

1. Fixed point algorithm

$$x_{k+1} = g(x_k)$$

$$g(x) = x$$

- 9) Show that analytically that for  $g(x) = ax + b$ ,  $|a| < 1$ , the fixed point iteration converges to the solution  $\bar{x} = b/(1-a)$

For a fixed point iteration  $|g'(x)| < 1$ .

$$g(x) = ax + b \Rightarrow g'(x) = a$$

$$|g'(x)| = |a| < 1$$

If  $|g'(x)| = |a| < 1$  is true then  $g(x)$  has a unique solution,  $g(\bar{x}) = \bar{x}$

$$a\bar{x} + b = \bar{x}$$

$$\bar{x} = \frac{b}{1-a}$$

hence  $g(x)$  converges to the solution  $\bar{x} = \frac{b}{1-a}$

Also for the fixed point iteration  $x_k$

$$\text{Suppose } |x_k - \bar{x}| = |g(x_{k+1}) - g(\bar{x})|$$

$$\text{Since } g(x_{k+1}) = x_{k+1} \quad g(x_{k-1}) = ax_{k-1} + b$$

$$|x_k - \bar{x}| = \left| ax_{k-1} + b - \frac{b}{1-a} \right|$$

$$\text{Since } g(\bar{x}) = \bar{x} = \frac{b}{1-a}$$

$$|x_k - \bar{x}| = \left| q x_{k-1} - \frac{ab}{1-q} \right|$$

$$\text{Take } \bar{x} = \frac{b}{1-q}$$

$$|x_k - \bar{x}| = |q(x_{k-1} - \bar{x})|$$

$$|x_k - \bar{x}| \leq |q| |x_{k-1} - \bar{x}|$$

$$\leq |q|^2 |x_{k-2} - \bar{x}|$$

$$|x_k - \bar{x}| \leq |q|^3 |x_{k-3} - \bar{x}|$$

⋮

$$|x_k - \bar{x}| \leq |q|^k |x_0 - \bar{x}|$$

As  $k \rightarrow \infty$ , since  $|q| < 1$ , then  $|q|^k |x_0 - \bar{x}| \rightarrow 0$   
therefore

$$|x_k - \bar{x}| \rightarrow 0$$

hence the fixed point iteration converges to  $\bar{x}$

$$x_k = \bar{x} = \frac{b}{1-q}$$


---

b) Show that for any fixed point problem, the error  $e_k = x_k - \bar{x}$  satisfies  $e_{k+1} = q^k e_0$

Using the Intermediate Value Theorem, it can be stated that

$$\frac{g(x_k) - g(\bar{x})}{x_k - \bar{x}} = g'(\xi)$$

$$g(x_k) - g(\bar{x}) = g'(\xi) (x_k - \bar{x})$$

but for fixed point Scheme

$$g(x_k) = x_{k+1}$$

$$g'(\xi) = q$$

$$g(\bar{x}) = \bar{x}$$

$$x_{k+1} - \bar{x} = q(x_k - \bar{x})$$

$$x_{k+1} - \bar{x} = q^2(x_{k-1} - \bar{x})$$

$$x_{k+1} - \bar{x} = q^3(x_{k-2} - \bar{x}) = q^4(x_{k-3} - \bar{x})$$

⋮

$$x_{k+1} - \bar{x} = q^k(x_0 - \bar{x})$$

but  $e_{k+1} = x_{k+1} - \bar{x}$ ,  $e_0 = x_0 - \bar{x}$

$$\underline{\underline{e_{k+1} = q^k e_0}}$$

c) Show that we can approximate the error using

$$e_{k+1} \approx \frac{q}{q-1} (x_{k+1} - x_k)$$

$$e_{k+1} = x_{k+1} - \bar{x}$$

Subtracting and adding  $x_k$  on the left hand side, we obtain

$$e_{k+1} = x_{k+1} - \bar{x} - x_k + x_k$$

$$e_{k+1} = x_{k+1} - x_k + x_k - \bar{x}$$

we have  $e_{k+1} = q e_k \Rightarrow e_k = \frac{q}{e_{k+1}}, *$

and  $e_k = x_k - \bar{x}$

therefore  $e_{k+1} = x_{k+1} - x_k + x_k - \bar{x}$  becomes

$$e_{k+1} \approx x_{k+1} - x_k + e_k$$

$$e_{k+1} \approx x_{k+1} - x_k + \frac{q}{e_{k+1}}$$

$$e_{k+1} \approx \frac{q}{q-1} (x_{k+1} - x_k)$$


---

d) Show that for the linear problem  $g(x) = qx + b$ , the error estimate in problem 1c is exactly equal to the error you found in problem 1b.

$$e_{k+1} \approx \frac{q}{q-1} (x_{k+1} - x_k)$$

we know that  $g(x) = x_{k+1} = qx_k + b$ .

$$e_{k+1} \approx \frac{q}{q-1} (g(x_k) - x_k) = \frac{q}{q-1} (qx_k + b - x_k)$$

$$e_{k+1} \approx q x_k + q \left( \frac{b}{q-1} \right), \text{ but } \bar{x} = \frac{b}{1-q}$$

$$e_{k+1} = q x_k - q \bar{x} = q(x_k - \bar{x})$$

$$e_{k+1} = q(x_k - \bar{x}), \text{ take } x_k - \bar{x} = e_k$$

$$e_{k+1} = q e_k = q^2 e_{k-2} = q^3 e_{k-3} \dots = q^k e_0$$

therefore  $x_{k+1} = q^k x_0$

e) How many iterations does the fixed point algorithm require to solve  $g(x) = \frac{1}{10}x + 1 = x$  to a tolerance of  $10^{-8}$ ?

from  $g(x) = \frac{1}{10}x + 1$ ,  $\Rightarrow a = \frac{1}{10}$ ,  $b = 1$

tolerance,  $\epsilon = 10^{-8}$

Using  $|x_{k+1}| \leq \epsilon$

but  $x_{k+1} = q^k x_0$

$$q^k x_0 \leq \epsilon$$

Introducing  $\log$  both sides

$$k \log q + \log |x_0| \leq \log \epsilon$$

$$k \log \left(\frac{1}{10}\right) + \log |x_0| \leq \log 10^{-8}$$

$$-k \log 10 \leq -8 \log 10 - \log |x_0|$$

$$k \geq 8 + \log |x_0|$$

\* The fixed point algorithm require atleast 8 iterations to solve  $g(x) = \frac{1}{10}x + 1$

$$k \geq 8 + \log |x_0|$$

and thus depend on  $\log |x_0|$



## 2. Steffensen's Method.

$$x_{k+1} = x_k - \frac{(g(x_k) - x_k)^2}{g(g(x_k)) - 2g(x_k) + x_k}$$

a) Show ~~that~~ analytically that for any  $g(x)$ , the iteration used in Steffensen's Method satisfies

$$\lim_{x \rightarrow \bar{x}} \left( x - \frac{(g(x) - x)^2}{g(g(x)) - 2g(x) + x} \right) = \bar{x}$$

Where  $\bar{x}$  satisfies  $g(\bar{x}) = \bar{x}$

Using L'Hopital's Rule.

$$\lim_{x \rightarrow \bar{x}} \left( x - \frac{2(g'(x) - 1)(g(x) - \bar{x})}{g'(x)g'(g(x)) - 2g'(x) + 1} \right)$$

$$\text{but } g(\bar{x}) = \bar{x}$$

$$= \bar{x} - \frac{2(g'(\bar{x}) - 1)(\bar{x} - \bar{x})}{g'(\bar{x})g'(g(\bar{x})) - 2g'(\bar{x}) + 1}$$

$$= \bar{x} - 0$$

$$= \bar{x}$$

b) Show analytically that Steffensen's iteration converges in one step for the fixed point problem.

$$g(x) = ax + b = x, \text{ for } |a| < 1$$

$$\text{from } x_{k+1} = x_k - \frac{(g(x_k) - x_k)^2}{g(g(x_k)) - 2g(x_k) + x_k}$$

at  $k=0$

$$x_1 = x_0 - \frac{(g(x_0) - x_0)^2}{g(g(x_0)) - 2g(x_0) + x_0}$$

$x_1 \neq$   $g(x_0) = ax_0 + b$

$$x_1 = x_0 - \frac{(ax_0 + b - x_0)^2}{a(ax_0 + b) + b - 2(ax_0 + b) + x_0}$$

$$x_1 = x_0 - \frac{(a-1)(x_0) + b}{(a-1)}$$

$$x_1 = x_0 - x_0 + \frac{b}{a-1} = x_0 - x_0 - \frac{b}{a-1}$$

$$x_1 = \frac{b}{1-a} = \bar{x}$$

$$\underline{\underline{x_1 = \bar{x}}}$$

hence it converges in one step.

# No. 3 LU Decomposition

$$E_4 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -L_{41} & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & -7 & -2 & 2 \\ -3 & 5 & 1 & 0 \\ 6 & -4 & 0 & -5 \\ -9 & 5 & -5 & 12 \end{bmatrix}$$

9) Show that

$$E_4 E_3 E_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -L_{41} & 1 & 0 & 0 \\ -L_{31} & 0 & 1 & 0 \\ -L_{41} & 0 & 0 & 1 \end{bmatrix}$$

$$E_4 E_3 E_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -L_{41} & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -L_{31} & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ -L_{21} & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -L_{41} & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ -L_{21} & 1 & 0 & 0 \\ -L_{31} & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$E_4 E_3 E_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -L_{41} & 1 & 0 & 0 \\ -L_{31} & 0 & 1 & 0 \\ -L_{41} & 0 & 0 & 1 \end{bmatrix}$$



- b) Choose multipliers  $L_{ij}$  so that applying  $E_{41} E_{31} E_{21}$  to  $A$  zeros out the entries below  $a_{11}$ .

$$E_{41} E_{31} E_{21} A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -L_{21} & 1 & 0 & 0 \\ -L_{31} & 0 & 1 & 0 \\ -L_{41} & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & -7 & -2 & 2 \\ -3 & 5 & 1 & 0 \\ 6 & -4 & 0 & -5 \\ -9 & 5 & -5 & 12 \end{bmatrix}$$

Choose  $L_{21} = -1$

$$L_{31} = 2$$

$$L_{41} = -3$$

$$E_{41} E_{31} E_{21} A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ -2 & 0 & 1 & 0 \\ 3 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & -7 & -2 & 2 \\ -3 & 5 & 1 & 0 \\ 6 & -4 & 0 & -5 \\ -9 & 5 & -5 & 12 \end{bmatrix}$$

$$= \begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & 10 & 4 & -9 \\ 0 & -16 & -11 & 18 \end{bmatrix}$$

- c) Show that the inverse of  $E_{41} E_{31} E_{21}$  is

$$(E_{41} E_{31} E_{21})^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ L_{21} & 1 & 0 & 0 \\ L_{31} & 0 & 1 & 0 \\ L_{41} & 0 & 0 & 1 \end{bmatrix}$$

$$(E_1 E_3 E_2)^{-1} = \frac{1}{\det(E_1 E_3 E_2)} (\text{Adjoint}(E_1 E_3 E_2))$$

$$\det(E_1 E_3 E_2) = \begin{vmatrix} 1 & 0 & 0 & 0 \\ -L_2 & 1 & 0 & 0 \\ -L_3 & 0 & 1 & 0 \\ -L_4 & 0 & 0 & 1 \end{vmatrix} = -1 \begin{vmatrix} 1 & 0 & 0 \\ -L_2 & 1 & 0 \\ -L_3 & 0 & 1 \end{vmatrix} = \underline{\underline{1}}$$

the Adjoint  $(E_1 E_3 E_2)$  is the transpose of the Cofactor Matrix  $(E_1 E_3 E_2)$

$$\text{Cofactor Matrix} = \begin{bmatrix} 1 & L_2 & L_3 & L_4 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\text{Adjoint}(E_1 E_3 E_2) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ L_2 & 1 & 0 & 0 \\ L_3 & 0 & 1 & 0 \\ L_4 & 0 & 0 & 1 \end{bmatrix}$$

$$|E_1 E_3 E_2| = \frac{1}{1} \begin{bmatrix} 1 & 0 & 0 & 0 \\ L_2 & 1 & 0 & 0 \\ L_3 & 0 & 1 & 0 \\ L_4 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ L_2 & 1 & 0 & 0 \\ L_3 & 0 & 1 & 0 \\ L_4 & 0 & 0 & 1 \end{bmatrix}$$

3(a) From the above steps, derive the LU decomposition of a general  $4 \times 4$  Matrix. Use these to derive the LU decomposition of the matrix in (3).

For U

$$E_{41} E_{31} E_{21} A = U_1$$

$$(E_{42} E_{32}) U_1 = U_2$$

$$E_{43} U_2 = U$$

So

$$U = \cancel{E_{43}} \cancel{E_{42}} \cancel{E_{41}} E_{32} E_{31} E_{21} A$$

$$U = E_{43} E_{42} E_{32} E_{41} E_{31} E_{21} A$$

for L

$$(E_{41} E_{31} E_{21})^{-1} = L_1$$

$$(E_{42} E_{32})^{-1} L_1 = L_2$$

$$(E_{43})^{-1} L_2 = L$$

So

$$L = (E_{43} E_{42} \cancel{E_{32}} \cancel{E_{41}} E_{31} E_{21})^{-1}$$

Suppose we have  $(AB)^{-1} = A^{-1} B^{-1}$

$$L = (E_{43} E_{42} E_{32} E_{41} E_{31} E_{21})^{-1} = (E_{43} E_{42} E_{31})^{-1} (E_{41} E_{31} E_{21})^{-1}$$

$$\text{Let } (E_{41} E_{31} E_{21})^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ l_{21} & 1 & 0 & 0 \\ l_{31} & 0 & 1 & 0 \\ l_{41} & 0 & 0 & 1 \end{bmatrix}$$

$$(E_{13} E_{42} E_{32})^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & L_{32} & 1 & 0 \\ 0 & L_{32}L_{42} + L_{43} & L_{43} & 1 \end{bmatrix}$$

$$L = (E_{13} E_{42} E_{32})^{-1} (E_{41} E_{31} E_{21})^{-1}$$

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & L_{32} & 1 & 0 \\ 0 & L_{32}L_{42} + L_{43} & L_{43} & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ L_{41} & 1 & 0 & 0 \\ L_{31} & 0 & 1 & 0 \\ L_{41} & 0 & 0 & 1 \end{bmatrix}$$

$$\text{Let } \begin{array}{ll} L_{21} = a & L_{32} = d \\ L_{31} = b & L_{42} = e \\ L_{41} = c & L_{43} = f \end{array}$$

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ a & 1 & 0 & 0 \\ da + b & d & 1 & 0 \\ fb + a(df + e) + c & df + e & f & 1 \end{bmatrix}$$

$$\text{And } U = E_{43} E_{42} E_{32} E_{41} E_{31} E_{21} A$$

48) Find the LU decomposition of the matrix in (3)

$$A = \begin{bmatrix} 3 & -7 & -2 & 2 \\ -3 & 5 & 1 & 0 \\ 6 & -4 & 0 & -5 \\ -9 & 5 & -5 & 12 \end{bmatrix}$$

$$A = LU$$

where

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ l_{21} & 1 & 0 & 0 \\ l_{31} & l_{32} & 1 & 0 \\ l_{41} & l_{42} & l_{43} & 1 \end{bmatrix}, \quad U = \begin{bmatrix} u_{11} & u_{12} & u_{13} & u_{14} \\ 0 & u_{22} & u_{23} & u_{24} \\ 0 & 0 & u_{33} & u_{34} \\ 0 & 0 & 0 & u_{44} \end{bmatrix}$$

Using Gaussian Elimination method on ~~a~~  $A$ , we obtain an ~~upper~~ triangular Matrix  $U$ , as follows.

take  $l_{21} = -1$

$$\begin{array}{l} R_1 \\ R_2 \\ R_3 \\ R_4 \end{array} \begin{bmatrix} 3 & -7 & -2 & 2 \\ -3 & 5 & 1 & 0 \\ 6 & -4 & 0 & -5 \\ -9 & 5 & -5 & 12 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 + R_1} \begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 5 \\ 6 & -4 & 0 & -5 \\ -9 & 5 & -5 & 12 \end{bmatrix}$$

take  $l_{31} = -2$  ~~In this case  $l_{21} = -1$~~

$$\begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 5 \\ 6 & -4 & 0 & -5 \\ -9 & 5 & -5 & 12 \end{bmatrix} \xrightarrow{R_3 \leftarrow R_3 + 2R_2} \begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 5 \\ 0 & -18 & -4 & -1 \\ -9 & 5 & -5 & 12 \end{bmatrix}$$

~~In this case  $l_{31} = -2$~~



$$\begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & -18 & -4 & -1 \\ -9 & 5 & -5 & 12 \end{bmatrix} \xrightarrow{R_4 \leftarrow R_4 + 3R_1} \begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & -18 & -4 & -1 \\ 0 & -16 & -11 & 18 \end{bmatrix}$$

In this case <sup>we took</sup>  $L_{41} = -3$

for  $L_{32}$  take  $L_{32} = 9$

$$\begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & -18 & -4 & -1 \\ 0 & -16 & -11 & 18 \end{bmatrix} \xrightarrow{R_3 \leftarrow R_3 - 9R_2} \begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & 0 & 5 & -19 \\ 0 & -16 & -11 & 18 \end{bmatrix}$$

take  $L_{42} = 8$

$$\begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & 0 & 5 & -19 \\ 0 & -16 & -11 & 18 \end{bmatrix} \xrightarrow{R_4 \leftarrow R_4 - 8R_2} \begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & 0 & 5 & -19 \\ 0 & 0 & -3 & 2 \end{bmatrix}$$

take  $L_{43} = -\frac{3}{5}$

$$\begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & 0 & 5 & -19 \\ 0 & 0 & -3 & 2 \end{bmatrix} \xrightarrow{R_4 \leftarrow R_4 + \frac{3}{5}R_3} \begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & 0 & 5 & -19 \\ 0 & 0 & 0 & -\frac{47}{5} \end{bmatrix}$$



Hence we Obtain,  $U$ ,

$$U = \begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & 0 & 5 & -19 \\ 0 & 0 & 0 & -\frac{47}{5} \end{bmatrix}$$

Correspondingly  $L$ ,

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ -2 & 9 & 1 & 0 \\ -3 & 8 & -\frac{3}{5} & 1 \end{bmatrix}$$

So  $A = LU$

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ -2 & 9 & 1 & 0 \\ -3 & 8 & -\frac{3}{5} & 1 \end{bmatrix} \begin{bmatrix} 3 & -7 & -2 & 2 \\ 0 & -2 & -1 & 2 \\ 0 & 0 & 5 & -19 \\ 0 & 0 & 0 & -\frac{47}{5} \end{bmatrix}$$


---

## 5. Jacobi Method

Assume that the following  $2 \times 2$  matrix  $A$  is strictly diagonally dominant

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

q) Show that  $\rho(I - \Delta^{-1}A) < 1$

take  $\Delta = \begin{bmatrix} a_{11} & 0 \\ 0 & a_{22} \end{bmatrix}$

$$\Delta^{-1} = \begin{bmatrix} 1/a_{11} & 0 \\ 0 & 1/a_{22} \end{bmatrix}$$

$$\Delta^{-1}A = \begin{bmatrix} 1/a_{11} & 0 \\ 0 & 1/a_{22} \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \begin{bmatrix} 1 & a_{12}/a_{11} \\ a_{21}/a_{22} & 1 \end{bmatrix}$$

then

$$I - \Delta^{-1}A = \begin{pmatrix} 0 & a_{12}/a_{11} \\ a_{21}/a_{22} & 0 \end{pmatrix}$$

the Spectral radius,  $\rho$ , is the maximum <sup>absolute</sup> value of the eigen values; so to compute the eigen values we use the characteristic equation.

$$|(I - \Delta^{-1}A) - \lambda I| = 0$$

$$\begin{vmatrix} -\lambda & a_{12}/a_{11} \\ a_{21}/a_{22} & -\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 = \frac{a_{12}a_{21}}{a_{11}a_{22}}$$

Since  $a_{22}$  and  $a_{11}$  are diagonally dominant  
~~and~~ entries then  $a_{22}a_{11} > a_{21}a_{12}$ , therefore

$$\lambda^2 = \frac{a_{21}a_{12}}{a_{22}a_{11}} < 1$$

$$\lambda = \pm \sqrt{\frac{a_{21}a_{12}}{a_{22}a_{11}}}$$

$\rho$  is the largest  $|\lambda|$ , so

$$|\lambda| = \left| \sqrt{\frac{a_{21}a_{12}}{a_{22}a_{11}}} \right| < 1$$

So the Spectral radius  $\rho(I - D^{-1}A) < 1$

Jacobi Iteration will Converge, since for Jacobi,  
 we take  $M = D$ , and we have shown that

$$\rho(I - M^{-1}A) < 1, \text{ hence the Iteration Converges}$$

Since according to ~~Convergence~~ an Iteration Converges  
 if and only if  $\rho(I - M^{-1}A) < 1$

$$X_{k+1} = (I - M^{-1}A)X_k + M^{-1}b.$$

a) Show that if  $M=A$ , the iteration converges in one step.

If  $M=A$

$$X_{k+1} = (I - A^{-1}A)X_k + A^{-1}b$$

but  $A^{-1}A = I$

$$X_{k+1} = (I - I)X_k + A^{-1}b$$

$$X_{k+1} = A^{-1}b$$

but  $A\bar{x} = b \Rightarrow \bar{x} = A^{-1}b$

therefore  $X_{k+1} = \bar{x}$ , hence converges in one step

b) Show that  $Ae_k = -r_k$ , where  $r_k = b - AX_k$ ,

$$e_k = x_k - \bar{x},$$

and  $\bar{x}$  solves  $AX = b$  exactly

$$Ae_k = A(x_k - \bar{x}).$$

$$Ae_k = AX_k - A\bar{x}$$

we know that  $A\bar{x} = b$

$$Ae_k = AX_k - b$$

$$\underline{Ae_k = -r_k} \quad \text{since } r_k = b - AX_k.$$

c) Show that the iteration for the error  $e_k$  is given by

$$e_{k+1} = (I - M^{-1}A) e_k$$

from

$$X_{k+1} = (I - M^{-1}A) X_k + M^{-1}b$$

Subtract  $\bar{x}$  from both sides

$$X_{k+1} - \bar{x} = (I - M^{-1}A) X_k - \bar{x} + M^{-1}b$$

We know that  $X_{k+1} - \bar{x} = e_{k+1}$

$$e_{k+1} = (I - M^{-1}A) X_k - \bar{x} + M^{-1}b$$

$$\text{Take } A\bar{x} = b.$$

$$e_{k+1} = (I - M^{-1}A) X_k - \bar{x} + M^{-1}A\bar{x}$$

$$e_{k+1} = (I - M^{-1}A) X_k - (I - M^{-1}A)\bar{x}$$

$$e_{k+1} = (I - M^{-1}A) (X_k - \bar{x})$$

$$\text{but } X_k - \bar{x} = e_k$$

$$e_{k+1} = (I - M^{-1}A) e_k$$


---

d) Show that

$$\|e_k\| \leq \|I - M^{-1}A\|^k \|e_0\|$$

from  $e_{k+1} = (I - M^{-1}A) e_k$

$$e_{k+1} = (I - M^{-1}A) (I - M^{-1}A) e_{k-1}$$

$$e_{k+1} = (I - M^{-1}A)^2 e_{k-1}$$

$$e_k = (I - M^{-1}A)^2 e_{k-2}$$

$$e_k = (I - M^{-1}A)^3 e_{k-3}$$

⋮

$$e_k = (I - M^{-1}A)^k e_0$$

take the Modulus both sides, and then apply the triangular inequality

$$\|e_k\| = \|(I - M^{-1}A)^k e_0\|$$

$$\|e_k\| \leq \|(I - M^{-1}A)\|^k \|e_0\|$$

Q Show that

$$k \geq \frac{\log(\epsilon)}{\log \|I - M^{-1}A\|}$$

from  $\|e_k\| \leq \epsilon$

~~but  $\|e_k\| \leq \|(I - M^{-1}A)\|^k \|e_0\|$~~

but  $e_k = (I - M^{-1}A)^k e_0$

$$\|(I - M^{-1}A)^k e_0\| \leq \epsilon$$

taking log both sides we obtain

$$k \log \|I - M^{-1}A\| + \log \|e_0\| \leq \log \epsilon$$



~~Since~~

$$k \log \|I - M^{-1}A\| \leq \log \epsilon - \log \|e_0\|$$

Since  $\log \|I - M^{-1}A\| < 0$ , then

$$k \geq \frac{\log \epsilon - \log \|e_0\|}{\log \|I - M^{-1}A\|}$$

$$k \geq \frac{\log \epsilon}{\log \|I - M^{-1}A\|} - \frac{\log \|e_0\|}{\log \|I - M^{-1}A\|}$$

The term  $\frac{\log(\epsilon)}{\log \|I - M^{-1}A\|}$  dominates therefore

$$k \geq \frac{\log(\epsilon)}{\log \|I - M^{-1}A\|}$$

f) Since  $\rho(I - M^{-1}A)$  is the largest absolute value of the eigen values of  $(I - M^{-1}A)$ , and the number of iterations is given by

$$k \geq \frac{\log \epsilon}{\log \|I - M^{-1}A\|} - \frac{\log \|e_0\|}{\log \|I - M^{-1}A\|}$$

So for larger values of  $\rho(I - M^{-1}A)$  implies the term  $\log \|e_0\|$

is also large. This is

because  $\log \|I - M^{-1}A\|$  <sup>will be</sup> ~~is~~ <sup>very</sup> small to reduce  $\log \|e_0\|$ .

But again, as  $\log \|I - M^{-1}A\|$  approaches to zero from the left side, it means that this term  $\log \|e_0\|$

$\log \|I - M^{-1}A\|$  increases and ~~are~~ eventually become

Undefined at  $\log \|I - M^{-1}A\| = 0$ , this case the solution ~~no longer~~ exists, so the the estimate iterations  $k$  will seem to underestimate the actual number of  $k$  i.e.

$$k \geq \frac{\log(\epsilon)}{\log \|I - M^{-1}A\|}$$

+ a very big term after which becomes undefined.

9) Show analytically that the update to the residual  $r_{k+1}$  in the Conjugate Gradient Algorithm is equal to  $b - AX_k$

Suppose  $A$  is symmetric, positive definite

$$F(X) = \frac{1}{2} X^T A X - b^T X$$

So the direction of the greatest decrease of  $F$  is given by  $-\nabla F(X_{k+1}) = r_{k+1}$  at the update to residual  $r_{k+1}$

So taking the residual as the search direction we have

$$X_{k+1} = X_k + \alpha_k r_k$$

$$-\nabla F(X_{k+1}) = r_{k+1}$$

$$-\nabla F(X_k + \alpha_k r_k) = r_{k+1}$$

$$F(X_k + \alpha_k r_k) = \frac{1}{2} (X_k + \alpha_k r_k)^T A (X_k + \alpha_k r_k) - b^T (X_k + \alpha_k r_k)$$

$$\nabla F(X_k + \alpha_k r_k) = \frac{dF}{dX_k} = \frac{1}{2} (2AX_k) - b$$

$$\nabla F(X_k + \alpha_k r_k) = AX_k - b$$

$$-\nabla F(X_k + \alpha_k r_k) = b - AX_k = r_{k+1}$$

therefore  $r_{k+1} = b - AX_k$