

# Ray Tracing in Entertainment Industry

Tanaboon Tongbuasirilai  
Dept. Computer Science  
Kasetsart University

Week 3  
Image formation and rays

Image  
formation  
and rays

---

Camera and Lens classes

---

Ray class

---

Utility class

# 1. Recapped – Basic camera components



[www.photographyaxis.com](http://www.photographyaxis.com)

- Image plane, sensor
- Shutter
- Aperture
- Lens

# Camera class

- Attributes
  - Image width and height
  - Aspect ratio
  - Field of view
  - Camera center or look from (position)
  - Camera look at (position)
  - Camera Lens
  - Viewport width and height
  - Camera frame coordinates
  - Delta pixel (spacing between each pixel)
  - Film or image sensor

Image C1

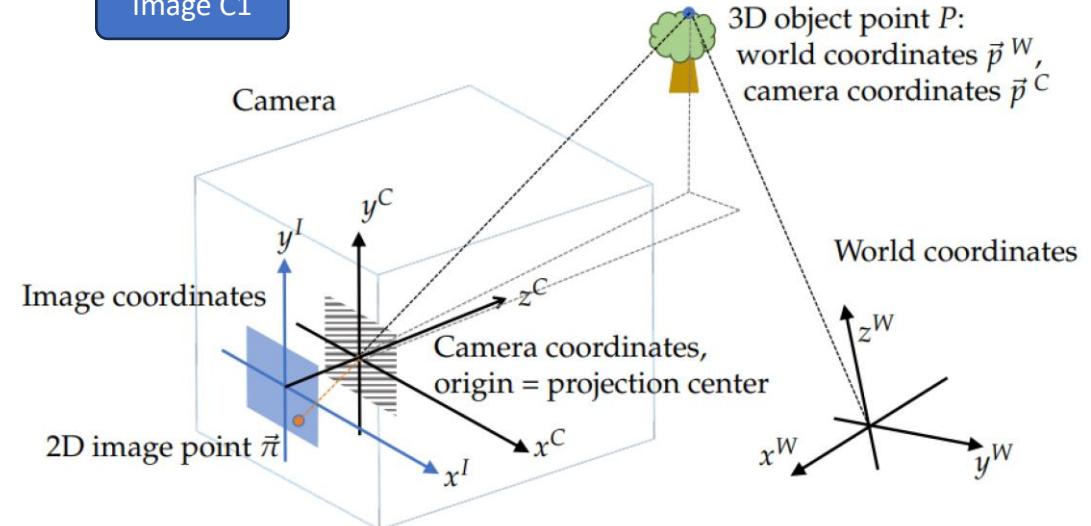
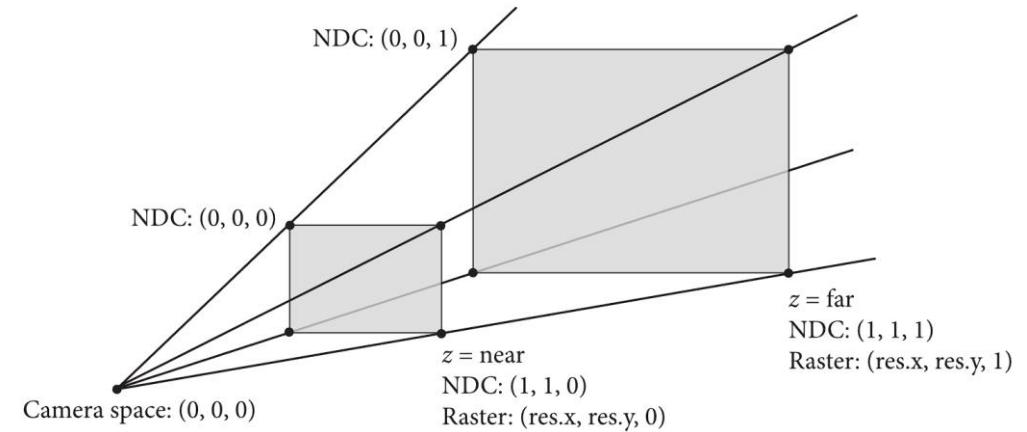
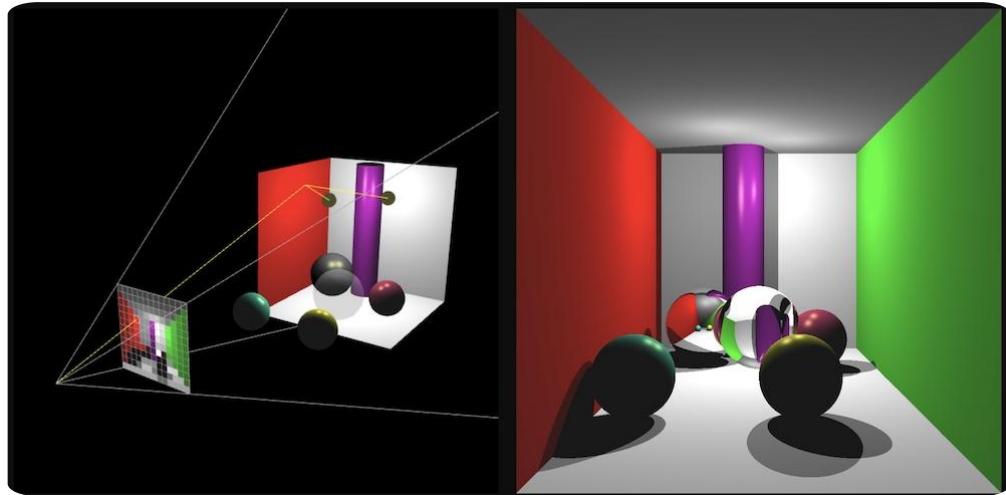


Image C2

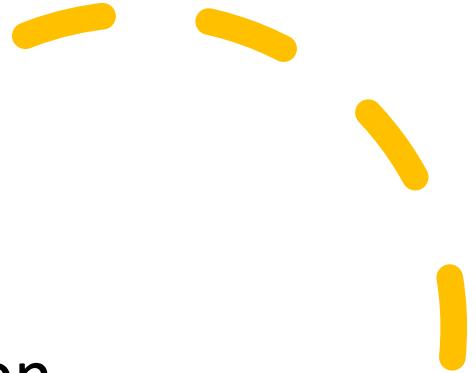




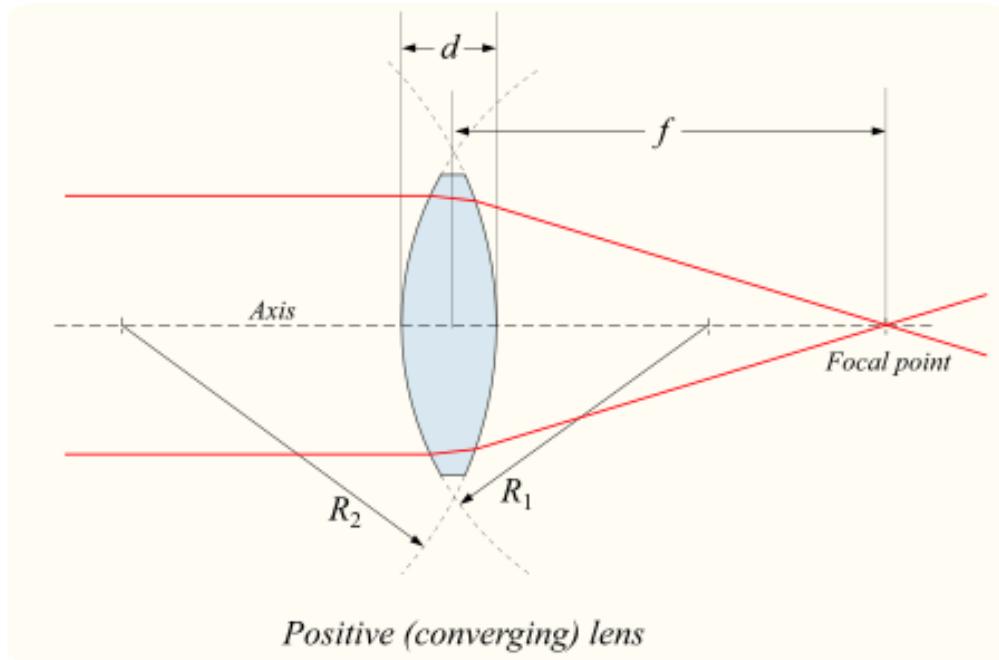
## Camera class (cont.)



- Methods
  - Lens setup
  - Camera setup
  - Ray shooting
  - Film writing



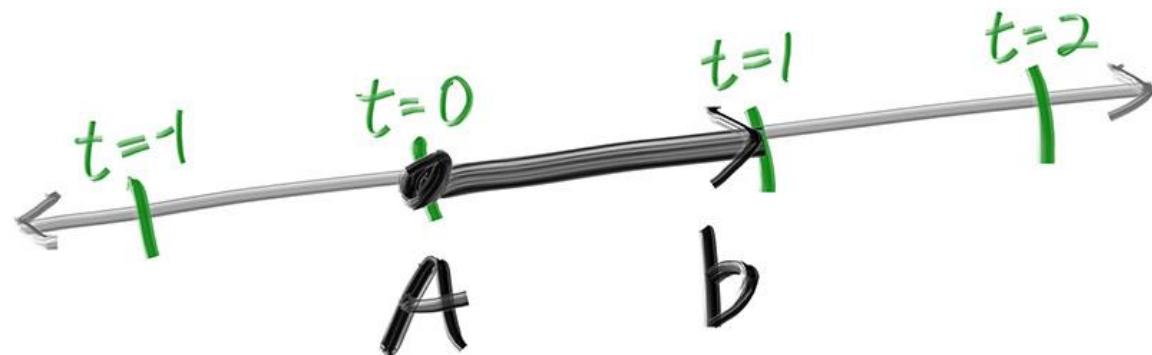
# Lens class



- This Lens approximation
  - Attributes
    - Defocus angle
    - Focus distance
  - Methods will be later explained in a late chapter.

# Ray class

---



- Attributes
  - Origin : ray origin position (in 3d)
  - Direction : ray direction (in 3d)
- Methods
  - Ray at t : To compute where a ray position is given time t.

# Utility classes



Vector class

Define cartesian coordinates



Color class

Define color spectrum (RGB or multi spectrum)



Interval class

Handle a value in a specified range.



Hit info class

Keep information of the ray intersection.

# Vector class

---

- Name : Vec3
- Attributes
  - Array e[3]
- Methods
  - Coordinate values : x(), y(), z()
  - Length of a vector
  - Unit vector / normalize
  - Dot product
  - Cross product
  - Mathematical binary operations : + - \* / (add, minus, multiply, div)
  - Unary operation : - (negation)

# Color class

---

- Vec3 as a base (parent) class
- Color is a child class of Vec3
- Attributes
  - Array e[3] (derived from Vec3)
- Methods
  - RGB color : r(), g(), b()
  - Binary operations : + - \* /
  - Unary operation : negation
  - Conversion : ex. [0,1) --> [0, 255]

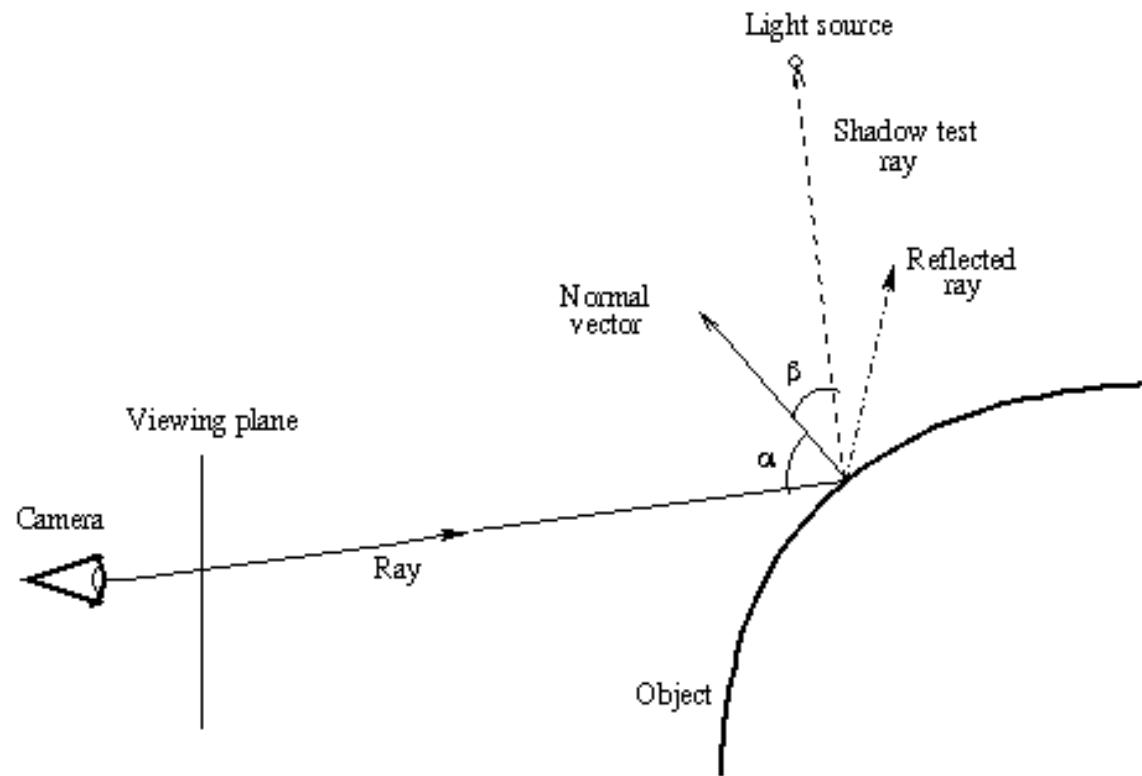
# Interval class

---

- Limit any arbitrary scalar value in the range.
- Attributes
  - Min value
  - Max value
- Methods
  - Is the value inside ?
  - Is the value bounded ?
  - Is the value near zero ?
  - Clamping the value
  - Empty interval
  - Unlimited interval

# Hit info class

- Point of intersection.
- When the intersected ray hits.
- Surface normal at the intersection point.
- What material is hit.
- Is it front face or back face ?



# Static method

---

A static method is a class method which can be called without instantiating.

---

A non-static method is a class method which can be called from instances of the class.

# Image writer (python)

- Python imaging library (PIL)
  - <https://pypi.org/project/Pillow/>

- Example (python)

```
from PIL import Image as im
png_film[y,x,color] = color
data = im.fromarray(png_film.astype(np.uint8))
data.save(strPng_filename)
```

# 8-bit color

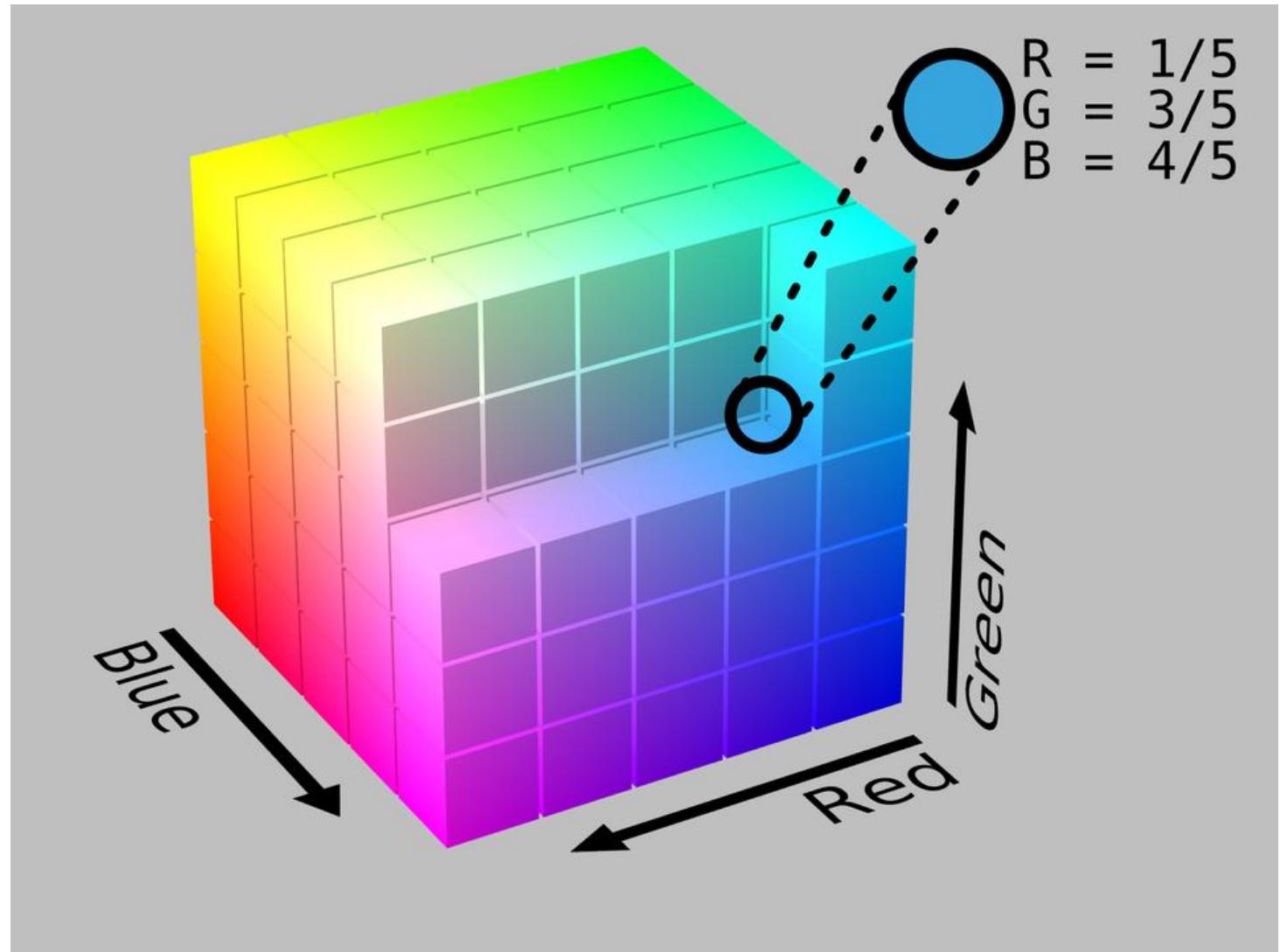
---

- Each color channel has 256 values.
- 8-bit RGB color ~ 16m colors.
- Color ranging from [0,1] --> [0,255].
- Clamping is sometimes needed.

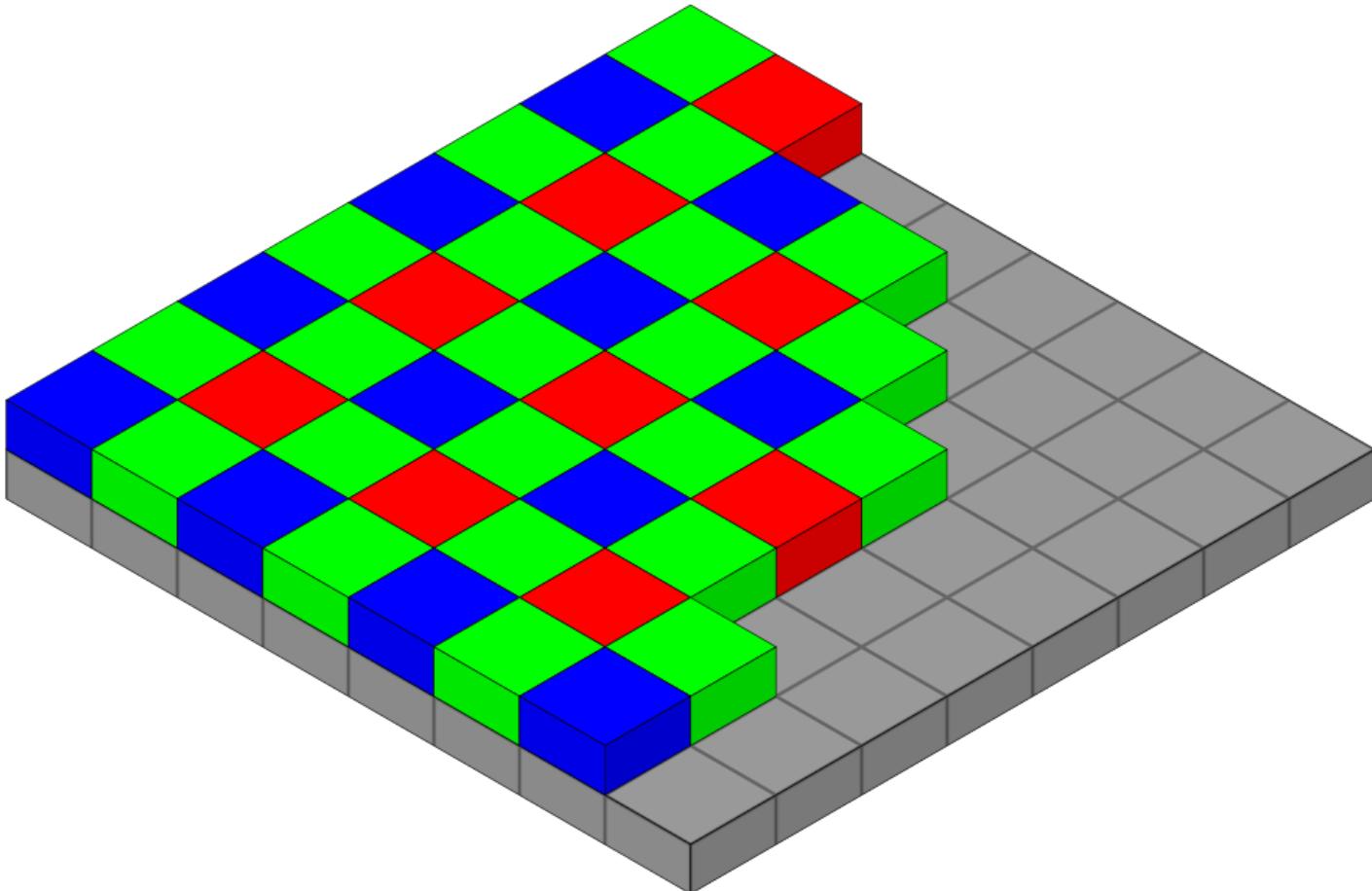
Notation	RGB triplet
Arithmetic	(1.0, 0.0, 0.0)
Percentage	(100%, 0%, 0%)
Digital 8-bit per channel	(255, 0, 0) #FF0000 (hexadecimal)
Digital 12-bit per channel	(4095, 0, 0) #FFF000000
Digital 16-bit per channel	(65535, 0, 0) #FFFF00000000
Digital 24-bit per channel	(16777215, 0, 0) #FFFFFF000000000000
Digital 32-bit per channel	(4294967295, 0, 0) #FFFFFFFF0000000000000000

# RGB Color space

- An RGB triplet describes the exact position of a specific color in a 3D color cube.
- Each number in the triplet (red, green, blue) corresponds to a coordinate, locating the color either inside the cube, on its surfaces, or along its edges.



# A Bayer filter mosaic in image sensor



- Cameras typically employ various **demosaicing algorithms** to reconstruct a full-color image from the incomplete color information captured by the image sensor.
- The image sensor usually has a **Bayer filter array**, which means each pixel only records one color (red, green, or blue).
- **Demosaicing** is the process of interpolating the missing color information for each pixel based on its neighbors.

# Shooting a ray (Class assignment (3.))

Shoot

Shoot a ray at the center of the pixel.

- `get_center_ray()`

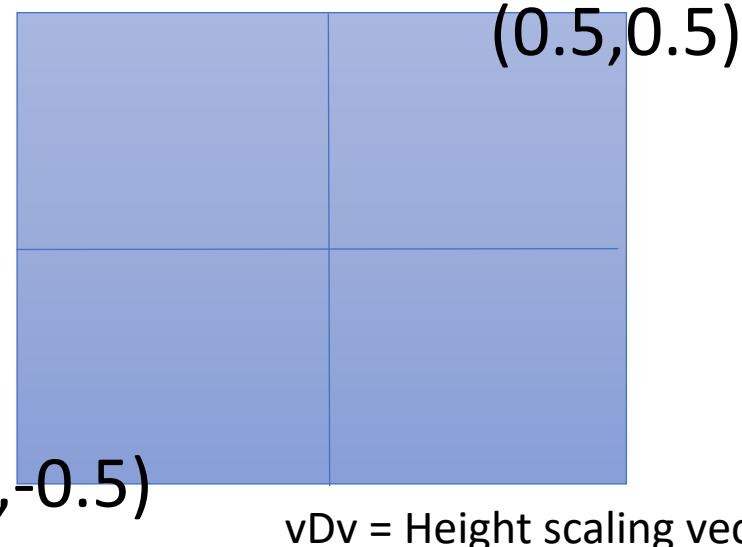
Shoot

Shoot a ray at a random location inside the pixel.

- `get_ray()`

# Shoot a ray at a random location

- Random a location inside a rectangle.
- Method : `random_pixel_in_square(vDu, vDv)`
- Pixel center is at (0,0)
- Pixel corners are (-0.5,-0.5) (-0.5,0.5) (0.5,-0.5) (0.5,0.5).



# Renderer class

- Regarding the class diagram, the renderer defines how we combine all ray tracing components.
- For now, it includes the following instances
  - Camera
- We also need to implement some functions to manage
  - Background color
  - Ray color
  - Simple ray intersection
- See RT\_renderer.py

# Codes and class assignment!

---

- Github : RT-python-week03
  - <https://github.com/KUGA-01418283-Raytracing/RT-python-week03>

