

Technology Advances

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Advances in Technology

- Technology has been advancing at lightning speed
- Architecture and IT as a whole were beneficiaries
- Technology advance is summarized by Moore's Law
 - You probably heard of it at some point. Something about ...
 - "X doubles every 18-24 months at constant cost"
- Is X:
 - CPU performance?
 - CPU clock frequency?

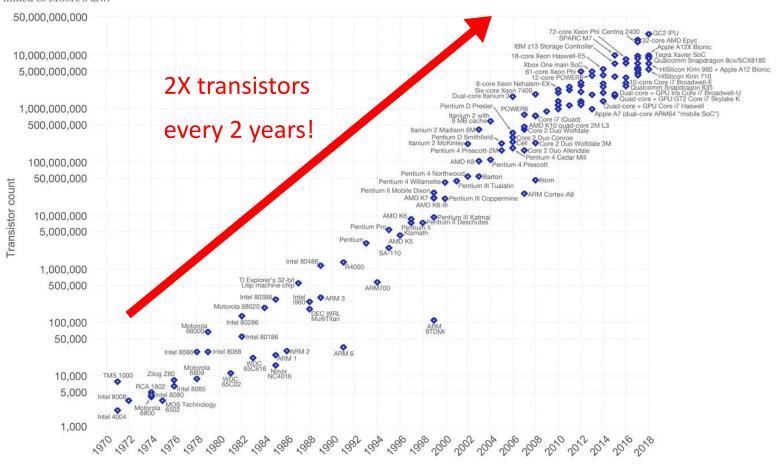




Moore's Law – The number of transistors on integrated circuit chips (1971-2018)

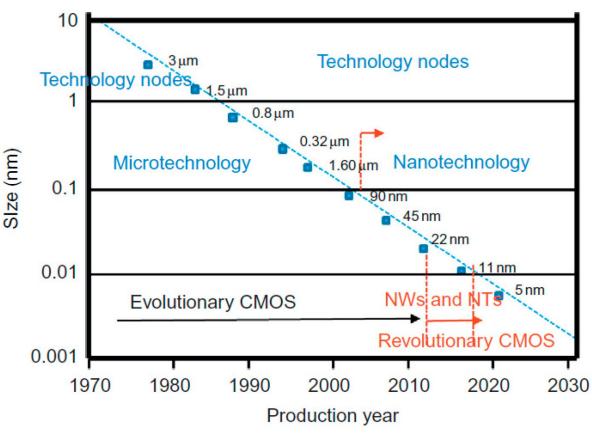


Moore's law describes the empirical regularity that the number of transistors on integrated circuits doubles approximately every two years. This advancement is important as other aspects of technological progress – such as processing speed or the price of electronic products – are linked to Moore's law.



Miniaturization of Transistors





Data source: Radamson, H.H.; He, X.; Zhang, Q.; Liu, J.; Cui, H.; Xiang, J.; Kong, Z.; Xiong, W.; Li, J.; Gao, J.; Yang, H.; Gu, S.; Zhao, X.; Du, Y.; Yu, J.; Wang, G. Miniaturization of CMOS. *Micromachines* **2019**, *10*, 293.

- Moore's Law has been driven by transistor miniaturization
 - CPU chip area hasn't changed much

Future of Moore's Law



- The semiconductor industry has produced roadmaps
 - Semiconductor Industry Association (SIA): 1977~1997
 - International Technology Roadmap for Semiconductors (ITRS): 1998~2016
 - International Roadmap for Devices and Systems (IRDS): 2017~Present
- IRDS Lithography Projection (2020)

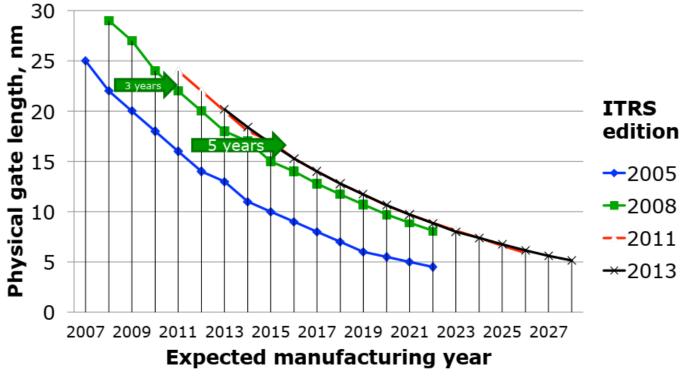
Year of Production	2018	2020	2022	2025	2028	2031	2034
Technology Node (nm)	7	5	3	2.1	1.5	1.0	0.7

- Moore's Law will continue into foreseeable future
- IRDS does not project significant increase in CPU chip size
- Increases in transistors will come from transistor density

IRDS isn't Perfect



ITRS (predecessor of IRDS) has made corrections before



- After all, you are trying to predict the future
- But architects rely on the roadmap to design future processors

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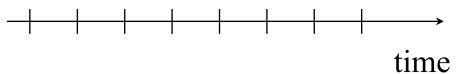
Moore's Law and Performance

- Did Moore's Law result in higher performance CPUs?
- How do you define performance?
 - When you buy a CPU, what number(s) do you look at?
- 1. Try running your favorite apps on it and measure time.
 - Most accurate, but manufacturers can't publish these numbers
- 2. Try running a suite of benchmark apps (e.g. SPECCPU)
 - Less accurate, but it is a number manufacturers can publish
- 3. Look at several important components of performance
 - Needs interpretation, but allows analysis of performance

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Components of Execution Time

Processor activity happens on clock "ticks" or cycles



On each tick, bits flow through logic gates and are latched

Execution time =
$$\frac{\text{seconds}}{\text{program}}$$

$$\frac{\text{seconds}}{\text{program}} = \frac{\text{cycles}}{\text{program}} \quad X \quad \frac{\text{seconds}}{\text{cycle}}$$

$$= \frac{\text{instructions}}{\text{program}} \quad X \quad \frac{\text{cycles}}{\text{instruction}} \quad X \quad \frac{\text{seconds}}{\text{cycle}}$$

How to improve Execution Time

$$\frac{\text{instructions}}{\text{program}}$$
 X $\frac{\text{cycles}}{\text{instruction}}$ X $\frac{\text{seconds}}{\text{cycle}}$

- Reduce seconds / cycle : a.k.a. clock frequency
 Clock frequency = cycles / second = reverse of seconds / cycle
 Higher clock frequency (GHz) leads to shorter exec time
- Reduce $\frac{\text{cycles}}{\text{instruction}}$: a.k.a. CPI (Cycles Per Instruction)

 IPC (Instructions Per Cycle) = $\frac{\text{instructions}}{\text{cycle}}$ = reverse of $\frac{\text{cycles}}{\text{instruction}}$

 - Higher IPC leads to shorter execution time
- Reduce $\frac{\text{instructions}}{\text{program}}$:

 Less instructions leads to shorter execution time
 - ISAs that do a lot of work with one instruction shortens time



Moore's Law impacts two layers

- Did Moore's Law result in higher performance CPUs?
- Law impacts both architecture and physical layers

Instruction Set Architecture Computer
Processor Organization Architecture

Transistor Implementation

Physical Layer

- Processor Organization: many more transistors to use in design
- Transistor Implementation: smaller, more efficient transistors

Moore's Law Impact on Architecture

- So where did architects use all those transistors?
- Well, we will learn this throughout the semester ©
 - Pipelining — Improves frequency
 - Parallel execution
 - Branch prediction
 - Speculative execution
 - Memory caching

Improves IPC

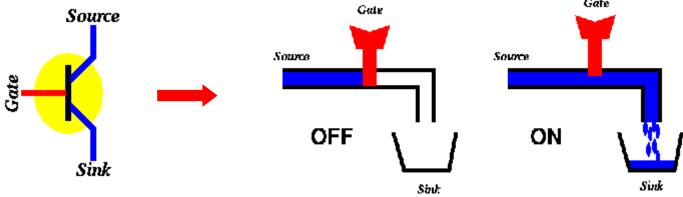
Let's go on to impact on the physical layer for now

Moore's Law Impact on Physical Layer

- Frequency = transistor speed ×
 number of transistors between clock ticks
 - Transistor speed is decided by the physical layer
 - Number of transistors between ticks is CPU design
- Given a CPU design, faster transistors \rightarrow faster CPUs
 - Intel's tick-tock model staggers transistor / design improvements
 - Tick: new generation due to new technology node
 - Tock: new generation due to new CPU design
- So did Moore's Law result in faster transistors?
 - In other words, are smaller transistors faster?

Speed of Transistors

Transistors are like faucets:

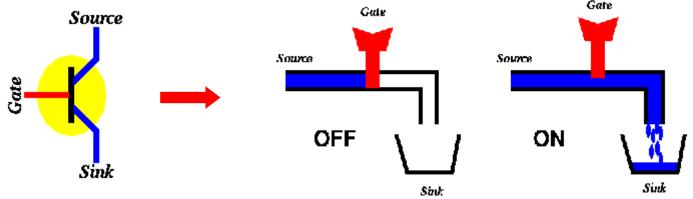


- To make a transistor go fast, do one of the following:
 - Increase water pressure (supply voltage)
 - Change faucet (transistor) design
- Transistor design can be changed in two ways:
 - Increase pipe thickness (reduce channel resistance R)
 - Reduce bucket size (reduce capacitance C)
 - $T_{switch} \propto RC$ (transistor switch delay is proportional to RC)

Smaller Transistors are Faster!



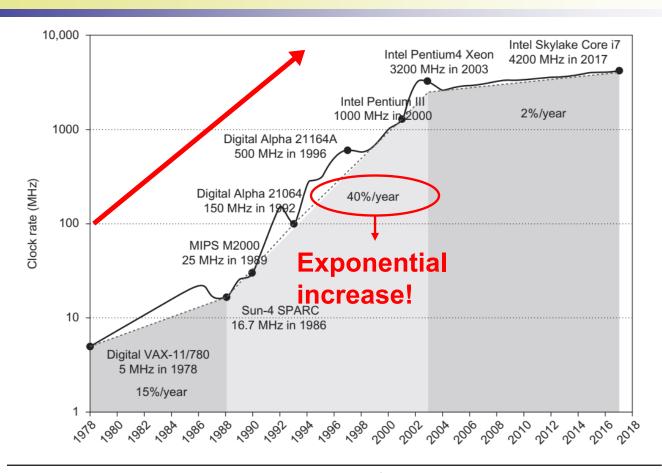
Transistors are like faucets!



- \blacksquare For transistor dimension d (node size)
 - Capacitance $C \propto d$
 - Channel resistance $R \propto$ Channel length $L \propto d$
 - $T_{switch} \propto RC \propto d^2$
- Given the same supply voltage, smaller is faster!
- Did Moore's Law enjoy faster and faster frequencies?

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Yes, for a while ...

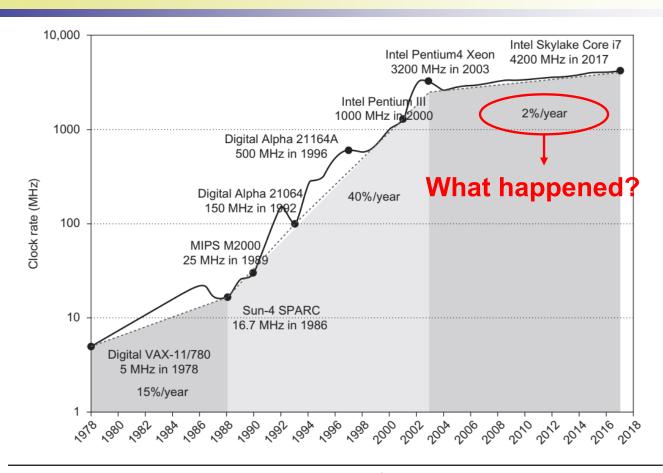


Source: Computer Architecture, A Quantitative Approach (6th ed.) by John Hennessy and David Patterson, 2017

- Due in large part to improvement in transistor speed
 - CPU design (pipelining) contributed but we'll discuss later

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But not so much lately



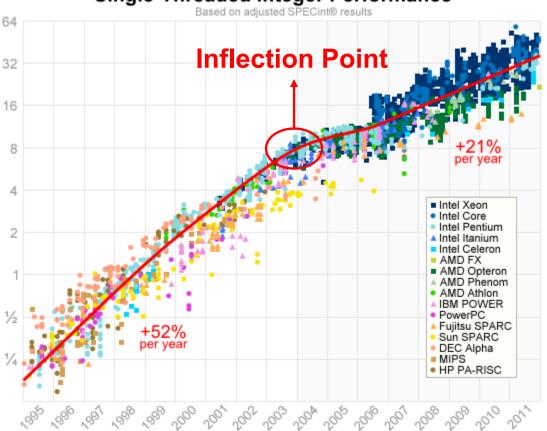
Source: Computer Architecture, A Quantitative Approach (6th ed.) by John Hennessy and David Patterson, 2017

- Suddenly around 2003, frequency scaling stops. Why?
 - Improvements in transistor speed stopped.
 - CPU design (pipelining) has met its limits.

Dent in CPU Performance



Single-Threaded Integer Performance



Source: https://preshing.com/20120208/ a-look-back-at-single-threaded-cpu-performance/

- This caused a big dent in CPU performance circa 2003
- Improvements henceforth mostly came from IPC

Why did frequency scaling stop? TDP.

- TDP (Thermal Design Power):
 - Maximum power (heat) that CPU is designed to generate
 - Capped by the amount of heat cooling system can handle
 - Cooling system hasn't improved much over generations
- CPU Power = A * N * CFV² must be < TDP</p>
 - A = Activity factor (% of transistors with activity)
 - N = Number of transistors
 - C = Capacitance
 - F = Frequency
 - V = Supply Voltage



What happens to each factor with Moore's Law?

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CPU Power (with Fixed Voltage)

- Change in CPU Power

 A * N * CFV², with fixed V:
 - A = Activity factor
 - N = Number of transistors $\propto 1/d^2$ û û

 - $F \propto 1/T_{\text{switch}} \propto 1/d^2 \Omega \Omega \Omega \Omega$ (if supply voltage is kept constant)
 - V = Supply Voltage (water pressure)
 - \rightarrow CPU Power $\propto 1/d^3 \Omega \Omega \Omega$
- Recipe used until 1990's until power started to matter
 - That meant F could not keep increasing while meeting TDP
- Q) So how did CPU frequency keep increasing up to 2003?

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CPU Power (with Dennard Scaling)

- Goal: to scale frequency while keeping power constant
- By reducing V proportional to d, then change in CPU Power ∝ A * N * CFV² is:
 - A = Activity factor
 - N = Number of transistors $\propto 1/d^2$ ☆ ☆

 - $F \propto 1/d$ 1 (Can scale by 1/d while keeping power constant!)
 - V = Supply Voltage (\propto d) \checkmark \rightarrow V² \checkmark \checkmark
- Dennard Scaling: Above recipe for scaling up frequency, while reducing supply voltage to keep power constant

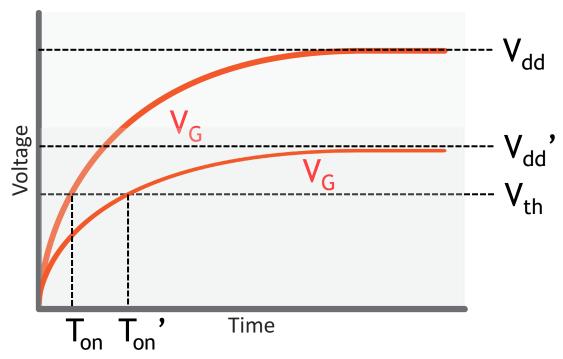
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Dennard Scaling and V_{th}

- So, it's that easy? Just reduce V until you meet TDP?
- No, it's not that simple ⊗.
- Reducing V_{dd} (supply voltage) affects CPU operation
 - As V_{dd} is reduced, transistor becomes slower (lower pressure)
 - Eventually, CPU stops working altogether
- Transistors need redesigning to work at lower voltage
 - V_{th} is the threshold voltage when switching happens
 - V_{th} needs to be reduced along with V_{dd} to maintain speed

Speed is determined by V_{dd} if V_{th} is fixed

RC Charging Curve of V_G (Gate Voltage)

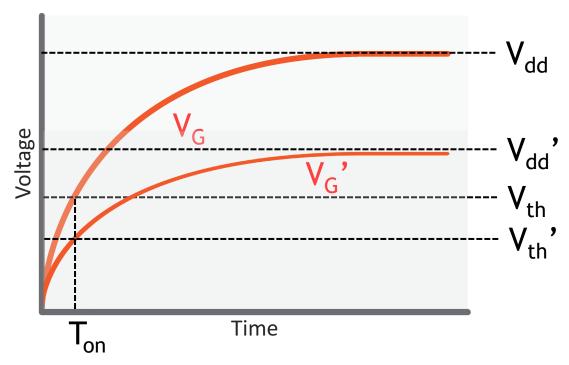


- V_{dd} is high $\rightarrow V_G$ reaches V_{th} slowly at T_{on} (high pressure)
- ullet V_{dd} ' is high $\to V_G$ reaches V_{th} slowly at T_{on} '(low pressure)

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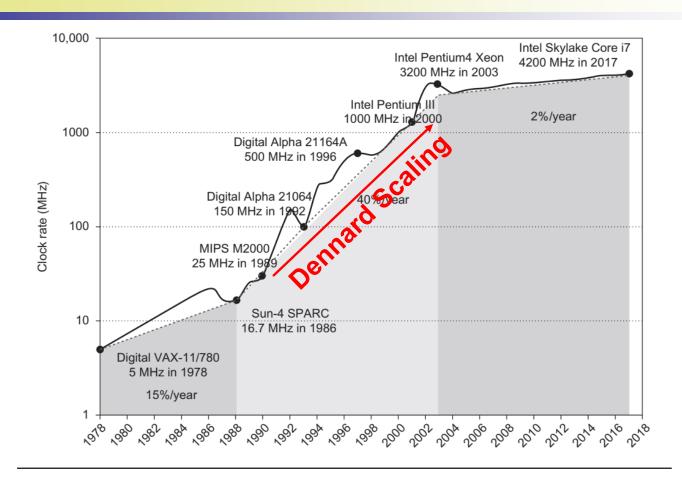
Speed is maintained with lower V_{th}

RC Charging Curve of V_G



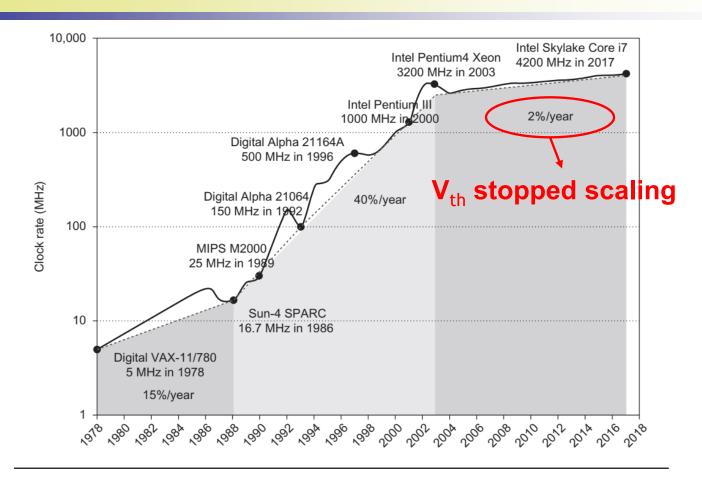
■ Speed (T_{on}) is maintained while reducing V_{dd} to V_{dd} , but only if V_{th} is also reduced to V_{th} .

Dennard Scaling paid dividends for a while



Aided by repeated reductions of V_{dd} and V_{th}

Then Dennard Scaling ended at 2003

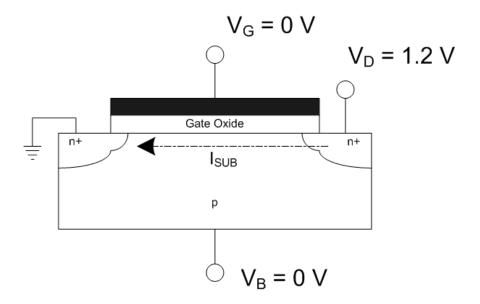


Main reason was that V_{th} could no longer be reduced

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Limits to Dropping V_{th}

- Subthreshold leakage
 - Transistor leaks current even when gate is off $(V_G = 0)$

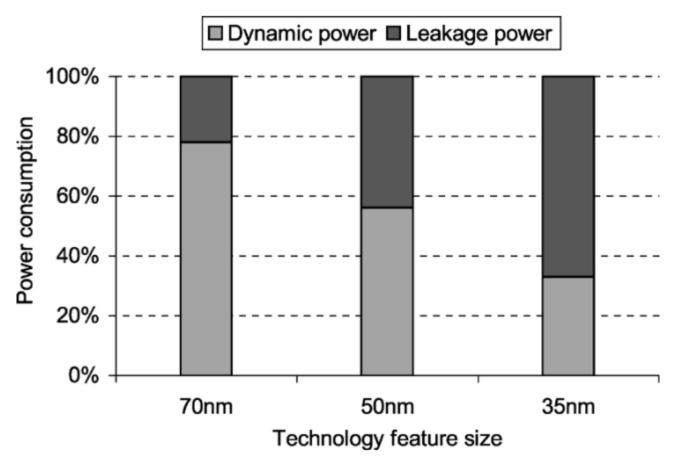


- This leakage current translates to leakage power
- Leakage worsens when V_{th} is dropped



Leakage Power across Generations

Leakage power has increased across technology nodes



Source: L. Yan, Jiong Luo and N. K. Jha, "Joint dynamic voltage scaling and adaptive body biasing for heterogeneous distributed real-time embedded systems," in *IEEE Transactions on Computer-Aided Design of Integrated Circuits and Systems*, vol. 24, no. 7, pp. 1030-1041, July 2005

CPU Power must now include leakage

- Previous power calculation was incomplete
 - CPU power is the sum of both dynamic and leakage power
- Power_{CPU} ∝ Power_{dynamic} + Power_{leakage}
 - Power_{dynamic} \propto A * N * CFV_{dd}²
 - Power_{leakage} \propto N * V_{dd} * e^{-Vth}
 - Leakage worsens exponentially when V_{th} is dropped
 - Catch-22: when dropping V_{th}, Power_{dynamic} ↓ but Power_{leakage} ☆☆
- V_{th} can't be reduced further, so V_{dd} can't be reduced
- Dennard Scaling relies on reducing V_{dd}, so it's the end

CPU Power (End of Dennard Scaling)

- What happens to frequency without Dennard Scaling?
- Power_{dynamic} (\propto A * N * CFV²) + Power_{leakage} (\propto N * V * e^{-Vth})
 - A = Activity factor
 - N = Number of transistors ($\propto 1/d^2$) ① ①
 - C = Capacitance (\propto d) \P
 - $V = Supply Voltage \Leftrightarrow (Due to fixed V_{th})$
 - F = Frequency ???
- To offset N, you actually have to decrease F
- Otherwise, if you want to maintain F, must decrease N
 - That is, you cannot power on all the transistors at any given point
 - Dark silicon: situation where chip is only partially powered

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Free Ride is Over

- "Free" speed improvements from transistors is over
- Now it's up to architects to improve performance
 - Moore's Law is still alive (although slowing down)
 - Architects are flooded with extra transistors each generation
 - But it's hard to even keep them powered without reducing F!
- Now is a good time to discuss technology constraints
 - Since we already mentioned a big one: TDP