

```
In [1]: import matplotlib.pyplot as plt
import numpy as np
import torch
from tqdm import tqdm
import h5py

from matplotlib.colors import LogNorm
from scipy import stats
from dataload import load_json_config, process_data, load_data
```

```
In [2]: import sys
sys.path.append('./')
from pytorch3dunet.unet3d.model import UNet3D, ResidualUNet3D
```

Load trained model

```
In [3]: device='cpu'
ckp='checkpoint_model_29999.pth'
size=64
pad=16
config = load_json_config(custom_path='config.json')
```

```
In [4]: model_b=ResidualUNet3D(in_channels=config["input_channels"],out_channels=config["output_channels"],\
                               f_maps=config["nchan"],num_levels=config["deep"],\
                               conv_upscale=2,\
                               upsample='deconv',\
                               layer_order='cbr',\
                               final_sigmoid=False, is_segmentation=False,dropout_prob=0.0)

model_z=ResidualUNet3D(in_channels=config["input_channels"],out_channels=config["output_channels"],\
                       f_maps=config["nchan"],num_levels=config["deep"],\
                       conv_upscale=2,\
                       upsample='deconv',\
                       layer_order='cbr',\
                       final_sigmoid=False, is_segmentation=False,dropout_prob=0.0)
```

```
In [5]: checkpoint = torch.load(ckp, map_location='cpu')

model_state_dict = checkpoint['model_b']
if isinstance(model_b, torch.nn.DataParallel) or isinstance(model_b, torch.nn.parallel.DistributedDataParallel):
    # If the model is wrapped, we need to load the state_dict into model
    model_b.module.load_state_dict(model_state_dict)
else:
    # If the model is not wrapped, load the state_dict directly
    model_b.load_state_dict(model_state_dict)

model_state_dict = checkpoint['model_z']
if isinstance(model_z, torch.nn.DataParallel) or isinstance(model_z, torch.nn.parallel.DistributedDataParallel):
    # If the model is wrapped, we need to load the state_dict into model
    model_z.module.load_state_dict(model_state_dict)
else:
```

```
# If the model is not wrapped, load the state_dict directly
model_z.load_state_dict(model_state_dict)
```

Load data

try to load the data into one batch, and get a smooth prediction without using split and stitch with a pad zone.

```
In [6]: bx,bx1,by,by1,bz,Zini,_,bscale=load_data(filename=config['filename'],hsize=c

dataset=torch.zeros((1,6,size*4,size*4,32),dtype=torch.float32)

dataset[0,0]=torch.tensor(bx[2*size:6*size,2*size:6*size],dtype=torch.float32)
dataset[0,1]=torch.tensor(by[2*size:6*size,2*size:6*size],dtype=torch.float32)
dataset[0,2]=torch.tensor(bz[2*size:6*size,2*size:6*size],dtype=torch.float32)
dataset[0,3]=torch.tensor(Zini[2*size:6*size,2*size:6*size],dtype=torch.float32)
dataset[0,4]=torch.tensor(bx1[2*size:6*size,2*size:6*size],dtype=torch.float32)
dataset[0,5]=torch.tensor(by1[2*size:6*size,2*size:6*size],dtype=torch.float32)
```

```
In [7]: del bx, by, bz, Zini, bx1, by1
```

Load true \vec{B} and Z

```
In [8]: with h5py.File(config['filename'],'r') as f:
    Ztrue = f['tz3d'][:]
    Bxtrue = f['bx'][:]
    Bytrue = f['by'][:]
    Bztrue = f['bz'][:]
    bscale=np.nanmax(np.sqrt(f['bx'][:]**2 + f['by'][:]**2 + f['bz'][:]**2))

    Ztrue=Ztrue[2*size:6*size,2*size:6*size]
    Bxtrue=Bxtrue[2*size:6*size,2*size:6*size]/bscale
    Bytrue=Bytrue[2*size:6*size,2*size:6*size]/bscale
    Bztrue=Bztrue[2*size:6*size,2*size:6*size]/bscale
```

Apply model to data

```
In [9]: pred_b=np.zeros((dataset.shape[0],3,dataset.shape[2],dataset.shape[3],dataset.shape[4]))
    pred_z=np.zeros((dataset.shape[0],1,dataset.shape[2],dataset.shape[3],dataset.shape[4]))
```

```
In [10]: with torch.no_grad():
    for ix in tqdm(range(dataset.shape[0])):
        pred_b[ix]=torch.tanh(model_b(dataset[ix].unsqueeze(0))).detach().numpy()
```

```
100%|██████████| 1/1 [00:16<00:00, 16.49s/it]
```

```
In [11]: with torch.no_grad():
    for ix in tqdm(range(dataset.shape[0])):
        pred_z[ix]=torch.tanh(model_z(dataset[ix].unsqueeze(0))).detach().numpy()
```

```
100%|██████████| 1/1 [00:16<00:00, 16.41s/it]
```

Map the splited data back the original data shape.

```
In [12]: Bxp=pred_b[0,0]
        Byp=pred_b[0,1]
        Bzp=pred_b[0,2]
        Zp=pred_z[0,0]
```

```
In [13]: del pred_b
        del pred_z
```

Visualization of \vec{B} and Z , prediction vs. Truth on $\tau=1.6$ for each batch.

Bottom is prediction, top is true value.

```
In [14]: fig,axs=plt.subplots(2,4,figsize=(18,9))
        itau=16

        axs[0,0].imshow(Bxtrue[... ,itau].T,origin='lower',vmin=-0.3,vmax=0.3,cmap='bwr')
        axs[1,0].imshow(Bxp[... ,itau].T,origin='lower',vmin=-0.3,vmax=0.3,cmap='bwr')

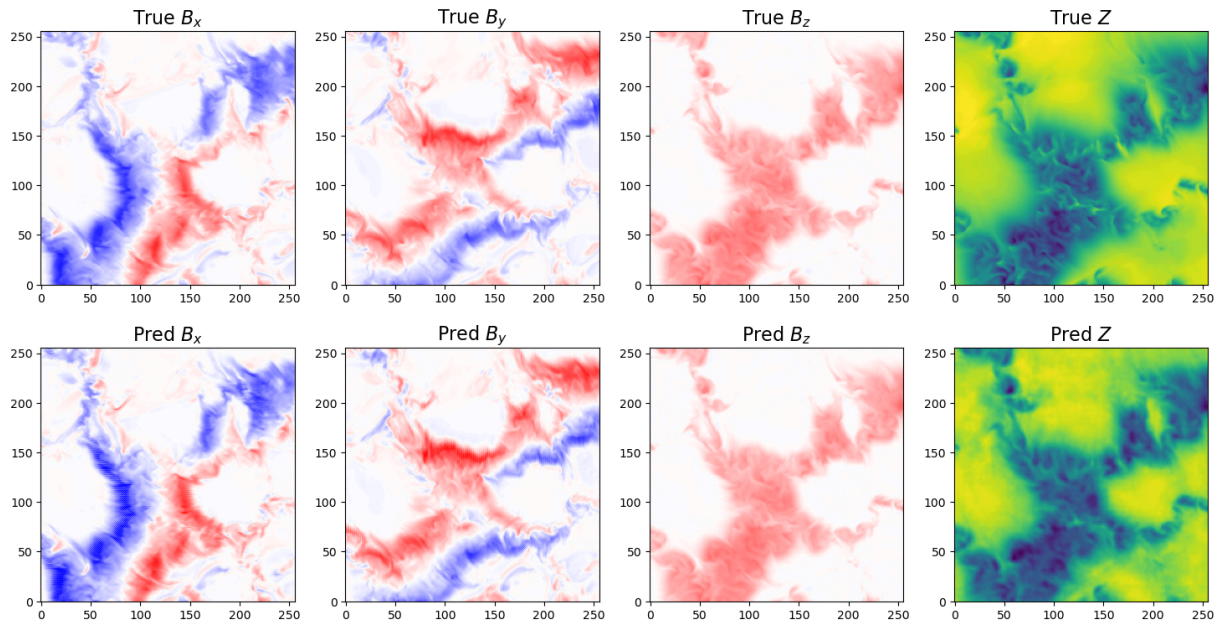
        axs[0,1].imshow(Bytrue[... ,itau].T,origin='lower',vmin=-0.3,vmax=0.3,cmap='bwr')
        axs[1,1].imshow(Byp[... ,itau].T,origin='lower',vmin=-0.3,vmax=0.3,cmap='bwr')

        axs[0,2].imshow(Bztrue[... ,itau].T,origin='lower',vmin=-1,vmax=1,cmap='bwr')
        axs[1,2].imshow(Bzp[... ,itau].T,origin='lower',vmin=-1,vmax=1,cmap='bwr')

        axs[0,3].imshow(Ztrue[... ,itau].T,origin='lower')
        axs[1,3].imshow(Zp[... ,itau].T,origin='lower')

        titlename=[r'True $B_x$',r'True $B_y$',r'True $B_z$',r'True $Z$',\
                    r'Pred $B_x$',r'Pred $B_y$',r'Pred $B_z$',r'Pred $Z$']

        axs=axs.flatten()
        for ix in range(len(axs)):
            axs[ix].set_title(titlename[ix],fontsize=16)
```



Check the ambiguity result

```
In [15]: tmp=Bxtrue+1j*Bytrue
phi_true=np.angle(tmp)

tmp= Bxp+1j*Byp
phi_pred=np.angle(tmp)
```

```
In [16]: binsize=1024
phisize=2048
d_phi=np.mod(phi_true-phi_pred,2*np.pi)
babs=np.sqrt(Bxtrue**2+Bytrue**2)
minvalue=np.log10(babs.min())
maxvalue=np.log10(babs.max())
val=np.logspace(minvalue,maxvalue,binsize)
d_phi=np.mod(phi_true-phi_pred,2*np.pi)
bins=(val,np.linspace(0,2*np.pi,phisize))
depart,yedges,xedges=np.histogram2d(babs[:,:::].flatten(),d_phi[:,:::].flatten(),
accurate=1-np.sum(depart[:,phisize//4:3*phisize//4],axis=1)/np.sum(depart,ax
```

```
/var/folders/rr/2n3c73qx6r141zscx2v__r9w0000gn/T/ipykernel_36536/117300874.p
y:11: RuntimeWarning: invalid value encountered in divide
accurate=1-np.sum(depart[:,phisize//4:3*phisize//4],axis=1)/np.sum(depart,
axis=1)
```

```
In [17]: plt.figure(figsize=(18, 8))
ax = plt.subplot(121, polar=True) # Create a polar subplot
c = ax.pcolormesh(xedges, yedges*bscale, depart, norm=LogNorm(vmax=1e2,vmin=
plt.colorbar(c, ax=ax, label='Pixel Numbers') # Add a colorbar to show the c
ax.set_title(r'$\Delta\Phi$, Angle difference between prediction and truth')
plt.yscale('log')
plt.ylim([8e-2,2e3])

ax1 = plt.subplot(122) # Create a polar subplot
xx=bscale*yedges
```

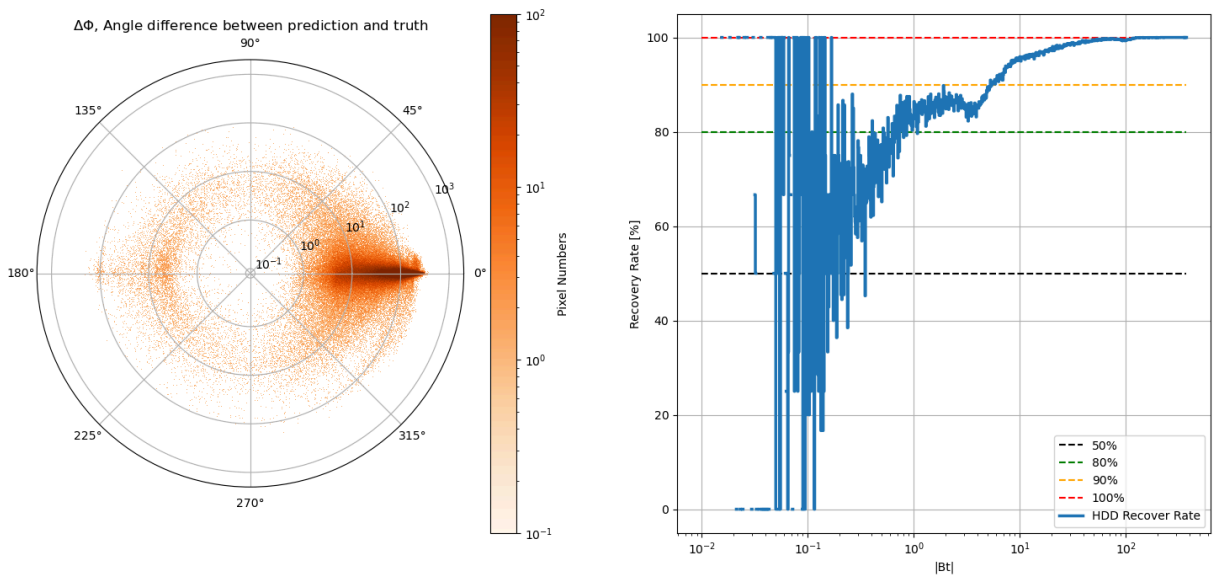
```

midpoints = bscale*(yedges[:-1] + yedges[1:]) / 2
ax1.plot([midpoints.min(),midpoints.max()], [50,50], 'k--', label='50%')
ax1.plot([midpoints.min(),midpoints.max()], [80,80], linestyle='--', color='green')
ax1.plot([midpoints.min(),midpoints.max()], [90,90], linestyle='--', color='orange')
ax1.plot([midpoints.min(),midpoints.max()], [100,100], linestyle='--', color='red')
ax1.set_ylabel('Recovery Rate [%]')
ax1.step(midpoints, accurate*100, where='mid', linewidth=2.5, label='HDD Recov')
ax1.grid()

ax1.legend()
ax1.set_xscale('log')
ax1.set_xlabel('|Bt|')

```

Out[17]: Text(0.5, 0, '|Bt|')



Check prediction of geometric height

```

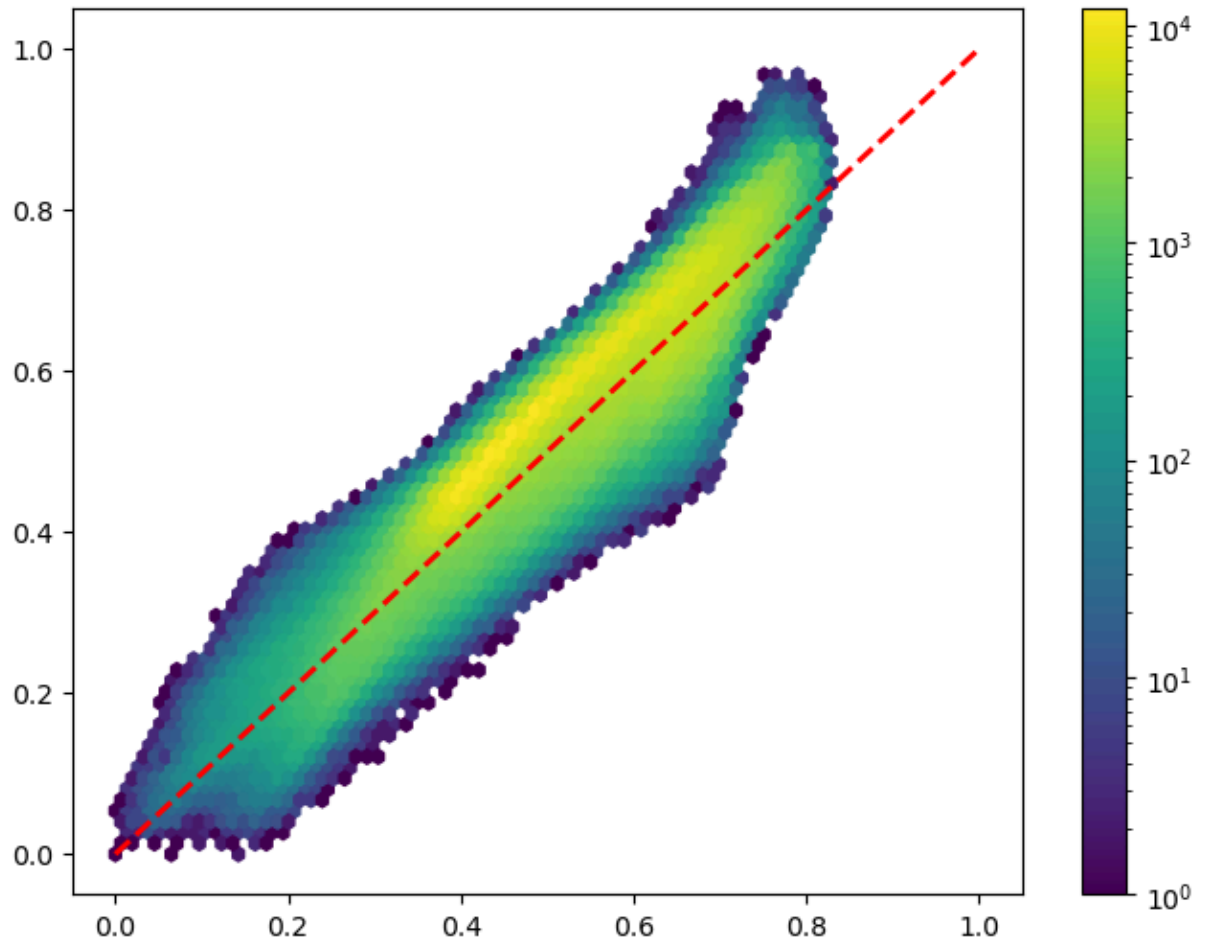
In [18]: fig=plt.figure(figsize=(8, 6))
         ilayer=1

         plt.hexbin(Zp[:, :, :].flatten()-Zp.min(), Ztrue[:, :, :].flatten()-Ztrue.min(), b
         plt.plot([0,1], [0,1], 'r--', linewidth=2, label='x=y line')

         plt.colorbar()

```

Out[18]: <matplotlib.colorbar.Colorbar at 0x3ddeb3690>



In []: