

## CS 305 Lab 10: Graphs Fall 2019

The purpose of this lab is to give you experience with implementing a graph data structure and implementing graph functions. This lab has a total of 100 possible points (30 points from pre-lab and 70 points from lab). You have 1.5 to 2 class periods to work on this lab.

Sit with your assigned partner.

### Objectives

Upon completion of the laboratory exercise, you will be able to do the following:

- use the adjacency matrix representation of a graph
- calculate degrees for vertices
- determine neighbors of vertices
- implement depth-first search
- determine the path from node  $x$  to  $y$  using the results of depth-first- search

### Part 1: Logging in (choose one person)

1. Follow the procedure from prior labs to log in and open Mobaxterm. Go into your cs305 directory. Make a new lab10 directory:

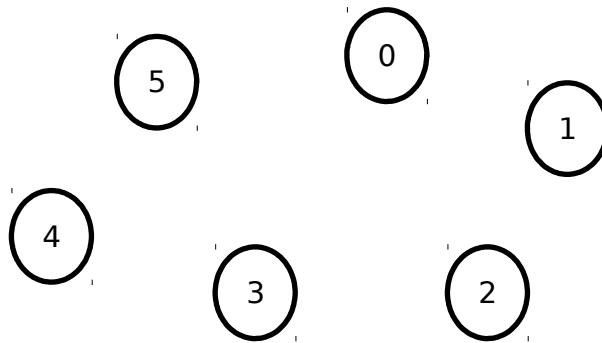
```
cd /drives/p/cs305
mkdir lab10
```

2. Get the lab 10 files. Download `graph.c` from moodle to your lab10 folder. Hopefully, you can see the file in the directory.

### Part 2: Understand the existing code

Open `graph.c`. In this lab, the graph is an **unweighted, directed** graph that is implemented using the adjacency matrix representation. The nodes are labeled 0 to  $|V|-1$  where  $V$  is the set of vertices in the graph. For example, if the graph has 4 nodes, then the node labels are  $\{0, 1, 2, 3\}$ .

1. What are the members of the Graph struct? int V, int \*\*M
2. What are the members of the DFS struct? COLOR color, int parent, int discover, int finish
3. Look at the `main` function. How many vertices does `g` have after it is created?  
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4. You'll see calls to `addEdge`. Some of these calls will not add an edge (if the `src` is out of range, if the `dest` is out of range, if an edge already exists). Draw the edges in the graph `g` below:



5. Scroll down to the function `createEmptyGraph`. Read through this. This function creates a graph with no edges of `numVertices` nodes. `freeGraph` frees all memory associated with a graph.

### Part 3: Implementing functions

As you work through the function definitions, you may want to compile often:

```
gcc -o g graph.c
./g
```

1. Go to the `addEdge` function definition. Complete this function so that it does the following:

- if graph is null, prints an error message about not adding an edge and return 0
- if `src` or `dest` is out of range for the graph ( $< 0$  or  $\geq g \rightarrow V$ ), print “src or dest vertex invalid” and return 0
- if graph already has an edge from `src` to `dest`, print “edge already exists between 0 and 3” if the `src` is 0 and `dest` is 3; return 0
- set `g->M[src][dest]` to 1 and return 1

After you get `addEdge` working, test it on the graph in main. Which of the `okX` variables are set to 0?

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2. Go to the `outDegree` function definition. Complete this function so that it does the following:

- if graph is null, returns 0
- if `v` is out of range, returns 0
- count the number of edges from `v` to other nodes and return this count (think about what row or column you need to look at in `G->M`)

3. Go to the `inDegree` function definition. Complete this function so that it does the following:

- if graph is null, returns 0
- if `v` is out of range, returns 0
- count the number of edges from other nodes to `v` and return this count (think about what row or column you need to look at in `G->M`)

4. Go to the `isNeighbor` function definition. Complete this function so that it does the following:

- if `g` is NULL, return 0
- if `x` or `y` are out of range, return 0
- if has an edge from `x` to `y`, return 1; else, return 0

**Checkpoint 1 [30 points]: Show your lab instructor/assistant the answers to the questions above and results of your program running.**

## **Part 4: Implementing Depth First Search and path finder**

1. Read through the `dfsInit` function. This initializes the array of DFS objects prior to calling `dfs`. Complete the `dfs` function so that it recursively performs depth-first search. It should print "visited 0" when it visits node 0. Note that the `time` variable is global, so the recursive function calls have access to a common `time` variable. Use `isNeighbor` to determine the vertices adjacent to the node you are currently processing.

2. Complete the `printReversePath` function so that it prints the path from dest to source. Note that a more user-friendly version would reverse the path to print from src to dest, which could easily be done with a stack. To implement this, you start with current node as the dest node. You find its parent and set this to the current node. Print the current node. Keep doing this while the current node is not -1 and current node is not the src.

An example printout for a path from 0 to 1 would look like:

```
PATH: 1 <-3 <-0 <-
```

**Checkpoint 2 [20 points]: Show your lab instructor/assistant the results of your program running.**

## **Part 5: Choose your own graph function**

1. Choose something you want to implement for the graph. Here are some options:

- a. breadth-first search (will also need a queue; can use queue code from earlier lab)

- b. distance-away from source to dest (# hops, based on breadth-first search), for example if node 5 is 3 hops away from 0, then it should return 3. If there is no path from the source to the dest, return -1.
- c. print a topological sort of the graph (based on depth-first search)
- d. re-do the graph representation as an adjacency list; update addEdge, isNeighbor, printGraph, inDegree, outDegree
- e. minimum spanning tree (Prim); note: graph needs to be undirected, so update addEdge to add edges between (src, dest) and (dest, src)
- f. minimum spanning tree (Kruskal); note: graph needs to be undirected, so update addEdge to add edges between (src, dest) and (dest, src)
- g. is-cyclic, check to see if there is a cycle from any node back to itself
- h. is-connected, check to see if there is a path from every src node to all other nodes
- i. is-subgraph, create new graph and check it against another graph. A graph  $G'$  is a subgraph of  $G$  if  $V'$  is a subset of  $V$  and  $E'$  is a subset of  $E$ .
- j. something of your own desire (ask me first if it is not on the above list); note that you are implementing dijkstra's for homework, so **do not do dijkstra** for the lab

2. What feature did you add to the code? \_\_\_\_\_

**Checkpoint 3 [20 points]: Show your lab instructor/assistant the results of your program running.**

## **Part 6: Finish up**

Close Mobaxterm and any other applications. Log off the computer.

If any checkpoints are not finished, they are due NLT midnight on Sunday. You may submit screenshots, the code file, and answers to questions electronically on moodle.