Kaiser Hamid

Lubbock, Texas

Website: https://kaiser-75.github.io/

EDUCATION

Texas Tech University (TTU)

PhD in Industrial Engineering

Aug 2024 - Present

Lubbock, TX

Texas Tech University (TTU)

MS in Electrical and Computer Engineering (ECE)

Aug 2024 - Present Lubbock, TX

Apr 2019 - Jul 2024

Dhaka, Bangladesh

BSc. in Civil Engineering WORK EXPERIENCE

Graduate Research Associate

Autonomous Driving, Computer Vision, Human Factors

Lubbock, Texas

Dhaka, Banqladesh

Aug 2024 - Current

• Advisor: Dr. Nade Liang

Research Associate

Deep Learning, App Development, Database Management

Bangladesh University of Engineering & Technology (BUET)

· Advisor: Dr. Annesha Enam

Dec 2022 - Jul 2024

TECHNICAL SKILLS

Languages: Python, C, C++, Dart, R, MATLAB

Developer Tools: VS Code, Android Studio

Technologies/Frameworks: GitHub, ReactJS, NodeJS, Git, Mongo, Flutter

Deep Learning Frameworks: TensorFlow, Keras, PyTorch

Libraries: Scikit-learn, Pandas, Numpy, Scipy, OpenCV, Matplotlib, Seaborn

Simulation tool for autonomous driving: CARLA

RESEARCH INTERESTS

Autonomous driving, Computer vision, Cyber security, Human factors.

PUBLICATIONS

- Hamid, Kaiser, Liang, Nade, PhD. "How Good is Good? Evaluating Driving Maneuver Quality Using AI Agents." Proceedings of the 69th HFES International Annual Meeting (ASPIRE 2025).
- Hamid, Kaiser, Noor, Md Sayem, Enam, Annesha, PhD. "Assessing the Potential of Google Location History (GLH) Data for Travel Behavior Research in the Context of Developing Country." Proceedings of the 27th IEEE International Conference on Intelligent Transportation Systems (IEEE ITSC 2024).

GRANTS AND AWARDS

- Research Grant, CASR (JULY, 2024): Awarded a prestigious \$2500 research grant for work on Google Location History.
- Graduate College Travel Award (SEPTEMBER, 2024): Received \$950 to attend the IEEE ITSC Conference (2024-25).

PROJECTS

• Pedestrian Detection using Deep Learning: Developed a pedestrian detection system utilizing deep learning models.

Technologies: Python, Google Colab [Watch Demo]

• Traffic Mode Detection & Tracking for Dhaka, Bangladesh: Built a traffic mode detection and tracking system for urban mobility analysis.

Technologies: Python, Google Colab [Watch Demo]

• Gulshan-1 Intersection Simulation for CAPSTONE Project: Simulated traffic flows at a major intersection to analyze and optimize performance.

Technologies: VISSIM Software [Watch Demo]

• Traffic Mode Detection for Dhaka, Bangladesh: Created a detection system to classify and analyze traffic modes in Dhaka.

Technologies: Python, Google Colab [Watch Demo]

• Trip Tracker App for Collecting User Data: Designed and implemented a mobile app to collect and analyze user trip data.

Technologies: Flutter, MongoDB [Watch Demo]

• CARLA HITL (Human In The LOOP): Designed framework to work with steering, pedal and gear box with data logging

Technologies: Unreal Engine [Watch Demo]

• Raspberry Pi 4 Data Logger with CAN Bus: Developed a compact system using Raspberry Pi 4 to interface with vehicle CAN bus for real-time data logging and sensor integration

Technologies: Raspberry Pi 4, CAN bus, Python [Watch Demo]

SELECTED COURSES

- Structured Programming and OOP (C, C++)
- Pattern Recognition
- Machine Learning
- Advanced Cognitive Systems
- Design of Experiment