

//功能：给定平面数据点的最小二乘B样条曲线逼近。

//输入参数：(m_xDVertex, m_yDVertex)-双精度数组给出的数据点；数据点数由m_xDVertex.GetSize()确定；m_aU-数据点参数化给出的双精度数组；m_nCtrl0-控制顶点数；m_Degree-逼近曲线次数。m_aNode-节点矢量双精度数组，求B样条基函数调用。都是受保护成员或公有成员。

//输出参数：(m_xAVertex, m_yAVertex)- B样条逼近曲线的控制顶点，受保护成员；Singular-若为true,表示线性方程组系数矩阵奇异。

//调用函数：GetBaseFunVal-求B样条基函数，见7.1.2节；agjdn-全选主元高斯-约当消去法解线性代数方程组，参考文献[79]改造而来。

```
void BsplineCuvApprox()
{
    int i0, i1;
    int n= m_xDVertex.GetSize()-1;
    CArray<double, double> Rx, Ry, a, b;
    CArray<CArray<double, double>, CArray<double, double>&> N;
    CArray<CArray<double, double>, CArray<double, double>&> F;
    a.SetSize((m_nCtrl0-1)*(m_nCtrl0-1));
    b.SetSize(2*(m_nCtrl0-1));
    N.SetSize(n-1);
    for(i0=0; i0<=n-2; i0++) N[i0].SetSize(m_nCtrl0-1);
    Rx.SetSize(n-1);    Ry.SetSize(n-1);
    m_xAVertex.SetSize(m_nCtrl0+1);    m_yAVertex.SetSize(m_nCtrl0+1);
    F.SetSize(m_nCtrl0-1);
    for(i0=0; i0<=m_nCtrl0-2; i0++) F[i0].SetSize(m_nCtrl0-1);
    for(i0=1; i0<=n-1; i0++)
    {
        for(int j=1; j<=m_nCtrl0-1; j++)
        {
            N[i0-1][j-1]=GetBaseFunVal(m_aU[i0], j, m_Degree);
        }
    }
    for(i0=0; i0<=m_nCtrl0-2; i0++)
    {
        for(int j=0; j<=m_nCtrl0-2; j++)
        {
            F[i0][j]=0.;
            for(int jj=0; jj<=n-2; jj++)
            {
                F[i0][j]=F[i0][j]+N[jj][i0]*N[jj][j];
            }
        }
    }
    for(i1=0; i1<=m_nCtrl0-2; i1++)
    {
        for(int j1=0; j1<=m_nCtrl0-2; j1++)    a[i1*(m_nCtrl0-1)+j1]=F[i1][j1];
    }
    for(i0=1; i0<=n-1; i0++)
    {
        double B0=GetBaseFunVal(m_aU[i0], 0, m_Degree);
        double Bn=GetBaseFunVal(m_aU[i0], m_nCtrl0, m_Degree);
        Rx[i0-1]=m_xDVertex[i0]-(B0*m_xDVertex[0]+Bn*m_xDVertex[n]);
        Ry[i0-1]=m_yDVertex[i0]-(B0*m_yDVertex[0]+Bn*m_yDVertex[n]);
    }
    for(int j=0; j<=m_nCtrl0-2; j++)
    {
        m_xAVertex[j]=0.;
        m_yAVertex[j]=0.;
        for(int i1=0; i1<=n-2; i1++)
        {
            m_xAVertex[j]=m_xAVertex[j]+N[i1][j]*Rx[i1];
            m_yAVertex[j]=m_yAVertex[j]+N[i1][j]*Ry[i1];
        }
    }
    for(i1=0; i1<=m_nCtrl0-2; i1++)
    {
        b[i1*2]=m_xAVertex[i1];
        b[i1*2+1]=m_yAVertex[i1];
    }
    if(agjdn(a, b, m_nCtrl0-1, 2)!=0)
    {
        for(i1=1; i1<=m_nCtrl0-1; i1++)
        {
            m_xAVertex[i1]=b[(i1-1)*2];
            m_yAVertex[i1]=b[(i1-1)*2+1];
        }
    }
}
```

BsplineCuvApprox.txt

```
m_xAVertex[0]=m_xDVertex[0];
m_yAVertex[0]=m_yDVertex[0];
m_xAVertex[m_nCtrl0]=m_xDVertex[n];
m_yAVertex[m_nCtrl0]=m_yDVertex[n];
}
else
{
    Singular=true;
    return;
}
}
```