Machine Learning - HW3

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All the questions that are not answered in this file can be found in related Jupyter Notebook

1 Statistical Learning: Hoeffding's Inequality

1.1 a

Proof. By Markov's inequality,

$$\Pr\left(X \ge \mu_X + t\right) = \Pr\left(X - \mu_X \ge t\right) \le \mathbb{E}\left[e^{\lambda(X - \mu_X)}\right] e^{-\lambda t} \tag{1}$$

This inequality is true for each $\lambda > 0$, therefore,

$$\Pr\left(X \ge \mu_X + t\right) \le \min_{\lambda \ge 0} \mathbb{E}\left[e^{\lambda(X - \mu_X)}\right] e^{-\lambda t} = \min_{\lambda \ge 0} M_{X - \mu_X}(\lambda) e^{-\lambda t} \tag{2}$$

1.2 b

$$\mathbb{P}\left(\frac{1}{n}\sum_{i=1}^{n}\left(X_{i}-\mu_{X_{i}}\right)\geq t\right) = \mathbb{P}\left(\sum_{i=1}^{n}\left(X_{i}-\mu_{X_{i}}\right)\geq nt\right)$$
By Chernoff bound, $\leq \mathbb{E}\left[\exp\left(\lambda\sum_{i=1}^{n}\left(X_{i}-\mu_{X_{i}}\right)\right)\right]e^{-\lambda nt}$

$$=\left(\prod_{i=1}^{n}\mathbb{E}\left[e^{\lambda\left(X_{i}-\mu_{X_{i}}\right)}\right]\right)e^{-\lambda nt}$$
By Hoeffding's Lemma, $\leq \left(\prod_{i=1}^{n}e^{\frac{\lambda^{2}(b-a)^{2}}{8}}\right)e^{-\lambda nt}$

Note that, the Chernoff bound is true for each $\lambda > 0$, therefore,

$$\mathbb{P}\left(\frac{1}{n}\sum_{i=1}^{n}\left(X_{i}-\mu_{X_{i}}\right)\geq t\right)=\min_{\lambda\geq0}\exp\left(\frac{n\lambda^{2}(b-a)^{2}}{8}-\lambda nt\right)=\exp\left(-\frac{2nt^{2}}{(b-a)^{2}}\right)\tag{4}$$

1.3 c

Consider a simple case with n = 1. Let X has a distribution as follow:

$$\mathbb{P}(X = -0.001) = 1 - 10^{-3}
\mathbb{P}(X = 10^{3}) = 10^{-3}$$
(5)

Let t = 1, then the LHS is,

$$\mathbb{P}\left(\frac{1}{n}\sum_{i=1}^{n}(X_{i}-\mu_{X_{i}})\geq t\right) = \mathbb{P}\left((X-\mu_{X})\geq 1\right) = 10^{-3}$$
(6)

The RHS is,

$$\exp\left(-\frac{2nt^2}{(b-a)^2}\right) = 0.99998\tag{7}$$

We can see that the information provide by this inequality is very limited.

2 SVM and the power of kernels

2.1 a

By the Representer Theorem, the solution to the SVM problem,

$$f^* \in \operatorname{argmin}_{f \in H_k} \sum_{i=1}^n \ell(f(x_i), y_i) + \Omega(\|f\|_{H_k}^2)$$
(8)

can all be expressed in the form

$$f^* = \sum_{i=1}^{n} \alpha_i k\left(x_i, \cdot\right) \tag{9}$$

It suffice to show that

$$f^*(x_i) = y_i \tag{10}$$

for each i.

We can show that

$$f^*(x_i) = \sum_{k=1}^n \alpha_k k(x_k, x_i) = e_i^T K \alpha$$
(11)

where e_i is the *i* th standard basis vector. Write all *i* in metric form.

$$K\alpha = y \tag{12}$$

Suppose K is inevitable (for example, symmetric and strictly positive definite), set $\alpha = K^{-1}y$, we have $f^*(x_i) = y_i$ as desired.

2.2 b

Since this is a separable SVM, the decision boundary must be right at the middle of a and b:

$$x_d = \frac{a+b}{2} \tag{13}$$

The relation of λ and x_d is given by

$$\lambda x_d + \lambda_0 = 0 \tag{14}$$

WLOG, suppose a is a support vector. Then

$$\lambda a + \lambda_0 = 1 \tag{15}$$

We have 3 unknown variables and 3 equations. Therefore, solve for λ :

$$\lambda = \frac{2}{a - b} \tag{16}$$

Thus,

$$f(x) = \frac{2x}{a-b} - \frac{a+b}{a-b} \tag{17}$$

The dual problem constrain

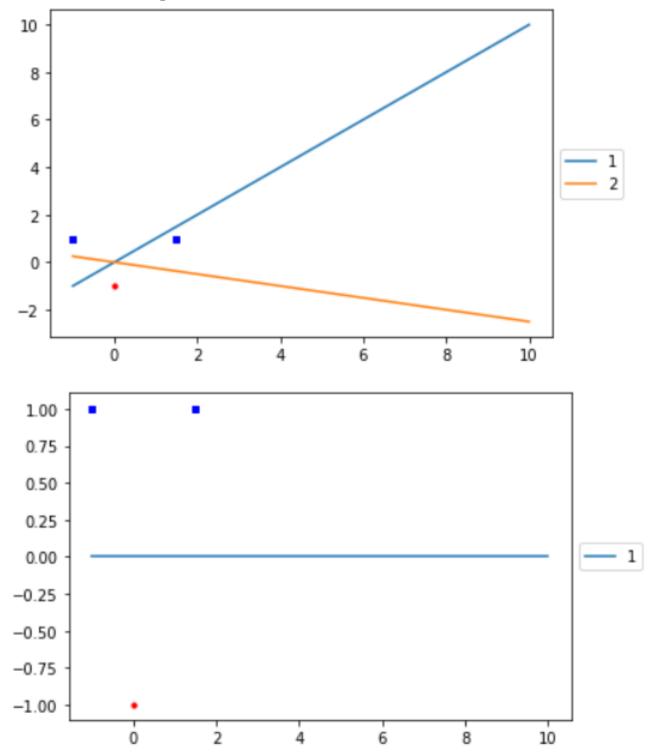
$$\alpha_a + \sum_{i \neq a} \alpha_i y_i = 0 \tag{18}$$

where $\alpha_a > 0$ suggests that $\sum_{i \neq a} \alpha_i y_i < 0$. Therefore, there must be at least one more support vector in the summation.

3 Perceptron: Theoretical

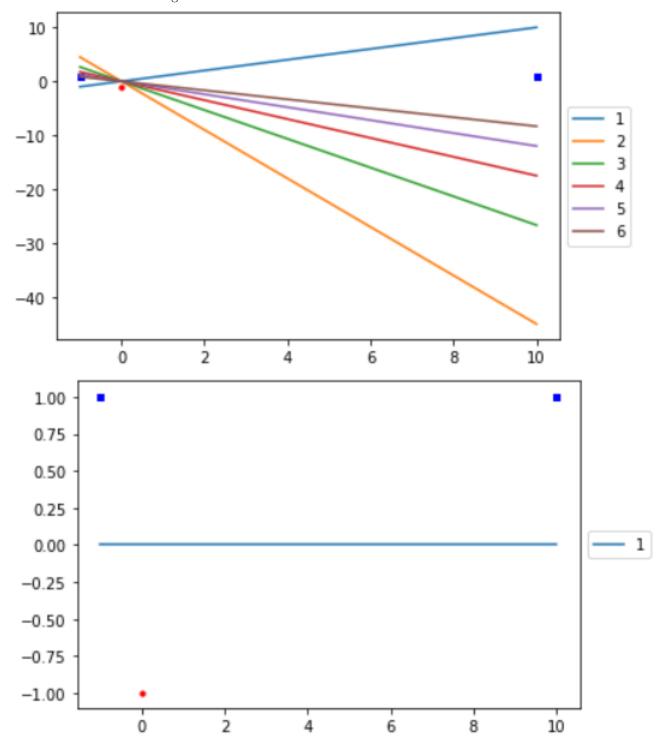
3.1 a

If the algorithm starts with point x_1 , it takes 2 mistakes until convergence. We can see the boundary in the first figure below. If the algorithm stats with point x_2 , it only takes 1 mistake until convergence. We can see the boundaries in the second figure below.



3.2 b

If the algorithm starts with point x_1 , it takes 6 mistakes until convergence. We can see the boundary in the first figure below. If the algorithm starts with point x_2 , it only takes 1 mistake until convergence. We can see the boundaries in the second figure below.



3.3 c

Firstly, we choose the first data point which can maximize the number of misclassified data points. Second;y, choose the closest misclassified data point to the boundary. This procedure makes sure that this new mistake (if it is a mistake) only provide very limited information, i.e., the boundary only moves a tiny bit after this update. Repeat the second step until we go over all data points.