

0 Intw & Electric Fields

- $q = \pm Ne$ (quantization of electric charges, elementary charge $e = 1.6 \times 10^{-19} \text{ C}$) permittivity of free space $= 8.854 \times 10^{-12} \text{ (F/m)}$

- $|\vec{F}| = \frac{k|q_1||q_2|}{r^2}$ (Coulomb's Law, $k \epsilon_0 = \frac{1}{4\pi}$)

$$\text{unit} = \frac{\text{N}}{\text{C}} = \frac{\text{V}}{\text{m}}$$

- $\vec{E} = \frac{\vec{F}_E}{q_0} = k_e \frac{q}{r^2} \hat{r} \xrightarrow{\text{continuous charge distribution}} k_e \int \frac{dq}{r^2} \hat{r}$

1 Gauss's Law

- charge densities:

rho ρ (volume) = Q/V $dq = \rho dV$

sigma σ (surface) = Q/A $\xrightarrow[\text{distributed charge}]{\text{non-uniformly}}$ $dq = \sigma dA$

λ (linear) = Q/l $dq = \lambda dl$

• Electric Flux

* $\Phi_E = EA_{\perp} = \vec{E} \cdot \vec{A}$

* general case:

$$\Phi_E \approx \sum \vec{E}_i \cdot \Delta \vec{A}_i = \int_{\text{surface}} \vec{E} \cdot d\vec{A}$$

* through any close surface

$$\Phi_E = \oint \vec{E} \cdot d\vec{A} = \int E_n dA$$

- Gauss's Law: $\Phi_E = \oint \vec{E} \cdot d\vec{A} = \frac{q_{in}}{\epsilon_0}$

[2] Electric Potential

- work done within a charge-field system by the electric field on the charge $W = \vec{F} \cdot d\vec{s} = q \vec{E} \cdot d\vec{s}$

- electric potential energy: $\Delta U = -W = -q \int_A^B \vec{E} \cdot d\vec{s}$
 \rightarrow electrostatic force F_E is conservative $V = \frac{kq}{r}$

- electric potential difference $\Delta V = \frac{\Delta U}{q} = - \int_A^B \vec{E} \cdot d\vec{s}$

(potential energy per unit charge)

$$\Rightarrow W = -\Delta U = -q \Delta V$$

$$U = \frac{kq_1 q_2}{r} \quad V_{\infty} = 0$$

- electron - volt (energy unit)

$$1\text{eV} = 1.6 \times 10^{-19} \text{ C} \cdot \text{V} = 1.6 \times 10^{-19} \text{ J}$$

- $V \rightarrow E$

$$E_x = -\frac{dV}{dx}, \quad E_y = -\frac{dV}{dy}, \quad E_z = -\frac{dV}{dz} \quad / \quad \vec{E}_r = -\frac{dV}{dr}$$

- continuous charge distribution

* if charge distribution is known:

$$dV = k_e \frac{dq}{r}$$

$$V = k_e \int \frac{dq}{r}$$

* if electric field is known:

$$\Delta V = -\int_A^B \vec{E} \cdot d\vec{s}$$

sum \rightarrow integral

- conductor in electrostatic equilibrium: V is the same anywhere inside the conductor (including the surface)
 1. $E_{\text{inside}} = 0 \Rightarrow \phi_E = 0 \Rightarrow q_{\text{inside}} = 0$
 2. Charge resides on its surface
 3. The electric field at a point just outside a charged conductor is perpendicular to the surface and $|\vec{E}| \approx \sigma / \epsilon_0$
 4. For irregularly-shaped conductor, σ is greatest where radius is of the smallest curvature

[3] Capacitance & Dielectrics

• $C = \frac{Q}{\Delta V}$ (2 conductors: charges of equal magnitude but opposite directions)

$$= \frac{\epsilon_0 A}{d} \quad (\text{parallel plate capacitor})$$

• equivalent capacitance

① in series: $\frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{C_2}$

② in parallel: $C_{eq} = C_1 + C_2$

• Energy stored in a capacitor:

$$U_E = \frac{Q^2}{2C} = \frac{QV}{2} = \frac{CV^2}{2}$$

* for a parallel-plate capacitor:

$$U_E = \frac{\epsilon_0 A d E^2}{2}$$

energy density

$$u_E = \frac{\epsilon_0 E^2}{2} = \frac{U_E}{Ad}$$

$$\frac{CV^2}{2}, \quad C = \frac{\epsilon_0 A}{d}, \quad V = Ed$$

- capacitors with dielectrics:
parallel-plate capacitor

$$C = \underset{\text{dielectric constant}}{K} C_0 = \frac{K \epsilon_0 A}{d}$$

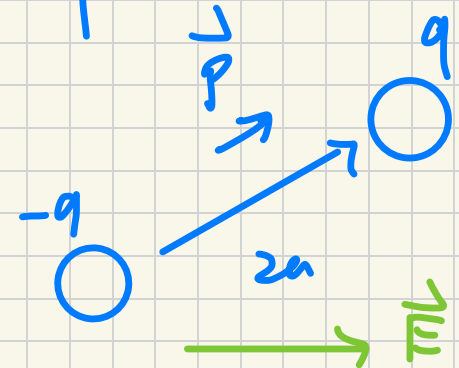
- Electric Dipole in Electric Field

* electric dipole moment \vec{p} { magnitude: $2aq$
direction: $-q \rightarrow +q$

* net force $F = 0$

* net torque $\vec{\tau} = \vec{p} \times \vec{E}$

* potential energy $U_E = -\vec{p} \cdot \vec{E}$



$$\vec{E} = \vec{E}_0 - \vec{E}_{ind}, \quad \vec{E} = \frac{\vec{E}_0}{K}$$

$$\vec{E}_{ind} = \frac{K-1}{K} \vec{E}_0, \quad \sigma_{ind} = \frac{K-1}{K} \sigma \quad (\text{Dielectrics})$$

4 Current & Resistance

$$\cdot I_{ave} = \frac{\Delta Q}{\Delta t} = \frac{(n A \Delta x) q}{\Delta t} = n q A v_d$$

drift velocity

$$\cdot \underset{\text{Current density}}{J} = \frac{I}{A} = n q v_d \quad \frac{\text{ohmic}}{\text{materials}} \quad \underset{\text{conductivity}}{\sigma} = \frac{E}{\underset{\text{resistivity}}{\rho}}$$

$$\cdot \Delta V = E l = \frac{l J}{\sigma} = \left(\frac{l}{\sigma A} \right) I = R I$$

$$R = \frac{V}{I} = \rho \frac{l}{A}$$

• Drude Model for Conduction

$$* \vec{V}_f = \vec{V}_i + \frac{q\vec{E}}{m} \tau$$

$$* \vec{V}_{f, \text{avg}} = \vec{V}_d = \frac{q\vec{E}}{m_e} \tau$$

average time interval b/w successive collisions

$$* I_{\text{avg}} = nq \left(\frac{qE}{m_e} \tau \right) A = \frac{nq^2 E}{m_e} \tau A$$

$$* J = nq v_d = \frac{nq^2 E}{m_e} \tau$$

$$* \text{resistivity } \rho = \frac{m_e}{nq^2 \tau}$$

Note : $\tau = l_{\text{avg}} / v_{\text{avg}}$

Drude model fails to predict the temperature dependence of resistivity $J = \frac{E}{\rho}$

temperature coefficient of resistivity

• resistivity & temperature : $\rho = \rho_0 [1 + \alpha (T - T_0)]$

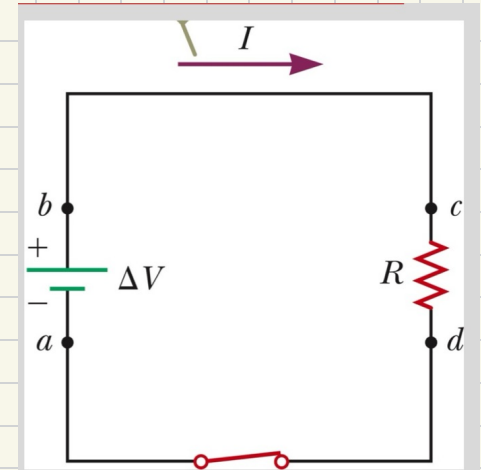
- rate of energy delivered to a resistor

(can be used generally)

$$\frac{dU_E}{dt} = \frac{d}{dt} (Q \Delta V) = \frac{dQ}{dt} \Delta V = I \Delta V$$

$$P = I \Delta V = I^2 R = \frac{(\Delta V)^2}{R}$$

(can be used on a resistor)



Note: transmit electricity by power companies usually have High voltages and low currents to minimize power losses

5 DC Circuits

- Kirchhoff's Rules

1. junction rule : $\sum_{\text{junction}} I = 0$

2. loop rule : $\sum_{\text{loop}} \Delta V = 0$

- Combination of Resistors

1. in series: $R_{eq} = R_1 + R_2$

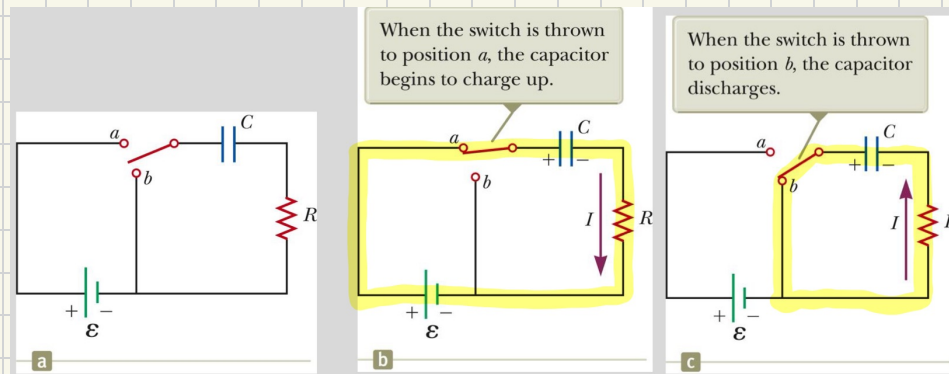
2. in parallel: $\frac{1}{R_{eq}} = \frac{1}{R_1} + \frac{1}{R_2}$

- RC Circuits

(i) set up equations:

* charging: $\mathcal{E} = V_C(t) + IR = V_C(t) + C \frac{dV_C(t)}{dt} R$

* discharging: $0 = V_C(t) - IR = V_C(t) - C \frac{dV_C(t)}{dt} R$



(4) result

$RC = \tau$ (time constant)

* charging:

$$q(t) = C\varepsilon (1 - e^{-t/RC}) = Q_{\max} (1 - e^{-t/RC})$$

$$V_c(t) = \varepsilon (1 - e^{-t/RC})$$

$$i(t) = \frac{\varepsilon}{R} e^{-t/RC}$$

* discharging:

$$q(t) = C\varepsilon e^{-t/RC} = C\varepsilon e^{-t/RC}$$

$$V_c(t) = \varepsilon e^{-t/RC}$$

$$i(t) = -\frac{Q_i}{RC} e^{-t/RC}$$

6 Magnetic Fields

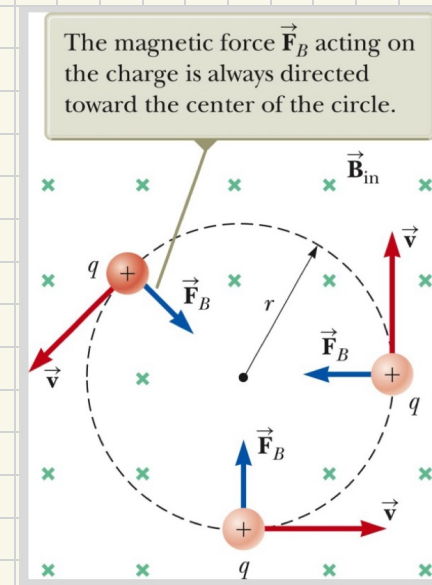
- magnetic flux $\Phi_B = \vec{B} \cdot \vec{A}$

- magnetic force $\vec{F}_B = q \vec{v} \times \vec{B}$

- $F_B = q v B = \frac{mv^2}{r} = F_c$

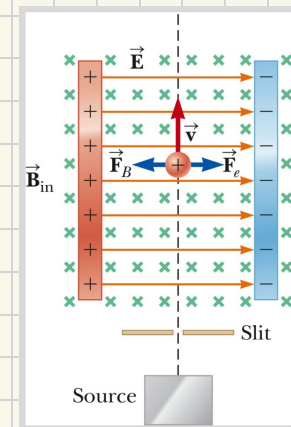
$\Rightarrow r = \frac{mv}{qB}$ radius of curvature

- angular velocity $\omega = \frac{v}{r} = \frac{qB}{m}$



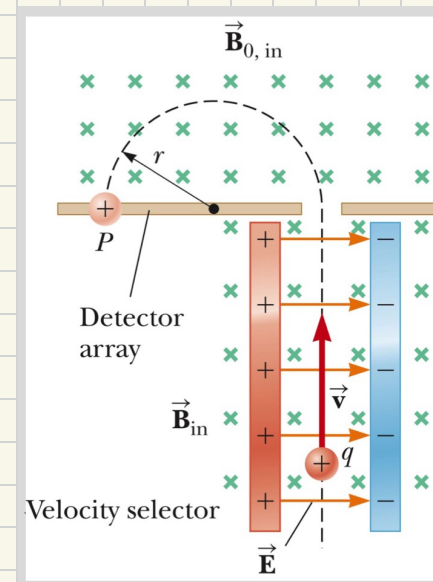
- Lorentz Force $\vec{F} = q (\vec{E} + \vec{v} \times \vec{B})$

- velocity selector: $qE = qvB \Rightarrow v = \frac{E}{B}$



- mass spectrometer :

$$r = \frac{mv}{qB_0} = \frac{mE}{qBB_0}$$



- Total Force of a Current-carrying Wire

$$F_B = (q \vec{v} \times \vec{B}) \cdot AL$$

$$= I \vec{L} \times \vec{B}$$

$$d\vec{F}_B = I d\vec{s} \times \vec{B}$$

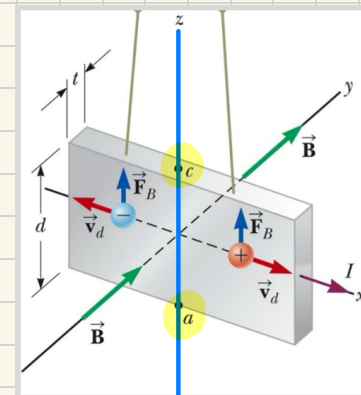
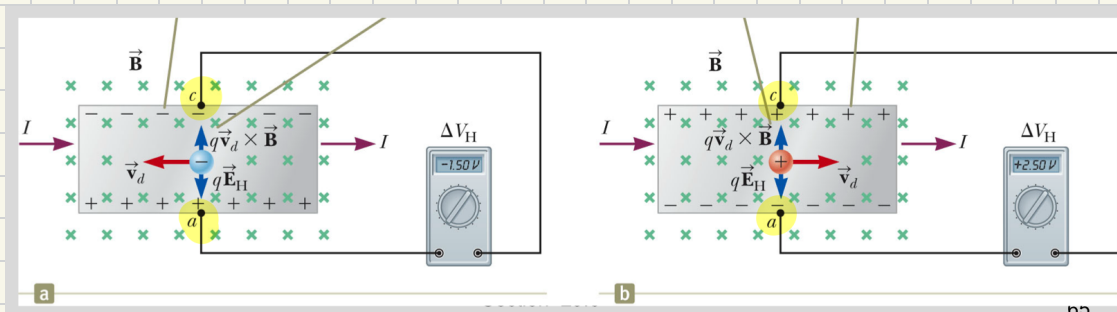
$$\vec{F}_B = I \int_A^B d\vec{s} \times \vec{B}$$

- Magnetic (Dipole) Moment: $\vec{\mu} = I \vec{A}$
- Torque on a Magnetic Dipole: $\vec{\tau} = \vec{\mu} \times \vec{B}$
- Magnetic Potential Energy: $U_B = - \vec{\mu} \cdot \vec{B}$

• Hall Effect

$$F_E = qE = qvB = F_B$$

$$\rightarrow \Delta V_H = E_H d = (v_d B) d = \frac{IB}{nqt}$$



[7] Source of Magnetic Fields

- Biot - Savart Law \rightarrow permeability of free space

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{s} \times \hat{r}}{r^2}$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{s} \times \hat{r}}{r^2}$$

- Ampere's Law

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I$$

magnetic flux

$$\Phi_B = \oint \vec{B} \cdot d\vec{A}$$

$$\text{unit} = \text{T} \cdot \text{m}^2$$

= Weber

• Gauss's Law in Magnetism: $\oint \vec{B} \cdot d\vec{A} = 0$

• $I = \frac{e}{T} = \frac{ev}{2\pi r}$

magnetic moment $\mu = \left(\frac{e}{2m_e} \right) L$

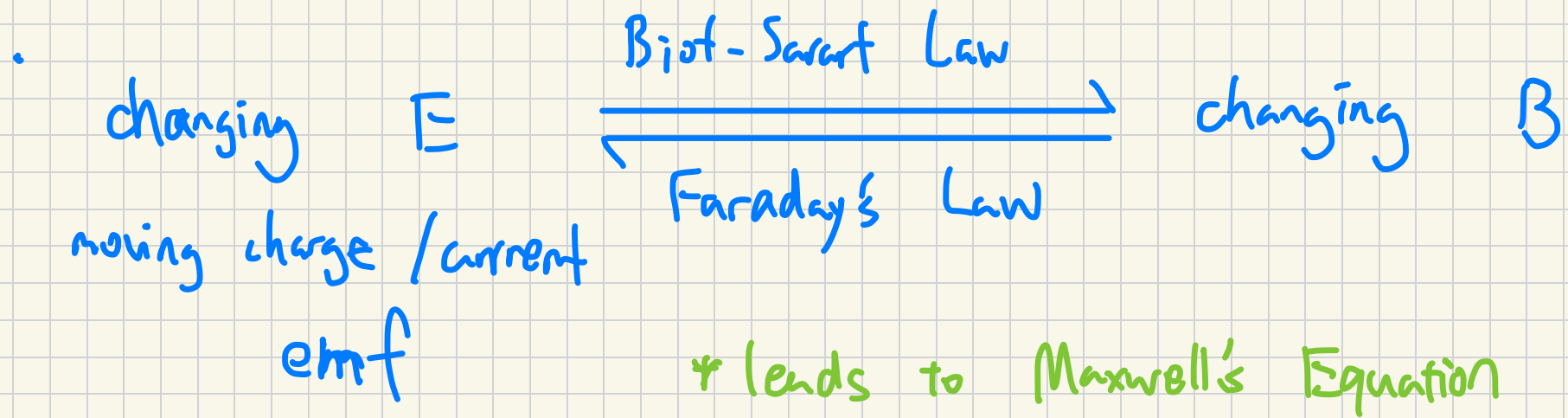
spin $S = \frac{\sqrt{3}}{2} \hbar$ (\hbar : Planck's constant)

$\mu_{\text{spin}} = \frac{e\hbar}{2m_e} = \mu_B$ (Bohr magneton)

quantization of
angular momentum

$\Rightarrow ?$

18 Faraday's Law



- Faraday's Law of Induction \rightarrow used in a closed loop setting

$$\mathcal{E} = - \frac{d\Phi_B}{dt}$$

Lenz's law

• General Form $E = - \frac{r}{2} \frac{dB}{dt}$

$$\mathcal{E} = \oint E \cdot d\vec{S} = - \frac{d\Phi_B}{dt}$$

• magnetic flux $\Phi_B = \int \vec{B} \cdot d\vec{A}$

9 Inductance

	i, V	P	W	AC	DC	series	parallel
C	$i = C \frac{dV}{dt}$	$CV \frac{dV}{dt}$	$\frac{CV^2}{2}$	i	open circuit	$\frac{C_1 C_2}{C_1 + C_2}$	$C_1 + C_2$
L	$V = L \frac{di}{dt}$	$Li \frac{di}{dt}$	$\frac{Li^2}{2}$	V	short circuit	$L_1 + L_2$	$\frac{L_1 L_2}{L_1 + L_2}$

$$\cdot L = \frac{\Phi_B}{i} \Rightarrow \mathcal{E}_L = \frac{-d\Phi_B}{dt} = -L \frac{di}{dt}$$

unit: Henries (H)

• RL Circuit :

(1) charging : $i = \frac{\mathcal{E}}{R} (1 - e^{-\frac{t}{\tau}})$

(2) discharging : $i = \frac{\mathcal{E}}{R} e^{-\frac{t}{\tau}}$

time constant $\tau = \frac{L}{R}$

Comparison:

$\nearrow U_c = \frac{Q^2}{2C} = \frac{QV}{2} = \frac{CV^2}{2}$

• Energy in a Magnetic Field, $U_B = \frac{1}{2} Li^2$

• Mutual Inductance $M = \frac{N_2 \phi_{12}}{i_1} = \frac{N_1 \phi_{21}}{i_2}$

• $\mathcal{E}_1 = -M \frac{di_2}{dt}$, $\mathcal{E}_2 = -M \frac{di_1}{dt}$

• Time Functions of a LC Circuit

• $q = Q_{\max} \cos(\omega t + \phi)$ charge on the capacitor

• $i = \frac{dq}{dt} = -\omega Q_{\max} \sin(\omega t + \phi)$
 \searrow I_{\max}

• $U = U_E + U_B = \frac{Q_{\max}^2}{2C} \cos^2 \omega t + \frac{L I_{\max}^2}{2} \sin^2 \omega t$
 \searrow total energy

• $\frac{q}{C} = -L \frac{di}{dt} = -L \frac{d^2 q}{dt^2} \quad (\text{KVL})$

$$\Rightarrow \frac{d^2 q}{dt^2} = -\frac{1}{LC} q = -\omega^2 q \Rightarrow \omega = \frac{1}{\sqrt{LC}}$$

\searrow angular frequency

- Damped RLC Circuit

- $q = Q_{\max} e^{-\frac{Rt}{2L}} \cos \omega_d t$

$\omega_d = \sqrt{\frac{1}{LC} - \left(\frac{R}{2L}\right)^2}$

- oscillation

damped critically damped overdamped

critical resistance $R_c = \sqrt{\frac{4L}{C}}$

10 AC Circuit

- AC Circuit = time-varying signal represented as sum of sinusoids
 - periodic function : $f(t) = \sum_{n=0}^{\infty} A_n \sin(\omega t + \phi)$
 - any function : $f(t) = \int_0^{\infty} A(\omega) \sin(\omega t + \phi)$
- sinusoids $v(t) = V_{\max} \sin(kx + \omega t + \phi)$

angular frequency
 $\omega = 2\pi f = 2\pi/T$

Phasor Diagram

- sinusoids

↓ simplify

phasors

time domain

frequency domain

$$V_R(t) = V_{\max} \sin(\omega t + \phi)$$

phase space

$$V_R = V_{\max} \angle \phi = V_{\max} e^{j\phi}$$

$$= V_{\max} \cos \phi + j V_{\max} \sin \phi$$

- AC Power Source : $\Delta V = \Delta V_{\max} \sin \omega t$ → here, voltage is the reference

- resistor : $i = \frac{\Delta V_{\max}}{R} \sin \omega t$

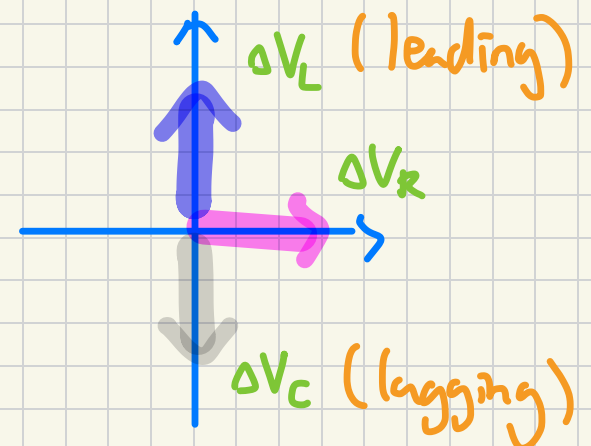
- inductor : $i = \frac{\Delta V_{\max}}{\omega L} \sin \left(\omega t - \frac{\pi}{2} \right)$
 → X_L (inductive reactance)

- capacitor : $i = \frac{\Delta V_{\max}}{\frac{1}{\omega C}} \sin \left(\omega t + \frac{\pi}{2} \right)$
 → X_C (capacitive reactance)

RLC Circuit

- $V_L = i \omega L \sin \left(\omega t + \frac{\pi}{2} \right)$

- $V_C = i \frac{1}{\omega C} \sin \left(\omega t - \frac{\pi}{2} \right)$



- $V = IZ$

$X_L = X_C \Rightarrow$ pure resistive
 \uparrow

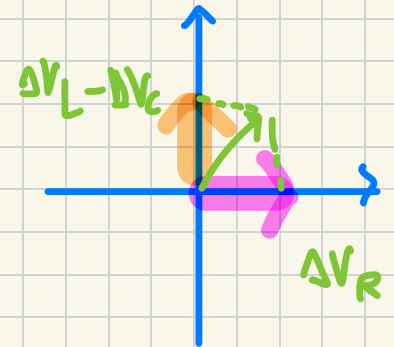
- Impedance $Z = R + j(X_L - X_C) \quad (\Omega)$

$$= R + j\left(\omega L - \frac{1}{\omega C}\right)$$

$$= A \angle \phi$$

$$A = \sqrt{R^2 + (X_L - X_C)^2}$$

$$\phi = \frac{X_L - X_C}{R}$$



- $I = \frac{V}{Z} = \frac{V_{max} \angle 0}{A \angle \phi} = \frac{V_{max}}{A} \angle (-\phi)$

$$i(t) = \frac{V_{max}}{A(\omega)} \sin(\omega t - \phi(\omega))$$

- reactance, $X_L \uparrow = \omega \uparrow L$, $X_C \downarrow = \frac{1}{\omega \uparrow C}$ ($\omega \propto f$)

- Power in an AC Circuit

- $I_{rms} = \frac{I_{max}}{\sqrt{2}}$, $V_{rms} = \frac{V_{max}}{\sqrt{2}}$ power factor of the circuit

- $P_{avg} = \frac{1}{2} I_{max} V_{max} \cos \phi = I_{rms} V_{rms} \cos \phi$

- For an RLC Circuit:

- resonance frequency when $X_L = X_C$

$$\omega L = \frac{1}{\omega C} \Rightarrow \omega_{res} = \frac{1}{\sqrt{LC}}$$

- $I_{rms} = \frac{\Delta V_{rms}}{Z} = \frac{\Delta V_{rms}}{\sqrt{R^2 + (X_L - X_C)^2}} = \frac{\Delta V_{rms}}{R} \Rightarrow Z \text{ min, } I_{max}$
 $\Rightarrow P \text{ max.}$

- Quality Factor $Q = \frac{\omega_0}{\Delta\omega} = \frac{\omega_0 L}{R}$
 (Q Factor) $\Delta\omega = \frac{R}{L}$ (width of the curve at half-power pts.)

- Transformer

$$\frac{\Delta V_2}{\Delta V_1} = \frac{N_2}{N_1} \quad \text{assume no power loss} \quad \frac{I_1}{I_2}$$

$\Delta V = -N \frac{d\phi_B}{dt}$ $P = IV$

$$R_{eq} = \frac{\Delta V_1}{I_1} = \left(\frac{N_1}{N_2}\right)^2 \frac{\Delta V_2}{I_2}$$

III EM Waves

Maxwell's Equations

$$\Phi_E = \oint \vec{E} \cdot d\vec{A} = \frac{q_{in}}{\epsilon_0} \quad (\text{Gauss's Law})$$

$$\Phi_B = \oint \vec{B} \cdot d\vec{A} = 0 \quad (\text{Gauss's Law in Magnetism})$$

$$\mathcal{E} = \oint \vec{E} \cdot d\vec{s} = - \frac{d\Phi_B}{dt} \quad (\text{Faraday's Law})$$

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I + \mu_0 \epsilon_0 \frac{d\Phi_E}{dt} \quad (\text{Ampere-Maxwell Law})$$

→ displacement current I_d

$$\vec{F} = q \vec{E} + q \vec{v} \times \vec{B} \quad (\text{Lorentz Force Law})$$

$$\begin{aligned} \frac{\partial^2 E}{\partial x^2} &= \mu_0 \epsilon_0 \frac{\partial^2 E}{\partial t^2} \\ \frac{\partial^2 B}{\partial x^2} &= \mu_0 \epsilon_0 \frac{\partial^2 B}{\partial t^2} \end{aligned} \quad \Rightarrow \quad \frac{\partial^2 y}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2} \Rightarrow v = c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

The simplest solution to partial differential equations:

$$\begin{cases} E = E_{\max} \cos(kx - \omega t) \\ B = B_{\max} \cos(kx - \omega t) \end{cases}$$

- angular wave number $k = 2\pi/\lambda$
- angular frequency $\omega = 2\pi f$

$$\frac{\omega}{k} = \frac{2\pi f}{2\pi/\lambda} = \lambda f = c$$

$$\cdot \frac{E_{\max}}{B_{\max}} = \frac{E}{B} = \frac{\omega}{k} = c$$

- Poynting Vector $\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu_0} \left(\frac{W}{m^2} \right)$

↘ time-varying quantity

→ in the direction of propagation

- Intensity is the time average of S over one or more cycles

$$I = S_{avg} = \frac{E_{max} B_{max}}{2\mu_0} = \frac{E_{max}^2}{2\mu_0 c} = \frac{c B_{max}^2}{2} \left(\frac{W}{m^2} \right)$$

- Energy density

$$U_E = \frac{\epsilon_0 E^2}{2}, \quad U_B = \frac{B^2}{2\mu_0}, \quad U = U_E + U_B = \epsilon_0 E^2 = \frac{B^2}{\mu_0}$$

$$U_{avg} = \frac{\epsilon_0 E^2}{2} = \frac{B^2}{2\mu_0}, \quad I = S_{avg} = c U_{avg}$$

- EM waves transport momentum $p = \frac{TER}{c}$ → total energy to a surface in Δt
 → radiation / light pressure
 * ER: electromagnetic radiation
 - Pressure is exerted on a surface as momentum is absorbed
- $$P_{\text{pres}} = \frac{F}{A} = (1 + f) \frac{S}{c}$$
- \rightarrow poynting vector
 \downarrow % (incident light reflected from the surface)

[12] The Nature of Light and the Laws of Geometic Optics

Refraction

$$\frac{\lambda_1}{\lambda_2} = \frac{v_1}{v_2} = \frac{\sin \theta_1}{\sin \theta_2} = \frac{n_2}{n_1}$$

$v = f\lambda$

Snell's Law:

$$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

index of refraction (折射率)

$$n = \frac{\text{speed of light in vacuum}}{\text{speed of light in a medium}} = \frac{c}{v}$$

$$n_{\text{vacuum}} = 1 \\ \approx n_{\text{air}}$$

[13] Other Formulas

- long, straight conducting wire

$$\cdot \quad B = \frac{\mu_0 I}{2\pi r}$$

- solenoid

- $B = \mu_0 n I$

- $L = \mu_0 n^2 V$

- Energy = $\frac{B^2}{2\mu_0} V$, Energy Density = $\frac{B^2}{2\mu_0}$

- $\mu_0 = 4\pi \times 10^{-7} \text{ (T} \cdot \text{m/A)}$

- $F_B = i l B \sin\theta$

- E unit : V/m