

Lecture 3: QR-Factorization

This lecture introduces the Gram–Schmidt orthonormalization process and the associated QR-factorization of matrices. It also outlines some applications of this factorization. This corresponds to section 2.6 of the textbook. In addition, supplementary information on other algorithms used to produce QR-factorizations is given.

1 Gram–Schmidt orthonormalization process

Consider n linearly independent vectors u_1, \dots, u_n in \mathbb{C}^m . Observe that we necessarily have $m \geq n$. We wish to ‘orthonormalize’ them, i.e., to create vectors v_1, \dots, v_n such that

(v_1, \dots, v_k) is an orthonormal basis for $V_k := \text{span}[u_1, \dots, u_k]$ for all $1 \leq k \in [1 : n]$.

It is always possible to find such vectors, and in fact they are uniquely determined if the additional condition $\langle v_k, u_k \rangle > 0$ is imposed. The step-by-step construction is based on the following scheme.

Suppose that v_1, \dots, v_{k-1} have been obtained; search in V_k for a vector

$$\tilde{v}_k = u_k + \sum_{i=1}^{k-1} c_{k,i} v_i \quad \text{such that} \quad \tilde{v}_k \perp V_{k-1};$$

the conditions $0 = \langle \tilde{v}_k, v_i \rangle = \langle u_k, v_i \rangle + c_{k,i}$, $i \in [1 : k-1]$, impose the choice $c_{k,i} = -\langle u_k, v_i \rangle$; now that \tilde{v}_k is completely determined, normalize it to obtain the vector $v_k = \frac{1}{\|\tilde{v}_k\|} \tilde{v}_k$.

For instance, let us write down explicitly all the steps in the orthonormalization process for the vectors

$$\underline{u_1} = [6, 3, 2]^\top, \quad \underline{u_2} = [6, 6, 1]^\top, \quad \underline{u_3} = [1, 1, 1]^\top.$$

- $\tilde{v}_1 = u_1, \quad \|\tilde{v}_1\| = \sqrt{36 + 9 + 4} = 7, \quad \underline{v_1} = 1/7 [6, 3, 2]^\top;$
- $\tilde{v}_2 = u_2 + \alpha v_1, \quad 0 = \langle \tilde{v}_2, v_1 \rangle \Rightarrow \alpha = -\langle u_2, v_1 \rangle = -(16 + 18 + 2)/7, \quad \underline{\alpha = -8},$
 $\tilde{v}_2 = 1/7 [7 \cdot 6 - 8 \cdot 6, 7 \cdot 6 - 8 \cdot 3, 7 \cdot 1 - 8 \cdot 2]^\top = 1/7 [-6, 18, -9]^\top = 3/7 [-2, 6, -3]^\top,$
 $\|\tilde{v}_2\| = 3/7 \sqrt{4 + 36 + 9} = 3, \quad \underline{v_2} = 1/7 [-2, 6, -3]^\top;$
- $\tilde{v}_3 = u_3 + \beta v_2 + \gamma v_1, \quad 0 = \langle \tilde{v}_3, v_2 \rangle, \quad \beta = -\langle u_3, v_2 \rangle = -(-2 + 6 - 3)/7, \quad \underline{\beta = -1/7},$
 $0 = \langle \tilde{v}_3, v_1 \rangle, \quad \gamma = -\langle u_3, v_1 \rangle = -(6 + 3 + 2)/7, \quad \underline{\gamma = -11/7},$
 $\tilde{v}_3 = 1/49 [49 + 2 - 66, 49 - 6 - 33, 49 + 3 - 22]^\top = 1/49 [-15, 10, 30]^\top = 5/49 [-3, 2, 6]^\top,$
 $\|\tilde{v}_3\| = 5/49 \sqrt{9 + 4 + 36} = 5/7, \quad \underline{v_3} = 1/7 [-3, 2, 6]^\top.$

$$\frac{1}{7} \begin{bmatrix} 6 & -2 & -3 \\ 3 & 6 & 2 \\ 2 & -3 & 6 \end{bmatrix} \begin{bmatrix} \|v_1\| & -\alpha & -\gamma \\ 0 & \|v_2\| & -\beta \\ 0 & 0 & \|v_3\| \end{bmatrix}$$

$\underline{Q} \quad \underline{R}$

2 QR-factorization

Theorem 1. For a nonsingular $A \in \mathcal{M}_n$, there exists a unique pair of unitary matrix $Q \in \mathcal{M}_n$ and upper triangular matrix $R \in \mathcal{M}_n$ with positive diagonal entries such that

$$A = QR.$$

conjugate transpose of U
 $U^* U = U U^* = I$ (U: complex square matrix)
 U: normal ($U^* U = U U^*$)
 $U = V D V^*$ (V, D: unitary, D: diagonal)

The QR-factorization can be used for the following tasks:

- solving linear systems according to

$$[Ax = b] \iff [Qy = b, \quad y = Rx],$$

since the system $y = Rx$ is easy to solve [backward substitution], and the system $Qy = b$ is even easier to solve [take $y = Q^* b$];

- calculate the (modulus of the) determinant and find the inverse [$|\det A| = \prod_{i=1}^n r_{i,i}$, $A^{-1} = R^{-1} Q^*$]; **$|\det(U)| = 1$**
- find the Cholesky factorization of a positive definite matrix $B = A^* A \in \mathcal{M}_n$, $A \in \mathcal{M}_n$ being nonsingular (we will later see why every positive definite matrix can be factored in this way), i.e., find a factorization

$$B = LL^*,$$

where $L \in \mathcal{M}_n$ is lower triangular with positive diagonal entries [$L = R^*$];

- find a Schur's factorization of a matrix $A \in \mathcal{M}_n$ via the QR-algorithm defined by

$$\begin{aligned} A_0 &:= A, & A_0 &:= Q_0 R_0, \\ A_1 &:= R_0 Q_0, & A_1 &:= Q_1 R_1, \\ &\vdots & &\vdots \\ A_k &:= R_{k-1} Q_{k-1}, & A_k &:= Q_k R_k, \\ &\vdots & &\vdots \end{aligned}$$

Note that A_k is always unitarily equivalent to A . If all the eigenvalues of A have distinct moduli, then A_k tends to an upper triangular matrix T (which is therefore unitarily equivalent to A , see Exercise 3). The eigenvalues of A are read on the diagonal of T .

In the general case of nonsingular or nonsquare matrices, the QR-factorization reads:

Theorem 2. For $A \in \mathcal{M}_{m \times n}$, $m \geq n$, there exists a matrix $Q \in \mathcal{M}_{m \times n}$ with orthonormal columns and an upper triangular matrix $R \in \mathcal{M}_n$ such that

$$A = QR.$$

Beware that the QR-factorization of a rectangular matrix A is not always understood with Q rectangular and R square, but sometimes with Q square and R rectangular, as with the MATLAB command `qr`.

$$A = QR = \underset{m \times m}{Q} \overset{n \times n}{\begin{bmatrix} R_1 \\ 0 \end{bmatrix}} = \underset{\substack{\text{orthogonal columns} \\ \vee}}{\begin{bmatrix} Q_1 & Q_2 \end{bmatrix}} \overset{2}{\begin{bmatrix} R_1 \\ 0 \end{bmatrix}} = Q_1 R_1 \quad \text{reduced QR factorization}$$

3 Proof of Theorems 1 and 2

Uniqueness: Suppose that $A = Q_1 R_1 = Q_2 R_2$ where Q_1, Q_2 are unitary and R_1, R_2 are upper triangular with positive diagonal entries. Then

$$M := R_1 R_2^{-1} = Q_1^* Q_2.$$

Since M is a unitary (hence normal) matrix which is also upper triangular, it must be diagonal (see Lemma 4 of Lecture 2). Note also that the diagonal entries of M are positive (because the upper triangular matrices R_1 and R_2^{-1} have positive diagonal entries) and of modulus one (because M is a diagonal unitary matrix). We deduce that $M = I$, and consequently that

$$R_1 = R_2, \quad Q_1 = Q_2.$$

Existence: Let us consider a matrix $A \in \mathcal{M}_{m \times n}$ with $m \geq n$, and let $u_1, \dots, u_n \in \mathbb{C}^m$ denote its columns. We may assume that u_1, \dots, u_n are linearly independent (otherwise limiting arguments can be used, see Exercise 4). Then the result is just a matrix interpretation of the Gram–Schmidt orthonormalization process of m linearly independent vectors in \mathbb{C}^n . Indeed, the Gram–Schmidt algorithm produces orthonormal vectors $v_1, \dots, v_n \in \mathbb{C}^m$ such that, for each $j \in [1 : n]$,

$$(1) \quad u_j = \sum_{k=1}^j r_{k,j} v_k = \sum_{k=1}^n r_{k,j} v_k,$$

with $r_{k,j} = 0$ for $k > j$, in other words, $R := [r_{i,j}]_{i,j=1}^n$ is an $n \times n$ upper triangular matrix. The n equations (1) reduce, in matrix form, to $A = QR$, where Q is the $m \times n$ matrix whose columns are the orthonormal vectors v_1, \dots, v_n .

[To explain the other QR-factorization, let us complete v_1, \dots, v_n with v_{n+1}, \dots, v_m to form an orthonormal basis (v_1, \dots, v_m) of \mathbb{C}^m . The analogs of the equations (1), i.e., $u_j = \sum_{k=1}^m r_{k,j} v_k$ with $r_{k,j} = 0$ for $k > j$, read $A = QR$, where Q is the $m \times m$ orthogonal matrix with columns v_1, \dots, v_m and R is an $m \times n$ upper triangular matrix.]

To illustrate the matrix interpretation, observe that the orthonormalization carried out in Section 1 translates into the factorization [identify all the entries]

$$\begin{bmatrix} 6 & 6 & 1 \\ 3 & 6 & 1 \\ 2 & 1 & 1 \end{bmatrix} = \underbrace{\frac{1}{7} \begin{bmatrix} 6 & -2 & -3 \\ 3 & 6 & 2 \\ 2 & -3 & 6 \end{bmatrix}}_{\text{unitary}} \underbrace{\begin{bmatrix} 7 & 8 & 11/7 \\ 0 & 3 & 1/7 \\ 0 & 0 & 5/7 \end{bmatrix}}_{\text{upper triangular}}.$$

Q

R

An aside: other QR-factorization algorithms

The Gram–Schmidt algorithm has the disadvantage that small imprecisions in the calculation of inner products accumulate quickly and lead to effective loss of orthogonality. Alternative ways to obtain a QR -factorization are presented below on some examples. They are based on the following idea and exploits the fact that the computed product of unitary matrices gives a unitary matrix with acceptable error.

Multiply the (real) matrix A on the left by some orthogonal matrices Q_i which ‘eliminate’ some entries below the main ‘diagonal’, until the result is an upper triangular matrix R , thus

$$Q_k \cdots Q_2 Q_1 A = R \quad \text{yields} \quad A = QR, \quad \text{with} \quad Q = Q_1^* Q_2^* \cdots Q_k^*.$$

We mainly know two types of unitary transformations, namely rotations and reflexions. Therefore, the two methods we describe are associated with Givens rotations [preferred when A is sparse] and Householder reflections [preferred when A is dense].

Givens rotations

The matrix

$$\Omega^{[i,j]} := \begin{bmatrix} \ddots & & & & & \\ & 1 & & \vdots & 0 & \vdots & 0 \\ & i & \cdots & \cos \theta & \cdots & \sin \theta & \cdots \\ & & 0 & \vdots & \ddots & \vdots & 0 \\ & j & \cdots & -\sin \theta & \cdots & \cos \theta & \cdots \\ & & 0 & \vdots & 0 & \vdots & 1 \\ & & & & & & \ddots \end{bmatrix}$$

corresponds to a rotation along the two-dimensional space $\text{span}[e_i, e_j]$. The rows of the matrix $\Omega^{[i,j]} A$ are the same as the rows of A , except for the i -th and j -th rows, which are linear combinations of the i -th and j -th rows of A . By choosing θ appropriately, we may introduce a zero

at a prescribed position on one of these rows. Consider for example the matrix $A = \begin{bmatrix} 6 & 6 & 1 \\ 3 & 6 & 1 \\ 2 & 1 & 1 \end{bmatrix}$

of the end of Section 1. We pick $\Omega^{[1,2]}$ so that $\Omega^{[1,2]} A = \begin{bmatrix} 6 & 6 & 1 \\ 0 & \times & \times \\ \times & \times & \times \end{bmatrix}$. Then we pick $\Omega^{[1,3]}$ so that

$\Omega^{[1,3]} \Omega^{[1,2]} A = \begin{bmatrix} \times & \times & \times \\ 0 & \times & \times \\ 0 & \times & \times \end{bmatrix}$. Finally, thanks to the leading zeros in the second and third rows,

we can pick $\Omega^{[2,3]}$ so that $\Omega^{[2,3]}\Omega^{[1,3]}\Omega^{[1,2]}A = \begin{bmatrix} \times & \times & \times \\ 0 & \times & \times \\ 0 & 0 & \times \end{bmatrix}$. The matrix $[\Omega^{[2,3]}\Omega^{[1,3]}\Omega^{[1,2]}]^*$ is the unitary matrix required in the factorization of A .

Householder reflections

The reflection in the direction of a vector v transforms v into $-v$ while leaving the space v^\perp unchanged. It can therefore be expressed through the Hermitian unitary matrix

$$H_v := I - \frac{2}{\|v\|^2} vv^*.$$

Consider the matrix $A = \begin{bmatrix} 6 & 6 & 1 \\ 3 & 6 & 1 \\ 2 & 1 & 1 \end{bmatrix}$ once again. We may transform $u_1 = [6, 3, 2]^\top$ into $7e_1 = [7, 0, 0]^\top$ by way of the reflection in the direction $v_1 = u_1 - 7e_1 = [-1, 3, 2]^\top$. The latter is represented by the matrix

$$H_{v_1} = I - \frac{2}{\|v_1\|^2} v_1 v_1^* = I - \frac{1}{7} \begin{bmatrix} 1 & -3 & -2 \\ -3 & 9 & 6 \\ -2 & 6 & 4 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 6 & 3 & 2 \\ 3 & -2 & -6 \\ 2 & -6 & 3 \end{bmatrix}.$$

Then the matrix $H_{v_1}A$ has the form $\begin{bmatrix} 7 & \times & \times \\ 0 & \times & \times \\ 0 & \times & \times \end{bmatrix}$, where the precise expression for the second column is

$$H_{v_1}u_2 = u_2 - \frac{\langle v_1, u_2 \rangle}{7} v_1 = u_2 - 2v_1 = \begin{bmatrix} 8 \\ 0 \\ -3 \end{bmatrix}.$$

To cut the argument short, we may observe at this point that the multiplication of $H_{v_1}A$ on the left by the permutation matrix $P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$ [which can be interpreted as $H_{e_2 - e_3}$] exchanges the second and third rows, thus gives an upper triangular matrix. In conclusion, the orthogonal matrix Q has been obtained as

$$(PH_{v_1})^* = H_{v_1}^* P^* = H_{v_1} P = \frac{1}{7} \begin{bmatrix} 6 & 2 & 3 \\ 3 & -6 & -2 \\ 2 & 3 & -6 \end{bmatrix}.$$

4 Exercises

Ex.1: Prove that a matrix $A \in \mathcal{M}_{m \times n}$, $m \leq n$, can be factored as $A = LP$ where $L \in \mathcal{M}_m$ is lower triangular and $P \in \mathcal{M}_{m \times n}$ has orthonormal rows.

Ex.2: Prove the uniqueness of the Cholesky factorization of a positive definite matrix.

Ex.3: Exercise 5 p. 117.

Ex.4: Fill in the details of the following argument: for $A \in \mathcal{M}_{m \times n}$ with $m \geq n$, there exists a sequence of matrices $A_k \in \mathcal{M}_{m \times n}$ with linearly independent columns such that $A_k \rightarrow A$ as $k \rightarrow \infty$; each A_k can be written as $A_k = Q_k R_k$ where $Q_k \in \mathcal{M}_{m \times n}$ has orthonormal columns and $R_k \in \mathcal{M}_n$ is upper triangular; there exists a subsequence (Q_{k_j}) converging to a matrix $Q \in \mathcal{M}_{m \times n}$ with orthonormal columns, and the sequence (R_{k_j}) converges to an upper triangular matrix $R \in \mathcal{M}_n$; taking the limit when $j \rightarrow \infty$ yields $A = QR$.

Ex.5: Fill in the numerical details in the section on Givens rotations.