UHURA & DIRC in the box Version 2



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1 Overview GPS-system "DIRC in the box / UHURA"



Figure 1: GPS-Antenna "UHURA"

Exact timing is a vital part of most fields of research. The most commonly used method of synchronization today is GPS. But many cheaper GPS receivers lack a pulse-per-second (PPS) signal and their time usually has high latency and jitter. The GNSS antenna "UHURA" is designed to receive GPS, GLONASS and GALILEO. It's BEIDOU-ready.

"UHURA" provides NMEA-data using RS485 with both 4800 baud and 9600 baud. Inside DIRc the signal is converted to RS232. An extra line provides a latency-free, DCF77 encoded PPS signal. On top of the second pulse the DCF77-Signal is encoded. This way you can synchronize systems that would otherwise need an extra radio receiver.

"UHURA" is delivered in a watertight housing and can be equipped with cables up to 100m length.



Figure 2: DIRC in the box

The central control center in the lab is called "DIRC in the box". "DIRC" provides power to "UHURA" and collects the GPS data. To communicate with the data logger, connect a PC and the seismic data logger "6D6" to "DIRC". You can also download the data with "DIRC". Finally, the data logger "6D6" can establish a WiFi access-point to communicate with the data logger using any WiFi device.

Size

| | Size | Cable length | Weight | IP code |
|-------|------------------------------|----------------|--------|---------|
| DIRC | 220 x 180 x 95 mm | 1m | 1700g | IP54 |
| UHURA | $D 140 \times 90 \text{ mm}$ | 30m, 50m, 100m | 800g | IP67 |

2 Internal Structure DIRC

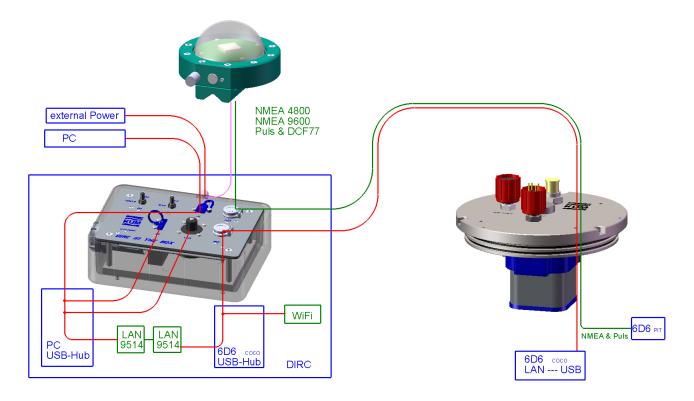


Figure 3: How DIRC works

In figure 3, you can see all functional components and wires from "DIRC in the box". All internal parts of "DIRC" are powered by USB from a PC while "UHURA" is powered either by the external power supply or by the internal battery. If the external power supply is used, the internal battery is charged simultaneously.



"DIRC" is equipped with a lithium-ion rechargeable battery (3.7V Li-Mn 3000mAh). For safe transport the battery can be removed. The picture above shows the endcap of the battery.

3 Pinout

3.1 Description of the connections



| Number | Connection | No. of Pins | Description | | |
|--------|------------|-------------|---------------------------------------------------|--|--|
| 1 | Power | 5 | External Power Supply | | |
| 2 | Battery | _ | Lithium rechargable, can be removed for transport | | |
| 3 | ON/OFF | _ | Switches power on ¹ | | |
| 4 | WiFi | _ | Switches WiFi on | | |
| 5 | PC | 4 | Connects internal USB hub to PC | | |
| 6 | GPS | 8 | Socket for GPS antenna "UHURA" | | |
| 7 | SD | 9 | Socket for SD card to download the data | | |
| 8 | StiK | 12 | Socket for $StiK^{TM}$ to download the data | | |
| 9 | 6D6 | 16 | Communication with the datalogger | | |
| 10 | Battery | _ | Charge control | | |

¹ This switches on the power supply for "UHURA" and boots the data logger "6D6". The sockets for StiKTM, SD card and USB are connected to the USB hub. In addition, an USB-ethernet-device for data logger communication is attached to the hub. For charging the internal battery, the external power supply needs to be attached.

3.2 8-pin Socket "GPS" for communication with "UHURA"

| Pin | Purpose | Source | Description |
|-----|-------------|--------|---------------------------------|
| 1 | Vcc | DIRC | 12 Volt |
| 2 | PPS - | UHURA | Second pulse minus ² |
| 3 | PPS + | UHURA | Second pulse plus |
| 4 | NMEA - 9600 | UHURA | NMEA 9600 baud minus |
| 5 | NMEA + 9600 | UHURA | NMEA 9600 baud plus |
| 6 | NMEA - 4800 | UHURA | NMEA 4800 baud minus |
| 7 | NMEA + 4800 | UHURA | NMEA 4800 baud plus |
| 8 | GND | DIRC | Signal Ground |

 $^{^2}$ RS485 is used for communication with the antenna, therefore a pair of cables is used for each signal line.

3.3 16-pin Socket "6D6" for datalogger communication

| Pin | Purpose | Source | Description | | |
|-----|-----------|--------|---------------------------------------------------------|--|--|
| 1 | NMEA 9600 | DIRC | NMEA with 9600 baud 1 | | |
| 2 | 1 PPS | DIRC | Pulse-per-second from GPS 2 | | |
| 3 | AGND | DIRC | Signal Ground GPS | | |
| 4 | Vcc USB | 6D6 | 5V USB | | |
| 5 | USB-DN | 6D6 | USB Data line | | |
| 6 | USB-DP | 6D6 | USB Data line | | |
| 7 | USB-GND | 6D6 | Signal Ground USB | | |
| 8 | VBAT2 | 6D6 | Vdd from the battery pack inside the pressure tube 3 | | |
| 9 | VCNC | DIRC | Vdd back to web server ³ | | |
| 10 | NMEA 4800 | DIRC | NMEA with 4800 baud 4 | | |
| 11 | _ | _ | _ | | |
| 12 | _ | _ | _ | | |
| 13 | _ | _ | | | |
| 14 | _ | _ | _ | | |
| 15 | _ | _ | _ | | |
| 16 | _ | _ | _ | | |

 $^{^{1}}$ 3.3V UART

 $^{^2}$ There is a DCF77-signal coded on top of the – latency free – second pulse to synchronize

systems that require a radio signal instead.

4 Meaning of the LED's: DIRC

| LED | Status | Description | | |
|----------|----------|------------------------------------------------------|--|--|
| Power | green | System is switched on | | |
| | off | System is switched off but battery can be charged | | |
| WiFi | green | WiFi is switched on | | |
| | off | WiFi is switched off | | |
| PC | green | USB Hub is powered by PC or power supply | | |
| | off | USB hub not powered | | |
| GPS | green | GPS connected, but no GPS Fix yet | | |
| | flashing | GPS signal is valid ¹ | | |
| | off | GPS not connected | | |
| BATTERY | green | External power, battery is charged / trickle charged | | |
| | red | Battery powers "DIRC" | | |
| | off | Not in use | | |
| SD green | | SD card is attached | | |
| | flashing | Data download from SD card | | |
| | off | No SD card attached | | |
| StiK | green | $\mathrm{StiK^{TM}}$ is attached | | |
| | flashing | Data download from $StiK^{TM}$ | | |
| | off | No $StiK^{TM}$ is attached | | |
| 6D6 | green | Connection between web server and PC | | |
| | flashing | Communication between web server and PC | | |
| | off | Web server not connected or connection using WiFi | | |

¹ The GPS-antenna is configured to only hand over validated signals. If there are less than 4 satellites or weak signal, the signals are set to zero. When the LED is flashing you can be sure that a GPS signal exists and that it is reliable. However, we recommend to wait at least

³ The data logger's webserver is only powered when connected to the communication socket. There is a bridge between VBAT2 and VCNC inside the socket. This way the web server is definitely shut off when the cable is unplugged.

⁴ You can use "DIRC in the box" to synchronize dataloggers manufactured by the company SEND (and other instruments that require 4800 baud) as well.

15 minutes after the first GPS fix. The reason for that is the information policy of the GPS system: information about leap seconds is transmitted every 15 minutes only. If another leap second occurred while "UHURA" has been shut off there would be a one second difference until this information is sent.

5 Meaning of the LED: UHURA

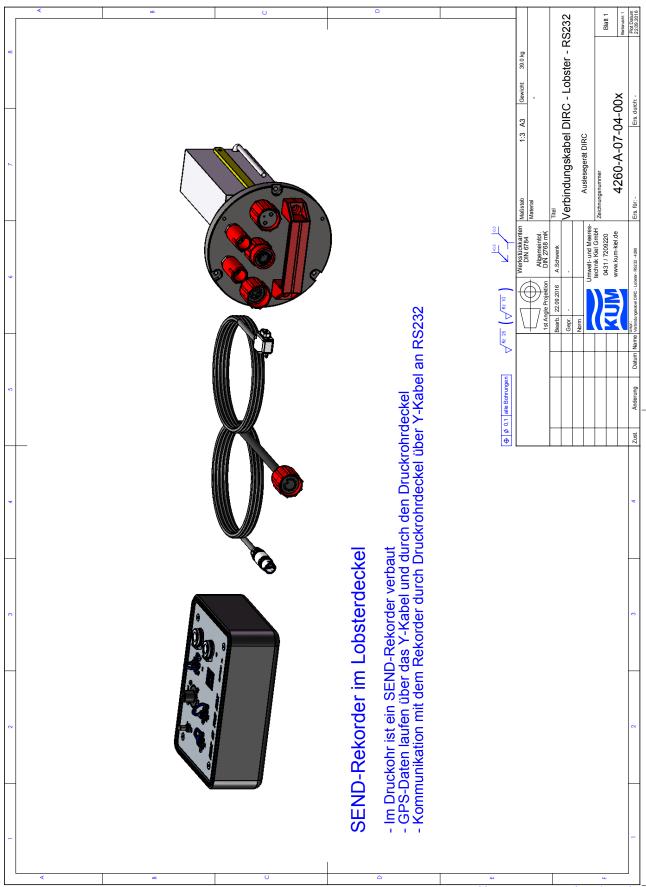
| Status | Description | | | | | |
|-------------|-------------------------------------------------------------------|--|--|--|--|--|
| red | System is booting. In case it keeps permanently, contact K.U.N | | | | | |
| orange | System has no fix yet | | | | | |
| green flash | System working. Second pulse represents a binary "0" ² | | | | | |
| blue flash | System working. Second pulse represents a binary "1" ² | | | | | |

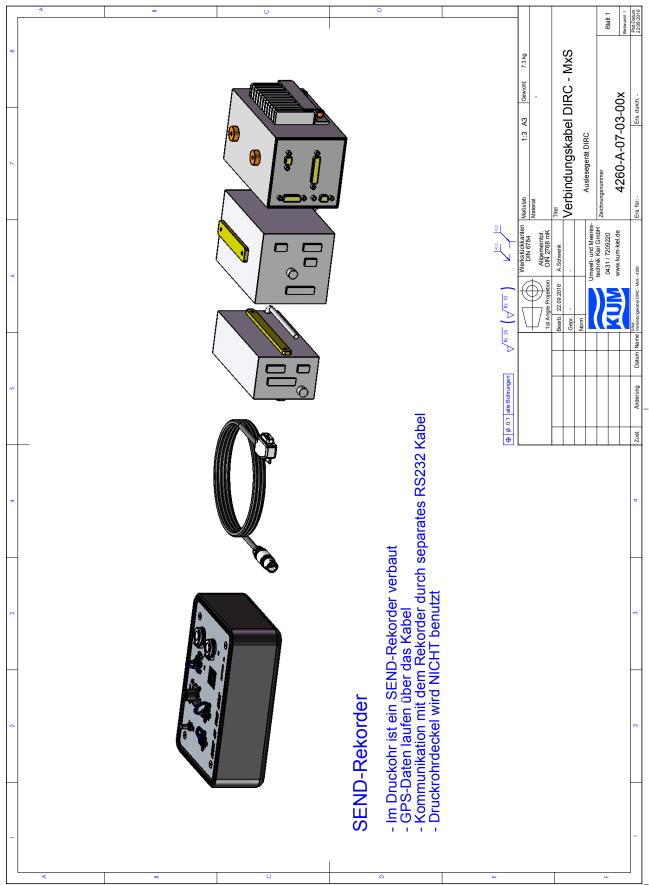
 $^{^2}$ On top of the GPS-NMEA the second pulse is DCF77 encoded. This is to supply outdated data logger that require this feature.

6 Available Cables









7 Performance

Receiver type: 72-channel UHURA engine; GPS L1C/A, SBAS L1C/A, QZSS L1C/A, QZSS L1 SAIF, GLONASS L1OF, BeiDou B1I, Galileo E1B/C

| Parameter | Specification | | | | | |
|-----------------------------|---------------------------|---------------------|----------|---------------|----------|------------------|
| Accuracy of | Accuracy of RMS | | | | | |
| time pulse sig | 99% | 60 ns | | | | |
| Frequency of | | 0.25 Hz to | | | | |
| time pulse sig | | 10 MHz | | | | |
| Operat. limits ¹ | Dynamics | ≤ 4 g | | | | |
| | Altitude | $50.000 \mathrm{m}$ | | | | |
| | Velocity | $500 \mathrm{m/s}$ | | | | |
| Velo. acc. ² | | $0.05 \mathrm{m/s}$ | | | | |
| Head. acc. ² | | 0.3 degrees | | | | |
| GNSS | | GPS | GLONASS | GLONASS | BeiDou | Galileo |
| | | | & GPS | | | |
| Horizontal | | 2.5m | 2.5m | $4\mathrm{m}$ | 3m | TBC^4 |
| pos. acc. ³ | | | | | | |
| Max navigation | | 5 Hz | 10 Hz | 10 Hz | 10 Hz | 10 Hz |
| update rate | | | | | | |
| Time-To- | Cold start | 26 s | 29 s | 30 s | 34 s | 45 s |
| First-Fix ⁵ | | | | | | |
| | Hot start | 1 s | 1 s | 1 s | 1 s | 1 s |
| | Aided starts ⁵ | 2 s | 2 s | 2 s | 3 s | 7 s |
| Sensitivity ⁷ | Track & Nav | -164 dBm | -164 dBm | -163 dBm | -160 dBm | -154 dBm |
| | Reacquis. | -160 dBm | -159 dBm | -156 dBm | -155 dBm | -152 dBm |
| | Cold start | -148 dBm | -147 dBm | -145 dBm | -143 dBm | -133 dBm |
| | Hot start | -157 dBm | -156 dBm | -155 dBm | -155 dBm | -151 dBm |

¹ Assuming Airborne < 4 g platform

 $^{^2}$ 50% @30m/s

 $^{^3}$ CEP, 50%, 24 hours static, -130 dBm, $>6~\mathrm{SVs}$

⁴ To be confirmed when Galileo reaches full operational capability

 $^{^5}$ All satellites at -130 dBm, except Galileo at -127 dBm

⁶ Dependent on aiding data connection speed and latency

⁷ Demonstrated with a good external LNA

8 WARNING - READ THIS FIRST!

All personnel involved with the installation, operation, or maintenance of the equipment described in this manual should read and understand the warnings and recommendations provided below.

WARNING

This manual is a reference book only. It does not claim completeness and refers to other literature in certain chapters. This manual cannot and shall not substitute an instrument introduction through an expert. Programming and deployment of an autonomous deep-sea instrument is an utmost complex affair and require the detailed know-how of all components and their composition in order to guarantee successful operation. That's why we expressly recommend that solely trained personnel shall operate and maintain the instruments.

Static Sensitive Devices

This equipment contains devices that are extremely sensitive to static electrical charges. Therefore extreme care should be taken when handling them, as static electricity may be present on the body and clothing. Normal handling precautions involve the use of anti-static protection materials and grounding straps for personnel.

High Voltages

High Voltage may be present in all parts of the GPS UHURA & DIRC . Use caution when the electronics are removed from their containers for servicing.

Improper Line Voltage

Operation with improper line voltage may cause serious damage to the equipment. Always ensure that the proper line voltage is used.

Hardware Variations and Compability

The GPS UHURA & DIRC contains both standard and proprietary hardware. At times K.U.M. may change the standard components due to their availability or performance improvements. Although the component manufacturers, along with their models and styles may change from unit to unit, replacement components will generally be interchangeable. K.U.M. will make every effort to see that replacement components are interchangeable. K.U.M. may also change certain hardware per customer requirements. Therefore, portions of this manual, such as parts lists and test features, are subject to change. These sections should be used for reference only. When changes are made that affect GPS UHURA & DIRC operation, they will be explicitly noted.

Purpose of this Manual

The purpose of this manual is to provide the user with information on the setup, operation, care, and features of the GPS UHURA & DIRC. Although this manual encompasses the latest operational features of the GPS UHURA & DIRC, some features of the GPS UHURA & DIRC may be periodically upgraded. Therefore the information in this manual is subject to change and should be used for reference only.

Warnings, Cautions, and Notes

Where applicable, warnings, cautions, and notes are provided in this manual as follows:

WARNING!

Identifies a potential hazard that could cause personal injury or death to yourself or to others. CAUTION!

Identifies a potential hazard that could be damaging to equipment or could result in the loss of data.

NOTE:

Recommendations or general information that is particular to the material being presented. It may also refer to another part of this manual or to another manual.

Liability

K.U.M. has made every effort to document the GPS UHURA & DIRC in this manual accurately and completely. However, K.U.M. assumes no liability for errors or for any damages that result from the use of this manual or the equipment it documents. K.U.M. reserves the right to

upgrade features of this software and to make changes to this manual without notice at any time.

Warranty statement

All equipment manufactured by K.U.M. is warranted against defective components and work-manship for a period of one year after shipment. Warranty repair will be done by K.U.M. free of charge. Shipping costs are to be borne by the customer. Malfunction due to improper use is not covered in the warranty, and K.U.M. disclaims any liability for consequential damage resulting from defects in the performance of the equipment. No product is warranted as being fit for a particular purpose, and there is no warranty of merchantability. This warranty applies only if:

- The items are used solely under the operating conditions and in the manner recommended in Seller's instruction manual, specifications, or other literature.
- The items have not been misused or abused in any manner, nor have repairs been attempted thereon without the approval of K.U.M. Customer Service.
- Written notice of the failure within the warranty period is forwarded to Seller and the directions received for properly identifying items returned under warranty are followed.
- The return notice authorizes Seller to examine and disassemble returned products to the extent Seller deems necessary to ascertain the cause for failure.

The warranties expressed herein are exclusive. There are no other warranties, either expressed or implied, beyond those set forth herein, and Seller does not assume any other obligation or liability in connection with the sale or use of said products. Any product or service repaired under this warranty shall be warranted for the remaining portion of the original warranty period only.

Equipment not manufactured by K.U.M. is supported only to the extent of the original manufacturer's warranties.

Returned Material Authorization

Prior to returning any equipment to K.U.M., a Returned Material Authorization (RMA) number must be obtained. The RMA will help us identify your equipment when it arrives at our receiving dock and track the equipment while it is at our facility. The material should be shipped to the address provided in the K.U.M. Customer Service section. Please refer to the

RMA number on all documents and correspondences as well. All returned material must be

shipped prepaid. Freight collect shipments will not be accepted.

CAUTION! Never attempt to ship portable topside units in their outdoor case alone. Al-

though rugged, these cases are not intended to be used as shipping containers, and the delicate

internal components could be damaged if used in this manner.

All shipments must be accompanied by a copy of your proforma invoice, showing the value of

the material and the reason for its return. When shippend from outside the European Union:

If the reason is for repair, it must be clearly stated in order to move through customs quickly

and without duties being charged. Whenever possible, please send copies of original export

shipping documents with the consignment.

Final Disposal

The GPS UHURA & DIRC contains materials (especially batteries) that need proper disposal.

Please contact customer service if your local disposal contractor is in doubt.

Customer Service

Customer service personnel at K.U.M. are always eager to hear from users of our products.

Your feedback is welcome, and is a valuable source of information which we use to continually

improve these products. Therefore we encourage you to contact K.U.M. Customer Service to

offer any suggestions or to request technical support:

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