I'm working with Rockit v0.6.6.  
Please avoid the following mistakes and follow these constraints strictly:

* Do **not** use ocp.phase(...). Use ocp.stage(...) instead.
* Do **not** use Phase(...) or ocp.add\_phase(...). These are not available.
* Do **not** use ocp.bounded(...). This method does not exist in v0.6.6. Use explicit inequality constraints with subject\_to(...).
* Do **not** write chained inequality constraints like 0 <= v <= 1.0. Use two separate constraints instead.
* Do **not** use ocp.minimize(...) or ocp.set\_objective(...). Use stage.add\_objective(...) inside each stage.
* Do **not** use ocp.method(...) when working with multiple stages. Use stage.method(...) for each individual stage.
* Do **not** use at\_t(...) (e.g. for time-based constraints like at\_t(5, x)). It is not implemented in this version. Use additional stages for waypoints instead.
* Do **not** apply constraints to stage-local variables (like v1, x1, etc.) using ocp.subject\_to(...).  
  Use stage.subject\_to(...) inside the same stage where the variable was declared.