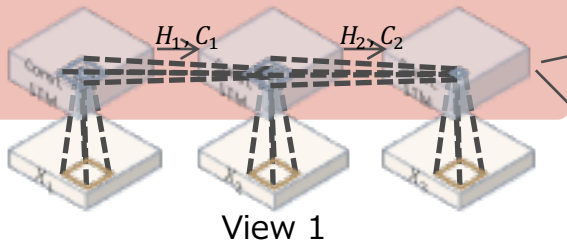
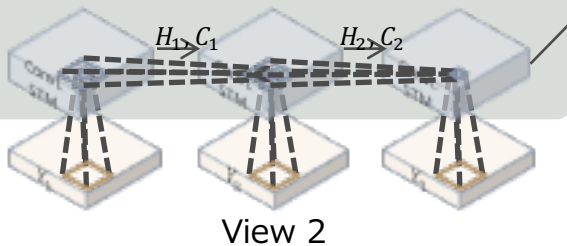


Encoder  $f$



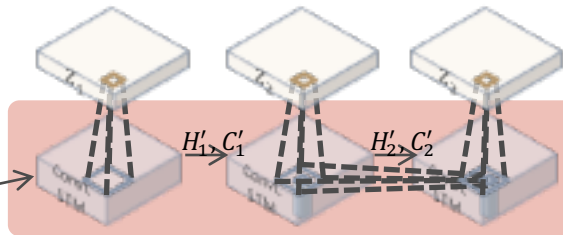
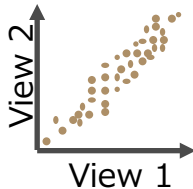
Encoder  $g$



$U^T f$

$U$

$V$



Predictor  $h$