## lab8-1

#### May 16, 2021

```
[1]: import keras
     from keras import layers
     from keras import backend as K
     from keras.models import Model
     from keras.datasets import mnist
     import matplotlib.pyplot as plt
     import numpy as np
     import tensorflow as tf
     %tensorflow_version 1.x
     print(tf.__version__)
     tf.compat.v1.disable_eager_execution()
     img\_shape = (28, 28, 1)
     batch size = 16
     latent_dim = 2
     #Define encoder network
     #Note that we are using keras functional API
     input_img = keras.Input(shape=img_shape)
     x = layers.Conv2D(32, 3, padding='same', activation='relu')(input_img)
     x = layers.Conv2D(64, 3, padding='same', activation='relu',strides=(2, 2))(x)
     x = layers.Conv2D(64, 3, padding='same', activation='relu')(x)
     x = layers.Conv2D(64, 3, padding='same', activation='relu')(x)
     shape_before_flattening = K.int_shape(x)
     x = layers.Flatten()(x)
     x = layers.Dense(32, activation='relu')(x)
     \#x = layers.Dense(2, activation='relu')(x)
     z_mean = layers.Dense(latent_dim)(x)
     z_log_var = layers.Dense(latent_dim)(x)
     #Sampling from the distributions to obtain latent space
     def sampling(args):
         z_mean, z_log_var = args
         epsilon = K.random_normal(shape=(K.shape(z_mean)[0], latent_dim),
         mean=0., stddev=1.)
         return z_mean + K.exp(z_log_var) * epsilon
     z = layers.Lambda(sampling)([z_mean, z_log_var])
```

```
encoder = Model(input_img, z)
#Define decoder network
decoder_input = layers.Input(K.int_shape(z)[1:])
x = layers.Dense(np.prod(shape_before_flattening[1:]),__

→activation='relu')(decoder_input)
x = layers.Reshape(shape_before_flattening[1:])(x)
x = layers.Conv2DTranspose(32, 3,padding='same', activation='relu', strides=(2,__
 \rightarrow 2))(x)
x = layers.Conv2D(1, 3,padding='same', activation='sigmoid')(x)
decoder = Model(decoder input, x)
z decoded = decoder(z)
def vae_loss(input_img, z_decoded):
    input_img = K.flatten(input_img)
    z_decoded = K.flatten(z_decoded)
    xent_loss = keras.metrics.binary_crossentropy(input_img, z_decoded)
    kl_loss = -5e-4 * K.mean(1 + z_log_var - K.square(z_mean) - K.
 \rightarrowexp(z_log_var), axis=-1)
    return K.mean(xent_loss + kl_loss)
vae = Model(input_img, z_decoded)
vae.compile(optimizer='adam', loss=vae_loss)
vae.summary()
decoder.summary()
#load the data and split into train + test sets
(x_train, _), (x_test, y_test) = mnist.load_data()
x_train = x_train.astype('float32') / 255.
x_train = x_train.reshape(x_train.shape + (1,))
x_test = x_test.astype('float32') / 255.
x_test = x_test.reshape(x_test.shape + (1,))
vae.fit(x=x_train,y=x_train, shuffle=True, epochs=10, batch_size=batch_size)
encoded = encoder.predict(x_test)
decoded = decoder.predict(encoded)
TensorFlow is already loaded. Please restart the runtime to change versions.
2.4.1
Model: "model_2"
Layer (type)
                            Output Shape Param # Connected to
______
_____
input 1 (InputLayer)
                            [(None, 28, 28, 1)] 0
_____
conv2d (Conv2D)
                             (None, 28, 28, 32) 320 input_1[0][0]
```

conv2d_1 (Conv2D)	(None, 14, 14, 64)		
conv2d_2 (Conv2D)	(None, 14, 14, 64)	36928	conv2d_1[0][0]
conv2d_3 (Conv2D)			
flatten (Flatten)	(None, 12544)		
dense (Dense)	(None, 32)	401440	flatten[0][0]
dense_1 (Dense)	(None, 2)		
dense_2 (Dense)	(None, 2)		
lambda (Lambda)	(None, 2)	0	dense_1[0][0] dense_2[0][0]
	(None, 28, 28, 1)	56385	lambda[0][0]
	(None, 28, 28, 1)	56385	lambda[0][0]
model_1 (Functional) ====================================	(None, 28, 28, 1)	56385	lambda[0][0]
model_1 (Functional) ====================================	(None, 28, 28, 1)	56385	lambda[0][0]
model_1 (Functional) ====================================	(None, 28, 28, 1)  Output Shape  [(None, 2)]	56385  Param #	lambda[0][0]
model_1 (Functional) ====================================	(None, 28, 28, 1)  Output Shape  [(None, 2)]  (None, 12544)	56385	lambda[0][0]
model_1 (Functional) ====================================	(None, 28, 28, 1)	56385 	lambda[0][0]
model_1 (Functional) ====================================	(None, 28, 28, 1)  Output Shape  [(None, 2)]  (None, 12544)  (None, 14, 14, 64)	Param # 0 37632	lambda[0][0]

```
Total params: 56,385
Trainable params: 56,385
Non-trainable params: 0
Train on 60000 samples
Epoch 1/10
60000/60000 [============= ] - 19s 323us/sample - loss: 0.2230
Epoch 2/10
60000/60000 [============= ] - 16s 267us/sample - loss: 0.2007
Epoch 3/10
60000/60000 [============== ] - 16s 269us/sample - loss: 0.1927
Epoch 4/10
60000/60000 [============== ] - 16s 264us/sample - loss: 0.1882
Epoch 5/10
60000/60000 [============= ] - 16s 267us/sample - loss: 0.1855
Epoch 6/10
60000/60000 [============= ] - 16s 266us/sample - loss: 0.1835
Epoch 7/10
60000/60000 [============= ] - 16s 267us/sample - loss: 0.1822
Epoch 8/10
60000/60000 [============= ] - 16s 269us/sample - loss: 0.1812
Epoch 9/10
Epoch 10/10
60000/60000 [============== ] - 16s 267us/sample - loss: 0.1795
/usr/local/lib/python3.7/dist-
packages/tensorflow/python/keras/engine/training.py:2325: UserWarning:
`Model.state_updates` will be removed in a future version. This property should
not be used in TensorFlow 2.0, as `updates` are applied automatically.
 warnings.warn('`Model.state updates` will be removed in a future version. '
```

### **HOMEWORK 1**

Interpolate between two latent vectors (i.e., moving in the latent space) and decode and visualize the interpolations. Provide a code (python notebook) to do this interpolation; and provide 3 interpolated images in-between.

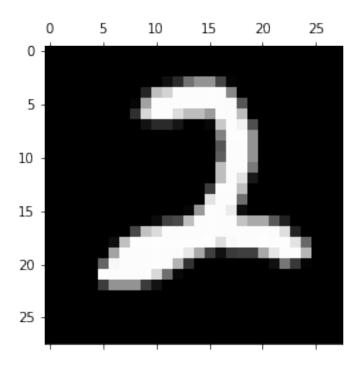
```
[2]: def interpolate_and_vis(num1, num2, num_of_images):
    idex_num1 = [idx for idx in range(len(y_test)) if y_test[idx] == num1]
    idex_num2 = [idx for idx in range(len(y_test)) if y_test[idx] == num2]
    encoded_num1 = encoded[idex_num1]
    encoded_num2 = encoded[idex_num2]

    idx1 = np.random.choice(idex_num1)
    idx2 = np.random.choice(idex_num2)
```

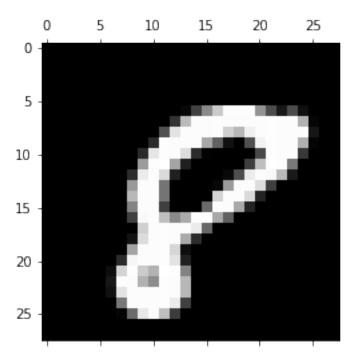
```
mu1, sigma1 = encoded[idx1]
mu2, sigma2 = encoded[idx2]
mu_linspace = np.linspace(mu1, mu2, num_of_images)
sigma_linspace = np.linspace(sigma1, sigma2, num_of_images)
params = np.array(list(zip(mu_linspace, sigma_linspace)))
decoded = decoder.predict(params)
print('First base image, from class: ', num1)
plt.matshow(x_test[idx1][:,:,0], cmap='gray')
plt.show()
print('Second base image, from class: ', num2)
plt.matshow(x_test[idx2][:,:,0], cmap='gray')
plt.show()
print('\n\n')
for index, param in enumerate(params):
  print('Image num: ', index+1)
  plt.matshow(decoded[index][:,:,0], cmap='gray')
  plt.show()
```

```
[3]: # between 2 and 8 interpolate_and_vis(2, 8, 3)
```

First base image, from class: 2



Second base image, from class: 8



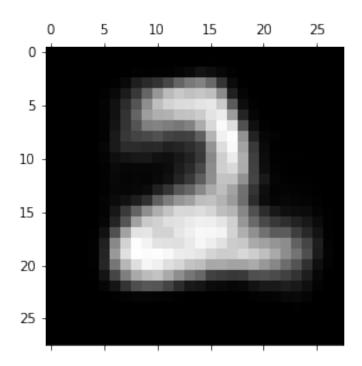


Image num: 2

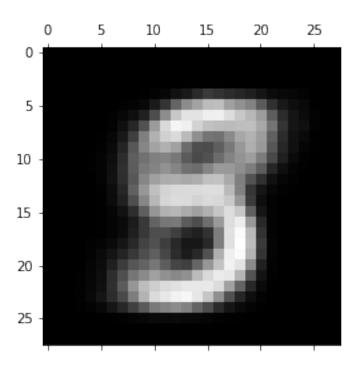
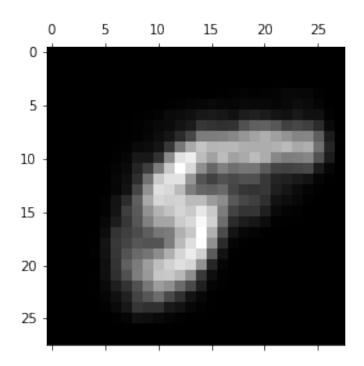
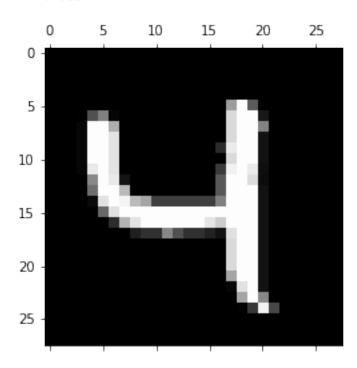


Image num: 3

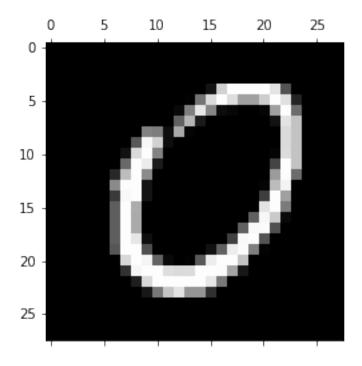


# [4]: # between 4 and 0 interpolate\_and\_vis(4, 0, 3)

First base image, from class: 4



Second base image, from class: 0



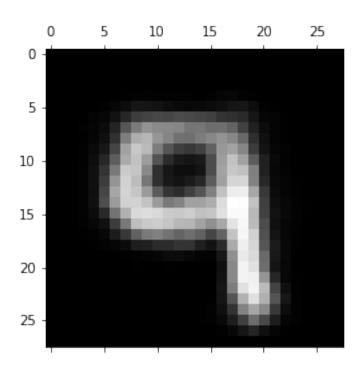


Image num: 2

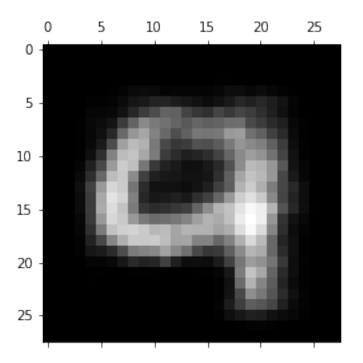
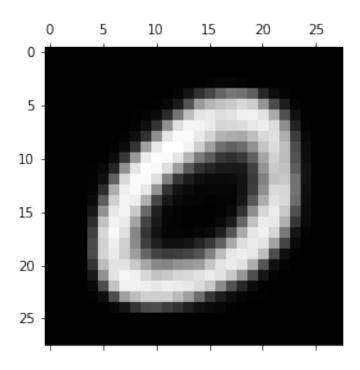


Image num: 3



### **HOMEWORK 2**

Apply VAE on the above ST data. Modify the earlier VAE architecture (used on MNIST), such as input data dimensions and other parameters (strides, layers, etc). Keep the 2 dimensions as latent variables. Visualize the scatter plot. Visualize the reconstructed data as the 2D heatmap. Make sure to submit the jupyterlab code.

```
[5]: import pandas as pd
     import numpy as np
     import matplotlib.pyplot as plt
     from google.colab import drive
     drive.mount('/content/drive')
     #file = 'drive/MyDrive/Colab Notebooks/Rep01 MOB_count_matrix-1.tsv'
     file = '/content/drive/MyDrive/Colab Notebooks/Rep1_MOB_count_matrix-1.tsv'
     data_orig = pd.read_csv(file, sep='\t')
     x = [float(i.partition('x')[0]) for i in data_orig.iloc[:,0]]
     y = [float(i.partition('x')[2]) for i in data_orig.iloc[:,0]]
     x_{int} = [int(i+0.5) \text{ for } i \text{ in } x]
     y_round = [int(i+0.5) for i in y]
     data = []
     #loop over genes
     for i in range(1,data_orig.shape[1]):
         mat = np.zeros([32,32])
         #fill spatial arrays for each gene
         for x_, y_, val in zip(x_round, y_round, data_orig.iloc[:,i]):
```

```
mat[y_,x_] = val
#scaling the data on each gene from 0 to 1
mat = mat/(mat.max())
data.append(mat)
data = np.array(data)
```

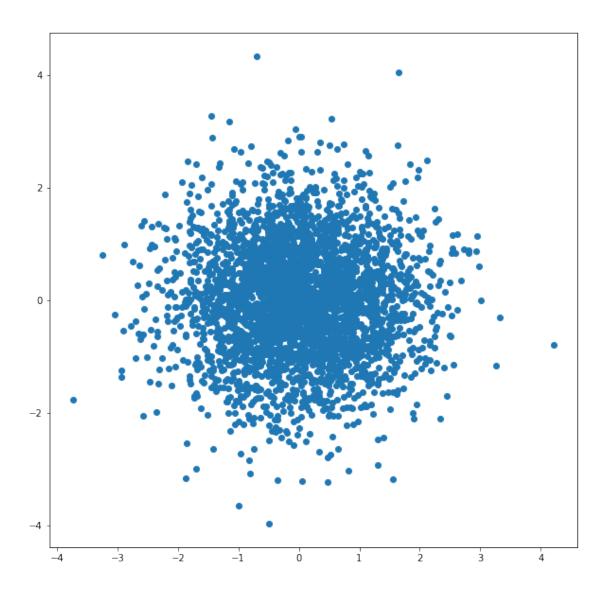
Mounted at /content/drive

```
[72]: import keras
      from keras import layers
      from keras import backend as K
      from keras.models import Model
      from keras.datasets import mnist
      import matplotlib.pyplot as plt
      import numpy as np
      import tensorflow as tf
      %tensorflow_version 1.x
      print(tf.__version__)
      tf.compat.v1.disable_eager_execution()
      img\_shape = (32, 32, 1)
      batch_size = 16
      latent_dim = 2
      #Define encoder network
      #Note that we are using keras functional API
      input_img = keras.Input(shape=img_shape)
      x = layers.Conv2D(32, 3, padding='same', activation='relu')(input_img)
      x = layers.Conv2D(64, 3, padding='same', activation='relu', strides=(2, 2))(x)
      x = layers.Conv2D(64, 3, padding='same', activation='sigmoid')(x)
      shape_before_flattening = K.int_shape(x)
      x = layers.Flatten()(x)
      x = layers.Dense(32, activation='relu')(x)
      z_mean = layers.Dense(latent_dim)(x)
      z_log_var = layers.Dense(latent_dim)(x)
      #Sampling from the distributions to obtain latent space
      def sampling(args):
          z_mean, z_log_var = args
          epsilon = K.random_normal(shape=(K.shape(z_mean)[0], latent_dim),
          mean=0., stddev=1.)
          return z_mean + K.exp(z_log_var) * epsilon
      z = layers.Lambda(sampling)([z_mean, z_log_var])
      encoder = Model(input_img, z)
```

```
#Define decoder network
decoder_input = layers.Input(K.int_shape(z)[1:])
x = layers.Dense(np.prod(shape_before_flattening[1:]),__
x = layers.Reshape(shape_before_flattening[1:])(x)
x = layers.Conv2DTranspose(32, 3,padding='same', activation='relu', strides=(2,,,
 \rightarrow 2))(x)
x = layers.Conv2D(1, 3,padding='same', activation='sigmoid')(x)
decoder = Model(decoder_input, x)
z_decoded = decoder(z)
def vae_loss(input_img, z_decoded):
   input_img = K.flatten(input_img)
   z_decoded = K.flatten(z_decoded)
   xent_loss = keras.metrics.binary_crossentropy(input_img, z_decoded)
   kl_loss = -5e-4 * K.mean(1 + z_log_var - K.square(z_mean) - K.
 \rightarrowexp(z_log_var), axis=-1)
   return K.mean(xent_loss + kl_loss)
vae = Model(input_img, z_decoded)
vae.compile(optimizer='adam', loss=vae_loss)
vae.summary()
decoder.summary()
#load the data and split into train + test sets
cut point = round(len(data) * 0.8)
x_train = data[:cut_point]
x_test = data[cut_point:]
x_train = x_train.astype('float32') / 255.
x_train = x_train.reshape(x_train.shape + (1,))
x_{test} = x_{test.astype}('float32') / 255.
x_test = x_test.reshape(x_test.shape + (1,))
TensorFlow is already loaded. Please restart the runtime to change versions.
2.4.1
Model: "model 11"
______
Layer (type)
                          Output Shape
                                       Param # Connected to
______
===========
input_7 (InputLayer)
                         [(None, 32, 32, 1)] 0
______
conv2d 14 (Conv2D)
                          (None, 32, 32, 32) 320
                                                    input_7[0][0]
______
conv2d_15 (Conv2D)
                         (None, 16, 16, 64) 18496 conv2d_14[0][0]
```

conv2d_16 (Conv2D)				conv2d_15[0][0]
flatten_3 (Flatten)				
dense_12 (Dense)				flatten_3[0][0]
dense_13 (Dense)	(None, 2)		66	dense_12[0][0]
dense_14 (Dense)			66	dense_12[0][0]
lambda_3 (Lambda)	(None, 2)		0	dense_13[0][0] dense_14[0][0]
model_10 (Functional)	(None, 32, 3	32, 1)	67905	lambda_3[0][0]
Total params: 648,101 Trainable params: 648,101 Non-trainable params: 0				
 Model: "model_10"				
	Output Shape		Param #	· <b>-</b>
input_8 (InputLayer)				=
dense_15 (Dense)	(None, 16384)		49152	<del></del>
reshape_3 (Reshape)			0	
conv2d_transpose_3 (Conv2DTr				-
conv2d_17 (Conv2D)	(None, 32, 32,	1)	289	· <del>-</del> :=
Total params: 67,905 Trainable params: 67,905 Non-trainable params: 0				

```
[73]: vae.fit(x=x_train, y=x_train, shuffle=True, epochs=10, batch_size=batch_size)
   Train on 13258 samples
   Epoch 1/10
   Epoch 2/10
   8.3309e-04
   Epoch 3/10
   13258/13258 [============= ] - 4s 269us/sample - loss:
   7.7646e-04
   Epoch 4/10
   7.5625e-04
   Epoch 5/10
   7.4923e-04
   Epoch 6/10
   13258/13258 [============= ] - 4s 269us/sample - loss:
   7.4597e-04
   Epoch 7/10
   13258/13258 [============= ] - 4s 273us/sample - loss:
   7.4378e-04
   Epoch 8/10
   13258/13258 [============= ] - 4s 270us/sample - loss:
   7.4215e-04
   Epoch 9/10
   13258/13258 [============== ] - 4s 273us/sample - loss:
   7.4100e-04
   Epoch 10/10
    7.4034e-04
[73]: <tensorflow.python.keras.callbacks.History at 0x7f3f041ef390>
[74]: x_test_encoded_st = encoder.predict(x_test)
    plt.figure(figsize=(10, 10))
    plt.scatter(x_test_encoded[:, 0], x_test_encoded[:, 1])
    plt.savefig('scatter_st.png')
    plt.show()
   /usr/local/lib/python3.7/dist-
   packages/tensorflow/python/keras/engine/training.py:2325: UserWarning:
    `Model.state updates` will be removed in a future version. This property should
   not be used in TensorFlow 2.0, as `updates` are applied automatically.
     warnings.warn('`Model.state_updates` will be removed in a future version. '
```



```
[75]: def heatmap(num_of_images):
    mu_linspace = np.linspace(-8, 8, num_of_images)
    sigma_linspace = np.linspace(-4, -4, num_of_images)

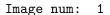
params = np.array(list(zip(mu_linspace, sigma_linspace)))
    decoded_new = decoder.predict(params).reshape(num_of_images, 32, 32)

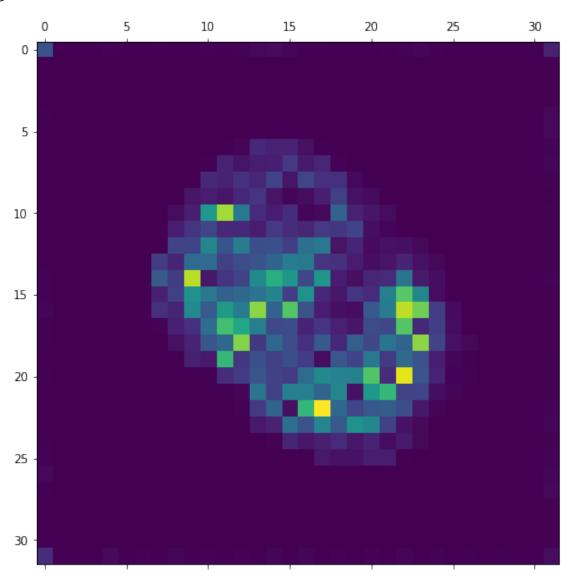
for index, param in enumerate(params):
    print('Image num: ', index+1)
    plt.matshow(decoded_new[index])
    plt.show()
```

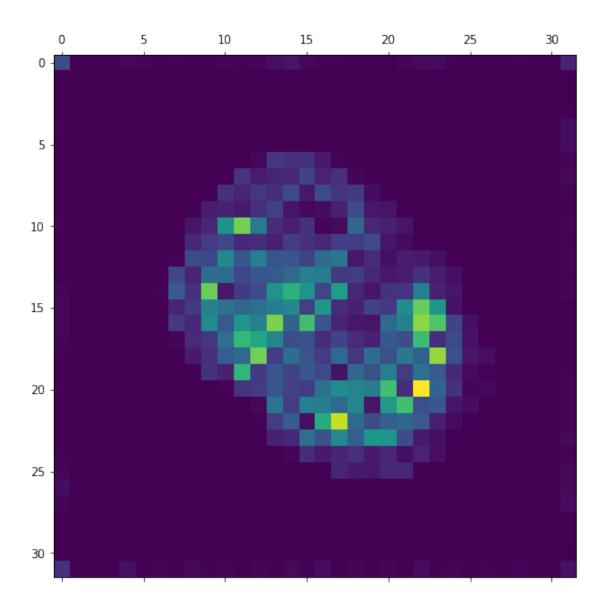
[76]: heatmap(10)

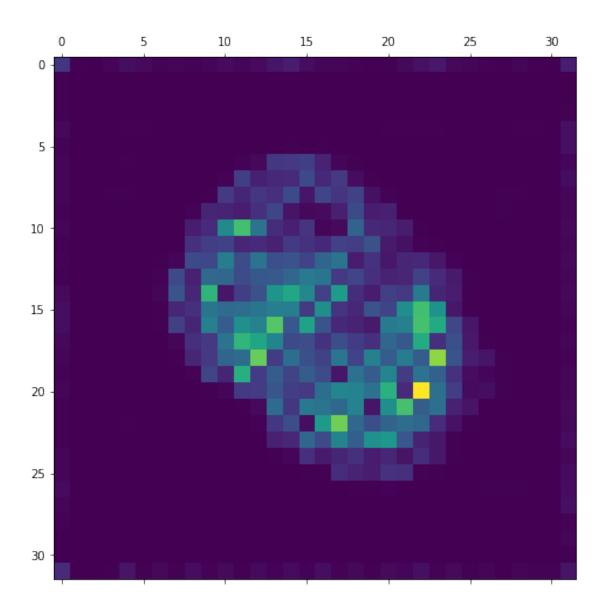
```
16
```

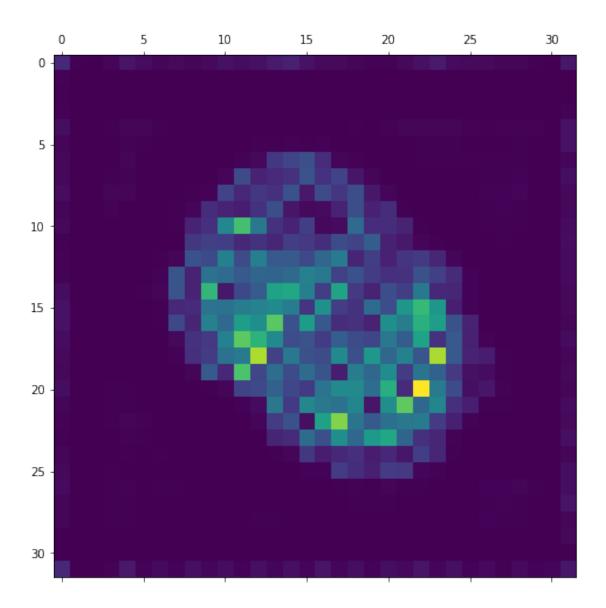
/usr/local/lib/python3.7/distpackages/tensorflow/python/keras/engine/training.py:2325: UserWarning:
`Model.state\_updates` will be removed in a future version. This property should
not be used in TensorFlow 2.0, as `updates` are applied automatically.
warnings.warn('`Model.state\_updates` will be removed in a future version. '

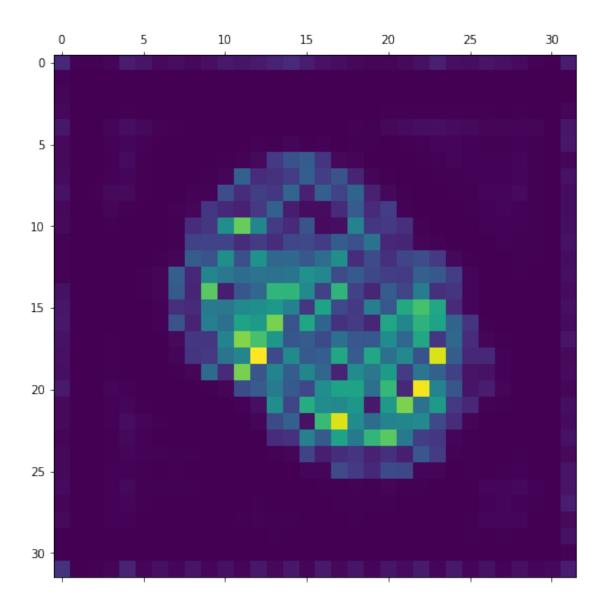


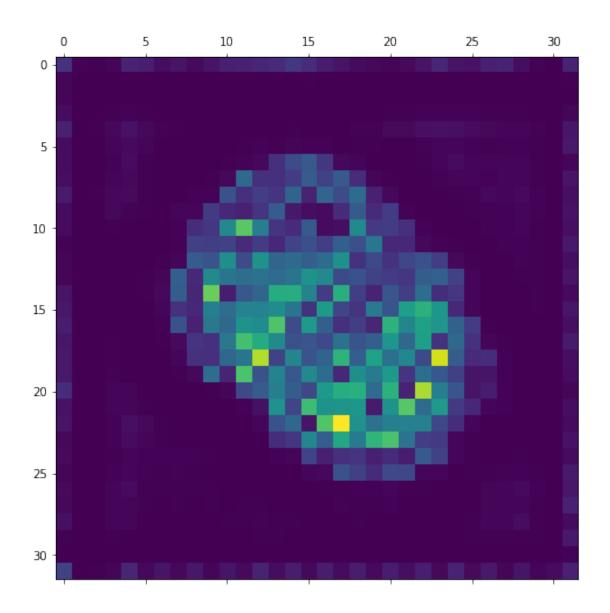


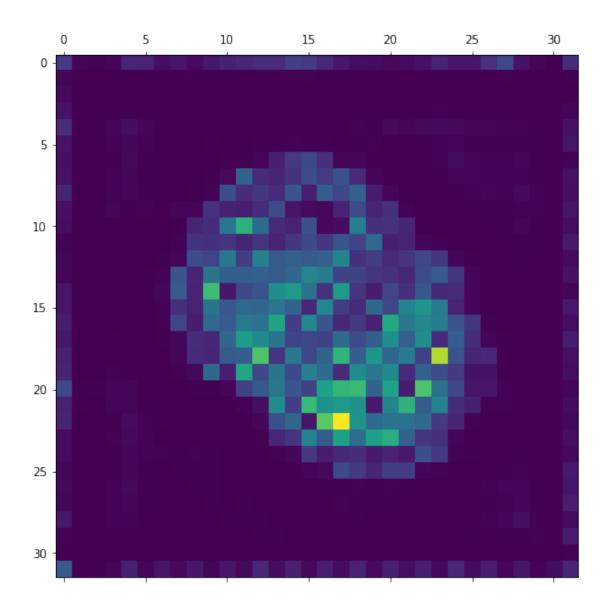


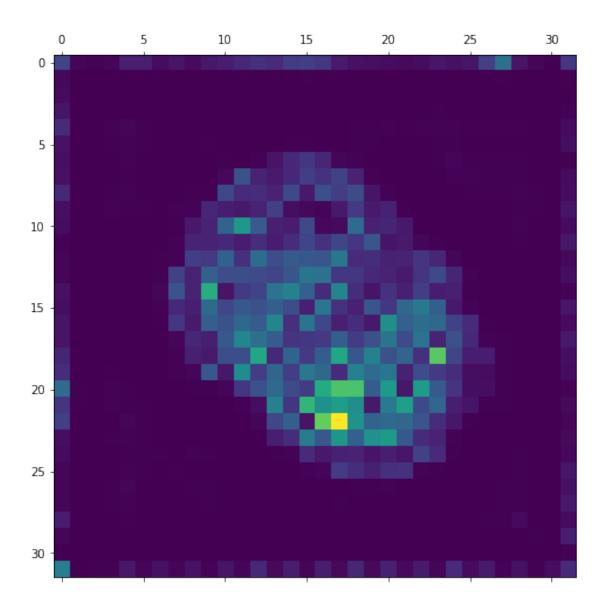


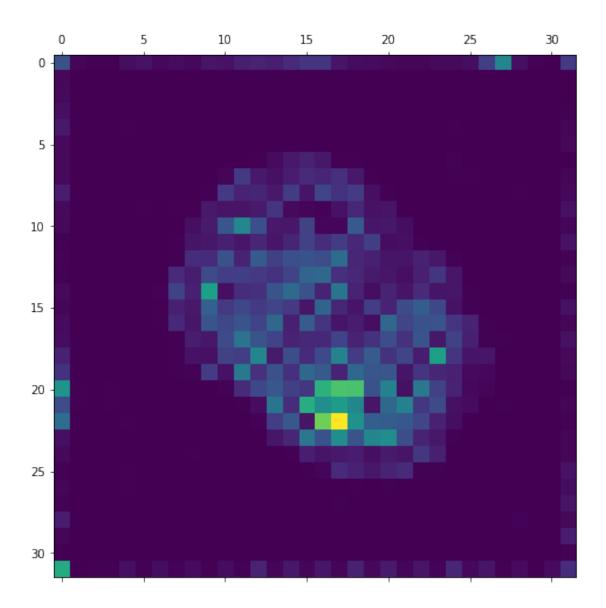


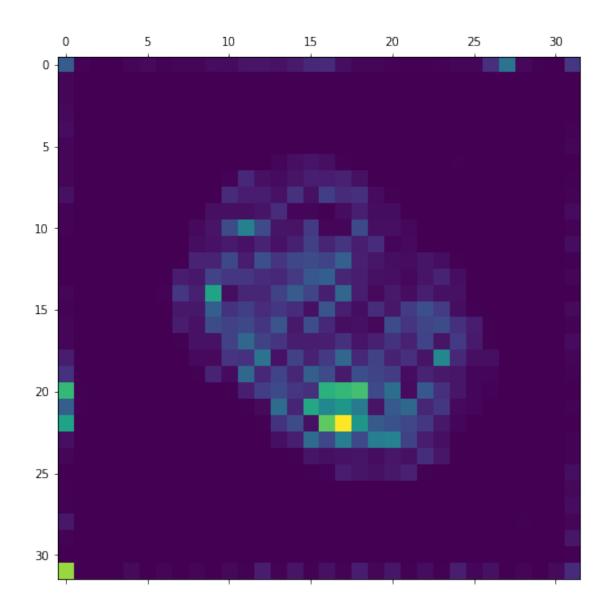












[]: