# KAI CHEN

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#### RESEARCH OVERVIEW

My research aims at constructing reliable **Multi-modal** AI systems from a **data-centric** perspective. Recently, we have witnessed the staged success of training foundational models on massive human data, which, however, is believed to come to an end. Towards the second half of AI, a scalable synthetic data generation and training pipeline is necessary, for which **Reinforcement Learning** acts as a well-formulated solution. Scaling RL has achieved remarkable success for LLMs, while it remains an open challenge for (native) **multi-modal LLMs**. Specifically, I'm currently trying to answer the following questions,

- Policy: How to build end-to-end Multi-modal LLMs with frontier visual, textual, and speech abilities?
- World: How to construct 3D visual world models in a controllable and scalable manner?
- Feedback: How to get effective intrinsic feedback from (M)LLMs themselves without a reward model?
- Optimization: Does more data always result in better performance?

Research Areas: Omni-modal LLMs, Visual World Modeling, Mixture-of-Experts (MoE)

#### **EDUCATION**

Hong Kong University of Science and Technology, Hong Kong SAR Sep 2020 - June 2026 (Expect)

Ph.D. in Computer Science and Engineering

GPA: 4.10/4.0

Advisor: Prof. Dit-Yan Yeung

Fudan University(FDU), Shanghai, China

Sep 2016 - June 2020

B.S. in Computer Science, Minor in Economics (Outstanding Graduates of Shanghai)

Overall GPA: 3.70/4.0, Major GPA: 3.90/4.0, Ranking: 3/32

Advisor: Prof. Yanwei Fu

University of Manchester, Manchester, UK

Sep 2018 - Jan 2019

Exchange student in the **Department of Computer Science** 

Advisor: Dr. Tingting Mu

## **EXPERIENCE**

# Mobile Intelligence Group (MIG), SenseTime

Oct 2019 - April 2020

Research Intern

Advisor:Dr. Wenxiu Sun

• Research on real-time (portrait) instance segmentation deployable on mobile devices.

Computer Vision Lab, Indiana University Bloomington (IUB)

June 2019 - Sep 2019

Global Talent Attraction Program (GTAP) Visiting Scholar

Advisor:Prof. David Crandall

• Research on semi-supervised semantic segmentation and indoor 3D reconstruction.

#### SELECTED HONORS

CVPR 2025 Travel Awards	May 2025
HKUST Research Travel Grant	2023-2025
HKUST Postgraduate Scholarship	Sep 2020
Outstanding Graduates of Shanghai [Wechat Post] (5%, by Shanghai Government)	April 2020
Scholarship for Outstanding Graduates (5%, by Fudan University)	April 2020
Oversea Visiting Student Stipend of (15,000 CNY, Fudan University)	Dec 2019

Joel & Ruth Spira Scholarship (1%, by Lutron Electronics) National Scholarship (1%, by Ministry of Education of P.R.China) Scholarship for Outstanding Undergraduate Students (5%, by Fudan University)	Mar 2019 Sep 2018 Oct 2017
PUBLICATIONS	
Full publication list on my Google Scholar. (* denotes equal contribution)	
I. Multi-modal Foundation Models  RQ: How to construct multi-modal LLMs with visual, textual, and speech reasoning abilities si	multaneously?
[C23] EMOVA: Empowering Language Models to See, Hear and Speak with Vivid Emotions Kai Chen*, Yunhao Gou*, Runhui Huang*, Zhili Liu*, Daxin Tan*, and other 26 authors	CVPR 2025
	Arxiv 2025
[C22] Perceptual Decoupling for Scalable Multi-modal Reasoning via Reward-Optimized Captioning Yunhao Gou*, <u>Kai Chen*</u> , Zhili Liu*, Lanqing Hong, Xin Jin, Zhenguo Li, James T. Kwok, Yu Zhang.	[link]
II. Multi-modal Foundation Models - Mixture of Cluster-conditional Experts (Mercy: Does more data always result in better performance during model pre-training and fine-tu-	,
[C21] Mixture of Cluster-conditional LoRA Experts for Vision-language Instruction Tuning Yunhao Gou*, Zhili Liu*, <u>Kai Chen*</u> , Lanqing Hong, Hang Xu, Aoxue Li, Dit-Yan Yeung, James Kwok, Yu Zhang.	Arxiv 2023 [ <u>link</u> ]
	2023 Spotlight
[C19] Task-Customized Self-Supervised Pre-training with Scalable Dynamic Routing Zhili Liu, Jianhua Han, <u>Kai Chen</u> , Lanqing Hong, Hang Xu, Chunjing Xu, Zhenguo Li.	AAAI 2022 [link]
III. Multi-modal Foundation Models - Scalable Oversight for (M)LLM Self-alignment RQ: Are there any intrinsic scalable oversight from (M)LLMs to supervise their own capability	
in Visual Instruction Tuning Yunhao Gou, Hansi Yang, Zhili Liu, <u>Kai Chen</u> , Yihan Zeng, Lanqing Hong, Zhenguo Li,	[link]
Qun Liu, James T Kwok, Yu Zhang.  [J2] Unified Triplet-Level Hallucination Evaluation for Large Vision-Language Models Junjie Wu*, Tsz Ting Chung*, <u>Kai Chen*</u> , Dit-Yan Yeung.	TMLR 2025
[C17] Mixture of insighTful Experts (MoTE): The Synergy of Thought Chains and Expert Mixtures in Self-Alignment Zhili Liu*, Yunhao Gou*, <u>Kai Chen*</u> , Lanqing Hong, Jiahui Gao, Fei Mi, Yu Zhang, Zhenguo Li, Xin Jiang, Qun Liu, James T. Kwok.	ACL 2025
[C16] Eyes Closed, Safety On: Protecting Multimodal LLMs via Image-to-Text Transformation Yunhao Gou*, <u>Kai Chen*</u> , Zhili Liu*, Lanqing Hong, Hang Xu, Zhenguo Li, Dit-Yan Yeung, James Kwok, Yu Zhang.	ECCV 2024 [ <u>link</u> ]
[C15] Gaining Wisdom from Setbacks: Aligning Large Language Models via Mistake Analysis	ICLR 2024

	<u>Kai Chen*</u> , Chunwei Wang*, Kuo Yang, Jianhua Han, Lanqing Hong, Fei Mi, Hang Xu, Zhengying Liu, Wenyong Huang, Zhenguo Li, Dit-Yan Yeung, Lifeng Shang, Xin Jiang, Qun Li	iu.	[ <u>link</u> ]
	IV. Visual World Models - Corner Cases for Autonomous Driving (CODA)  RQ: How to enhance the robustness of self-driving agents towards road corner cases?  A: 1) corner case collection, 2) corner case generation, and 3) multi-modal reasoning		
[C14	ECCV 2024 W-CODA: 1st Workshop on Multimodal Perception and Comprehension of Corner Cases in Autonomous Driving	ECCV	2024
	<u>Kai Chen*</u> , Ruiyuan Gao*, Lanqing Hong*, Hang Xu, Xu Jia, Holger Caesar, Dengxin Dai, Bingbing Liu, Dzmitry Tsishkou, Songcen Xu, Chunjing Xu, Qiang Xu, Huchuan Lu, Dit-Yan	Yeung.	[ <u>link</u> ]
[C13	CODA-LM: Automated Evaluation of Large Vision-Language Models on Self-driving Corner Cases	WACV	2025
	Kai Chen*, Yanze Li*, Wenhua Zhang*, Yanxin Liu, Pengxiang Li, Ruiyuan Gao, Lanqing Hong, Meng Tian, Xinhai Zhao, Zhenguo Li, Dit-Yan Yeung, Huchuan Lu, Xu Jia.		[link]
[C12	CODA: A Real-World Road Corner Case Dataset for Object Detection in Autonomous Driving	ECCV	2022
	Kaican Li*, <b>Kai Chen*</b> , Haoyu Wang*, Lanqing Hong, Chaoqiang Ye, Jianhua Han, Yukuai Chen, Wei Zhang, Chunjing Xu, Dit-Yan Yeung, Xiaodan Liang, Zhenguo Li, Hang Xu		[ <u>link</u> ]
	V. Visual World Models - Geometric-controllable Visual Generation RQ: How to generate the 3D visual world in a controllable and scalable manner?		
[C11	MagicDrive3D: Controllable 3D Generation for Any-View Rendering in Street Scenes	Arxiv	2024
	Ruiyuan Gao, <u>Kai Chen</u> , Zhihao Li, Lanqing Hong, Zhenguo Li, Qiang Xu.		$[\underline{\mathrm{link}}]$
-	MagicDrive-V2: High-Resolution Long Video Generation for Autonomous Driving with Adaptive Control	ICCV	2025
	Ruiyuan Gao, <u>Kai Chen</u> , Bo Xiao, Lanqing Hong, Zhenguo Li, Qiang Xu.		$[\underline{\mathrm{link}}]$
[C9]	Implicit Concept Removal of Diffusion Models Zhili Liu*, <u>Kai Chen*</u> , Yifan Zhang, Jianhua Han, Lanqing Hong, Hang Xu, Zhenguo Li, Dit-Yan Yeung, James Kwok.	ECCV	<b>2024</b> [link]
[C8]	DetDiffusion: Synergizing Generative and Perceptive Models for Enhanced	CVPR	2024
	Data Generation and Perception Yibo Wang*, Ruiyuan Gao*, <u>Kai Chen*</u> , Kaiqiang Zhou, Yingjie Cai, Lanqing Hong, Zhenguo Li, Lihui Jiang, Dit-Yan Yeung, Qiang Xu, Kai Zhang.		[link]
[C7]	MagicDrive: Street View Generation with Diverse 3D Geometry Control Ruiyuan Gao*, <u>Kai Chen*</u> , Enze Xie, Lanqing Hong, Zhenguo Li, Dit-Yan Yeung, Qiang Xu.	ICLR	2024 [ <u>link</u> ]
[C6]	TrackDiffusion: Tracklet-Conditioned Video Generation via Diffusion Models Pengxiang Li*, <u>Kai Chen*</u> , Zhili Liu*, Ruiyuan Gao, Lanqing Hong, Dit-Yan Yeung, Huchuan Lu, Xu Jia.	WACV	<b>2025</b> [link]
[C5]	GeoDiffusion: Text-Prompted Geometric Control for Object Detection Data Generation	ICLR	
	<u>Kai Chen*</u> , Enze Xie*, Zhe Chen, Yibo Wang, Lanqing Hong, Zhenguo Li, Dit-Yan Yeung.		[ <u>link</u> ]
	VI. Representation Learning - Object-level Self-supervised Learning (SSL)  RQ: How to perform object-level SSL for better transferability on downstream dense perception	tasks?	
[C4]	Mixed Autoencoder for Self-supervised Visual Representation Learning Kai Chen*, Zhili Liu*, Lanqing Hong, Hang Xu, Zhenguo Li, Dit-Yan Yeung.	CVPR	$\frac{2023}{[\underline{link}]}$

[C3] MultiSiam: Self-supervised Multi-instance Siamese Representation Learning for Autonomous Driving <u>Kai Chen</u> , Lanqing Hong, Hang Xu, Zhenguo Li, Dit-Yan Yeung.	ICCV 2021 [link]
[C2] SODA10M: A Large-Scale 2D Self/Semi-Supervised Object Detection Dataset for Autonomous Driving Jianhua Han, Xiwen Liang, Hang Xu, <u>Kai Chen</u> , Lanqing Hong, Jiageng Mao, Chaoqiang Ye, Wei Zhang, Zhenguo Li, Xiaodan Liang, Chunjing Xu.	NeurIPS 2021 [ <u>link</u> ]
Early Works	
[J1] Automatic Dense Annotation for Monocular 3D Scene Understanding Md. Alimoor Reza, <u>Kai Chen</u> , Akshay Naik, David Crandall, Soon-Heung Jung.	EE Access 2020 [ <u>link</u> ]
[C1] Automatic Annotation for Semantic Segmentation in Indoor Scenes Md Alimoor Reza, Akshay Naik, <u>Kai Chen</u> , David Crandall.	$\begin{array}{c} \textbf{IROS 2019} \\ \underline{[\text{link}]} \end{array}$
ACADEMIC SERVICES	
Program Committee / Organizer	
<ul> <li>The 1st W-CODA Workshop at ECCV 2024 on Multimodal Perception and Comprehension Corner Cases in Autonomous Driving.</li> </ul>	n of 2024
• The 2nd SSLAD workshop at ECCV 2022.	2022
• The 1st SSLAD workshop at ICCV 2021 on Self-supervised Learning for Next-generation Industry-level Autonomous Driving.	2021
Area Chair	
• International Joint Conferences on Artificial Intelligence (IJCAI)	2025
Conference Reviewer	
• IEEE Conference on Computer Vision and Pattern Recognition (CVPR)	2022-2025
• IEEE International Conference on Computer Vision (ICCV)	2023 - 2025
• European Conference on Computer Vision (ECCV)	2022-2024
• International Conference on Learning Representations (ICLR)	2023-2026
• International Conference on Machine Learning (ICML)	2025
• Neural Information Processing Systems (NeurIPS)	2021-2025
• International Joint Conferences on Artificial Intelligence (IJCAI)	2023-2025
• AAAI Conference on Artificial Intelligence (AAAI)	2022
<ul> <li>International Conference on Robotics and Automation (ICRA)</li> <li>ACM International Conference on Multimedia (ACM MM)</li> </ul>	2022
<ul> <li>ACM International Conference on Multimedia (ACM MM)</li> <li>IEEE Winter Conference on Applications of Computer Vision (WACV)</li> </ul>	2025 $2026$
• Asian Conference on Computer Vision (ACCV)	2024
Journal Reviewer	
• IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)	
• IEEE Transactions on Circuits and Systems for Video Technology (TCSVT)	
• IEEE Transactions on Image Processing (TIP)	
• IEEE Access	

# **PATENTS**

• [CN116665219A] GeoDiffusion: Text-Prompted Geometric Control for Object Detection Data Generation. Enze Xie, <u>Kai Chen</u>, Lanqing Hong, Zhenguo Li. *Published in May 26th*, 2023.

• [CN115731530A] MultiSiam: Self-supervised Multi-instance Siamese Representation Learning for Autonomous Driving. Kai Chen, Lanqing Hong, Hang Xu, Zhenguo Li. Published in Aug. 24th, 2021.

## **TEACHING**

- HKUST COMP 4211 Machine Learning, Teaching Assistant, Fall 2025.
- HKUST COMP 2012 Object-Oriented Programming and Data Structures, Teaching Assistant, Fall 2024.
- HKUST COMP 2012 Object-Oriented Programming and Data Structures, Teaching Assistant, Fall 2021.
- HKUST COMP 2012 Object-Oriented Programming and Data Structures, Teaching Assistant, Spring 2021.

#### INVITED TALKS

- [AI TIME Online] EMOVA: Empowering Language Models to See, Hear and Speak with Vivid Emotions. [Recording]
- [VALSE Webinar] Geometric-controllable Visual Generation: A Systemetric Solution. [Recording]
- [AIDriver Online] Controllable Corner Case Generation for Autonomous Driving.[Recording]
- [AI TIME Online] Gaining Wisdom from Setbacks: Aligning Large Language Models via Mistake Analysis. [Recording]
- [TechBeat Online] Gaining Wisdom from Setbacks: Aligning Large Language Models via Mistake Analysis. [Recording]
- [VALSE 2023@Wuxi] Mixed Autoencoder for Self-supervised Visual Representation Learning. [Recording]
- [VALSE 2023@Wuxi] CODA: A Real-World Road Corner Case Dataset for Object Detection in Autonomous Driving. [Recording]

#### TECHNICAL SKILLS

 $\label{eq:program} \textbf{Parguages} \qquad \text{ Python, Matlab, C/C++/C\#, SQL, } \\ \underline{\texttt{LMT}}\underline{\texttt{E}}\underline{\texttt{X}}$ 

Framework Pytorch, Tensorflow

Language Native in Mandarin, Fluent in English and Japanese

CET-4(649), CET-6(619), TOEFL-iBT(101)