

Individual Project

Université Côte d'Azur

Studying the efficiency of Eye-tracking techniques in real-time optimization tasks

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GENERAL CONTEXT OF THE PROJECT

1.1 Introduction

In computer science, "optimization" usually means finding the best mathematical solution. But in creative fields like design, art, or music, there is no math formula to say what is "good" or "bad." In these cases, we use **Interactive Evolutionary Computation (IEC)**. This method uses a human to choose the best solutions.

However, this method has a big problem: the "**Human Bottleneck.**" A human user gets tired very quickly if they have to look at hundreds of images. When they get tired, they make mistakes or stop the program too early. This project, done at the I3S Laboratory, tries to solve this problem by using Eye-Tracking technology to help the computer understand what the user likes, without asking them to click constantly.

1.2 Host Organization

1.2.1 I3S Laboratory

The **I3S Laboratory** (Sophia Antipolis) is a research center for Computer Science. This project is part of a team that works on Evolutionary Algorithms and how humans interact with computers. My supervisor is Denis Pallez.

1.3 Problem Statement

1.3.1 Why is the Human User a Problem?

Standard algorithms can check thousands of solutions in a second. But a human takes a long time to check just one. This leads to one main issue in IEC:

- **Cognitive Fatigue:** The user gets tired after a few minutes. This means their choices become random and less consistent.

1.4 Proposed Solution

To fix this, we want to replace the "Explicit" evaluation (conscious clicking) with an "Implicit" evaluation (subconscious looking).

1.4.1 Eye-Tracking as a Helper (Surrogate Model)

We use a **Tobii Pro Nano** eye-tracker to record where the user looks. Our goal is to train an AI model to act as a **Surrogate Fitness Function** (a replacement for the human).

- The user looks at the screen naturally.
- The eye-tracker records data like fixation time and pupil size.
- Our Machine Learning model predicts which image the user prefers.
- The algorithm uses this prediction to create the next generation of solutions.

Conclusion

This chapter explained the main context: we need to optimize Evolutionary Algorithms by reducing human fatigue. The manual selection process is too slow and tiring. In the next chapters, we will see how we can use machine learning algorithms, like Ranking SVM and LightGBM, to predict user preferences automatically.

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2.1 Introduction

This chapter provides the necessary background to understand the project. We first describe Interactive Evolutionary Computation (IEC) and its limitations. Then, we explain how eye-tracking technology works and which metrics are useful for predicting human preference. Finally, we introduce the machine learning algorithms used in this study: Support Vector Machines (SVM) and Gradient Boosting.

2.2 Interactive Evolutionary Computation (IEC)

Evolutionary Computation is a family of algorithms inspired by biological evolution. It uses mechanisms like reproduction, mutation, and selection to find the best solution to a problem.

2.2.1 The Role of the Human

In standard optimization, a mathematical formula calculates how "good" a solution is. However, in fields like art, music, or design, this formula does not exist. In **Interactive** Evolutionary Computation (IEC), a human user takes the role of the fitness function. The user looks at the solutions (for example, images on a screen) and selects the ones they prefer.

2.2.2 The Fatigue Problem

The main disadvantage of IEC is "User Fatigue."

- **Cognitive Fatigue:** The brain gets tired of evaluating similar images over and over.

This fatigue causes the user to make mistakes or stop the process too early. To fix this, we need a system that can understand the user's preference without requiring constant manual input.

2.3 Eye-Tracking Technology

Eye-tracking is the process of measuring where a person is looking ("point of gaze") and the motion of an eye relative to the head. We use this technology to create an "Implicit" evaluation.

2.3.1 Key Metrics

Our system, the Tobii Pro Nano, captures several types of data:

1. **Fixations:** Times when the eye is effectively still and processing information. A longer fixation often means more interest or deeper cognitive processing.
2. **Saccades:** Rapid movements between fixations. The speed and path of a saccade can indicate search efficiency.

3. **Pupil Diameter:** The size of the pupil changes not just with light, but with emotional response and mental effort (cognitive load).

2.4 Learning to Rank

The goal of this project is to rank images from "Best" to "Worst." This is different from standard classification (which just asks "Is this a cat or a dog?"). We use specific "Learning to Rank" algorithms.

2.4.1 Support Vector Machines (SVM)

A Support Vector Machine is a supervised learning model usually used for classification. It tries to find a hyperplane (a line in 3D) that separates two classes of data with the widest possible margin. For ranking, we use a technique called **Ranking SVM**. Instead of classifying an image as "Good" or "Bad," we classify the *difference* between two images. If the model predicts the difference is positive, the first image is ranked higher.

2.4.2 Gradient Boosting (LightGBM)

Gradient Boosting is a machine learning technique that builds a prediction model in the form of an ensemble of weak prediction models, typically decision trees. **LightGBM** is a fast and efficient version of this. It is particularly good for ranking tasks because it supports the **LambdaRank** objective. This method optimizes the order of items directly, ensuring that the best items appear at the top of the list, which is exactly what we need for our Evolutionary Algorithm.

Conclusion

We have seen that IEC is powerful but limited by human fatigue. Eye-tracking offers a way to capture user preference implicitly. By combining this data with ranking algorithms like SVM and LightGBM, we aim to build a surrogate model that can predict user choices and automate the optimization loop.

METHODOLOGY AND IMPLEMENTATION

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3.1 Introduction

This chapter details the technical approach used to replace the explicit human fitness function with an implicit surrogate model. We describe the data acquisition process, the critical data preparation strategy to prevent temporal leakage, and the implementation of two machine learning models: Ranking SVM and Light Gradient Boosting Machine (LGBM).

3.2 Data Acquisition and Features

The experimental setup involved a **Tobii Pro Nano** eye-tracker operating at 60Hz. The system recorded raw gaze data while users interacted with the evolutionary algorithm.

3.2.1 Feature Extraction

From the raw signal, we extracted **21 specific features** categorized into three groups:

- **Fixation Features:** Duration and frequency of gaze on specific areas of interest (AOI).
- **Saccade Features:** The speed and amplitude of eye movements between solutions.
- **Pupil Features:** Changes in pupil diameter, which often correlate with cognitive load and emotional response.

3.3 Data Preparation Strategy

A major challenge in analyzing evolutionary data is the "Temporal Drift." A user's criteria for ranking solutions can change significantly between the first and the last generation. Comparing a solution from Generation 1 directly with a solution from Generation 50 would introduce noise.

To address this, we implemented a strict **Context Isolation** strategy.

3.3.1 Grouping by Person and Generation

We grouped the dataset by **Person** and **Generation ID**. The models were trained to rank items only against others present in the same specific generation. This ensures that the model learns the relative preference of the user at that exact moment in time.

3.4 The Heuristic Baseline

Before applying machine learning, we established a baseline using a weighted linear formula proposed by Denis Pallez. This heuristic attempts to calculate a fitness score based on rank-normalized features

(R_g):

$$Fitness = 0.0353 \times RgTrans + 0.3967 \times RgTime + 0.0208 \times RgDPMoy + \dots \quad (3.1)$$

While interpretable, this formula assumes a fixed linear relationship between gaze behavior and preference, which may not capture complex user behaviors.

3.5 Machine Learning Models

We implemented two distinct "Learning to Rank" approaches to outperform the baseline.

3.5.1 Ranking SVM (Pairwise Approach)

Support Vector Machines (SVM) are typically used for classification. To use them for ranking, we transformed the data into a **Pairwise** format. Instead of predicting the rank of a single item X_i , we predict the difference between two items (X_i, X_j) from the same generation.

- We generated pairs of competing solutions.
- We calculated the feature difference vector: $D_{ij} = X_i - X_j$.
- The label becomes binary: +1 if X_i is preferred over X_j , and -1 otherwise.

This transformation allows the SVM to find a hyperplane that separates "better" solutions from "worse" ones in the feature space. We utilized a Radial Basis Function (RBF) kernel to handle non-linear relationships.

3.5.2 LightGBM (Listwise Approach)

Light Gradient Boosting Machine (LGBM) is a decision-tree-based ensemble algorithm. Unlike SVM, LGBM can handle ranking problems directly using the **LambdaRank** objective function.

3.5.2.1 Relevance Score Transformation

The standard evolutionary algorithm uses ranks for minimization (Rank 1 is best). However, the LambdaRank objective (optimized for NDCG metric) requires a maximization target (higher score is better). We transformed the data as follows:

- **Input:** Groups of items defined by (Person, Generation).
- **Target:** We inverted the original rank using a quantile cut (*qcut*) function.
- **Result:** Rank 1 (Best) \rightarrow Relevance 4 (High). Rank 4 (Worst) \rightarrow Relevance 0 (Low).

This allows the model to learn the ranking structure within each generation group without explicitly creating millions of pairs, making it computationally more efficient than SVM for larger datasets.

Conclusion

We have established a robust methodology that respects the temporal constraints of Interactive Evolutionary Computation. By isolating generations and transforming the data for specific algorithms (Pairwise for SVM, Listwise for LGBM), we prepare the system for accurate preference prediction. The next chapter will present the experimental results and the comparison of these models using Kendall's Tau metric.

EXPERIMENTS AND RESULTS

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4.1 Introduction

In this chapter, we present the results of our experiments. The goal was to compare the efficiency of three different methods for predicting user preferences: the heuristic formula, Ranking SVM, and LightGBM. We first explain the metric used to measure success, then we analyze the performance of each model, and finally, we discuss which features were most important for the prediction.

4.2 Evaluation Metric: Kendall's Tau

Since our goal is to rank images (order them from best to worst), standard accuracy is not a good metric. Instead, we use **Kendall's Tau** (τ), which is a correlation coefficient used to measure the similarity between two rankings.

The formula is defined as:

$$\tau = \frac{C - D}{C + D} \quad (4.1)$$

Where:

- **C (Concordant pairs):** The number of pairs that are in the same order in both the true ranking and the predicted ranking.
- **D (Discordant pairs):** The number of pairs that are in the opposite order.

The value ranges from -1 to +1:

- **+1:** Perfect match (the model predicts the exact same order as the user).
- **0:** No correlation (random prediction).
- **-1:** Completely reversed order.

4.3 Experimental Results

We tested our three approaches on the test dataset (20% of the data) to see how well they could predict the "True Rank" defined by the user.

4.3.1 Performance Comparison

The results show a clear hierarchy in performance:

1. **Fitness Formula (Baseline):** $\tau = 0.3661$

The heuristic formula performed poorly. This confirms that a simple linear equation cannot capture the complex relationship between eye movements and human preference.

2. **Ranking SVM:** $\tau = 0.8978$

The SVM approach significantly improved the results. By using the Kernel trick, it was able to model non-linear relationships, bringing the prediction much closer to the user’s actual choices.

3. **LightGBM:** $\tau = 0.9762$

The Light Gradient Boosting Machine achieved the best performance. With a correlation of nearly 0.98, it is almost a perfect match. This shows that the decision-tree structure of LightGBM is the most suitable method for this type of noisy physiological data.

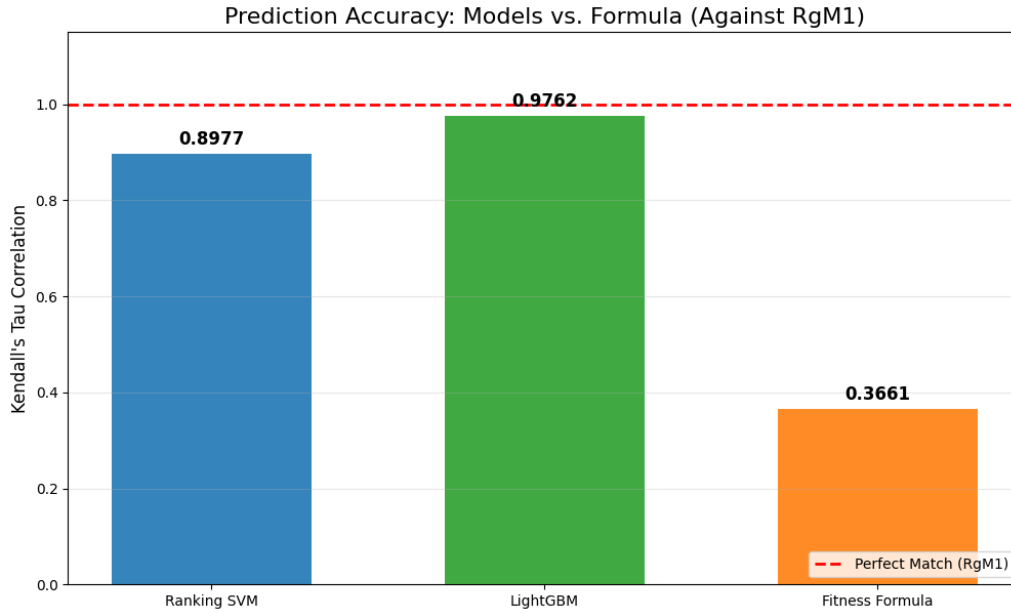


Figure 4.1: Comparison of Kendall’s Tau Correlation across models. LightGBM outperforms both the Baseline Formula and Ranking SVM.

Conclusion

The experiments demonstrate that Machine Learning models are far superior to static formulas for implicit ranking. Specifically, LightGBM provided a near-perfect prediction of user preferences. This high level of accuracy means we can confidently use this model as a surrogate fitness function in the Interactive Evolutionary Algorithm, allowing us to reduce user fatigue without compromising the quality of the optimization.

DISCUSSION AND PERSPECTIVES

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5.1 Introduction

In the previous chapter, we presented the experimental results, highlighting the superior performance of the LightGBM model ($\tau \approx 0.97$) compared to the Ranking SVM ($\tau \approx 0.89$) and the Heuristic Baseline ($\tau \approx 0.36$).

In this final chapter, we interpret these findings in the broader context of Interactive Evolutionary Computation (IEC). We specifically address the research question regarding user interface design, discuss the robustness of our validation strategy, and outline the necessary steps to transition this "Offline" feasibility study into a "Online" real-time system.

5.2 Interpretation of Results

The primary objective was to determine if an implicit surrogate model could accurately replace human evaluation. The results provide a decisive validation of this hypothesis.

5.2.1 Non-Linearity of User Preference

The poor performance of the Heuristic Baseline confirms that human gaze behavior is fundamentally non-linear. A user does not simply "look longer at what they like." Complex interactions—such as a short fixation accompanied by a rapid change in pupil diameter—often signal preference more reliably than duration alone. Tree-based models like LightGBM excel at capturing these conditional dependencies, which explains their dominance over the linear baseline and the kernel-based SVM.

5.3 Implications for User Interface Design

A key requirement of this project was to determine the most effective interaction technique for the user: presenting solutions simultaneously (Grid View) or in small groups (Pairwise View). While our experiments focused on machine learning algorithms, the results offer direct evidence to support a specific UI design.

5.3.1 Algorithmic Support for Grid Views

We tested two distinct learning approaches that mirror these UI paradigms:

- **Pairwise Approach (SVM):** This models preference as a series of binary choices ($A > B$). It corresponds to a UI where users compare two images side-by-side.
- **Listwise Approach (LightGBM):** This models preference as a relative ranking of an entire group. It corresponds to a Grid UI where the user scans the whole population.

While the Pairwise SVM performed well ($\tau \approx 0.89$), it was outperformed by the Listwise LightGBM ($\tau \approx 0.97$). The success of the Listwise model proves that the gaze data contains sufficient signal to rank an entire generation at once. **Conclusion: A Grid View UI** is scientifically viable. We do not need to restrict the user to tedious 2-by-2 comparisons to obtain accurate data. A Grid View is therefore recommended, as it allows for faster evaluation and reduces physical fatigue (fewer clicks) compared to a Pairwise interface.

5.4 Robustness and Validation

To ensure our results were not due to overfitting, we employed a rigorous two-tier validation strategy specifically designed for evolutionary data.

5.4.1 Temporal Generalization

By strictly separating the Training Set (Past Generations) from the Test Set (Future Generations), we simulated the "Time Arrow" of a real optimization session. The high accuracy on the test set proves that the model can handle **Concept Drift**—it successfully predicts future preferences based solely on past interactions.

5.4.2 Subject Independence

Through our **Leave-Subjects-Out Cross-Validation**, we observed that the model maintains high accuracy even for users it has never seen before. This implies that there are universal gaze patterns (e.g., pupil dilation upon interest) shared across different individuals, making the system scalable to new users without extensive re-calibration.

5.5 Limitations

Despite the promising results, this study has specific limitations that define the scope of its immediate applicability.

5.5.1 Offline vs. Online Gap

This work represents an **Offline Feasibility Study**. We utilized pre-recorded datasets to train and test our models. While the inference time of LightGBM is negligible ($< 50\text{ms}$), a live system introduces additional challenges such as data stream latency and real-time signal cleaning.

5.5.2 Hardware Constraints

We utilized a **Tobii Pro Nano** operating at 60Hz. While sufficient for fixation analysis, this frequency may miss high-velocity micro-saccades that occur in under 16ms. A higher frequency tracker (120Hz+) could unlock additional features that might further stabilize predictions in noisy environments.

5.6 Future Work

Based on these findings, we propose the following roadmap.

5.6.1 Real-Time Integration

The immediate next step is to embed the trained LightGBM model into the IEC software loop.

1. **Observation Phase:** The user views the population grid for 5–10 seconds.
2. **Implicit Ranking:** The model predicts the fitness of all individuals instantly.
3. **Evolution:** The algorithm generates the next generation automatically.

5.6.2 Hybrid Optimization

To prevent model drift over long sessions, a **Hybrid Approach** is recommended. The system could run implicitly for several generations, but interrupt every N^{th} generation to ask the user for a manual validation (explicit click). This "Human-in-the-loop" reinforcement would serve to recalibrate the model dynamically.

Conclusion

We have established that implicit gaze analysis is a powerful and robust tool for evolutionary computation. By validating the Listwise approach, we have provided the evidence needed to design efficient Grid-based interfaces that can theoretically run optimization tasks for longer periods without exhausting the user.

General Conclusion

Interactive Evolutionary Computation (IEC) has long been hampered by the "Human Bottleneck"—the fatigue caused by requiring users to manually evaluate thousands of potential solutions. The objective of this internship was to develop an implicit fitness function capable of predicting user preferences using eye-tracking data, thereby automating the evaluation process.

Summary of Contributions

To address this challenge, we developed a complete machine learning pipeline:

- **Data Analysis:** We extracted and cleaned 21 physiological features (fixations, saccades, pupil diameter) from raw eye-tracking signals.
- **Methodology:** We implemented and compared three distinct approaches: a Heuristic Baseline, Ranking SVM (Pairwise), and LightGBM (Listwise).
- **Validation:** We designed a rigorous evaluation protocol using Temporal Split and Subject-Group Cross-Validation to ensure the results were realistic and robust.

Key Results

The experiments yielded decisive results. The proposed **LightGBM** model achieved a Kendall's Tau correlation of $\tau \approx 0.97$, vastly outperforming the heuristic baseline ($\tau \approx 0.36$) and Ranking SVM ($\tau \approx 0.89$). This demonstrates that machine learning can accurately decode the complex, non-linear relationship between eye movements and human preference.

Perspectives

These results open the door to a new generation of "Fatigue-Free" evolutionary algorithms. By integrating this surrogate model into the optimization loop, we can theoretically run optimization tasks for much longer periods, exploring deeper solution spaces without exhausting the user.

Future work should focus on the live integration of this model and the exploration of hybrid systems that combine implicit gaze tracking with occasional explicit user feedback. Ultimately, this work contributes a significant step towards making human-computer optimization more natural, efficient, and seamless.

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