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Experiment-04

Name of the Experiment: Butting tool grinding operation

hiven tool (tuning tool) geometry: In ASA system,

8°, 11.5°, 7°, 8°, 25°, 30°, 0° (inch)

Thus, $Y_y = 8^\circ$, $Y_x = 11.5^\circ$, $y_y = 7^\circ$, $y_z = 8^\circ$, $y_z = 8$

Im ORS system: 0°, 12°, 3°, 8°, 15°, 60°, 0 (mm)

Thus, $d=0^{\circ}$, $V_0=12^{\circ}$, $V_0=9^{\circ}$, $V_0=8^{\circ}$, $V_0=15^{\circ}$, $V_0=60^{\circ}$, $V_0=0$ mm

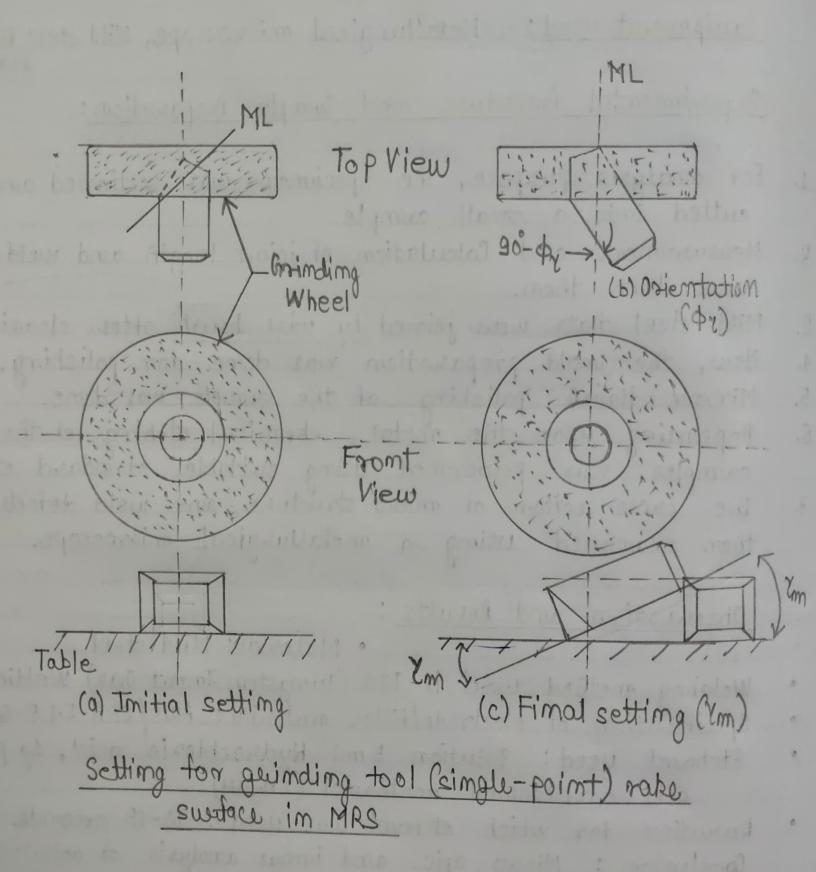
Since single-point tools are preferably re-sharpened by grinding in maximum rake system (MRs) and minimum cleanance system (MCs). Thus converting above given system into MRS system by using following formulaes:

- 1. $\phi_{\chi} = \tan^{-1}\left(\frac{\tan \chi_{\chi}}{\tan \chi_{\chi}}\right) = \tan^{-1}\left(\frac{\tan(11.5^{\circ})}{\tan(8^{\circ})}\right) \Rightarrow \phi_{\chi} = 55.36^{\circ}$
- 2. $l_{m} = \frac{1000}{100} \left(\sqrt{\frac{1000}{1000} l_{x} + \frac{1000}{1000} l_{y}} \right) = \frac{1000}{1000} \left(\sqrt{\frac{1000}{1000} (11.50) + \frac{1000}{1000} (80)} \right) = 13.889^{\circ}$
- 3. $\phi_{V} = \phi \tan^{-1}\left(\frac{\tan \theta}{\tan v_{0}}\right) = 50 \cdot \tan^{-1}\left(\frac{\tan \theta}{\tan (12^{\circ})}\right) = 550 \cdot 60^{\circ}(0.85 + 0.000)$
- 4. $tan Y_{mn} = \sqrt{tan^{2} (12^{\circ}) + tan^{2} (0)} \Rightarrow Y_{mn} = tan^{-1} (tan 12^{\circ})$
- (ORS to MRS) 5. $\phi_{\alpha} = \tan^{-1}\left(\frac{\cot \alpha_{\alpha}}{\cot \alpha_{\nu}}\right) = \tan^{-1}\left(\frac{\cot(8^{\circ})}{\cot(7^{\circ})}\right) = 31.11^{\circ}$
- 6. \approx cot $d_m = \sqrt{\cot^2 d_n + \cot^2 d_y} = \sqrt{\cot^2 (8^\circ) + \cot^2 (7^\circ)}$

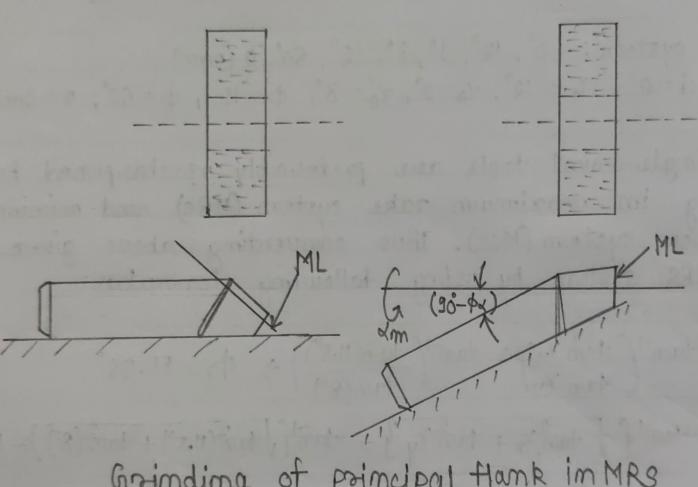
> <m=5.28°

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	7. $\phi_{x}' = \phi_{1} - \tan^{3}(\tan x_{0}' + \tan x_{0}') = 60^{\circ} - \tan^{3}(\frac{0.0193}{10.23}) = 59.88^{\circ}$
	8. cot $q_m' = \int \cot^2 q_0' + \cot^2 q_1' = 10.23 \Rightarrow q_m' = \cot^2 (10.23)$
	$\Rightarrow \forall m = 5.583^{\circ}$
	Procedure:
1.	brimding of tool rake surface in MRS:
•	Values of ty (orientation angle) and mm (setting angle, i.e.
	maximum rake angle) was calculated from the given
	tool geometry in ASA, ORS and NRS.
•	The tool shamk was placed below the grinding wheel of the
	tool and the cutter grinder, keeping the shank parallel
•	to the wheel axis. Now the shank was rotated (oriented) about the Zm axis
	by an angle of 90- by to bring the master line (ML)
	parallel to the wheel axis.
•	Now the tool was tilted about the master line by mari-
	-mum rake angle 2m.
•	The tool-table was reciprocated as such bringing the tool
	(rake face) in contact with the wheel surface for
	guinding action.
•	Reciprocation was repeated with small infeeds.
۵.	Grinding of Bincipal Hank in MRS:
	of finality of fathering
•	For this, the value of the and of was determined from the
	given tool geometry.
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Grinding of principal Hank in MRS

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	placed the tool shamk below the grimding wheel. The tool was now rotated about 7m oxis by 90-by to bring the master line (Mr) of the principal flank parallel to the wheel axis. Rotated the tool shank (vice) about the master line by 4m. The tool was reciprocated (flanked) in contact with the wheel Reciprocation was repeated with slight infeeds.
3.	Grinding Auxiliary Hank surface in MRS:
	the value of the and of the auxiliary flank was determined from the given tool geometry. The tool shamk was placed below the grinding wheel. The tool was made notated by an angle the to bring the master line parallel to the wheel aris. Rotated the tool about the master line of the auxiliary flank by ofm. The table with the tool was reigneated against the grinding wheel periphery. Resiprocation was repeated with small infeeds.
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