# Deep Generative Models: Discrete Latente Variables

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Philip Schulz and Wilker Aziz

https:
//github.com/philschulz/VITutorial
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First Attempt: Wake-Sleep

Neural Variational Inference

Score function estimator

Variance reduction

#### Generative Models

Joint distribution over observed data x and latent variables Z.

$$p(x, z|\theta) = \underbrace{p(z)}_{\text{prior}} \underbrace{p(x|z, \theta)}_{\text{likelihood}}$$

The likelihood and prior are often standard distributions (Gaussian, Bernoulli) with simple dependence on conditioning information.

### Deep generative models

Joint distribution with deep observation model

$$p(x, z|\theta) = \underbrace{p(z)}_{\text{prior}} \underbrace{p(x|z, \theta)}_{\text{likelihood}}$$

mapping from z to  $p(x|z,\theta)$  is a NN with parameters  $\theta$ 

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mapping from z to  $p(x|z,\theta)$  is a NN with parameters  $\theta$ 

Marginal likelihood

$$p(x|\theta) = \int p(x, z|\theta) dz = \int p(z)p(x|z, \theta) dz$$

intractable in general

#### We want

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but we can't perform gradient-based MLE

We need approximate inference techniques!

#### First Attempt: Wake-Sleep

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## Wake-sleep Algorithm

- ► Generalise latent variables to Neural Networks
- ► Train generative neural model
- ► Use variational inference! (kind of)

#### 2 Neural Networks:

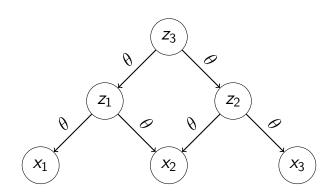
A generation network to model the data (the one we want to optimise) – parameters:  $\theta$ 

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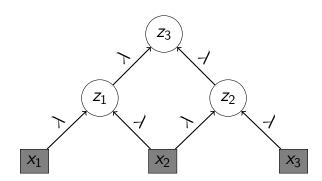
- A generation network to model the data (the one we want to optimise) parameters:  $\theta$
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- Original setting: binary hidden units

- ▶ A generation network to model the data (the one we want to optimise) – parameters:  $\theta$
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- Original setting: binary hidden units
- Training is performed in a "hard EM" fashion

### Generator



### Inference Network



## Wake-sleep Training

#### Wake Phase

- Use inference network to sample hidden unit setting z from  $q(z|x,\lambda)$
- ▶ Update generation parameters  $\theta$  to maximize join log-likelihood of data and latents  $p(x, z|\theta)$

## Wake-sleep Training

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#### **Sleep Phase**

- Produce dream sample  $\tilde{x}$  from random hidden unit z
- ▶ Update inference parameters  $\lambda$  to maximize probability of latent state  $q(z|\tilde{x}, \lambda)$

Objective

$$\underset{\theta}{\operatorname{arg \, min}} \, \operatorname{\mathsf{KL}} \left( q(z|x,\lambda) \mid\mid p(z|x,\theta) \right)$$

#### Objective

$$\begin{aligned} & \operatorname*{arg\,min}_{\theta} \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z|x,\theta)\right) \\ & = \operatorname*{arg\,max}_{\theta} \ \ \underbrace{\mathbb{E}_{q(z|x,\lambda)}\left[\log p(z,x|\theta)\right] + \mathbb{H}[q(z|x,\lambda)\right]}_{\mathcal{G}(\theta)} \end{aligned}$$

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$$\begin{split} \boldsymbol{\nabla}_{\boldsymbol{\theta}} \mathcal{G}(\boldsymbol{\theta}) &= \boldsymbol{\nabla}_{\boldsymbol{\theta}} \mathbb{E}_{q(\boldsymbol{z}|\boldsymbol{x},\boldsymbol{\lambda})} \left[ \log p(\boldsymbol{z},\boldsymbol{x}|\boldsymbol{\theta}) \right] + \boldsymbol{\nabla}_{\boldsymbol{\theta}} \mathbb{H}[q(\boldsymbol{z}|\boldsymbol{x},\boldsymbol{\lambda})] \\ &= \mathbb{E}_{q(\boldsymbol{z}|\boldsymbol{x},\boldsymbol{\lambda})} \left[ \boldsymbol{\nabla}_{\boldsymbol{\theta}} \log p(\boldsymbol{z},\boldsymbol{x}|\boldsymbol{\theta}) \right] \\ &\stackrel{\mathsf{MC}}{\approx} \boldsymbol{\nabla}_{\boldsymbol{\theta}} \log p(\boldsymbol{z},\boldsymbol{x}|\boldsymbol{\theta}) \quad \text{where } \boldsymbol{z} \sim q(\boldsymbol{z}|\boldsymbol{x},\boldsymbol{\lambda}) \end{split}$$

Assumes latent state z to be fixed random draws from  $q(z|x, \lambda)$ .

$$\operatorname*{arg\;min}_{\theta} \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z|x,\theta)\right) \\ \overset{\mathsf{MC}}{\approx} \operatorname*{arg\;max}_{\theta} \log p(z,x|\theta)$$

This is simply supervised learning with imputed latent data!

# Wake Phase Sampling

Sampling 
$$z \sim q(z|x,\lambda)$$

 $\left(z_3\right)$ 

 $\left(z_1\right)$ 

 $\left(z_{2}\right)$ 

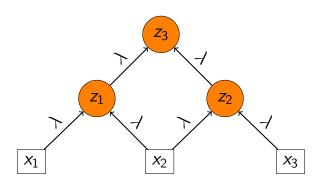
 $x_1$ 

*X*<sub>2</sub>

*X*<sub>3</sub>

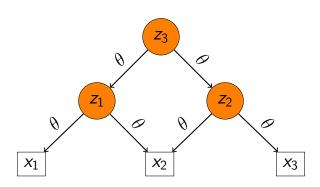
## Wake Phase Sampling

Sampling  $z \sim q(z|x,\lambda)$ 



# Wake Phase Update

#### Update $\theta$



#### Objective

$$\underset{\lambda}{\operatorname{arg\,min}} \operatorname{\mathsf{KL}} \left( q(z|x,\lambda) \mid\mid p(z|x,\theta) \right)$$

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$$\mathbf{\nabla}_{\lambda}\mathcal{R}(\lambda) = \mathbf{\nabla}_{\lambda}\mathbb{E}_{q(z|x,\lambda)}\left[\log p(z,x|\theta)\right] + \mathbf{\nabla}_{\lambda}\mathbb{H}[q(z|x,\lambda)]$$

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Gradient estimate

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Let's change the objective!

# Sleep Phase (Convenient) Objective

Flip the direction of the KL

$$\operatorname*{arg\,min}_{\lambda} \mathbb{E}_{p(x)} \left[ \mathsf{KL} \left( p(z|x, heta) \mid\mid q(z|x, \lambda) 
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#### Gradient

$$\nabla_{\lambda} \mathcal{R}(\lambda) = \nabla_{\lambda} \mathbb{E}_{p(x,z|\theta)} [\log q(z|x,\lambda)]$$

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Assumes fake data  $\tilde{x}$  and latent variables z to be fixed random draws from  $p(x, z|\theta)$ .

$$\underset{\lambda}{\operatorname{arg max}} \ \mathbb{E}_{p(x,z|\theta)} \left[ \log q(z|x,\lambda) \right]$$

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$$rg \max_{\lambda} \; \mathbb{E}_{
ho(x,z| heta)} \left[ \log q(z|x,\lambda) 
ight] \ \stackrel{\mathsf{MC}}{pprox} \; rg \max_{\lambda} \; \log q(z| ilde{x},\lambda)$$

where  $z \sim p(z)$  and  $\tilde{x} \sim p(x|z)$ 

(fake data!)

## Sleep Phase Sampling

Sampling  $(z, \tilde{x}) \sim p(x, z|\theta)$ 

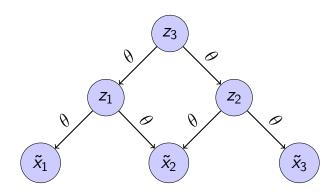


$$(z_1)$$

$$\left(z_{2}\right)$$

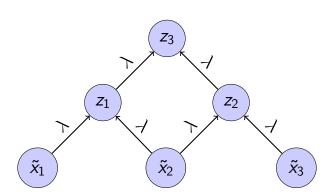
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Sampling  $(z, \tilde{x}) \sim p(x, z|\theta)$ 



## Sleep Phase Update

#### $\mathsf{Update}\ \lambda$



### Wake-sleep Algorithm

#### **Advantages**

- Simple layer-wise updates
- ightharpoonup Amortised inference: all latent variables are inferred from the same weights  $\lambda$

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#### **Advantages**

- ► Simple layer-wise updates
- ightharpoonup Amortised inference: all latent variables are inferred from the same weights  $\lambda$

#### **Drawbacks**

- Inference and generative networks are trained on different objectives
- Inference weights  $\lambda$  are updated on fake data  $ilde{x}$
- Generative weights are bad initially, giving wrong signal to the updates of  $\lambda$

First Attempt: Wake-Sleep

Neural Variational Inference

Score function estimator

Variance reduction

Generative model with NN likelihood

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Generative model with NN likelihood

Let us consider a latent factor model for topic modelling:

- ▶ a document  $x = (x_1, ..., x_N)$  consists of n i.i.d. categorical draws from that model
- ▶ the categorical distribution in turn depends on binary latent factors  $z = (z_1, ..., z_K)$  which are also i.i.d.

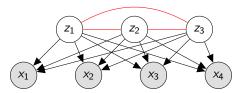
#### Latent factor model

$$Z_j \sim \mathsf{Bernoulli}\left(\phi
ight) \qquad (1 \leq k \leq K) \ X_i | z \sim \mathsf{Categorical}\left(f(z; heta)
ight) \quad (1 \leq i \leq N)$$

Here  $0 < \phi < 1$  specifies a Bernoulli prior and  $f(\cdot; \theta)$  is a function computed by a neural network with softmax output, e.g.

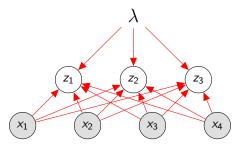
$$f(z; \theta) = \text{softmax}(Wz + b)$$
  
 $\theta = \{W, b\}$ 

## **Example Model**



At inference time the latent variables are marginally dependent. For our variational distribution we are going to assume that they are not (recall: mean field assumption).

### Mean Field Inference



The inference network needs to predict K Bernoulli parameters  $b_1^K$ . Any neural network with sigmoid output will do that job.

#### Inference Network

$$q(z|x,\lambda) = \prod_{k=1}^K \mathsf{Bern}(z_k|b_k)$$
 where  $b_1^K = g(x;\lambda)$ 

Example architecture

$$h = \frac{1}{N} \sum_{i=1}^{N} E_{x_i}$$
  $b_1^K = sigmoid(Mh + c)$ 

$$\lambda = \{E, M, c\}$$

## Objective

$$egin{aligned} \mathsf{ELBO} &= \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x,z| heta) 
ight] + \mathbb{H} \left( q(z|x,\lambda) 
ight) \ &= \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z, heta) 
ight] - \mathsf{KL} \left( q(z|x,\lambda) \mid\mid p(z) 
ight) \end{aligned}$$

Parameter estimation

$$\argmax_{\theta,\lambda} \; \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] - \mathsf{KL} \left( q(z|x,\lambda) \; || \; p(z) \right)$$

### KL

KL between K independent Bernoulli distributions is tractable

$$egin{aligned} \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z|\phi)
ight) &= \sum_{k=1}^K \mathsf{KL}\left(q(z_k|x,\lambda) \mid\mid p(z_k|\phi)
ight) \ &= \sum_{k=1}^K b_k \log rac{b_k}{\phi} + (1-b_k) \log rac{1-b_k}{1-\phi} \end{aligned}$$

#### Generative Network Gradient

$$\frac{\partial}{\partial \theta} \left( \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] - \overbrace{\mathsf{KL} \left( q(z|x,\lambda) \mid\mid p(z) \right)}^{\mathsf{constant wrt } \theta} \right)$$

#### Generative Network Gradient

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$$= \underbrace{\mathbb{E}_{q(z|x,\lambda)} \left[ \frac{\partial}{\partial \theta} \log p(x|z,\theta) \right]}_{\mathsf{expected gradient } :)}$$

### Generative Network Gradient

$$\begin{split} &\frac{\partial}{\partial \theta} \left( \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] - \overbrace{\mathsf{KL} \left( q(z|x,\lambda) \mid \mid p(z) \right)}^{\mathsf{constant wrt } \theta} \right) \\ &= \mathbb{E}_{q(z|x,\lambda)} \left[ \frac{\partial}{\partial \theta} \log p(x|z,\theta) \right] \\ &\overset{\mathsf{expected gradient } :)}{\underset{\approx}{\mathsf{E}} \sum_{s=1}^{S} \frac{\partial}{\partial \theta} \log p(x|z^{(s)},\theta)} \quad \mathsf{where } z^{(s)} \sim q(z|x,\lambda) \end{split}$$

$$\frac{\partial}{\partial \lambda} \left( \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] - \overbrace{\mathsf{KL} \left( q(z|x,\lambda) \mid\mid p(z) \right)}^{\mathsf{analytical}} \right)$$

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The first term again requires approximation by sampling, but there is a problem

$$rac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} \left[ \log p_{ heta}(x|z) \right]$$

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] \\ = \frac{\partial}{\partial \lambda} \sum_{z} q(z|x,\lambda) \log p(x|z,\theta)$$

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MC estimator is non-differentiable

$$\begin{split} &\frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} \left[ \log p_{\theta}(x|z) \right] \\ &= \frac{\partial}{\partial \lambda} \sum_{z} q(z|x,\lambda) \log p(x|z,\theta) \\ &= \underbrace{\sum_{z} \frac{\partial}{\partial \lambda} (q(z|x,\lambda)) \log p(x|z,\theta)}_{\text{not an expectation}} \end{split}$$

- MC estimator is non-differentiable
- Differentiating the expression does not yield an expectation: cannot approximate via MC

#### Score function estimator

We can again use the log identity for derivatives

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q_{\lambda}(z|x)} [\log p_{\theta}(x|z)] \\
= \sum_{z} \frac{\partial}{\partial \lambda} (q(z|x,\lambda)) \log p(x|z,\theta)$$

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#### Score function estimator: remarks

We can now build an MC estimator

$$\begin{split} & \frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] \\ & = \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \frac{\partial}{\partial \lambda} \log q(z|x,\lambda) \right] \end{split}$$

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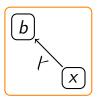
ightharpoonup magnitude of  $\log p(x|z,\theta)$  varies widely

## Score function estimator: remarks

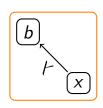
We can now build an MC estimator

$$\begin{split} & \frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] \\ &= \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \frac{\partial}{\partial \lambda} \log q(z|x,\lambda) \right] \\ & \overset{\mathsf{MC}}{\approx} \frac{1}{S} \sum_{s=1}^{S} \log p(x|z^{(s)},\theta) \frac{\partial}{\partial \lambda} \log q(z^{(s)}|x,\lambda) \\ & \text{where } z^{(s)} \sim q(z|x,\lambda) \end{split}$$

- ightharpoonup magnitude of log  $p(x|z,\theta)$  varies widely
- model likelihood does not contribute to direction of gradient

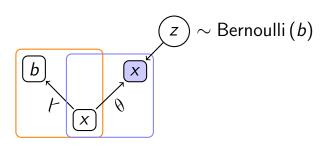


inference model



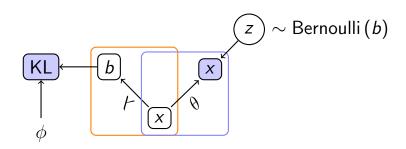


inference model



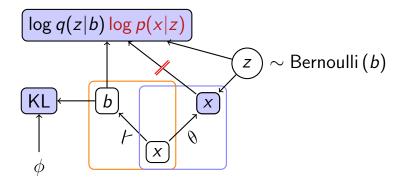
inference model

generation model



inference model

generation model



inference model

generation model

## Pros and Cons

- Pros
  - Applicable to all distributions
  - Many libraries come with samplers for common distributions

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- Pros
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- Cons
  - ► High Variance!

First Attempt: Wake-Sleep

Neural Variational Inference

Score function estimator

Variance reduction

# When variance is high we can

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# When variance is high we can

- sample more
- use variance reduction techniques (e.g. baselines and control variates)

## Control variates

Suppose we want to estimate  $\mathbb{E}[f(Z)]$ 

$$\hat{f} \stackrel{\mathsf{MC}}{pprox} \frac{1}{S} \sum_{s=1}^{S} f(z^{(s)})$$

and we know the expected value of another function  $\psi(z)$  on the same support.

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and we know the expected value of another function  $\psi(z)$  on the same support.

It holds that

$$\mathbb{E}[f(Z)] = \mathbb{E}[f(Z) - \psi(Z)] + \mathbb{E}[\psi(Z)]$$

## Variance reduction

$$\hat{d} = \frac{1}{S} \left( \sum_{s=1}^{S} f(z^{(s)}) - \psi(z^{(s)}) \right) + \underbrace{\mathbb{E}[\psi(Z)]}_{\mu_{\psi}}$$

In general

$$\mathsf{Var}(\hat{d}) = \mathsf{Var}(\hat{f}) - 2\,\mathsf{Cov}(\hat{f},\hat{\psi}) + \underbrace{\mathsf{Var}(\mu_{\psi})}_{0}$$

If f and  $\psi$  are strongly correlated, then we improve on the original estimation problem.

#### Fact

The Expectation of the score function is 0.

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$$\mathbb{E}_{q(z|x,\lambda)}\left[\frac{\partial}{\partial\lambda}\log q(z|x,\lambda)\right]=0$$

We attempt to centre the gradient estimate. To do this we learn a quantity C that we subtract from the reconstruction loss.

$$\mathbb{E}_{q(z|\lambda)}\left[\log q(z|\lambda)\left(\log p(x|z,\theta)-C\right)\right]$$

We call C a baseline. It does not change the expected gradient (Williams, 1992).

$$\mathbb{E}_{q(z|\lambda)} \left[ \frac{\partial}{\partial \lambda} \log q(z|\lambda) \left( \log p(x|z,\theta) - C \right) \right] =$$

$$\mathbb{E}_{q(z|\lambda)} \left[ \frac{\partial}{\partial \lambda} \log q(z|\lambda) \left( \log p(x|z,\theta) - C \right) \right] =$$

$$\mathbb{E}_{q(z|\lambda)} \left[ \frac{\partial}{\partial \lambda} \log q(z|\lambda) \log p(x|z,\theta) \right] -$$
score function gradient

$$\mathbb{E}_{q(z|\lambda)} \left[ \frac{\partial}{\partial \lambda} \log q(z|\lambda) \left( \log p(x|z,\theta) - C \right) \right] = \\ \mathbb{E}_{q(z|\lambda)} \left[ \frac{\partial}{\partial \lambda} \log q(z|\lambda) \log p(x|z,\theta) \right] - \\ \mathbb{E}_{q(z|\lambda)} \left[ \frac{\partial}{\partial \lambda} \log q(z|\lambda) \right] C$$

We can make baselines input-dependent to make them more flexible.

$$\log q(z|\lambda) (\log p(x|z,\theta) - C(x;\omega))$$

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$$\log q(z|\lambda) \left(\log p(x|z,\theta) - C(x;\omega)\right)$$

However, baselines may not depend on the random value z! Quantities that may depend on the random value (C(z)) are called **control variates**.

See Blei et al. (2012); Ranganath et al. (2014); Gregor et al. (2014).

Baselines are predicted by a regression model (e.g. a neural net).

The model is trained using an  $L_2$ -loss.

$$\min_{\omega} \left( C(x; \omega) - \log p(x|z, \theta) \right)^2$$

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- NVIL: a single objective (ELBO) for both models
- Use score function estimator
- ► Always use baselines for variance reduction!

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