

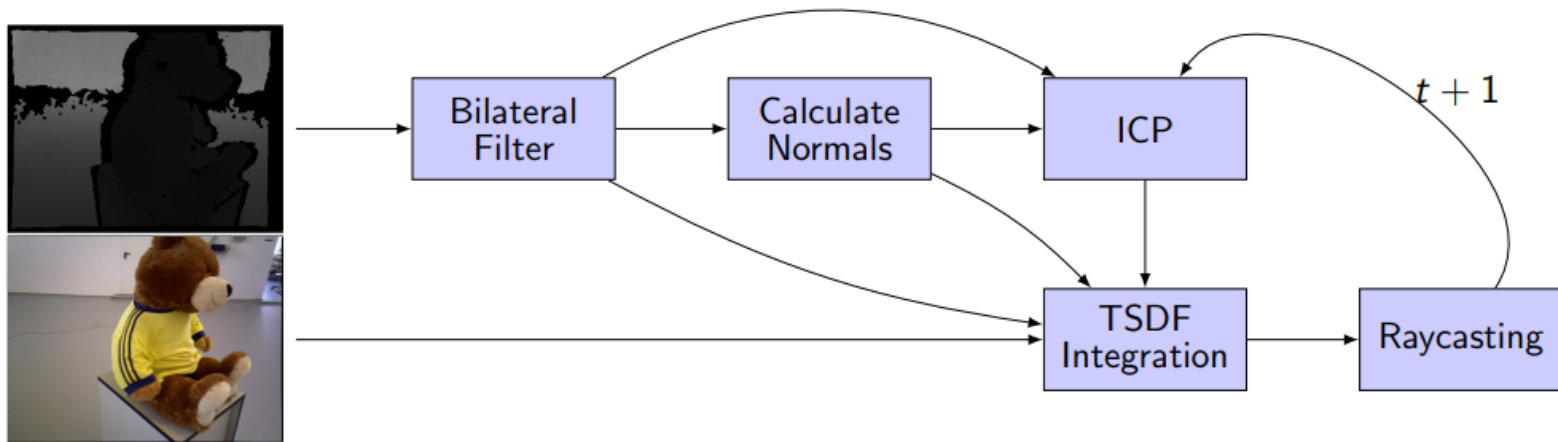
Mapping-TSDF

April. 14, 2019

김하영

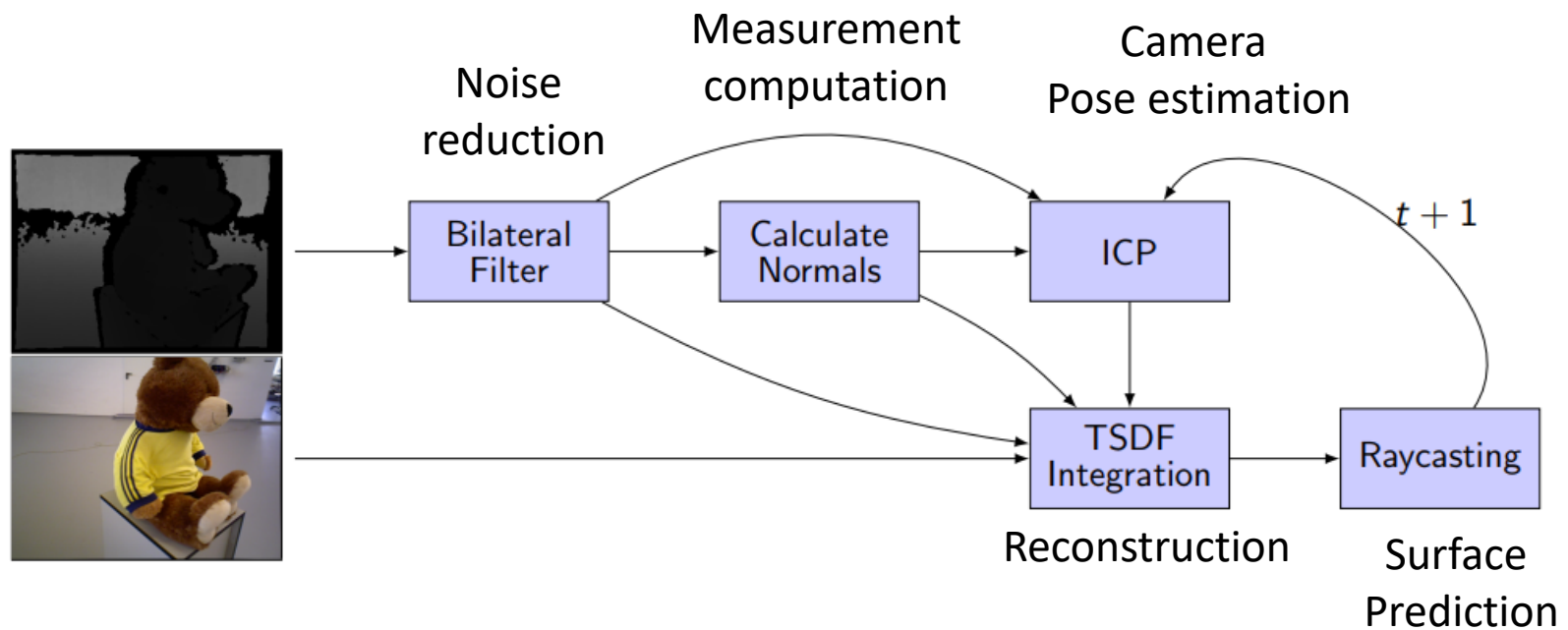
3D Reconstruction

- From (RGB-)D images to 3D voxel grid

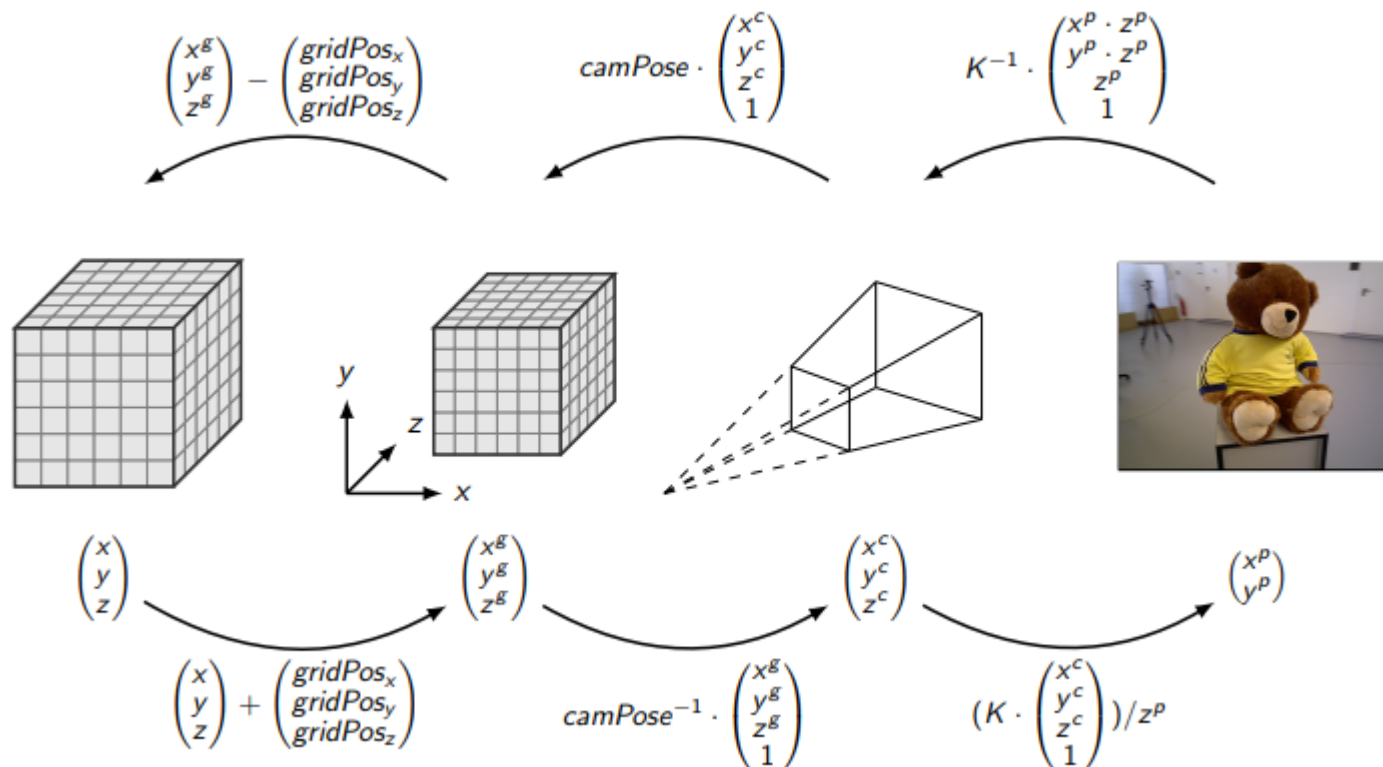


3D Reconstruction

- From (RGB-)D images to 3D voxel grid

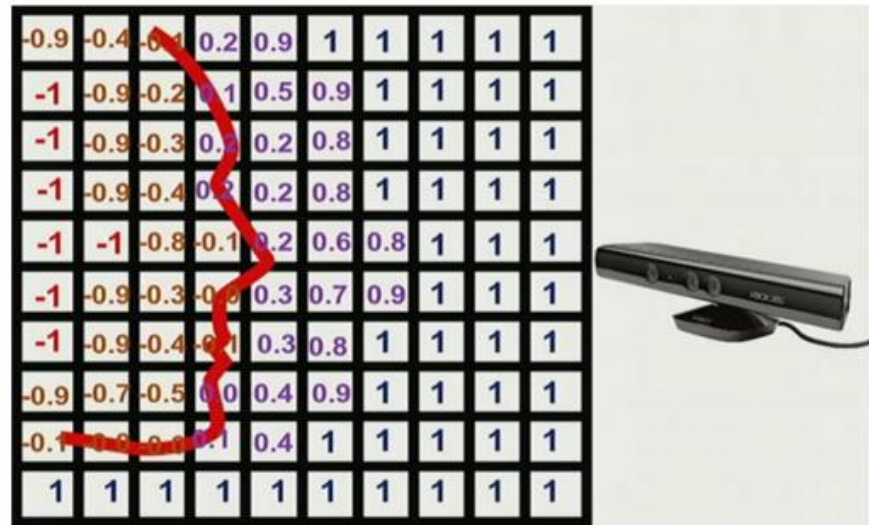
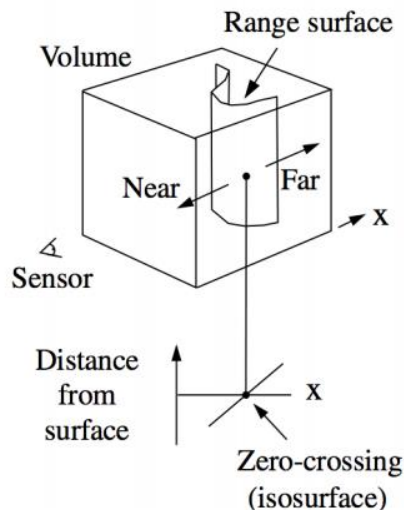


Transformations between the different coordinate systems



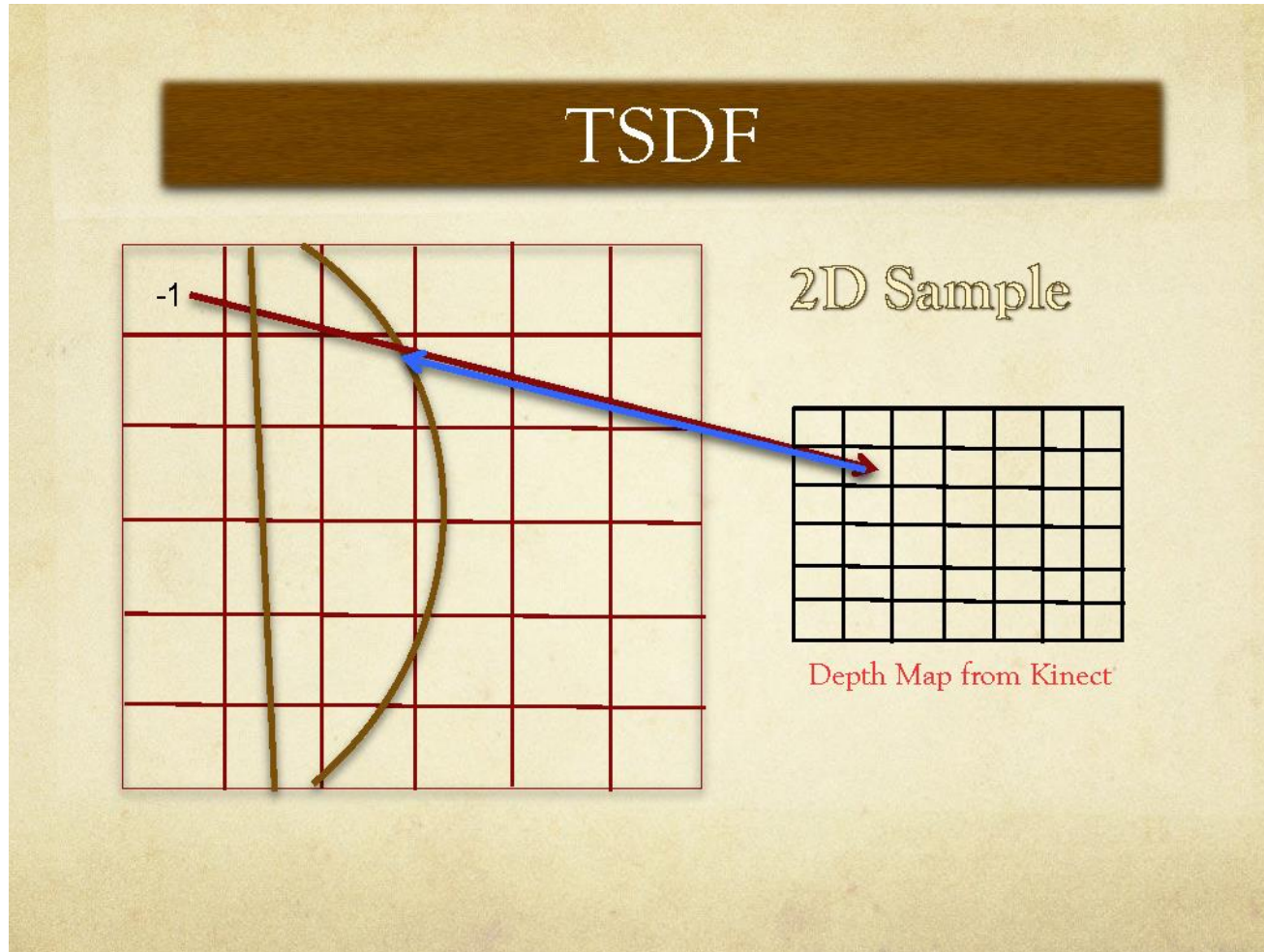
TSDF

- Truncated Signed Distance Function (TSDF)
 - Signed distance function
 - Distance of the closest zero crossing (surface)
 - Truncated signed distance function
 - Subtract it from the distance of the voxel itself and divide by the truncation threshold



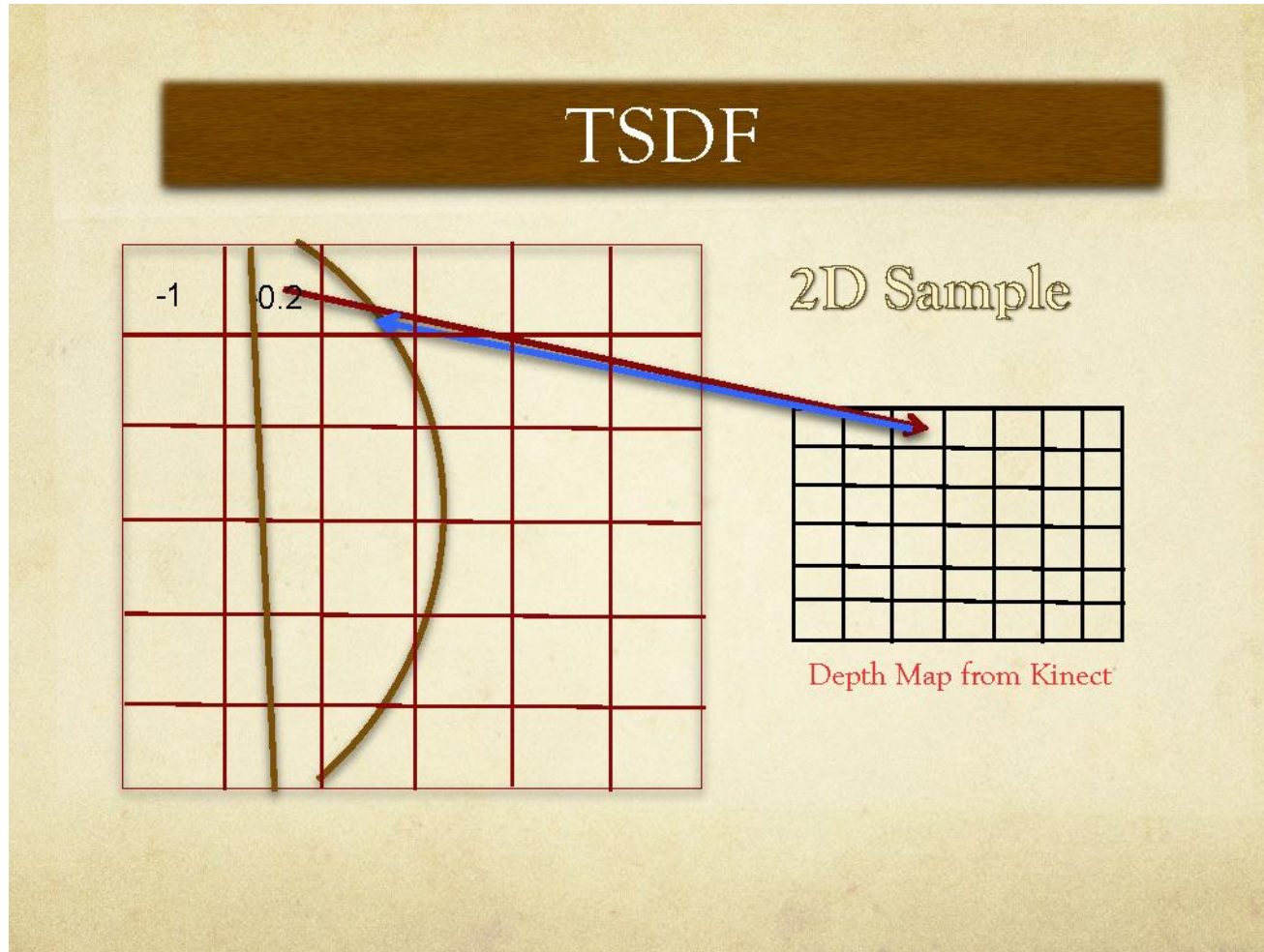
TSDF

- Build TSDF



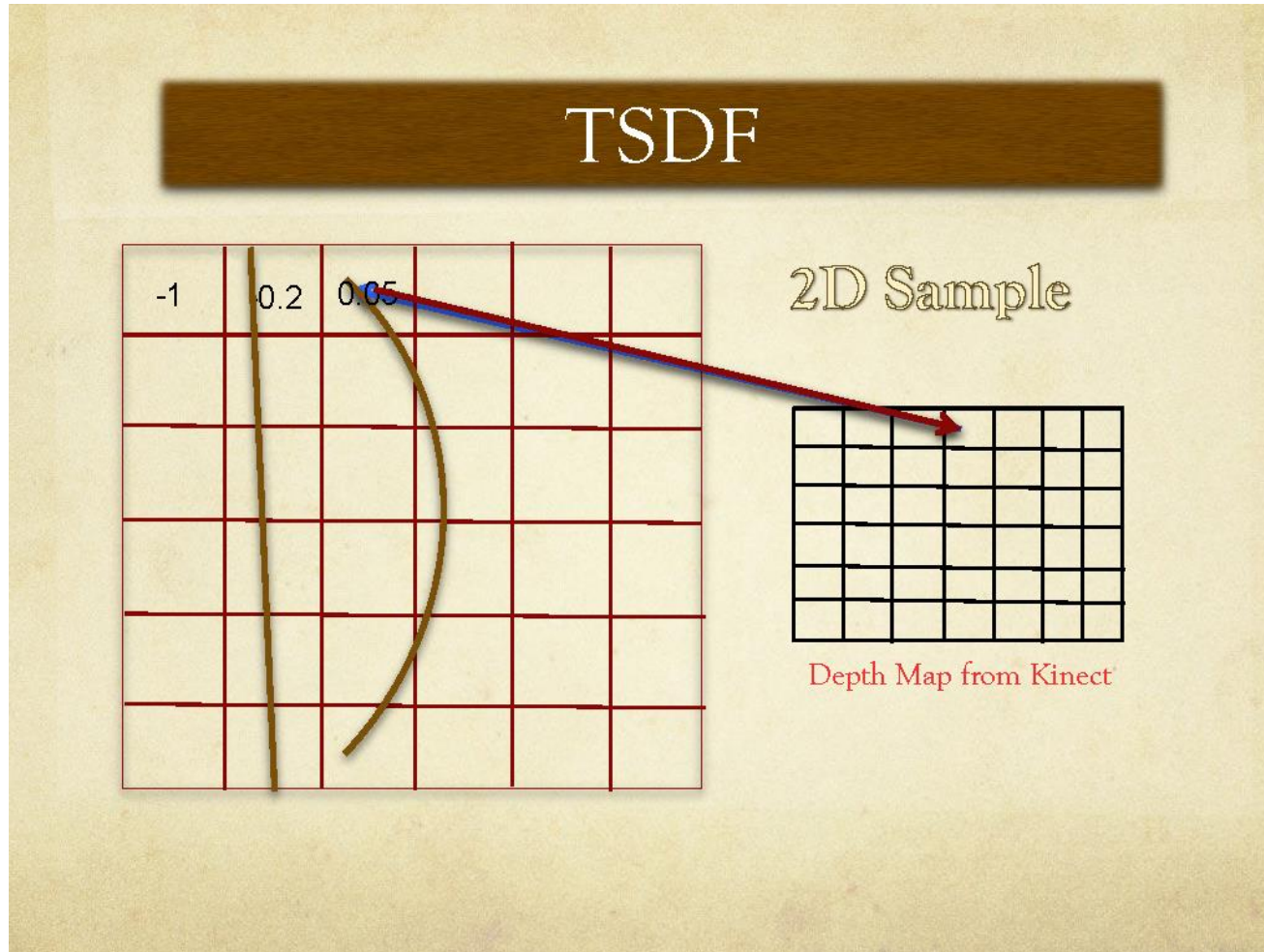
TSDF

- Build TSDF



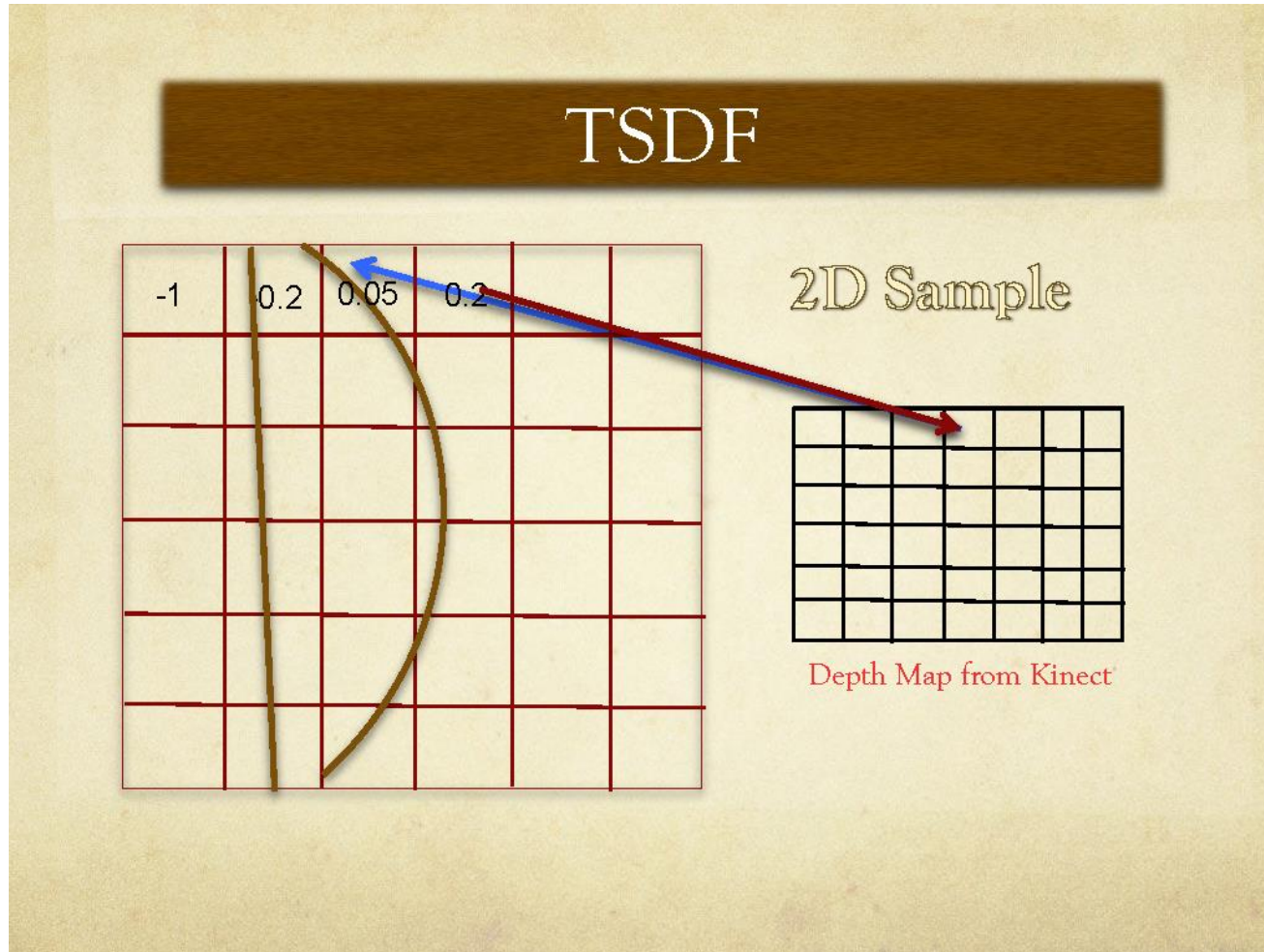
TSDF

- Build TSDF



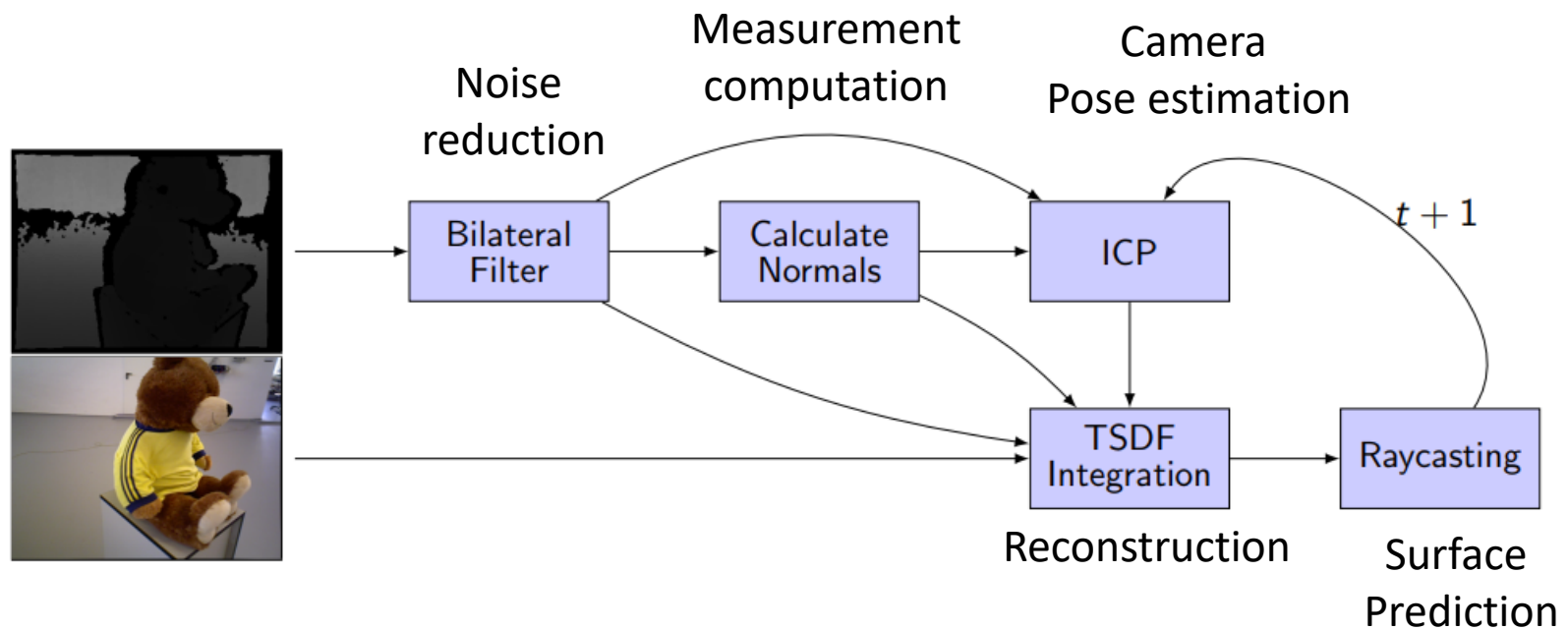
TSDF

- Build TSDF



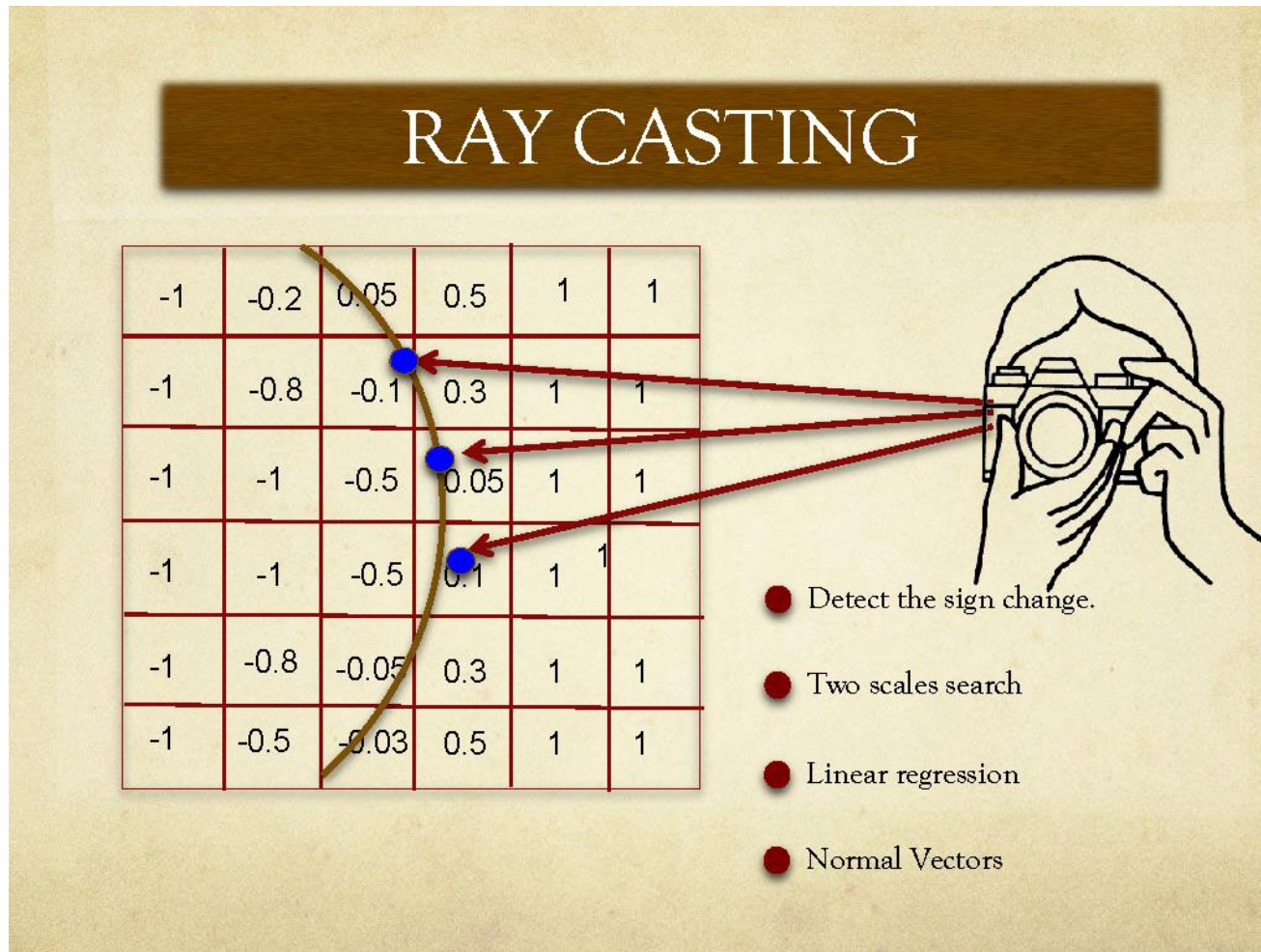
Overview

- From (RGB-)D images to 3D voxel grid



Raycasting

- From TSDF Voxel map to normal vectors



Results



Exponential falloff



Linear falloff



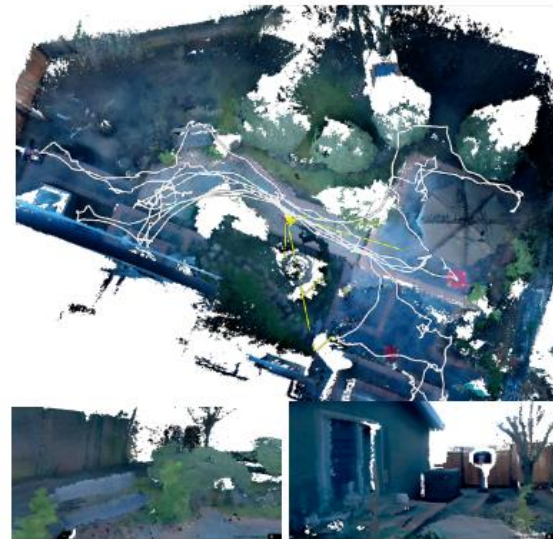
No falloff

Open sources

- Volumetric TSDF Fusion of RGB-D Images in Python (2018)
 - <https://github.com/andyzeng/tsdf-fusion-python>
 - GPU (CUDA)
- CHISEL: Real Time Large Scale 3D Reconstruction Onboard a Mobile Device using Spatially-Hashed Signed Distance Fields (RSS 2015)
 - <https://github.com/personalrobotics/OpenChisel>
 - CPU



Volumetric TSDF Fusion of RGB-D Images in Python



CHISEL Result

Thank you



Q&A