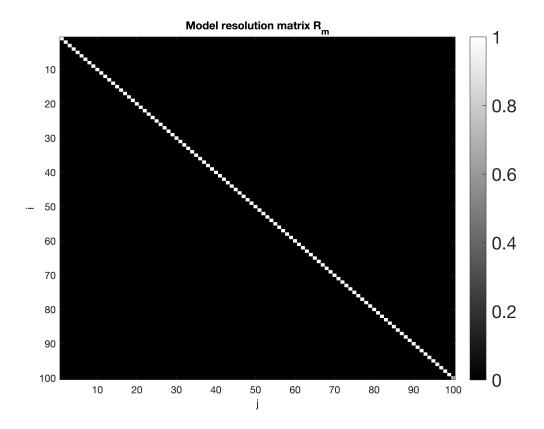
## Habeeb and Brian

## a. Invert for density perturbations along the pipe transect in kg/m3 using least squares.

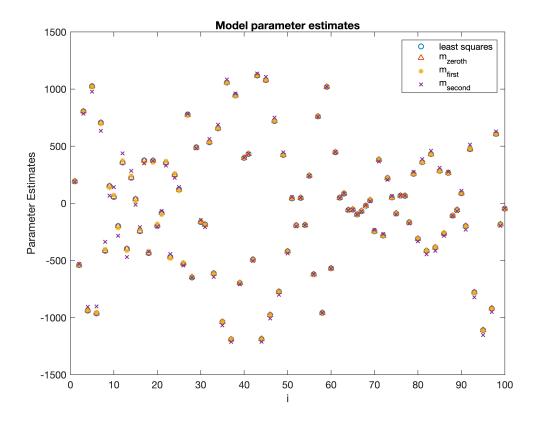
The magnitude of the least square estimates coincide with those of rhox, hence the estimates approximate rhox. The estimates lies between  $-1.1891 * 10^3$  and  $1.1185 * 10^3$ 

Analyze the resolution in your model parameter estimates.



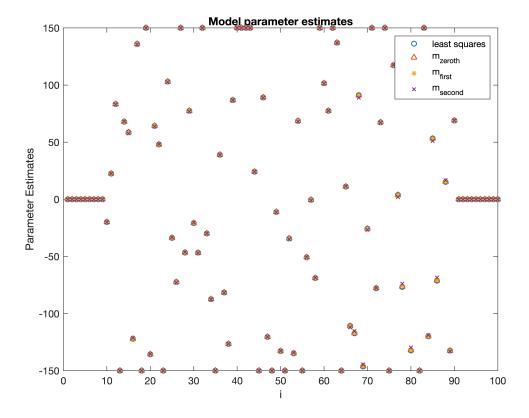
The model parameter estimates are perfectly resolved, since all the entries on the major diagonal equal to 1 and the rest are zeros.

b. Invert for density perturbations along the pipe transect in kg/m3 using second order Tikhonov regularization and TGSVD.



According to the plot above, they all have almost the same estimates, however the TGSVD solutions depends on the value of q.

c. Solve the problem using second-order Tikhonov regularization combined with BVLS and a TGSVD analysis.



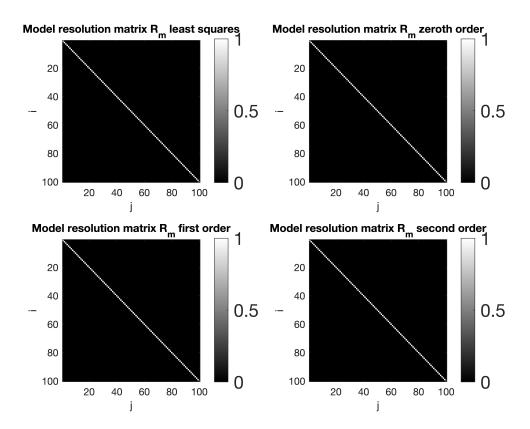
According to the plot above, they all have almost the same estimates, however after implementing the bounds, the estimates outside the bounds are neglible (hence made zeros.

## Where are the prominent maxima and minima located?

minima_locations = 1×11											
13	18	23	35	45	48	51	55	64	75	82	
						_		-		_	
maxima locations = 1×12											
19	27	32	40	41	42	43	59	62	71	74	83
		-						-			
$maxima_locations_zeroth = 1 \times 11$											
19	27			41	42	43	62	71	74	83	
_		_	-			_	-				

They all have the same prominent minima and maxima locations except the mxima for the zeroth order solution.

Analyze the resolution in your model parameter estimates.



The model parameter estimates are perfectly resolved, since all the entries on the major diagonal equal to 1 and the rest are zeros, in all the four approaches used.

## **Appendix**

```
clc
clear all
data = load('gdata.mat');
dn = data.dn;
x = data.x;
rhox = data.rhox;
a = 0; b = 1000; n = 100; m = 500;
R = 6.67428e-11; % Newton's gravitational constant
A = 1;
h = 25 - sqrt(A/pi);
dxc = (b-a)/n;
g = @(xc,x) (R^*h./((xc - x).^2 + h^2)^(3/2));
xc = \Pi;
for j = 1:n
  xc = [xc a + (dxc/2) + (j-1)*dxc]; %form xc
end
xc;
G = zeros(m,n);
for i = 1:m
  for j = 1:n
     G(i,j) = g(xc(j), x(i)).*dxc;
  end
end
G;
a. Invert for density perturbations along the pipe transect in kg/m3 using least squares.
ML2 = inv(G'*G)*G'*dn;
min(ML2);
max(ML2);
Analyze the resolution in your model parameter estimates.
% Get the singular values for the system matrix
[U,S,V] = svd(G);
[m,n] = size(G);
%rank
p=rank(G);
% model resolution matrix
Vp=V(:,1:p);
Rm=Vp*Vp';
figure(1)
```

```
clf
colormap('gray')
imagesc(Rm)
set(colorbar, 'Fontsize', 18);
xlabel('i')
ylabel('i')
title('Model resolution matrix R_{m}')
b. Invert for density perturbations along the pipe transect in kg/m3 using second order Tikhonov
regularization and TGSVD.
%generate roughening matrices
L1 = get \mid rough(n,1);
L2 = get_l_rough(n,2);
% TGSVD
[U.V.X.S.M] = gsvd(G.eve(n)): Y = (inv(X)'):
[U1,V1,X1,S1,M1] = gsvd(G,L1); Y1 = (inv(X1)');
[U2,V2,X2,S2,M2] = gsvd(G,L2); Y2 = (inv(X2)');
% generalized singular values of G and L
lam = @(S)  sqrt(diag(S'*S));
mu = @(M)  sqrt(diag(M'*M));
k = 0: %m > n
q2 = 100;
Lam = lam(S); Lam1 = lam(S1); Lam2 = lam(S2);
M0 = model parameters(q2,U,Lam,Y,k,dn,n);
M 1 = model parameters(g2,U1,Lam1,Y1,k,dn,n);
M 2 = model parameters(q2,U2,Lam2,Y2,k,dn,n);
figure(2)
clf
plot(ML2, 'o', 'LineWidth', 2, "MarkerSize", 5); hold on
plot(M0,'^','LineWidth',2,"MarkerSize",5);
plot(M 1,'*','LineWidth',2,"MarkerSize",5);
plot(M_2,'x','LineWidth',2,"MarkerSize",5); hold off
legend('least squares', 'm {zeroth}', 'm {first}', 'm {second}')
xlabel('i'); ylabel('Parameter Estimates')
title('Model parameter estimates')
c. Solve the problem using second-order Tikhonov regularization combined with BVLS and a TGSVD
analysis.
%zeroth order
L = eye(n);
% get the points and solutions for the first and second order TGSVD L-curve
[rho,eta,reg_param,ms]=I_curve_tgsvd(U,dn,X,S,G,L);
[rho1,eta1,reg_param1,m1s]=I_curve_tgsvd(U1,dn,X1,S1,G,L1);
```

```
[rho2,eta2,reg_param2,m2s]=I_curve_tgsvd(U2,dn,X2,S2,G,L2);
irea corner = 90:
alpha0=rho(ireg corner);
alpha1=rho1(ireg corner);
alpha2=rho2(ireg_corner);
alpha = [alpha0 alpha1 alpha2];
%generate lower and upper bounds
l= -150.*ones(n.1):
u = 150.*ones(n,1);
%stack the dn matrices
d0 = [dn; zeros(n,1)];
d1 = [dn; zeros(n-1,1)];
d2 = [dn; zeros(n-2,1)];
%stack the matrices
A = [G; alpha(1)*L];
A1 = [G; alpha(2)*L1];
A2 = [G; alpha(3)*L2];
%find positions of 91 and 899 in m
pos = find(xc < 91); pos 91 = pos(end);
pos = find(xc > 899); pos 899 = pos(1);
%setting bounds for xc
I(1:pos_91) = 0; I(pos_899:end) = 0;
u(1:pos_91) = 0; u(pos_899:end) = 0;
ML2 = bvls(G, dn,l, u); %least squares
M0 = bvls(A, d0, I, u);
M1 = bvls(A1, d1, l, u);
M2 = bvls(A2, d2, l, u);
figure(3)
clf
plot(ML2, 'o', 'LineWidth', 2, "MarkerSize", 5); hold on
plot(M0,'^','LineWidth',2,"MarkerSize",5);
plot(M1, '*', 'LineWidth', 2, "MarkerSize", 5);
plot(M2,'x','LineWidth',2,"MarkerSize",5); hold on
legend('least squares', 'm_{zeroth}', 'm_{first}', 'm_{second}')
xlabel('i'); ylabel('Parameter Estimates')
title('Model parameter estimates')
Where are the prominent maxima and minima located?
%minima
find(ML2==min(ML2))';
minima locations =find(M0==min(M0))'
find(M1==min(M1))';
find(M2==min(M2))';
```

```
%maxima
maxima locations = find(ML2==max(ML2))'
maxima locations zeroth =find(M0==max(M0))'
find(M1==max(M1))';
find(M2==max(M2))';
Analyze the resolution in your model parameter estimates.
figure(4)
clf
colormap('gray')
subplot(2,2,1)
[U,S,V] = svd(G); p=rank(G);
Vp=V(:,1:p);
Rm=Vp*Vp';
imagesc(Rm)
set(colorbar, 'Fontsize', 18);
xlabel('i')
vlabel('i')
title('Model resolution matrix R {m} least squares')
subplot(2,2,2)
[U,S,V] = svd(A); p=rank(A);
Vp=V(:,1:p);
Rm=Vp*Vp':
imagesc(Rm)
set(colorbar, 'Fontsize', 18);
xlabel('j')
ylabel('i')
title('Model resolution matrix R_{m} zeroth order')
subplot(2,2,3)
[U,S,V] = svd(A1); p=rank(A1);
Vp=V(:,1:p);
Rm=Vp*Vp';
imagesc(Rm)
set(colorbar, 'Fontsize', 18);
xlabel('j')
ylabel('i')
title('Model resolution matrix R {m} first order')
subplot(2,2,4)
[U,S,V] = svd(A2); p=rank(A2);
Vp=V(:,1:p);
Rm=Vp*Vp';
imagesc(Rm)
set(colorbar, 'Fontsize', 18);
xlabel('j')
ylabel('i')
title('Model resolution matrix R {m} second order')
function [M] = model_parameters(q,U,Lam,Y,k,d,n)
  M = 0;
```

```
\label{eq:fori} \begin{aligned} & \text{for i} = \text{n-q+1:n} \\ & \text{M} = \text{M} + (\text{U(:,i-k)'*d})/(\text{Lam(i))*Y(:,i)}; \\ & \text{end} \\ & \text{end} \end{aligned}
```