Processor Review

CS 1541 Wonsun Ahn



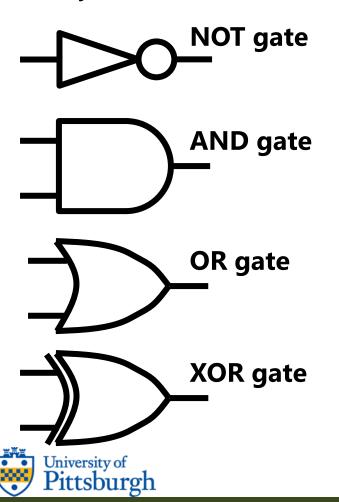
Clocking Review

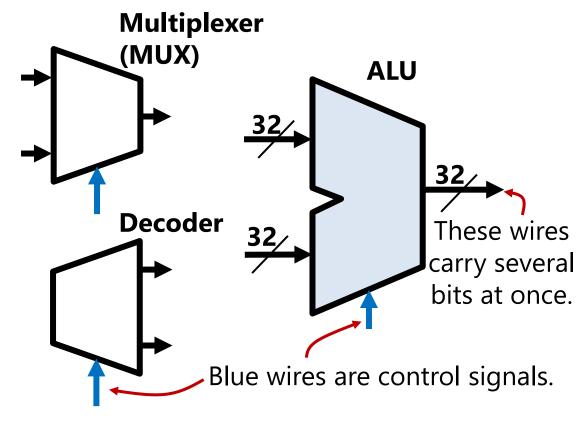
Stuff you learned in CS 447



Logic components

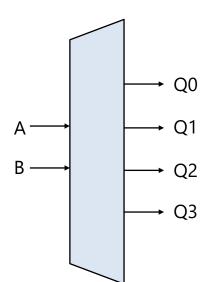
• Do you remember what all these do?





Uses of a Decoder

- Translates a set of input signals to a bunch of output signals.
 - A binary decoder (e.g. used in register decoding):



Truth Table for Decoder

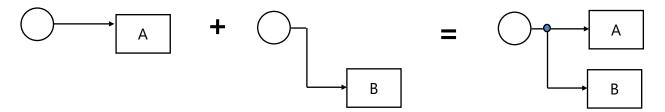
A	В	Q0	Q1	Q2	Q3
0	0	1	0	0	0
0	1	0	1	0	0
1	0	0	0	1	0
1	1	0	0	0	1

- You can come up with any truth table and make a decoder for it!
- o Instruction decoder: generates control signals from instructions

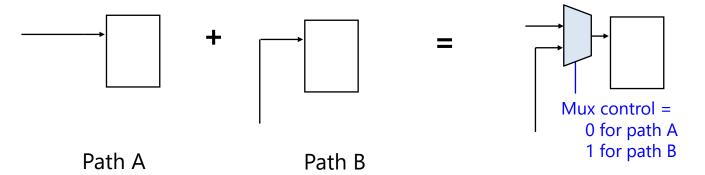


Uses of a Multiplexer

No problem in fanning out one signal to two points



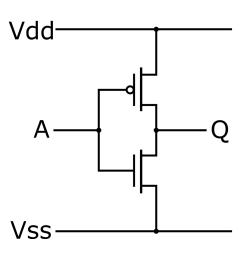
- Cannot connect two signals to one point
 - Must use a multiplexer to select between the two



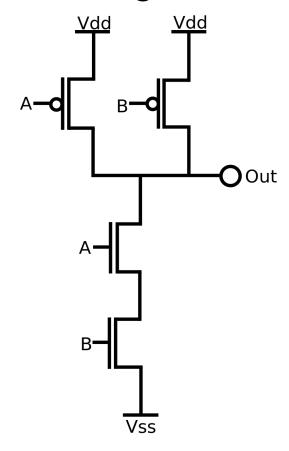


Gates are made of transistors (of course)

NOT gate



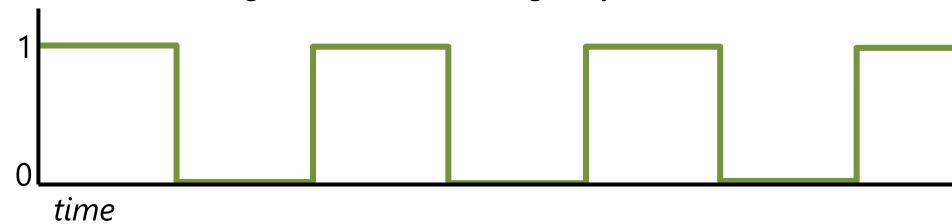
NAND gate





The clock signal

• The clock is a signal that alternates regularly between 0 and 1:

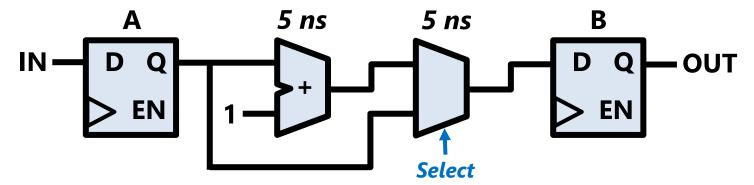


- Bits are latched on to registers and flip-flops on rising edges
- In between rising edges, bits propagate through the logic circuit



Critical Path

- Propagation Delay: delay to propagate data to next storage location
- Critical Path: path in a circuit that has longest propagation delay
 - \circ PropagationDelay_{CriticalPath} < CycleTime
- How fast can we clock this circuit?



- \circ Is it 1 / 5 ns (5 × 10⁻⁹s) = 200 MHz?
- \circ Or is it 1 / 10 ns (10 × 10⁻⁹s) = 100 MHz? \checkmark



MIPS Review

Stuff you learned in CS 447



The MIPS ISA - Registers

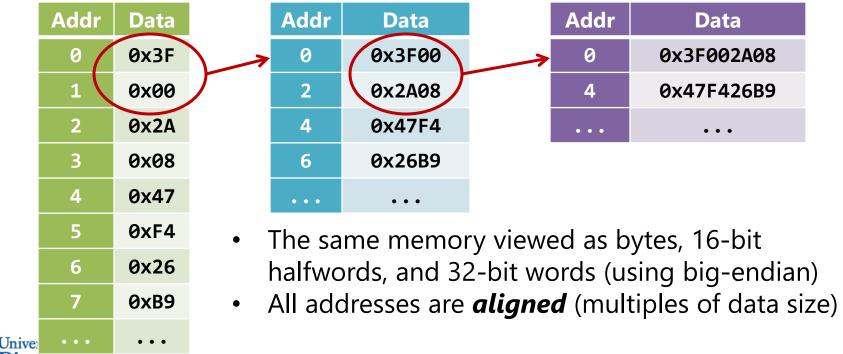
- MIPS has 32 32-bit registers, with the following usage conventions
 - o But really, all are general purpose registers (nothing special about them)

Name	Register number	Usage	
\$zero	0	the constant value 0 (can't be written)	
\$at	1	assembler temporary	
\$v0-\$v1	2-3	values for results and expression evaluation	
\$a0-\$a3	4-7	function arguments	
\$t0-\$t7	8-15	unsaved temporaries	
\$s0-\$s7	16-23	saved temporaries (like program variables)	
\$t8-\$t9	24-25	more unsaved temporaries	
\$k0-\$k1	26-27	reserved for OS kernel	
\$gp	28	global pointer	
\$sp	29	stack pointer	
\$fp	30	frame pointer	
\$ra	31	return address	



The MIPS ISA - Memory

- MIPS is a *RISC (reduced instruction set computer)* architecture
- It is also a *load-store* architecture
 - All memory accesses performed by load and store instructions
- Memory is a giant array of 2³² bytes



The MIPS ISA - Memory

• Loads move data *from* memory *into* the registers.

0x0000BEEF

0x00000004

Registers

This is the address, and it means "the value of \$s4 + 8."

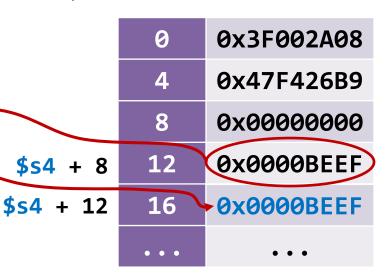
lw

SW

• Stores move data *from* the registers *into* memory.



\$t0 is the SOURCE!



Memory



s4

The MIPS ISA – Flow control

Jump and branch instructions change the flow of execution.

- **j** : jumps *unconditionally*
- jumps to _top

```
li $s0, 10
—loop:

# ....
addi $s0, $s0, -1
bne $s0, $zero, _loop
jr $ra
```

bne: jumps conditionally

If \$50 != \$zero, jumps to _loop

```
If $s0 == $zero, continues to jr $ra
```

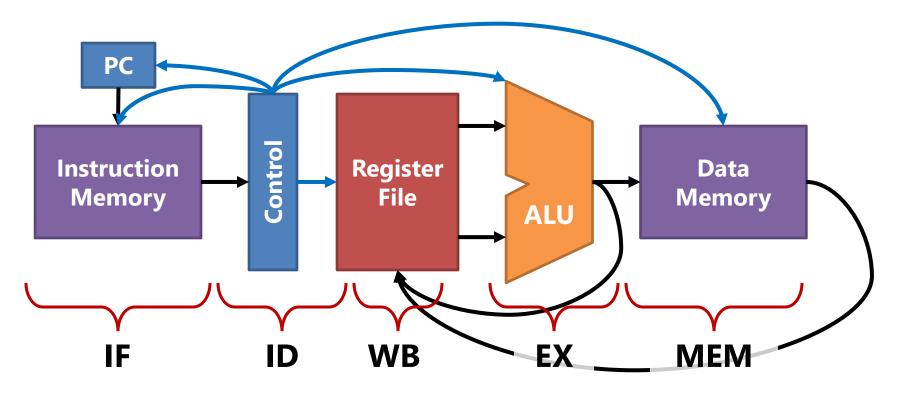


Phases of instruction execution

- In most architectures, there are five phases:
 - **1. IF** (Instruction Fetch) get next instruction from memory
 - 2. ID (Instruction Decode) figure out what instruction it is
 - **3. EX** (Execute ALU) do any arithmetic
 - **4. MEM** (Memory) read or write data from/to memory
 - **5. WB** (Register Writeback) write any results to the registers
- Sometimes these phases are chopped into smaller stages



A simple single-cycle implementation



An instruction goes through IF/ID/EX/MEM/WB in one cycle



"Minimal MIPS"



It's a "subset" of MIPS

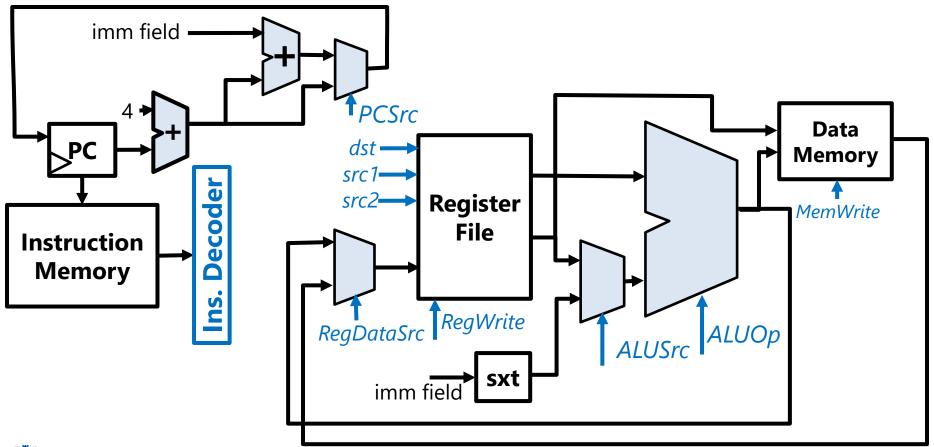
- For pedagogical (teaching) purposes
- Contains only a minimal number of instructions:
 - o lw, sw, add, sub, and, or, slt, beq, and j
 - Other instructions in MIPS are variations on these anyway
- Let's review the Minimal MIPS CPU focusing on the control signals
 - o Again, these control signals are decoded from the instruction



The Minimal MIPS single-cycle CPU

University of **Pittsburgh**

A more detailed view of the 5-phase implementation

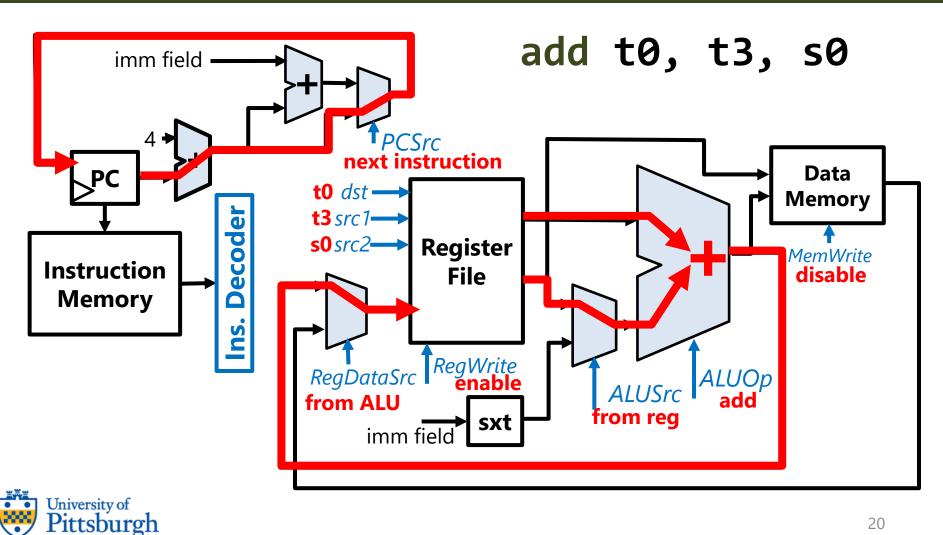


Control signals

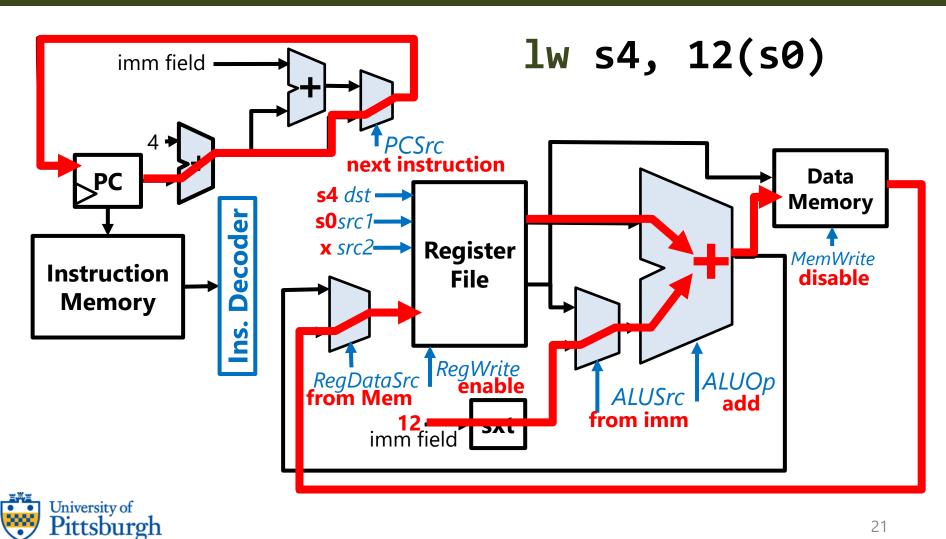
- Registers
 - RegDataSrc: controls source of a register write (ALU / memory)
 - RegWrite: enables a write to the register file
 - o src1, src2, dst: the register number for each respective operand
- ALU
 - ALUSrc: whether second operand of ALU is a register / immediate
 - ALUOp: controls what the ALU will do (add, sub, and, or etc)
- Memory
 - MemWrite: enables a write to data memory
- PC
 - PCSrc: controls source of next PC (PC + 4 / PC + 4 + imm)
- → All these signals are decoded from the instruction!



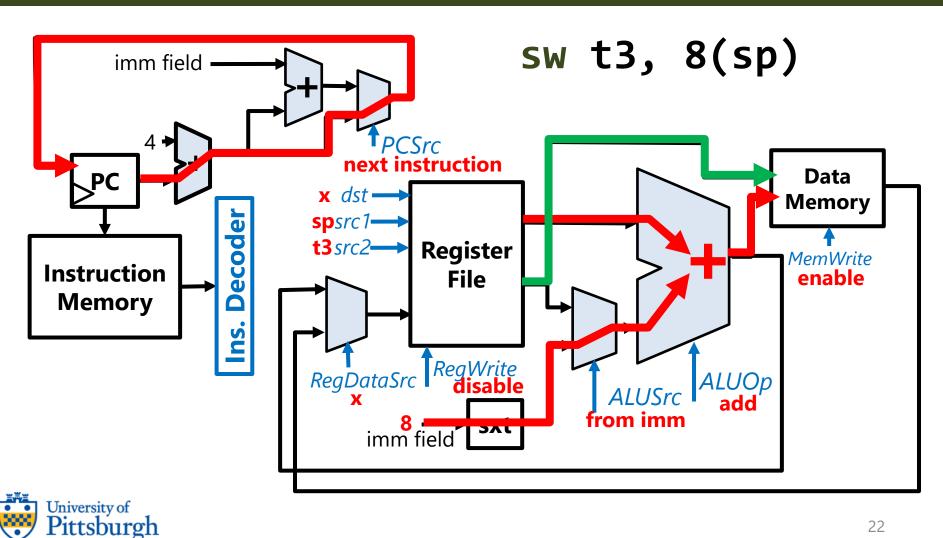
How an add/sub/and/or/slt work



How an **lw** works

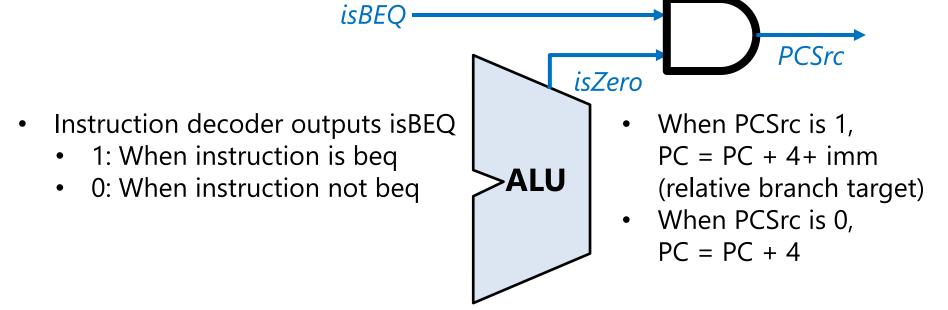


How an **sw** works



What about **beq**?

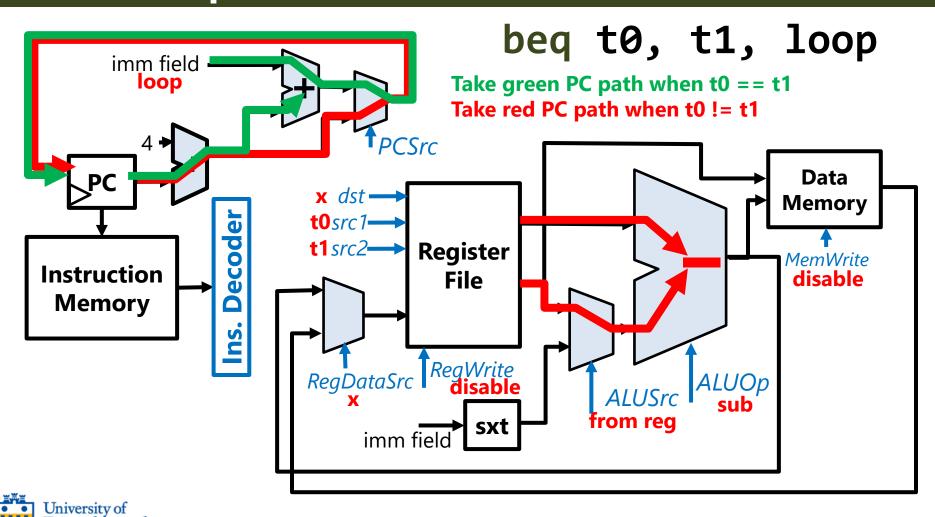
- Compares numbers by subtracting and see if result is 0
 - If result is 0, we set PCSrc to use the branch target.
 - Otherwise, we set PCSrc to PC + 4.





How a **beq** works

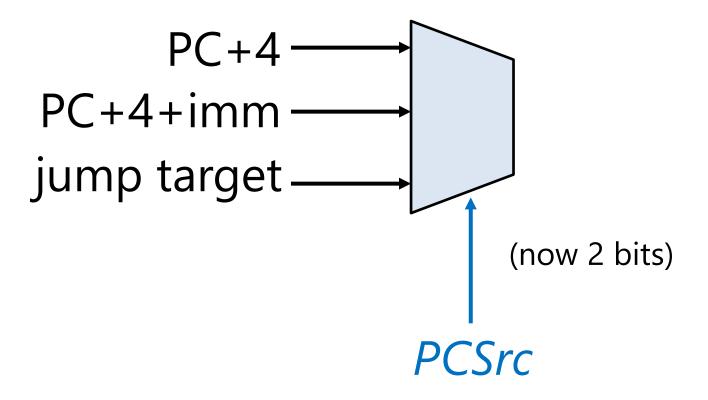
Pittsburgh



What about j?

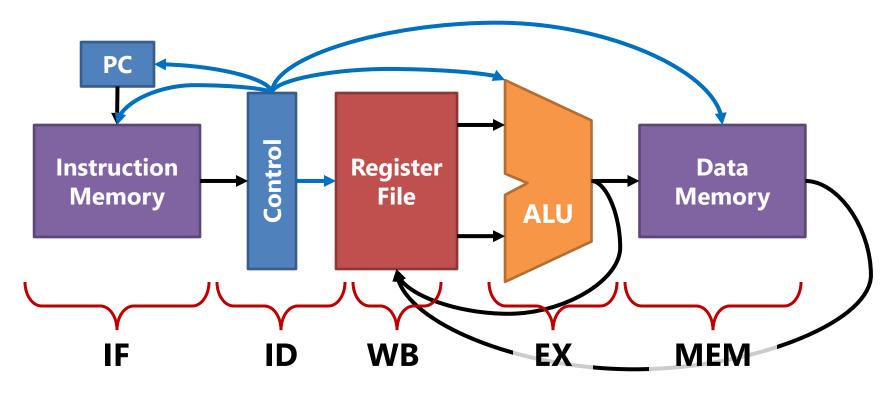
We have to add another input to the PCSrc mux.

j top





A Single-cycle Implementation is not Optimal



- Why? Since the *longest* critical path must be chosen for cycle time
 - And there is a wide variation among different instructions

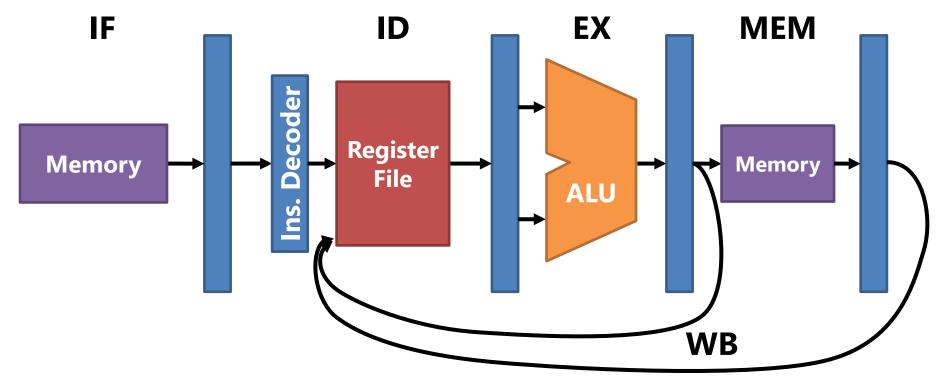


A Single-cycle Implementation is not Optimal

- In our CPU, the **lw** instruction has the longest critical path
 - Must go through all 5 stages: IF/ID/EX/MEM/WB
 - Whereas add goes through just 4 stages: IF/ID/EX/WB
- If each phase takes 1 ns each, cycle time must be 5 ns:
 - o Because it needs to be able to handle **lw**, which takes 5 ns
 - o **add** also takes 5 ns when it could have been done in 4 ns
- Q) If **lw** is 1% and **add** is 99% of instruction mix, what is the average instruction execution time?
- A) Still 5 ns! Even if **lw** is only 1% of instructions!

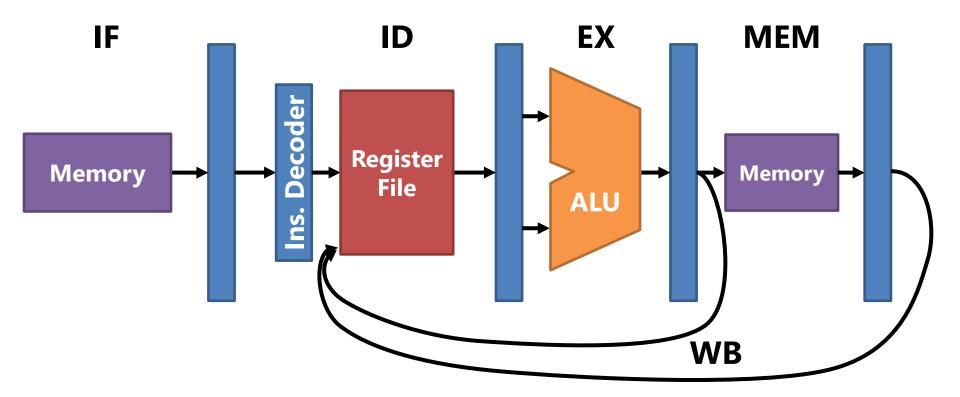


- Internal latches store data needed for that stage
 - o E.g. Latch before EX stores operands to ALU



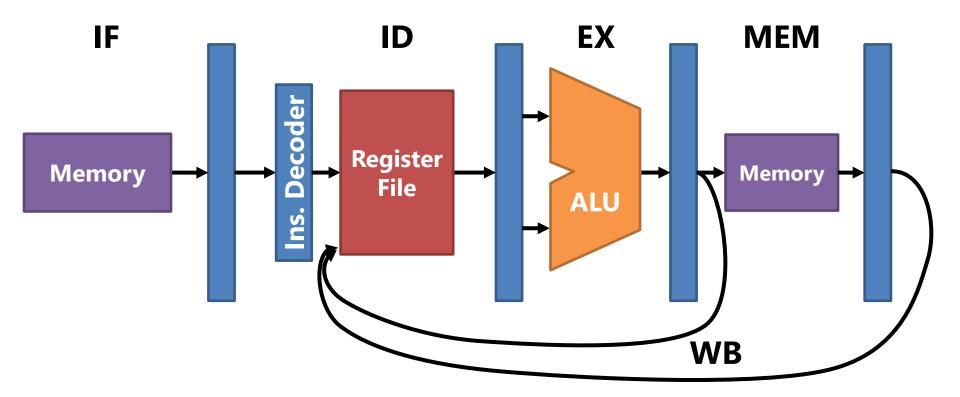


• A Load instruction completes in 5 cycles.



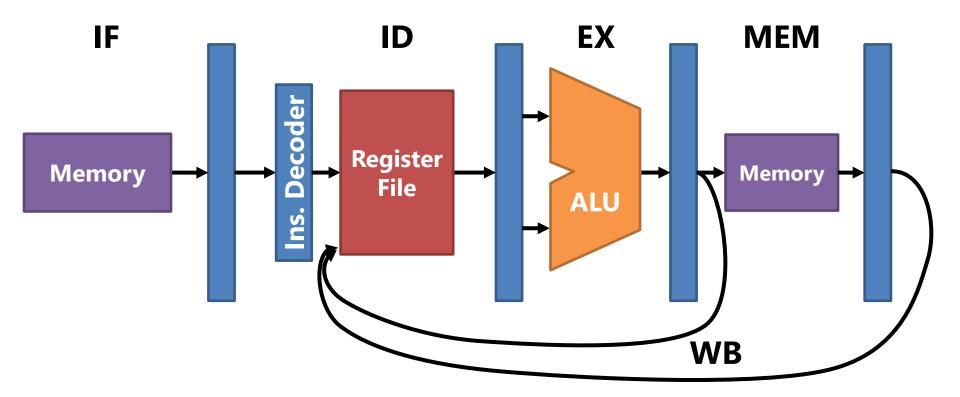


• But a Store instruction completes in 4 cycles.





• Register-to-register ALU instructions complete in 4 cycles too.





A Multi-cycle Implementation is Faster!

- Now each instruction takes different number of cycles to complete
 - lw takes 5 cycles: IF/ID/EX/MEM/WB
 - o add takes 4 cycles: IF/ID/EX/WB
- If each phase takes 1 ns as before:
 - Iw takes 5 ns and add takes 4 ns
- Q) If **lw** is 1% and **add** is 99% of instruction mix, what is the average instruction execution time?
- A) 0.01 * 5 ns + 0.99 * 4 ns = 4.01 ns (25% faster than single cycle)
- * Caveat: delay due to the added latches not shown, but net win



And we can do even better!

- Did you notice?
 - When an instruction is on a particular phase (e.g. IF) ...
 - o ... other phases (ID/EX/MEM/WB) are not doing any work!
- Our CPU is getting chronically underutilized!
 - If CPU is a factory, 80% (4/5) of the workers are idling!
- Car factories create an assembly line to solve this problem
 - No need to wait until a car is finished before starting on next one
 - Our CPU is going to use a *pipeline* (similar concept)

