Math Notes

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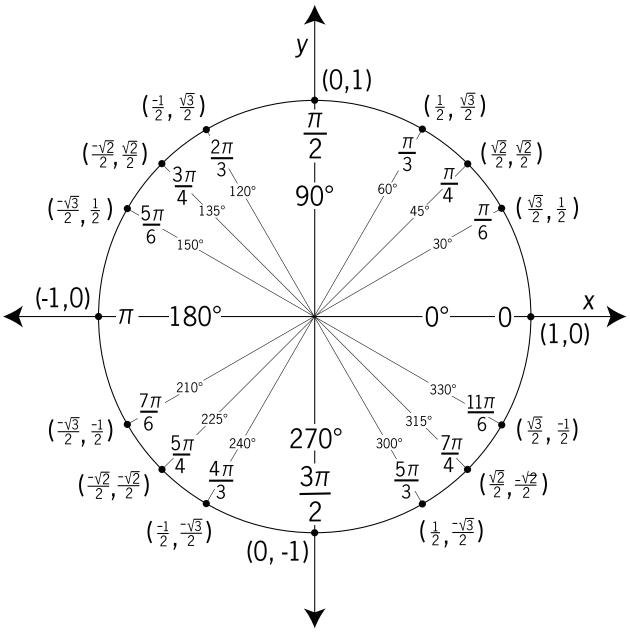
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1 Trigonometric Concepts

1.1 Unit Circle



Source: https://etc.usf.edu/clipart/43200/43215/unit-circle7_43215.htm

1.2 Basic Trigonometry

$$sin(\theta) = \frac{Opposite}{Hypotenuse} \qquad cos(\theta) = \frac{Adjacent}{Hypotenuse} \qquad tan(\theta) = \frac{Opposite}{Adjacent}$$

$$= \frac{y}{1} = y \qquad = \frac{x}{1} = x \qquad = \frac{y}{x}$$

$$= \frac{sin(\theta)}{cos(\theta)}$$

$$csc(\theta) = \frac{1}{sin(\theta)} \qquad sec(\theta) = \frac{1}{cos(\theta)} \qquad cot(\theta) = \frac{cos(\theta)}{sin(\theta)}$$

1.3 Pythagorean Theorem Identities

$$sin^{2}\theta + cos^{2}\theta = 1$$
$$tan^{2}\theta + 1 = sec^{2}\theta$$
$$1 + cot^{2}\theta = csc^{2}\theta$$

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1.4 Half Angle Identities

$$cos(\frac{\theta}{2}) = \pm \sqrt{\frac{1 + cos(\theta)}{2}}$$

$$sin(\frac{\theta}{2}) = \pm \sqrt{\frac{1 - cos(\theta)}{2}}$$

$$= \frac{sin(\theta)}{1 + cos(\theta)}$$

$$= \frac{1 - cos(\theta)}{sin(\theta)}$$

1.5 Double Angle Identities

$$sin(2\theta) = 2sin\theta cos\theta$$

$$cos(2\theta) = cos^2\theta - sin^2\theta$$

$$= 2cos^2\theta - 1$$

$$= 1 - 2sin^2\theta$$

$$tan(2\theta) = \frac{2tan\theta}{1 - tan^2\theta}$$

1.6 Power Reduction Identities

$$sin^{2}\theta = \frac{1 - cos2\theta}{2}$$

$$cos^{2}\theta = \frac{1 + cos2\theta}{2}$$

$$tan^{2}\theta = \frac{1 - cos2\theta}{1 + cos2\theta}$$

$$cot^{2}\theta = \frac{2}{1 + cos2\theta}$$

$$cot^{2}\theta = \frac{2}{1 + cos2\theta}$$

$$cot^{2}\theta = \frac{1 + cos2\theta}{1 - cos2\theta}$$

2 Trigonometric Substitution

| Expression | Substitution | Identity |
|------------------------|---------------------------------|-------------------------------------|
| $\sqrt{a^2 - b^2 x^2}$ | $x = \frac{a}{b}sin\theta$ | $1 - \sin^2 \theta = \cos^2 \theta$ |
| $\sqrt{a^2 + b^2 x^2}$ | $x = \frac{a}{b}tan\theta$ | $1 - tan^2\theta = sec^2\theta$ |
| $\sqrt{b^2x^2 - a^2}$ | $x = \frac{a}{\hbar} sec\theta$ | $sec^2\theta - 1 = tan^2\theta$ |

3 Table of Basic Deriva- 4 Table of Basic Integrals tives $f(x) = \int_{\mathbb{R}^{d}} f(x) dx - F(x) + C$

| $\frac{y}{C}$ | $\frac{dy}{dx}$ |
|-----------------------|--|
| C | 0 |
| x | 1 |
| $ax^2 + bx + c$ | 2ax + b |
| x^n | nx^{n-1} |
| $x^{-1}, \frac{1}{x}$ | $-\frac{1}{x^2}$ -1 |
| \sqrt{x} | $\frac{1}{2\sqrt{x}}$ |
| $\sqrt[n]{x}$ | $\frac{1}{n\sqrt[n]{x^{n-1}}}$ |
| ln(x) | $\frac{1}{x}$ |
| $log_a(x)$ | $\frac{1}{xln(a)}$ |
| a^x | $a^x ln(a)$ |
| e^x | e^x |
| sin(x) | cos(x) |
| cos(x) | -sin(x) |
| tan(x) | $\frac{1}{\cos^2 x}$, $\sec^2 x$ |
| cot(x) | $-\frac{1}{\sin^2 x}, -\csc^2 x$ |
| sec(x) | $\frac{-\frac{\cos^2 x}{\sin^2 x}, -\csc^2 x}{\tan(x)\sec(x)}$ |
| csc(x) | -cot(x)csc(x) |

| f(x) | $\int f(x)dx = F(x) + C$ |
|------------------------------|---|
| x^{α} | $\frac{x^{\alpha+1}}{\alpha+1} + C$ |
| $\alpha \neq 0$ | |
| sin(kx) | $-\frac{\cos(kx)}{k} + C$ |
| cos(kx) | $\frac{\sin(kx)}{k} + C$ |
| $sec^2(kx)$ | $\frac{k}{tan(kx)} + C$ |
| $csc^2(kx)$ | $-\frac{\cot(kx)}{k+C}$ |
| e^{kx} | $\frac{-\frac{1}{k+C}}{\frac{e^{kx}}{k}+C}$ |
| $x^{-1}, \frac{1}{x}$ | ln x + C |
| $\frac{1}{\sqrt{1-x^2}}$ | $sin^{-1} + C$ |
| 1 | $tan^{-1}x + C$ |
| $\frac{1+x^2}{a^{kx}}$ | $\frac{1}{k \ln a} a^{kx} + C$ |
| $\frac{1}{\sqrt{a^2 - x^2}}$ | $sin^{-1}\frac{x}{a}+C$ |
| $\frac{1}{a^2 + x^2}$ | $\frac{1}{a}tan^{-1}(x/a) + C$ |

Substitution Techniques

5.2 Integration by Parts

5.1 U Substitution

$$\int f(x)g'(x)dx = f(x)g(x) - \int g(x)f'(x)dx$$
$$\int udv = uv - \int vdu$$

$$\int f(g(x))g'(x)dx = \int f(u)du = F(u) + C$$
where: $u = g(x), du = g'(x)$

$$\int_{a}^{b} f(x)g'(x) = f(x)g(x)\Big|_{a}^{b} - \int_{a}^{b} g(x)f'(x)dx$$

6 Engineering Formulas

6.1 Spring Formulas

$$F = kx$$

$$W = \int_{a}^{b} kx dx$$

$$F = \text{Force (Newtons [N])}$$

$$k = \text{spring constant (Newton meters }^{N}/_{m})$$

$$x = \text{change in distance (meters [m])}$$

$$W = \text{Work (Joules [J])}$$

$$a = \text{initial length (meters [m])}$$

$$b = \text{final length (meters [m])}$$

6.2 Fluid Formulas

$$W = F \cdot d = \int F dx$$

$$V = \pi r^2 h \text{(apply to cylinders)}$$

$$F = m \cdot a = V \cdot \rho$$

$$W = \text{Weight ()}$$

$$F = \text{Force (Newtons [N])}$$

$$d = \text{distance (meters [d])}$$

$$m = \text{mass (meters}^3[m^3])$$

$$a = \text{acceleration (meters per second}^2[m/s^2])$$

$$\rho = \text{Something}$$

7 Method of Partial Fractions

$$\int \frac{P_n(x)}{Q_m(x)} dx \text{ when } m > n$$

n and m are defined as the degree of the numerator and the denominator.

7.1 Decomposition Types

| Type | Factor Example | Decomposition |
|---------------------------------------|----------------|---|
| Linear Factor | (x-4) | $\frac{A}{x-4}$ |
| Repeated Linear Factor | $(x-4)^2$ | $\frac{A}{(x+4)} + \frac{B}{(x+4)^2}$ |
| Quadratic Irreducible Factor | $(x^2 + 4)$ | $\frac{Ax+B}{x^2+4}$ |
| Repeated Quadratic Irreducible Factor | $(x^2+4)^2$ | $\frac{Ax+B}{(x^2+4)} + \frac{Cx+D}{(x^2+4)^2}$ |

8 Additional Resources

Print

Calculus Study Guide: https://mt-jfk.com/ap-calculus-study-guide.pdf

Video

The Organic Chemistry Tutor: https://www.youtube.com/channel/UCEWpbFLzoYGPfuWUMFPSaoA Black Pen Red Pen: https://www.youtube.com/user/blackpenredpen