

LECTURE-5(B)

COURSE TITLE LINEAR ALGEBRA & GEOMETRY (MT-272)

DEPARTMENT OF TELECOMMUNICATION ENGINEERING



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COORDINATES RELATIVE TO A BASIS

If $S = \{v_1, v_2, \dots, v_n\}$ is a basis for a vector space V , and

$$v = c_1 v_1 + c_2 v_2 + \dots + c_n v_n$$

is the expression for a vector v in terms of the basis S , then the scalars c_1, c_2, \dots, c_n are called the **coordinates** of v relative to the basis S .

The vector (c_1, c_2, \dots, c_n) in \mathbb{R}^n constructed from these coordinates is the vector of v relative to S ; it is denoted by

$$(v)_S = (c_1, c_2, \dots, c_n)$$



EXAMPLE-1

Example-1: Let $S = (\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$ be the basis for R^3 where

$$\mathbf{v}_1=(1,2,1), \mathbf{v}_2=(2,9,0), \mathbf{v}_3=(3,3,4)$$

(a) Find the coordinate vector of $\mathbf{v}=(5,-1,9)$ with respect to S .

Sol: Let c_1, c_2 , & c_3 be scalars, then vector equation can be written as

$$\mathbf{v}=c_1\mathbf{v}_1+c_2\mathbf{v}_2+c_3\mathbf{v}_3$$

In terms of components

$$(5,-1,9) = c_1(1,2,1) + c_2(2,9,0) + c_3(3,3,4)$$

On comparing both sides

$$\begin{aligned} c_1 + 2c_2 + 3c_3 &= 5 \\ 2c_1 + 9c_2 + 3c_3 &= -1 \quad \dots(1) \\ c_1 + 4c_3 &= 9 \end{aligned}$$



EXAMPLE-1 ...Con'd

Solving the above system for c_1, c_2 , & c_3 the augmented matrix is

$$\begin{bmatrix} 1 & 2 & 3 & 5 \\ 2 & 9 & 3 & -1 \\ 1 & 0 & 4 & 9 \end{bmatrix} \xrightarrow{\text{G.J.E}} \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

$\therefore c_1 = 1, c_2 = -1, c_3 = 2$. Therefore,

$$(\mathbf{v})_S = (1, -1, 2)$$

(b) Find the vector \mathbf{v} in \mathbb{R}^3 whose coordinate vector with respect to the basis S is $(\mathbf{v})_S = (-1, 3, 2)$.

Sol: By using the definition of coordinate vector $(\mathbf{v})_S$, we obtain

$$\mathbf{v} = (-1)\mathbf{v}_1 + 3\mathbf{v}_2 + 2\mathbf{v}_3$$

$$\text{or } \mathbf{v} = (-1)(1, 2, 1) + (3)(2, 9, 0) + (2)(3, 3, 4)$$



EXAMPLE-1 ...Con'd

$$\text{or } \mathbf{v} = (-1, -2, -1) + (6, 27, 0) + (6, 6, 8)$$

$$\text{or } \mathbf{v} = (-1+6+6, -2+27+6, -1+0+8)$$

$$\text{or } \mathbf{v} = (11, 31, 7)$$



DIMENSION OF A VECTOR SPACE

The dimension of a vector space V is defined to be the number of vectors in a basis for V

V : a vector space

S : a basis for V

$$\Rightarrow \dim(V) = \#(S) \quad (\text{the number of vectors in a basis } S)$$

Finite dimensional:

A vector space V is finite dimensional if it has a basis consisting of a finite number of elements

Infinite dimensional:

If a vector space V is not finite dimensional, then it is called infinite dimensional



DIMENSION

■ Notes:

(1) $\dim(\{\mathbf{0}\}) = 0$

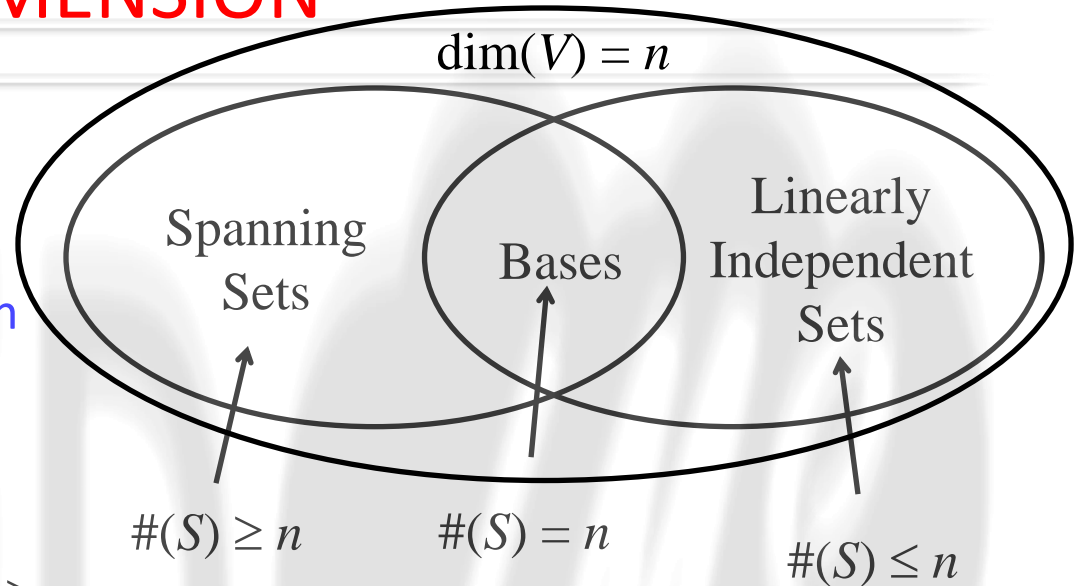
(If V consists of the zero vector alone, the dimension of V is defined as zero)

(2) Given $\dim(V) = n$, for $S \subseteq V$

S : a spanning set $\Rightarrow \#(S) \geq n$

S : a L.I. set $\Rightarrow \#(S) \leq n$

S : a basis $\Rightarrow \#(S) = n$



(3) Given $\dim(V) = n$, if W is a subspace of $V \Rightarrow \dim(W) \leq n$

✂ For example, if $V = \mathbb{R}^3$, you can infer the $\dim(V)$ is 3, which is the number of vectors in the standard basis



Example -1

Example-1: Find the dimension of a vector space according to the standard basis

✧ The simplest way to find the dimension of a vector space is to count the number of vectors in the standard basis for that vector space

(1) Vector space $R^n \Rightarrow$ standard basis $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$

$$\Rightarrow \dim(R^n) = n$$

(2) Vector space $M_{m \times n} \Rightarrow$ standard basis $\{E_{ij} \mid 1 \leq i \leq m, 1 \leq j \leq n\}$

$$\text{and in } E_{ij} \quad \begin{cases} a_{ij} = 1 \\ \text{other entries are zero} \end{cases}$$

$$\Rightarrow \dim(M_{m \times n}) = mn$$

(3) Vector space $P_n(x) \Rightarrow$ standard basis $\{1, x, x^2, \dots, x^n\}$

$$\Rightarrow \dim(P_n(x)) = n+1$$

(4) Vector space $P(x) \Rightarrow$ standard basis $\{1, x, x^2, \dots\}$

