

# **(CHAPTER-12)**

## **KNOWLEDGE REPRESENTATION**

**Yanmei Zheng**

# Outline

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- ✓ **A general ontology**
- ✓ **The basic categories**
- ✓ **Representing actions**

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# Ontological Engineering

# Ontological Engineering

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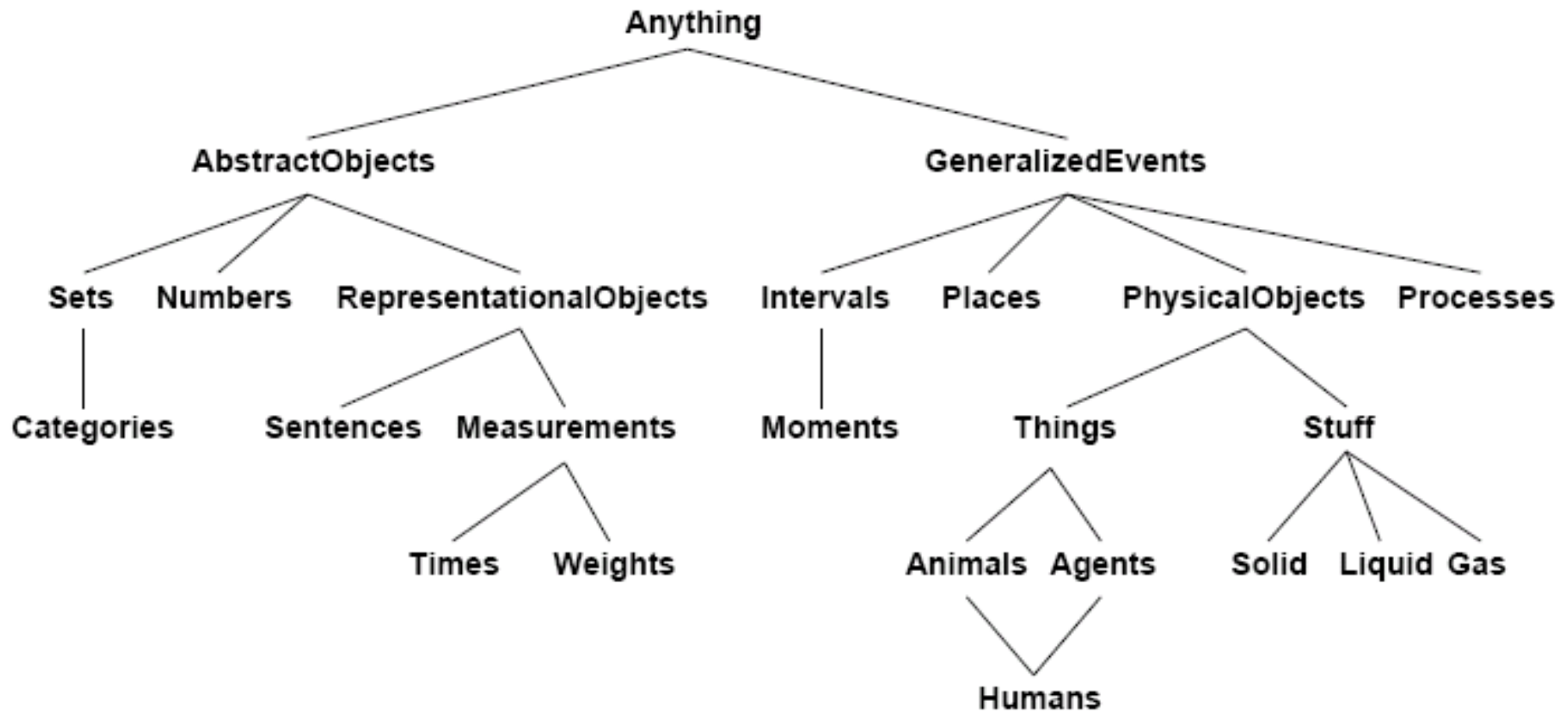
## @Complex domains

- ✓ Require very general & flexible representations
  - Include actions, time, physical objects, beliefs, ....
- ✓ Ontological engineering
  - The process of finding/deciding on representations for these abstract concepts
- ✓ Somewhat like **Knowledge Engineering**
  - But at a larger scale
  - Generalized to a more complex real world

# Ontological Engineering

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## *Upper ontology*



# Ontological Engineering

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@Our initial discussion may have omitted them

- ✓ **There are limitations to a FOL representation**
- ✓ e.g. there are exceptions to generalizations
  - They hold only to some degree
  - “Tomatoes are red”
  - But there are green, yellow, even purple tomatoes
- ✓ **Exceptions & uncertainty** are important topics
  - However, they are orthogonal to a general ontology
    - Their discussions are deferred
    - e.g. uncertainty later in Ch 13

# Ontological Engineering

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## @Goal

- ✓ Develop a **general purpose ontology**
- ✓ One that's usable in any special purpose domain
  - With the addition of **domain-specific axioms**
- ✓ Deal with any sufficiently demanding domains
  - Different areas of knowledge must be unified
  - Involves several areas simultaneously

We will use it later for the internet shopping agent example

# Ontological Engineering

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@We begin with objects & categories

- ✓ Organizing objects into categories
  - Though physical interaction involves individual objects
  - **Reasoning** processes need to operate at the level of **categories**



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# Categories and objects

# Categories and objects {12.2}

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@KR requires the organization of objects into categories

- ✓ Interaction at the level of the object
- ✓ Reasoning at the level of categories

@Category = set of its members

@Categories can be represented by FOL

- ✓ Predicates: **Basketball(b)**
- ✓ Or reify the category as an object: Basketballs.  
**Memberof(b, Basketballs)**

# Categories and objects {12.2}

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@Categories serve to organize and simplify the knowledge base through **inheritance**

- ✓ All instances of food are edible
- ✓ fruit is a subclass of food
- ✓ apples is a subclass of fruit
- ✓ then an apple is edible.

@Subclass relations organize categories into a **taxonomy**, or **taxonomic hierarchy**

# FOL & Categories

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## @Expressiveness of FOL

- ✓ Express relations between categories
  - *Disjoint*
    - No members in common between categories
  - *Exhaustive decomposition*
    - Any individual must be in one of the categories
  - *Partition*
    - An exhaustive disjoint decomposition of a category

# FOL and categories {12.2}

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## 1. State facts & quantify over members

@An object is a **member** of a category

$$BB_9 \in Basketballs$$

# FOL and categories {12.2}

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## 1. State facts & quantify over members

@An object is a **member** of a category

✓  $BB_9 \in \text{Basketballs}$

@A category is a **subclass** of another category

✓ Basketball is a kind of ball:

# FOL and categories {12.2}

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@ A category is a **subclass** of another category

✓  $\text{Subsetof}(\text{Basketballs}, \text{Balls}), \text{Basketballs} \subset \text{Balls}$

# FOL and categories {12.2}

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@All **members** of a category have some **properties**

✓ **Basketballs are round.**



# FOL and categories {12.2}

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✓  $(x \text{ Basketballs}) \Rightarrow \text{Spherical}(x)$

# FOL and categories {12.2}

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@ All **members** of a category have some **properties**

✓  $(x \in \text{Basketballs}) \Rightarrow \text{Spherical}(x)$

@ All members of a category can be recognized by some properties

✓ A round orange ball with diameter 9.5" is a basketball

# FOL and categories {12.2}

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$\text{Orange}(x) \wedge \text{Round}(x) \wedge \text{Diameter}(x)=9.5'' \wedge x \in \text{Balls} \Rightarrow$

$x \in \text{BasketBalls}$

# FOL and categories {12.2}

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@ A category as a whole has some properties.

✓ Dogs are among Domesticated Species

# FOL and categories {12.2}

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@ An object is a **member** of a category

✓  $BB_9 \in Basketballs$

@ A category is a **subclass** of another category

✓  $Subsetof(Basketballs, Balls), Basketballs \subset Balls$

@ All **members** of a category have some **properties**

✓  $(x \in Basketballs) \Rightarrow Spherical(x)$

@ All members of a category can be recognized by some properties

$Orange(x) \wedge Round(x) \wedge Diameter(x)=9.5'' \wedge x \in Balls \Rightarrow$   
 $x \in BasketBalls$

A category as a whole has some properties.

✓  $Dogs \in DomesticatedSpecies$

## Relations between categories {12.2}

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@Two or more categories are **disjoint** if they have no members in common:

✓ *Disjoint({animals, vegetables})*

✓ *Disjoint(s)*  $\Leftrightarrow$  \_\_\_\_\_

## Relations between categories {12.2}

---

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✓ Disjoint({animals, vegetables})

*Disjoint(s)*  $\Leftrightarrow$

$$(\forall c_1, c_2 \ c_1 \in s \wedge c_2 \in s \wedge c_1 \neq c_2 \text{ Intersection}(c_1, c_2) = \{\})$$

## Relations between categories {12.2}

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@Two or more categories are **disjoint** if they have no members in common:

✓ *Disjoint*({animals, vegetables})

$$\text{Disjoint}(s) \Leftrightarrow \forall C_1, C_2 (C_1 \in s \wedge C_2 \in s \wedge C_1 \neq C_2 \Rightarrow \text{Intersection}(C_1, C_2) = \{ \} )$$

@A set of categories **s** constitutes an **exhaustive decomposition** of a category **c** if all members of the set **c** are covered by categories in **s**:

✓ *ExhaustiveDecomposition*({Americans, Canadians, Mexicans}, NorthAmericans).

✓ *E.D.*(s,c)  $\Leftrightarrow$



## Relations between categories {12.2}

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@A set of categories **s** constitutes an **exhaustive decomposition** of a category **c** if all members of the set **c** are covered by categories in **s**:

✓ *ExhaustiveDecomposition*({Americans, Canadians, Mexicans}, NorthAmericans).

$$E.D.(s, c) \Leftrightarrow (\forall i i \in c \Rightarrow \exists C_2 C_2 \in s \wedge i \in C_2)$$

# Relations between categories {12.2}

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@ A **partition** is a disjoint exhaustive decomposition:

@ *Partition({Males, Females}, Animals)*

@ *Partition(s,c)  $\Leftrightarrow$  \_\_\_\_\_*

# Relations between categories {12.2}

---

@A **partition** is a disjoint exhaustive decomposition:

@*Partition({Males, Females}, Animals)*

$$Partition(s,c) \Leftrightarrow Disjoint(s) \wedge E.D.(s,c)$$

# Define a category {12.2}

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☞ Categories can be defined by providing necessary and sufficient conditions for membership

✓ *example: a bachelor is an unmarried adult male*

$$x \in \text{Bachelors} \Leftrightarrow \text{Unmarried}(x) \wedge x \in \text{Adults} \wedge x \in \text{Males}$$

# Physical composition {12.2.1}

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@One object may be **part of** another:

- ✓ Use a **partof** relation
- ✓ Allows grouping of objects into partof hierarchies
- ✓ Similar to the subset, subclass hierarchy of categories
- ✓ *Partof(bucharest,romania)*
- ✓ *Partof(romania,easterneurope)*
- ✓ *Partof(easterneurope,europe)*
  
- ✓ **Properties:** the partof relation is reflexive and transitive
  - *Partof(x, x)*
  - *Partof(x, y)  $\wedge$  partof(y, z)  $\Rightarrow$  partof(x, z)*
  - **Allows the inference:** *partof(bucharest, europe)*

# Physical Composition

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## @Categories of composite objects

- ✓ structural relations among parts
- ✓ Example: a biped has 2 legs attached to a body

$$\begin{aligned} \text{Biped}(a) \Rightarrow \exists l_1 l_2 b \text{ Leg}(l_1) \wedge \text{Leg}(l_2) \wedge \text{Body}(b) \wedge \\ \text{PartOf}(l_1, a) \wedge \text{PartOf}(l_2, a) \wedge \text{PartOf}(b, a) \wedge \\ \text{Attached}(l_1, b) \wedge \text{Attached}(l_2, b) \wedge l_1 \neq l_2 \\ \wedge [\forall l_3 \text{ Leg}(l_3) \wedge \text{PartOf}(l_3, a) \Rightarrow (l_3 = l_1 \vee l_3 = l_2)] \end{aligned}$$

- ✓ The awkward specification of "exactly two" relaxed later

# Physical Composition {12.2.1}

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@There may also be composite objects

- ✓ that have parts but *no specific structure*, use the idea of a *bunch*
- ✓ *BunchOf* ({Apple1, Apple2, Apple3})
- ✓ a *composite, unstructured* object
  - define BunchOf in terms of PartOf relation
  - each element of *s* is a part of the BunchOf(s)

$$\forall x, x \in s \Rightarrow \text{PartOf}(x, \text{BunchOf}(s))$$

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# Measurements



# Measurements

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## @ Measured properties of objects

- ✓ Real objects have **length, width, mass, cost, ...**
- ✓ We refer to values assigned to these properties as *measures*
- ✓ Express them by
  - **Combining a units function with a number**
  - $Length(l_1) = Cm(3.8)$
  - $Cost(BasketBall_7) = \$(29)$

# Measurements

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## @ Measured properties of objects

- ✓ We can do **conversions**
  - Between different units for the same property
  - By equating multiples of 1 unit to another
  - $Cm(2.54 \times d) = Inches(d)$

$Length(L_1) = Inches(1.5) = Centimeters(3.81)$

$Centimeters(2.54 \times d) = Inches(d)$

$Diameter(Basketball_{12}) = Inches(9.5)$

$ListPrice(Basketball_{12}) = \$(19)$

$d \in Days \Rightarrow Duration(d) = Hours(24)$

# Measurements

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## @ Measured properties of objects

- ✓ One issue with the approach is that many "measures" **have no standard scale**
  - Beauty, difficulty, tastiness, ...
- ✓ **The key aspect** of measures is not their numeric values, but the ability to order them、 compare them with **ordering** symbols  $>$ ,  $<$

# Measurements

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## @Measured properties of objects

- ✓  $e1 \in \text{Exercise} \wedge e2 \in \text{Exercise} \wedge \text{Write}(\text{Norvig}, e1) \wedge \text{Write}(\text{Russell}, e2) \Rightarrow \text{Difficult}(e1) > \text{Difficult}(e2)$
- ✓  $e1 \in \text{Exercise} \wedge e2 \in \text{Exercise} \wedge \text{Difficult}(e1) > \text{Difficult}(e2) \Rightarrow \text{ExpertedScore}(e1) < \text{ExpertedScore}(e2)$

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# **Substances & Objects**

# Substances & Objects

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@Some things we wish to reason about

- ✓ Can be **subdivided**, yet **remain the same**
- ✓ We'll use a generic term:
  - **Stuff** (opposed to thing)
- ✓ Stuff
  - **Corresponds to mass nouns** of Natural Language
- ✓ Things
  - **Correspond to count nouns**
- ✓ Water vs Book, Butter vs Dog, ....

# Substances & Objects

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## @Mass nouns (stuff) vs count nouns (things)

- ✓ In general, for **stuff, mass nouns**:
  - **Intrinsic properties** define the substance
  - These are unchanged under subdivision: colour, taste, ...
    - At least under macroscopic subdivision
- ✓ While for **things, countable nouns**:
  - We include **extrinsic properties**
  - That change under subdivision: weight, length, shape, ...

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# Situation calculus



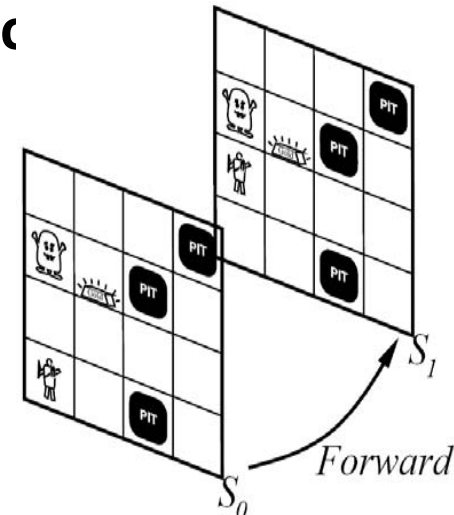
# Actions, Situations & Events

## @Reasoning about outcomes of actions

- ✓ Is central to the idea of a KB agent
- ✓ Recall that when we mentioned action sequences for the Wumpus World agent `Forward()`, `Turn(Right)`, ...
- ✓ We required a different copy of an action description for each time the action was executed

## @Use the ontology of **situation calculus**

- ✓ Situations are the results of executing actions

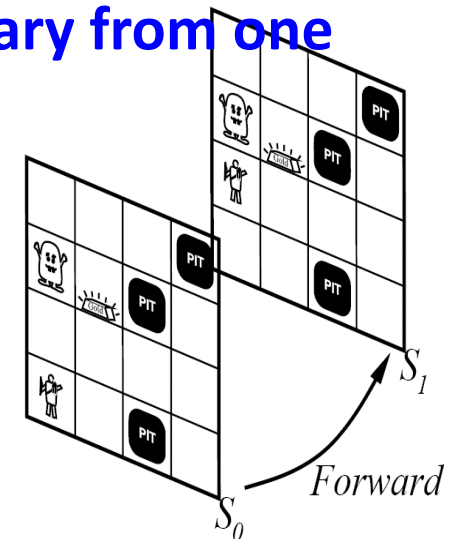


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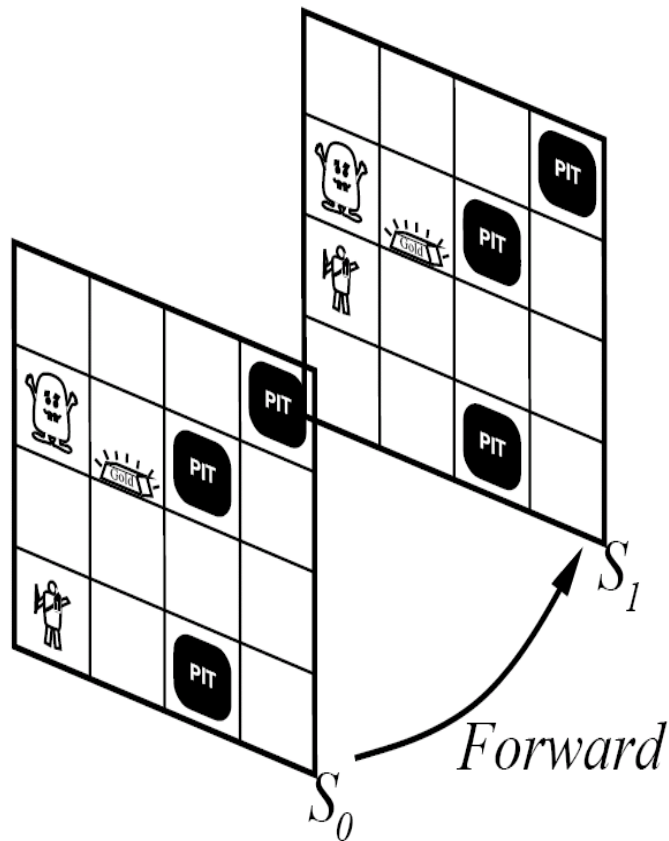
# Situation Calculus

## @Situation calculus (SC):

1. **Actions are logical terms**
  - Forward(), turn(right), ...
2. **Situations are logical terms consisting of**
  - The initial situation  $S_0$
  - All situations resulting from the action on certain situation  $s$  ( $=Result(a,s)$ )
3. **Fluent are functions and predicates that vary from one situation to the next.**
  - E.g.  $\neg Holding(G_1, S_0)$
4. **Eternal predicates are also allowed**
  - E.g.  $Gold(G_1)$



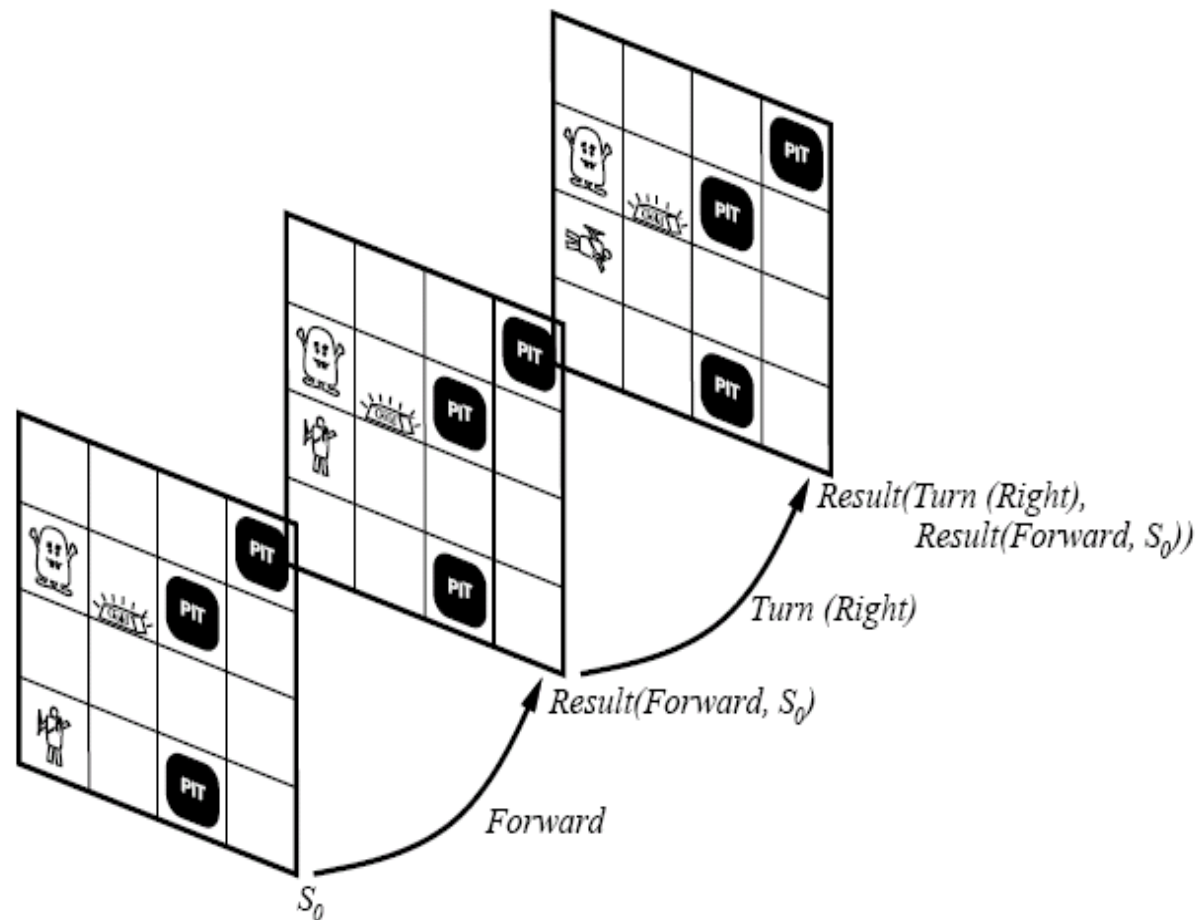
# Situation Calculus



- ⌚ Results of action sequences are determined by the individual actions.
- ⌚ *Projection task*: a SC agent should be able to deduce the outcome of a sequence of actions.
- ⌚ *Planning task*: find a sequence that achieves a desirable effect

# Situation Calculus

## @Situation calculus & the Wumpus World



# Events {12.3}

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@Now we add an ability to **reason about action sequences**

- ✓ A. executing the empty sequence leaves the situation **unchanged**
  - **$\text{Result}([], s) = s$**
- ✓ B. executing a non-empty sequence is the same as executing the **first** action then executing the **rest** in the resulting situation
  - **$\text{Result}([a]\text{seq}, s) = \text{Result}(\text{seq}, \text{Result}(a, s))$**

# Events {12.3}

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## @Describing change in situation calculus

- ✓ The simplest version
  - Uses *possibility and effect* axioms for each action
- ✓ A *possibility axiom* & an *effect axiom* specify
  - A. when it is possible to execute an action
  - B. what happens when a possible action is executed

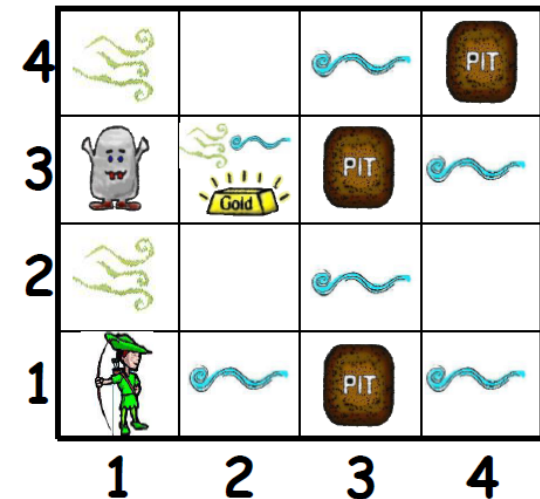
The general forms of these axioms

- ✓ A possibility axiom
  - **Preconditions  $\Rightarrow$  Poss(a, s)**
- ✓ An effect axiom
  - **Poss(a, s)  $\Rightarrow$  changes resulting from action a**

# Situation Calculus

## @A situation calculus example

- ✓ Change over time in Wumpus World
- ✓ Conventions
  - 1. Omit universal quantifiers if scope is a whole sentence
  - 2. Simplify the agent's moves as just **Go**
  - 3. Variables & their ranges
    - **s** ranges over situations
    - **a** ranges over actions
    - **g** ranges over gold
    - **x & y** range over locations
    - **o** ranges over objects (including the Agent)



# Situation Calculus

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## @ A situation calculus example: Wumpus World

### ✓ Sample possibility axioms

$$At(\text{Agent}, x, s) \wedge \text{Adjacent}(x, y) \Rightarrow Poss(\text{Go}(x, y), s)$$

$$\text{Gold}(g) \wedge At(\text{Agent}, x, s) \wedge At(g, x, s) \Rightarrow Poss(\text{Grab}(g), s)$$

### ✓ Sample effects axioms

$$Poss(\text{Go}(x, y), s) \Rightarrow At(\text{Agent}, y, \text{Result}(\text{Go}(x, y), s))$$

$$Poss(\text{Grab}(g), s) \Rightarrow Holding(g, \text{Result}(\text{Grab}(g), s))$$

### ✓ these apparently allow an agent

- to make a plan to get the gold



# Situation Calculus

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@To make a plan to get the gold requires

- ✓ Representing **that gold's location stays the same**
- ✓ The need to represent things that stay the same & to do it *efficiently*
  
- ✓ One possible approach is to **use frame axioms**
  - Explicit axioms to say what stays the same
    - Example: agent's moving does not affect objects not held

$$\begin{aligned} &At(o, x, s) \wedge (o \neq Agent) \wedge \neg Holding(o, s) \\ &\Rightarrow At(o, x, Result(Go(y, z), s)) \end{aligned}$$

# Representational frame problem

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@If there are  $F$  fluents and  $A$  actions then we need  $AF$  frame axioms to describe other objects are stationary unless they are held.

- ✓ We write down the effect of each actions

@Solution; describe how each fluent changes over time

- ✓ Successor-state axiom:

$$Pos(a,s) \Rightarrow (At(Agent,y,Result(a,s)) \Leftrightarrow (a = Go(x,y)) \vee (At(Agent,y,s) \wedge a \neq Go(y,z)))$$

- ✓ Note that next state is completely specified by current state.
- ✓ Each action effect is mentioned only once.



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**Thank you**

**End of  
Chapter 12-2**