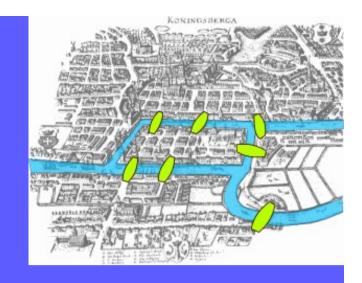
# Algorithms

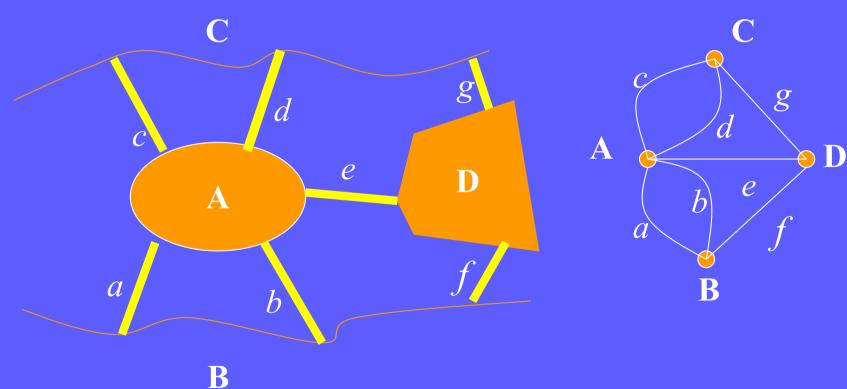
Graph-1

#### Introduction

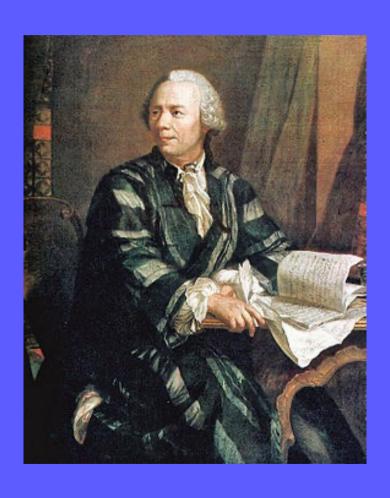
# Graph Theory

■ 1736, Euler's Koenigsberg bridge problem





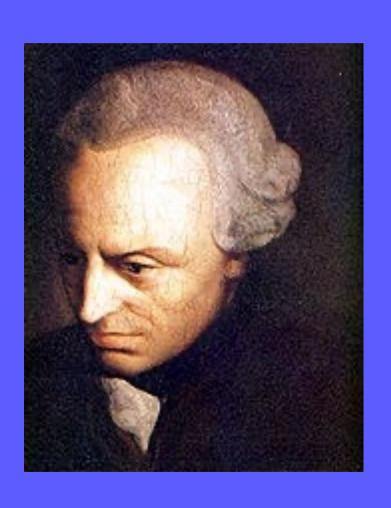
#### Leonhard Euler



Read Euler, read Euler, he is the master of us all

He ceased to calculate and to live

#### Immanuel Kant



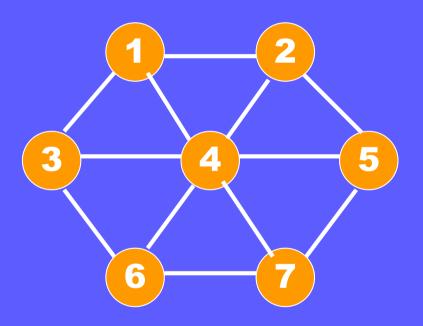
Two things fill the mind with ever new and increasing admiration and awe, the more often and steadily we reflect upon them:

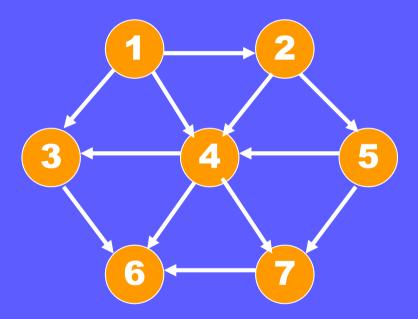
The starry heavens above me and the moral law within me.

# Terminology of Graph

- Graph: G=(V, E), V: a set of vertices, E: a set of edges
- Edge (arc): a pair (v,w), where v,  $w \in V$
- Adjacent: w is adjacent to v if  $(v, w) \in E$
- Directed graph (Digraph): graph if pairs are ordered (directed edge)
- Undirected graph: if  $(v,w) \in E$ , (v,w)=(w,v)

#### Undirected vs. Directed

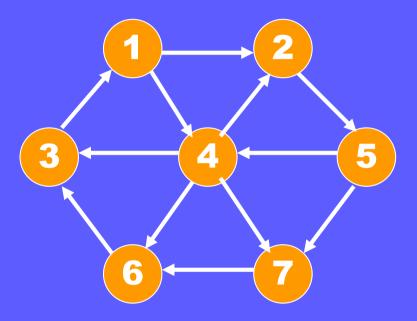




### Terminology of Graph (Cont.)

- Path: a sequence of vertices  $w_1, w_2, w_3, ..., w_N$  where  $(w_i, w_{i+1}) \in E, \forall 1 \le i \le N$ .
- Length of a path: number of edges on the path.
- **Loop:** an edge (v, v) from vertex to itself
- Simple path: a path where all vertices are distinct except the first and last.
- □ Cycle in a directed graph: a path such that  $w_1 = w_N$
- Acyclic graph (DAG): a directed graph which has no cycles.

### Simple Path



 $1 \rightarrow 4 \rightarrow 3 \rightarrow 1$ : simple path

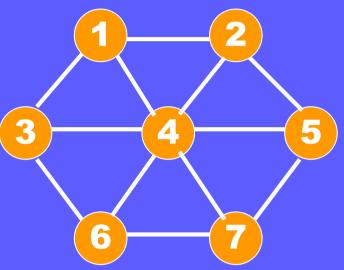
 $1 \rightarrow 4 \rightarrow 2 \rightarrow 5 \rightarrow 4 \rightarrow 3 \rightarrow 1$ : Non-simple path

### Terminology of Graph (Cont.)

- Connected: an undirected graph if there is a path from every vertex to every vertex.
- Strongly connected: a directed graph if there is a path from every vertex to every vertex.
- Weakly connected: a directed graph which is not strongly connected, but the underlying graph is connected.
- Complete graph: a graph in which there is an edge between every pair of vertices.

## Connected Graph

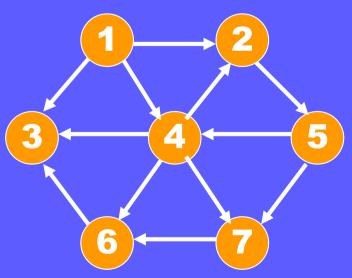
connected



strongly connected

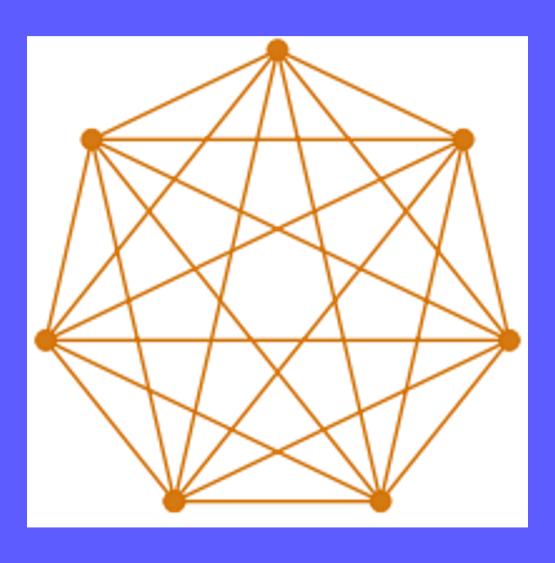
3 4 5

weakly connected



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# Complete Graph

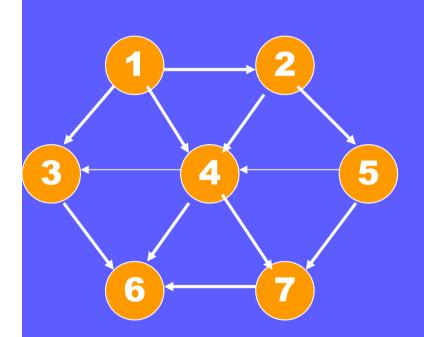


(ref: https://en.wikipedia.org/wiki/Complete\_graph)

### Representation of Graphs

- Data structures for representation of graphs
  - □ adjacency matrix representation
  - □ adjacency list representation

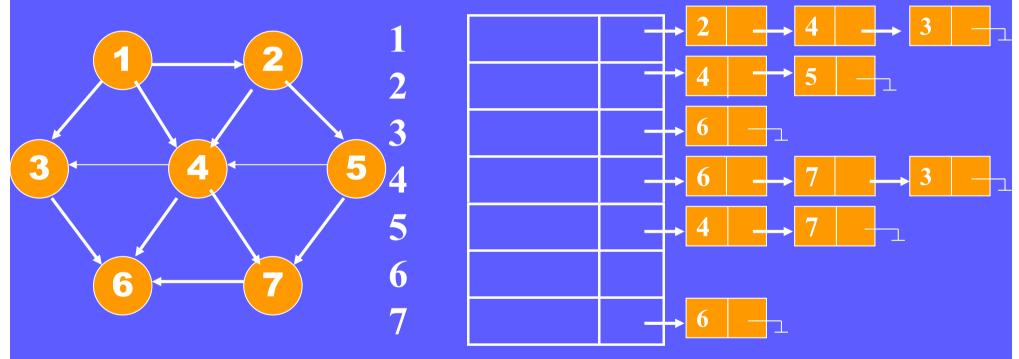
## Adjacency Matrix Representation



	1	2	3	4	5	6	7
1	0	1	1	1	0	0	0
2	0	0	0	1	1	0	0
3	0	0	0	0	0	1	0
4	0	0	1	0	0	1	1
5	0	0	0	1	0	0	1
6	0	0	0	0	0	0	0
7	0	0	0	0	0	1	0

- Space:  $\Theta(|V|^2)$ , good for dense, not for sparse
- \* Undirected graph: symmetric matrix

## Adjacency List Representation



Space: O(|V|+|E|) good for sparse

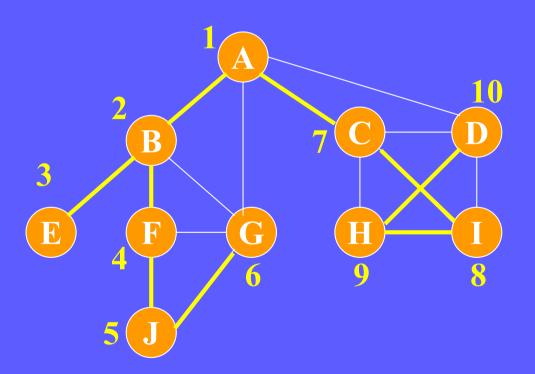
# Graph Traversal

(pp. 189~199)

## Graph Traversal

- **■** Traverse: visiting the vertices in graph
- **■** Traversal algorithms
  - □ Depth-First Search (DFS): 先深後廣
  - □ Breadth-First Search (BFS): 先廣後深

# Depth-First Search



#### Depth-First Search

```
Algorithm DFS(G,v);

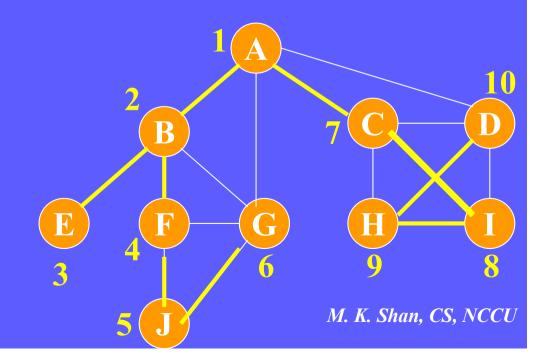
Begin

mark v;

for all edges (v,w) do

if w is unmarked then DFS(w)

End
```



#### Lemma 7.1

- If G is connected
  Then
  - (1) all its vertices will be marked by algorithm DFS
  - (2) all its edges will be looked at least once during the execution of algorithm DFS

## Generalized Depth-First Search

```
Algorithm DFS(G,v);
Begin
   mark v;
   prework(v)
  for all edges (v,w) do
     if w is unmarked then DFS(w)
     postwork(v,w)
End
                                      B
 prework: mark time
 postwork
                                            G
 (1) backtrack
 (2) w is a marked vertex
                                                M. K. Shan, CS, NCCU
```

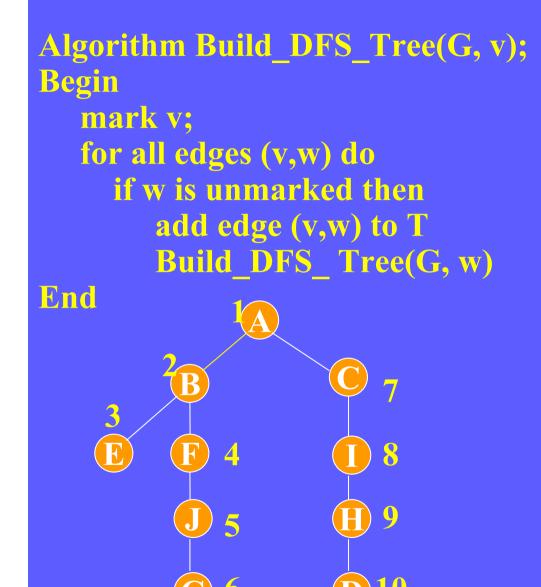
## Finding Connected Components

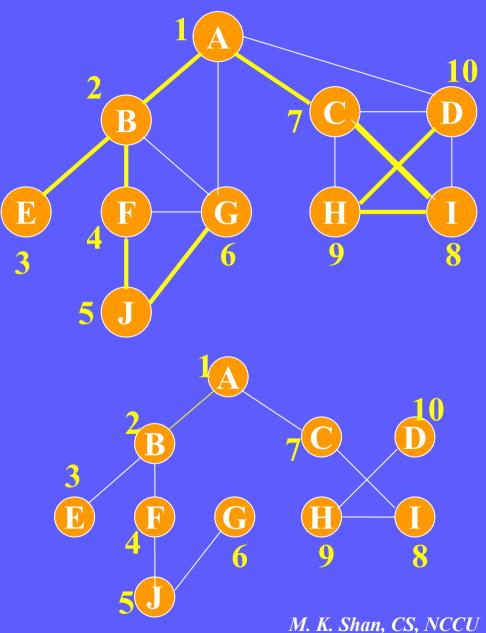
```
Algorithm Connected Components (G)
Input: G(=(V,E)
Output: assignment of component number
Begin
  component no:=1;
  while there is an unmarked vertex v do
     DFS(G, v); {prework v.component:=component no}
     component no:=component no+1;
                                        Algorithm DFS(G,v);
End
                                        Begin
                                          mark v;
                                          v.component:=component no;
                                          for all edges (v,w) do
                                            if w is unmarked then DFS(w)
                                        End
```

## DFS Numbering

```
Algorithm DFS Numbering (G, v)
Begin
  Initialize DFS Number := 1;
  DFS(G, v)
End
Algorithm DFS(G,v);
Begin
  mark v;
  v.DFS := DFS Number;
  DFS Number := DFS Number + 1;
  for all edges (v,w) do
    if w is unmarked then DFS(w)
    postwork(v,w)
End
```

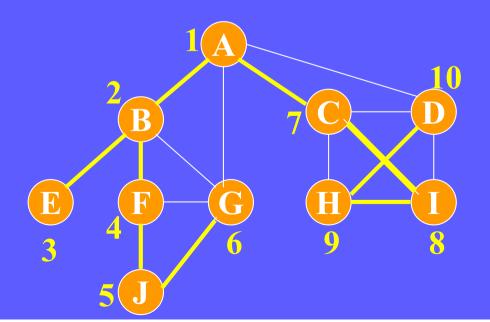
#### Build DFS Tree





#### Lemma 7.2 (for Undirected DFS Trees)

Let G = (V, E) a connected <u>undirected</u> graph T = (V, F) a DFS tree of G then every edge  $e \in E$  either belongs to T (yellow edges) or connects two vertices of G, one of which is the ancestor of the other in T. (white edges)



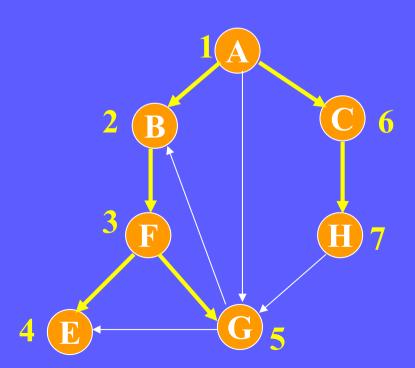
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#### Lemma 7.3 (for directed DFS Trees)

Let G = (V, E) a <u>directed</u> graph

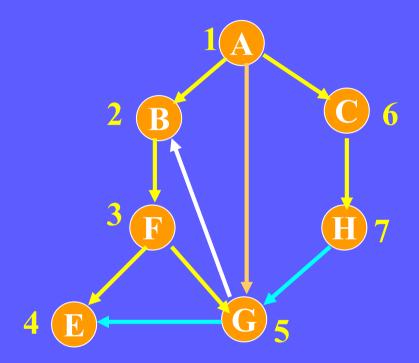
T = (V, F) a DFS tree of G

If (v, w) ∈ E and v.DFS\_Number < w.DFS\_Number,
then v is the ancestor of w in the tree T



### Four Types of Edges

- **■** tree edges
- back edges
- **■** forward edges
- **cross edges**



- \* In undirected DFS trees, there exists no cross edges
- \* In directed DFS trees, cross edge must cross from right to left)

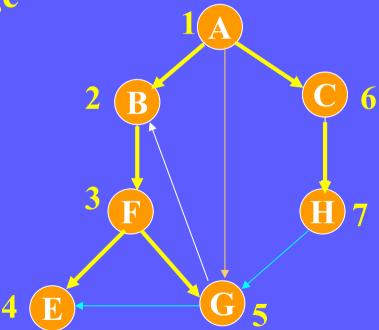
#### Lemma 7.4

Let G = (V, E) be a directed graph

T be a DFS tree of G

Then G contains a directed cycle

iff G contains a back edge



## Find\_a\_Cycle

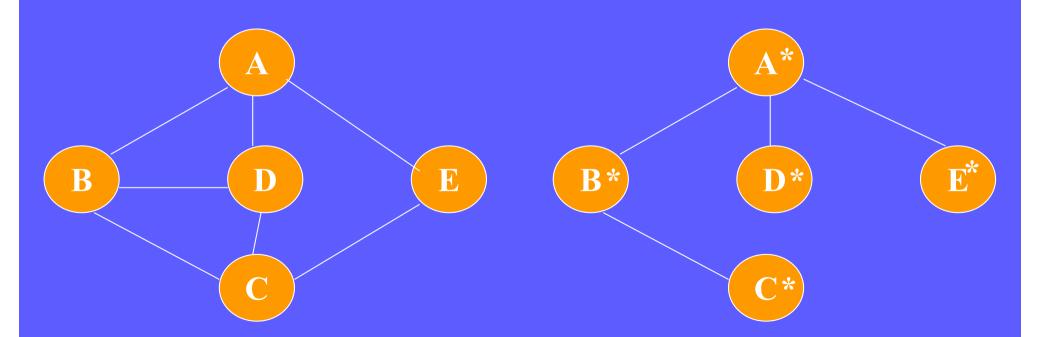
```
Algorithm Find a Cycle(G, v)
Begin
  for each vertex v
     v.on the path:=false
  DFS(G, v)
End
Algorithm DFS(G,v);
Begin
  mark v;
  v.on_the_path:=true;
  for all edges (v,w) do
     if w is unmarked then DFS(w)
     if w.on the path then Find a Cycle:=true; halt;
  v.on_the_path:=false;
```

End

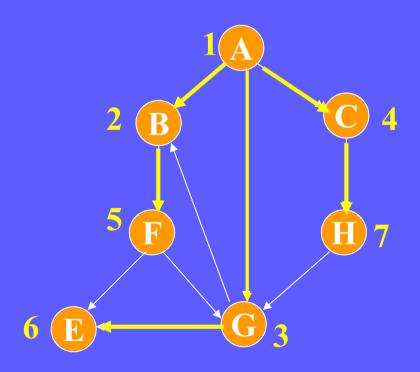
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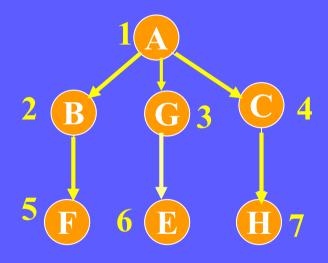
#### Breadth First Search

- Breadth First search (BFS): level order tree traversal
- BFS algorithm: using queue



#### Breadth-First Search





### Algorithm of BFS

```
Algorithm BFS
Begin
  mark v;
  put v in queue;
  while queue is not empty do
     remove the first vertex w from queue;
     prework on w;
     for all edges (w,x) such that x is unmarked do
         mark x;
         add (w,x) to the tree T;
         put x in queue;
```

End

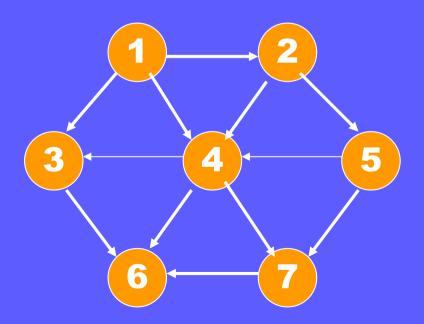
# Topological Sorting

(pp. 199~201)

# Topological Sorting

■ Topological sorting:

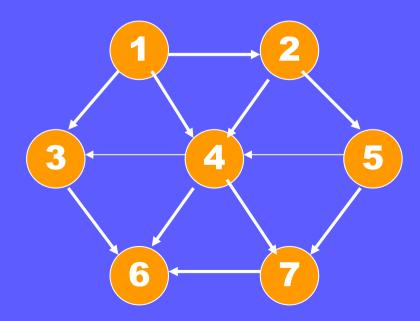
ordering of vertices in a DAG such that
if there is a path from  $v_i$  to  $v_j$ ,
then  $v_i$  appears after  $v_i$  in the ordering.



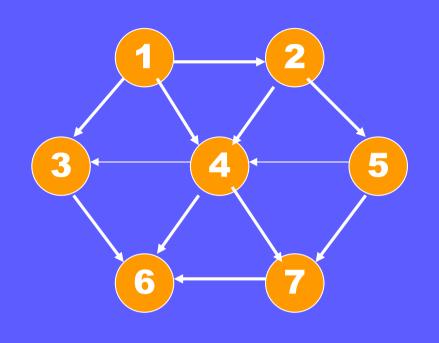
1, 2, 5, 4, 3, 7, 6

# Topological Sorting

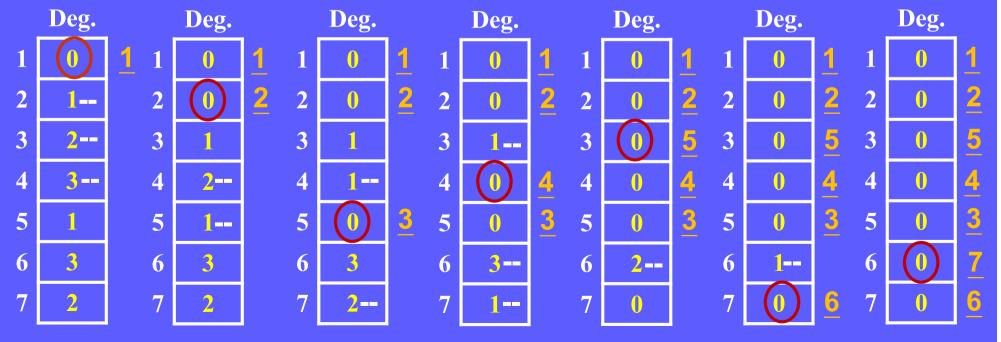
- If there is a path from  $v_i$  to  $v_j$ , then  $v_j$  appears after  $v_i$  in the ordering.
- Prerequisite of Courses
  - $\square$  2: {1}, 3: {1, 4}, 4:{1, 2, 5}, 5:{2}, 6:{3, 4, 7}, 7:{4, 5}
  - ☐ Ordering of course taking



1, 2, 5, 4, 3, 7, 6

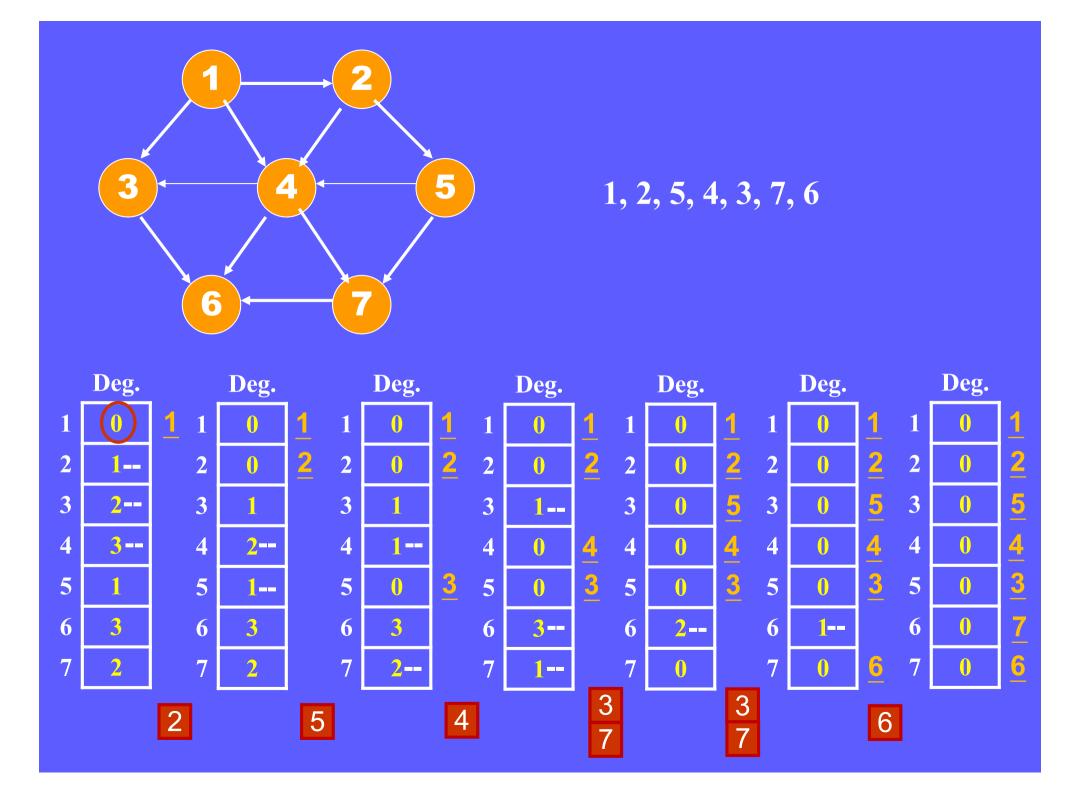


1, 2, 5, 4, 3, 7, 6



# Algorithm for Topological Sorting

```
/* O(|V|^2) */
Void Topsort(Graph G)
 int Counter;
 vertex V,W;
 for (Counter=0; Counter < NumVertex; Counter++)
     V=FindNewVertexOfDegreeZero();
    TopNum[V]=Counter;
    For each W adjacent to V
      Indegree [W]--;
```



#### Improved Algorithm for Topological Sorting

```
void Topsort(Graph G); /* O(|E|+|V|) */
  queue Q;
   int Counter=0;
   vertex V,W;
   Q=CreateQueue(NumVertex); MakeEmpty(Q);
   for each vertex V
      if (Indegree[V] == 0)
          Enqueue(V,Q);
   While (!IsEmpty(Q)) {
       V=Dequeue(Q);
        TopNum[V] = ++Counter;
       for each W adjacent to V
          if (--Indegree[W] == 0)
             Enqueue(W,Q);
   if (Counter != NumVertex)
     Error("Cycle!");
   DisposeQueue(Q);
                                                     M. K. Shan, CS, NCCU
```