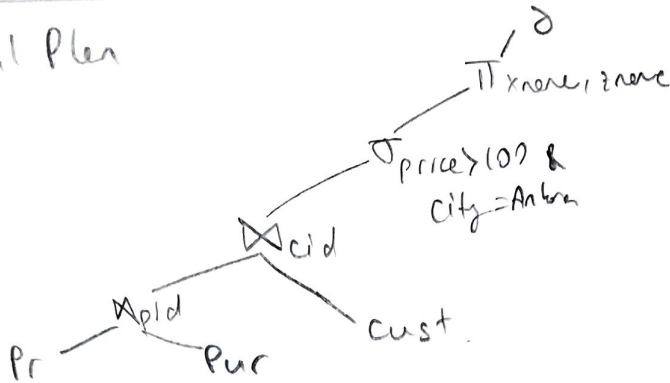


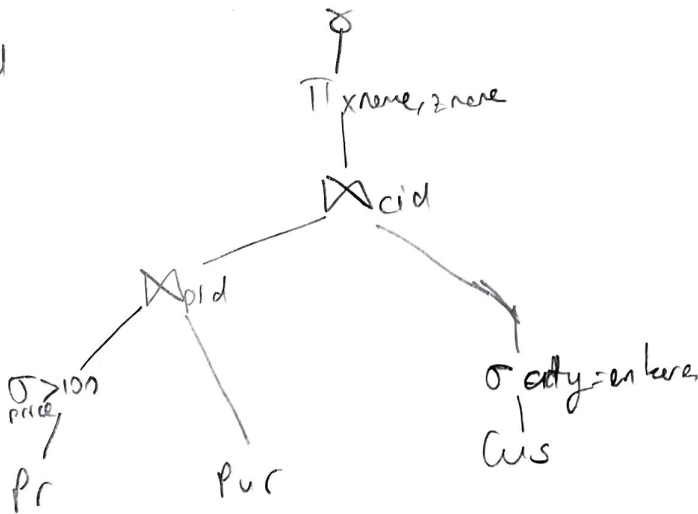
Query

S, D. xname, zname
 F Pr x, Pur y, Cus z
 W xpid=ypid & ycid=zcid
 & xprice>100 & zcity=Antara

1st Logical Plan

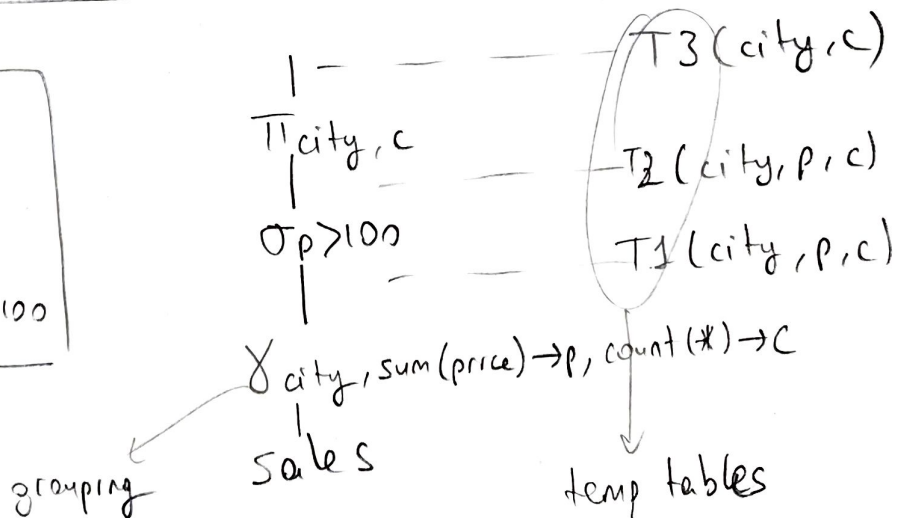


2nd, optimized



ex2:

S city, count(*)
 F Sales
 Group By city
 Having Sum(price)>100



ex: Supplier (sno, sname, scity, district)
 Part (pno, pname, psize, pcolor)
 Supply (sno, pno, price)

C.V. NearbySup as
 S sno, sname
 F Sup
 W city = ankara and
 district = Gorkaya

↓
 π_{sno, sname}
 ↓
 σ_{city = ankara & district = Gorkaya}
 ↓
 Supplier

Suppose dbms gets:

S sname
 F NearbySup
 W sno in (S sno
 F Supplies
 W pno = 2)

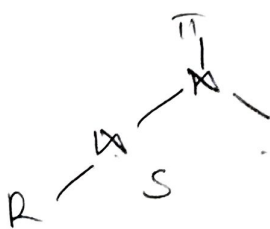
rewritten
 ⇒

S sname
 F Supplier S, Supplier U
 W S.city = Ankara &
 S.district = Gorkaya &
 S.no = U.no &
 U.pno = 2

Find logical plan, generate physical plan.

→ B+ tree
 → File scan
 → which algorithm
 is used (will come to this later)

We need to work on 1 query (no nesting)



Typical
 Select
 Project
 Join

having



typical
 aggregation

ex: S Q.sno
 F Supplier Q
 W Q.dis = Garkanya
 and not exist

Correlation

(

 se. ★

 F Supply P

 W P.sno = Q.sno &

 P.price > 100

)

DBMS works block by block. Decorrelate (NOT IN)

If we don't write, DBMS will write

decorrelation

S Q.sno
 F Supplier Q
 W Q.dis = G. &
 Q.sno not in
 (

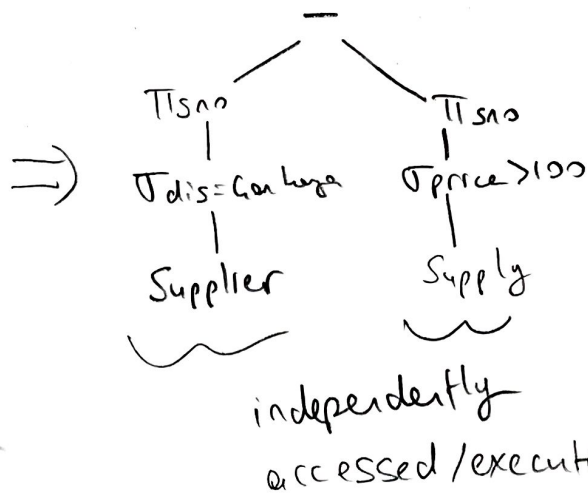
 S P.sno
 F Supply P
 W P.price > 100

)

still nested block

unnest (using EXCEPT = set difference)

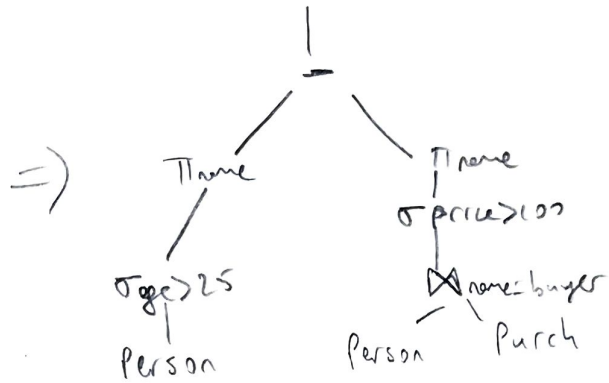
S Q.sno
 F Supplier Q
 W Q.d = G.
 EXCEPT
 S P.sno
 F Supply P
 W P.price > 100



ex:

S Q.name
F Person Q
W Q.age > 25
and not exist

(S ~~Q~~ Purchase P
F Purchase P
W P.buyer = Q.name
and P.price > 100)



For each SQL query \rightarrow many logical plans

For each logical plan \rightarrow many physical plans.

Fast physical plan?

DBMS will generate physical plans w.o. executing. It guesses the cost.

Generating plans are costly. But spending ^{time} on a query generation is better than executing the worst query.

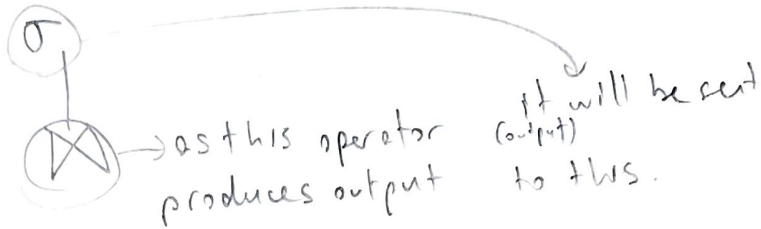
2 execution type \rightarrow Pipelined execution
 \rightarrow Intermediate result (keeping temp Tables)
materialization

Each operator ($\pi, \sigma, \gamma, \bowtie$) implements an interface.

\downarrow
open() \rightarrow init & point to file, set parameters
getNext() \rightarrow get next item in the stream
close() \rightarrow close

Pipelined Execution

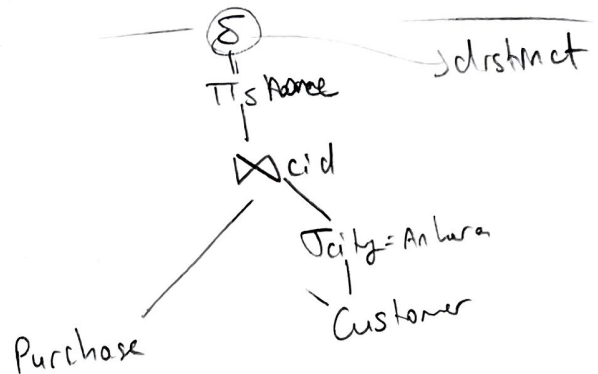
- No operator sync
- No write to disk (intermediate tables)
- No read intermediate table from disk



Intermediate Tuple Materialization

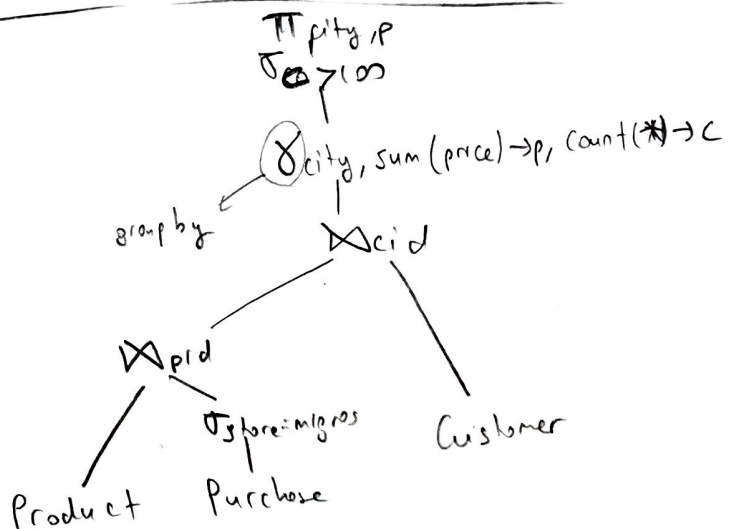
- No direct benefit
- Necessary for some op.
- When the op needs to examine some tuples multiple times

ex: S. D. x.store
F purch x, Cust y
W x.cid=y.cid
& y.city=Ankara



ex2:

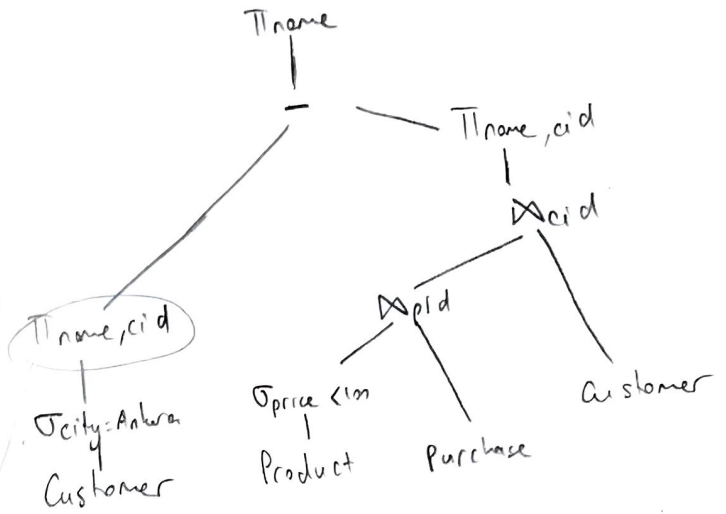
S. z.city, sum(x.price)
F Product x, Purchase y, Cust z
W x.pid=y.pid & y.cid=z.cid
& y.store=Migros
Group By z.city
Having count(*) > 100



ex3:

S z.name
 F Cust z
 W z.city = Ankara and
 $NOT\ EXIST$ $\left(\begin{array}{l} S \text{ } \& \\ F \text{ Product X,} \\ \text{Purchase Y,} \\ W \text{ } x.pid = y.pid \& \\ y.cid = z.cid \& \\ x.price < 100 \end{array} \right)$

\Rightarrow



cid olmasi agni 2 isimli (2 migros ana farketli cid)
 elemanini engelliyor.

ex4:

σ
 $\pi_{f,g}$
 $\bowtie c$

$\bowtie b$

$\pi_{b,f}$

$\sigma_{a>5}$

$R(a,b,f)$

$\pi_{b,c}$

$S(b,c,h)$

$\sigma_{g<9} \Rightarrow$

$\pi_{c,g}$

$T(c,d,g)$

Select Distinct f,g
 F R, S, T
 W R.b = S.b &
 $T.c = S.c$ &
 $R.a > 5$ &
 $T.g < 9$

Selection (σ)

$\sigma_{city=Ankara}$
 Customer

If customer does not have an index on city

\hookrightarrow File scan. Cost $B(R) \rightarrow$ size of R in blocks (page)

If rows are sorted on attribute **AND** operation is $\geq \leq$ (range)

Use binary search $(\log_2 B(R)) \rightarrow$ locate first data page.

+
 there could be more than 1 page containing that data
 Cost = $\log_2 B(R) +$ scan linearly Cost of scan

B+ tree on attribute

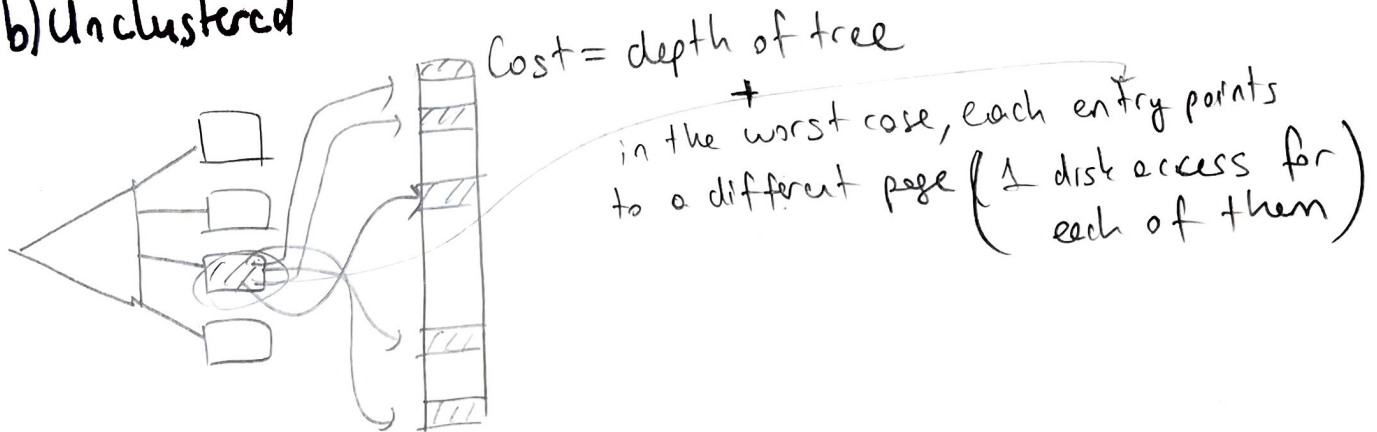
a) Clustered



Start from root. Each level is a disk access.

$$\text{Cost} = \text{depth of tree} + \# \text{ of pages occupied}$$

b) Unclustered



Hash Index

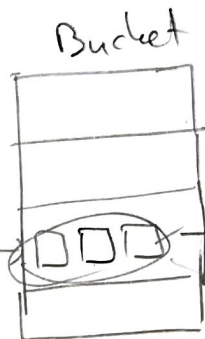
$$\text{Cost} \approx 1.2$$

$\nabla_{\text{city}} = \text{Ankara}$

hash Ankara
find correct bucket, which contains hash of Ankara

a) Clustered

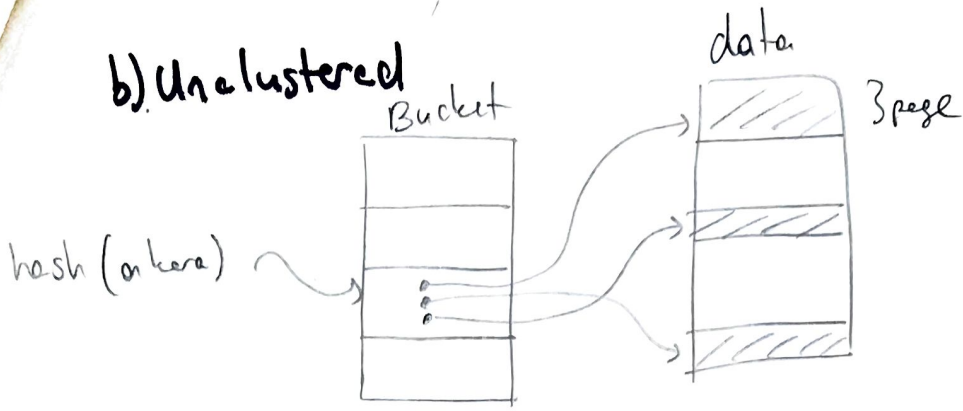
hash (Ankara)



maybe chain (overflow) in the bucket.
all data is here.

$$\text{cost} = \# \text{ of } \underline{\text{pages}} \text{ in the bucket.}$$

b) Unclustered

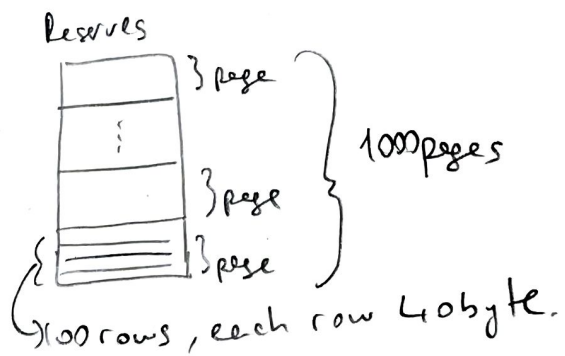


Cost = # of rows in bucket.

Farkları: Clustered olunca Bucketta page şeklinde data duruyor.
hash ile doğru bucketı bulunca Bucketteki page'i almanız → datayı almanız demek.
Unclustered olunca Bucketta bir sıra row oluyor. Bu rowlar diskteki yeri point ediyor. Her row için bir ~~disk~~ access yapmanız gerekebilir.

ex: Sailors (sid, sname, rating, age)
Reserves (sid, bid, day, name)

Reserves → each tuple 40 byte
→ 100 tuple per page
→ 1000 pages



Sailors → each tuple 50 byte
→ 80 tuples per page
→ 500 pages

Questions

S*

F Reserves R

W R.name = Joe

1) With no index, unsorted

↳ file scan $\Rightarrow B(R) = 1000 \rightarrow 1000 \text{ page I/O}$

2) With no index, sorted.

↳ $\log_2 B(R) \approx 10 \text{ I/O.}$ to find first Joe

3) B+tree, index on name, clustered

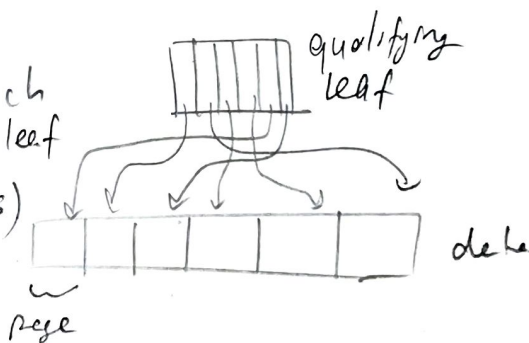


cost of finding this = depth of tree

= 2 or 3 I/O?

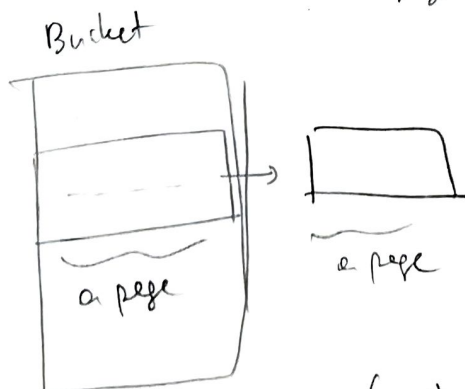
4) B+tree, index on name, unclustered.

2 or 3 I/O for finding Joe
then for each entry in the leaf (1 page access)



5) Hash index

1 or 2 I/O for retrieving index



If # of reservation of Joe > 100 (in the question 100 tuple per page)

If clustered 1 + maybe 1

unclustered for each entry a page access

Range query example

S	★
F	Reserves R
W	R name < 'C%'

- Assume we have 10% of Reserves in the result (total is 1000 * 10%)
 ↳ 10,000 tuples → 100 pages

Clustered index → 1 or 2 disk access for index + 100 I/O

Unclustered index → each tuple can point different page. → 10,000 I/O. (Might be cheaper to file scan 1000 I/O)

Projection (π)

- Remove unwanted attr.
- Eliminate duplicates

$\pi_{sid, bid}$
 |
 Reserves } → S sid, bid
 F Reserves

2 approaches → Sorting
 ↳ hashing

Sorting

Reserves → each tuple 40 byte, 1000 pages.

S	Dist sid, bid
F	Reserves

Assume we have 20 buffer page.
 // each small tuple (sid, bid) = 10 byte

Block 40 byte + 10% dist. sig.

M page in memory → each run will have 4M.

Pass 0.

read 1000 page. out smaller tuples.

If M pages in memory, runs of 2M pages can be produced (size dependent)

(40 byte + 20% dist. sig. 100 byte)

Hoca derste cok
 hazi geeti.

Nasil yapildigini
 bilmiyorum

Projection / Sorting

S Dist. Rsid, Rbid
F reserves

Reserves, each tuple 40 byte, 1000 page.

- Assume each smaller tuple (sid, bid) = 10 byte.

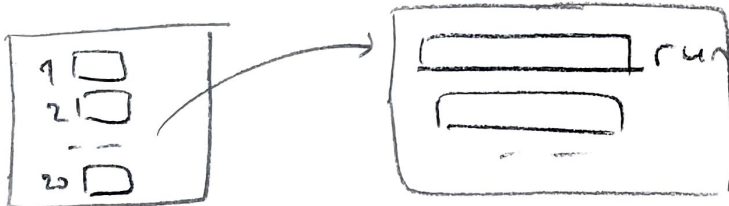
- // we have 20 buffer pages.

1) Read 1000 pages.

Normalde her page'de 40 byte var, ama projection yaparken 10 byte oluyor. Bu yüzden toplamda 250 page yaz.

- Slide'deki 7 runs 40 page muhabbeti:

↳ normalde



each run will be 20 pages long.

Ama farklı bir algoritma kullanıldığı zaman 2 katına çıkarabiliyor.
★ Önemli bilgi ★

250 page yazdık

2) Read 250 page & merge

Total cost $1000 + 250 + 250 = 1500$

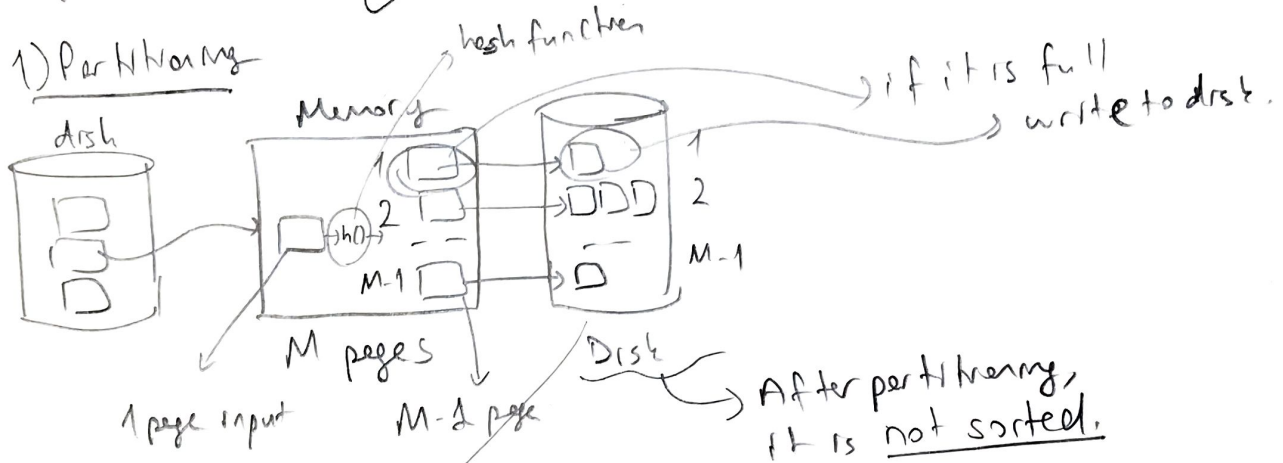
Hashing

as I read from disk, build hash table in memory.
(Suppose it fits in mem.)

each (sid, bid) will be hashed and it will not be put, if it already exist (Distinct).

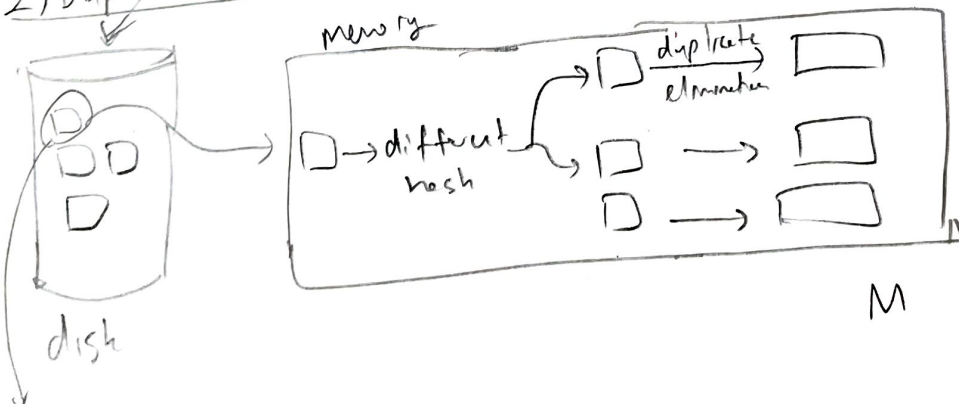
If it does not fit in the memory, send it to disk. Then k-way merge.

1) Partitioning



it is only hashed.
 (101, 500) → may not be in the same bucket.
 (102, 600)

2) Duplicate Elimination



Since it is a small file it will fit in memory