{2}\right]^2 \sinh[w], \sinh\left[\frac{w}{2}\right]^4 \right\}, \right. \\
& \left\{ \frac{1}{2} (1 + \cosh[w]) \sinh[w], \frac{1}{2} (\cosh[w] + \cosh[2w]), \right. \\
& \left. \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \frac{1}{2} (-\cosh[w] + \cosh[2w]), \sinh\left[\frac{w}{2}\right]^2 \sinh[w] \right\}, \\
& \left\{ \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2, \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \frac{1}{4} (1 + 3 \cosh[2w]), \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \right. \\
& \left. \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 \right\}, \left\{ \sinh\left[\frac{w}{2}\right]^2 \sinh[w], \frac{1}{2} (-\cosh[w] + \cosh[2w]), \right. \\
& \left. \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \frac{1}{2} (\cosh[w] + \cosh[2w]), \frac{1}{2} (1 + \cosh[w]) \sinh[w] \right\}, \\
& \left. \left\{ \sinh\left[\frac{w}{2}\right]^4, \sinh\left[\frac{w}{2}\right]^2 \sinh[w], \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2, \frac{1}{2} (1 + \cosh[w]) \sinh[w], \cosh\left[\frac{w}{2}\right]^4 \right\} \right\}
\end{aligned}$$

Out[448]/MatrixForm=

$$\begin{pmatrix}
\cosh\left[\frac{w}{2}\right]^4 & \frac{1}{2} (1 + \cosh[w]) \sinh[w] & \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 & \sinh\left[\frac{w}{2}\right]^2 \sinh[w] \\
\frac{1}{2} (1 + \cosh[w]) \sinh[w] & \frac{1}{2} (\cosh[w] + \cosh[2w]) & \sqrt{\frac{3}{2}} \cosh[w] \sinh[w] & \frac{1}{2} (-\cosh[w] + \cosh[2w]) \\
\frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 & \sqrt{\frac{3}{2}} \cosh[w] \sinh[w] & \frac{1}{4} (1 + 3 \cosh[2w]) & \sqrt{\frac{3}{2}} \cosh[w] \sinh[w] \\
\sinh\left[\frac{w}{2}\right]^2 \sinh[w] & \frac{1}{2} (-\cosh[w] + \cosh[2w]) & \sqrt{\frac{3}{2}} \cosh[w] \sinh[w] & \frac{1}{2} (\cosh[w] + \cosh[2w]) \\
\sinh\left[\frac{w}{2}\right]^4 & \sinh\left[\frac{w}{2}\right]^2 \sinh[w] & \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 & \frac{1}{2} (1 + \cosh[w]) \sinh[w]
\end{pmatrix}$$

Out[449]= Kolumny macierzy obrotu o X

$$\text{Out[450]} = \left\{ \cosh\left[\frac{w}{2}\right]^4, \frac{1}{2} (1 + \cosh[w]) \sinh[w], \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2, \sinh\left[\frac{w}{2}\right]^2 \sinh[w], \sinh\left[\frac{w}{2}\right]^4 \right\}$$

$$\begin{aligned}
\text{Out[451]} = & \left\{ \frac{1}{2} (1 + \cosh[w]) \sinh[w], \frac{1}{2} (\cosh[w] + \cosh[2w]), \right. \\
& \left. \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \frac{1}{2} (-\cosh[w] + \cosh[2w]), \sinh\left[\frac{w}{2}\right]^2 \sinh[w] \right\}
\end{aligned}$$

$$\text{Out[452]} = \left\{ \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2, \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \right.$$

$$\left. \frac{1}{4} (1 + 3 \cosh[2w]), \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2 \right\}$$

$$\text{Out[453]} = \left\{ \sinh\left[\frac{w}{2}\right]^2 \sinh[w], \frac{1}{2} (-\cosh[w] + \cosh[2w]), \right.$$

$$\left. \sqrt{\frac{3}{2}} \cosh[w] \sinh[w], \frac{1}{2} (\cosh[w] + \cosh[2w]), \frac{1}{2} (1 + \cosh[w]) \sinh[w] \right\}$$

$$\text{Out[454]} = \left\{ \sinh\left[\frac{w}{2}\right]^4, \sinh\left[\frac{w}{2}\right]^2 \sinh[w], \frac{1}{2} \sqrt{\frac{3}{2}} \sinh[w]^2, \frac{1}{2} (1 + \cosh[w]) \sinh[w], \cosh\left[\frac{w}{2}\right]^4 \right\}$$

Out[455]= **Ortogonalność**

Out[456]= **0**

Out[457]= **0**

Out[458]= **0**

Out[459]= **1**

Out[460]= **0**

Out[461]= **-1**

Out[462]= **0**

Out[463]= **0**

Out[464]= **0**

Out[465]= **0**

Out[466]= **Sprawdzenie czy dla pchnięcia w X była by taka sama macierz, jak widać TAK**