

AIM-Edge psdx/psdn AI Computing Device

User Manual

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Version 1.5

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Revision History

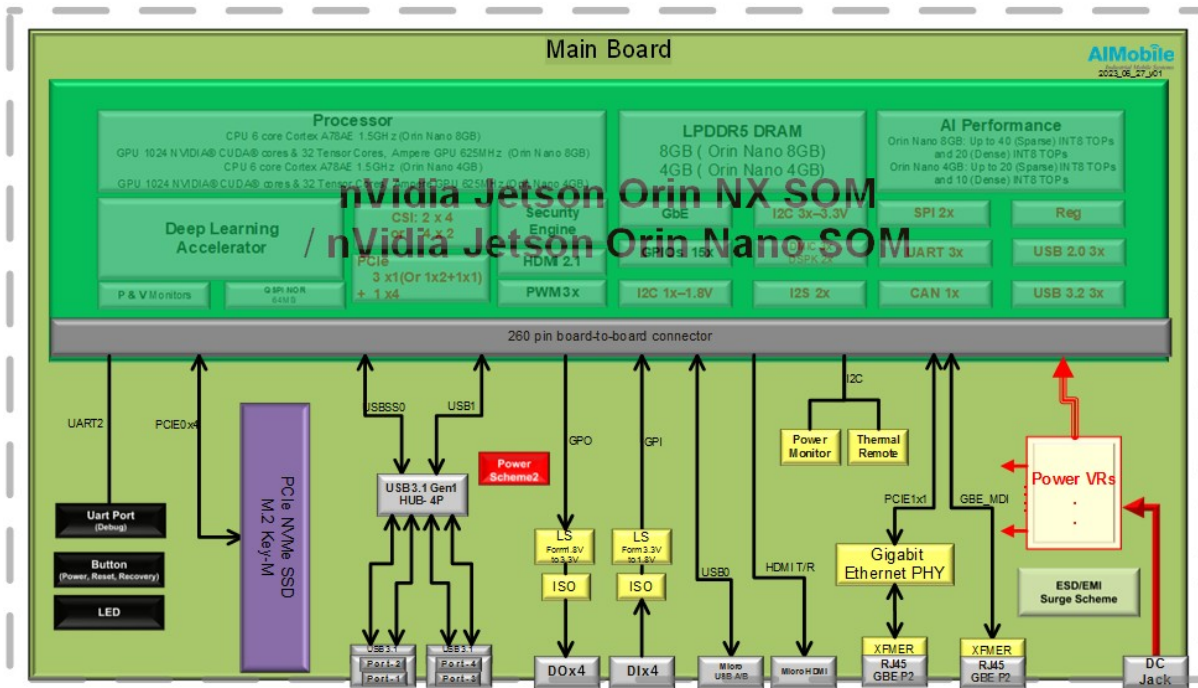
Date	Version	Modification
2023/10/25	1.0	Creation
2023/11/13	1.1	Add AlMobile container usage
2024/2/1	1.2	Specify the login password needs to be changed after the first login
2024/3/4	1.3	Specify the DO spec clearly
2024/3/8	1.4	1. Remove 5V after DO port because no current output 2. Add DO relay coil current/voltage limitation
2024/3/18	1.5	Specify the DC-in voltage range is 12~19V

1. Introduction

AIM-Edge psox/pson is a Nvidia Jetson AI computing device running on Linux platform, it supports NVidia Orin NX/Orin Nano SOM.

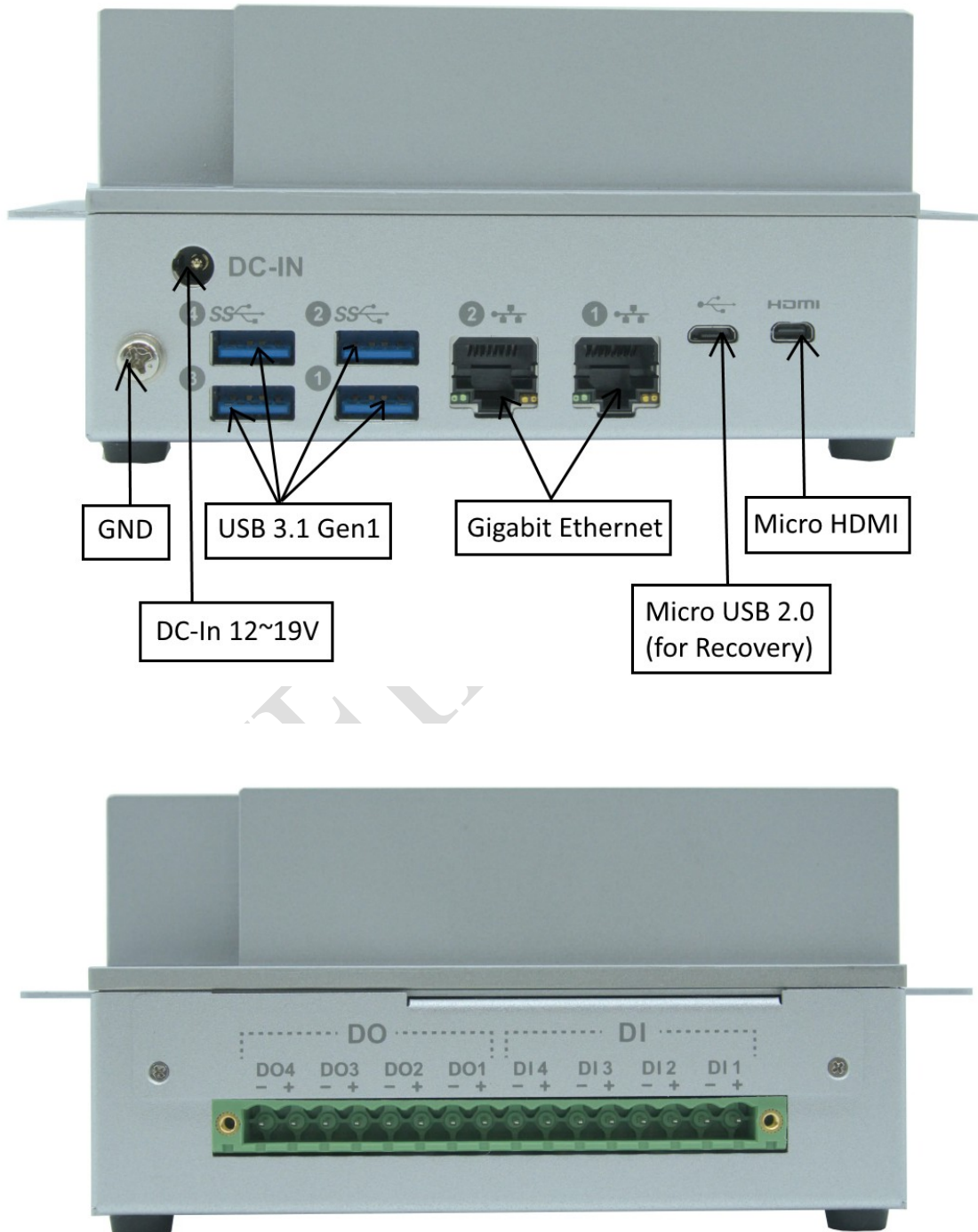
AIM-Edge psox/pson Specification	
SOM	NVIDIA Jetson Orin NX 16GB/8GB, Orin Nano 8GB/4GB
OS	Ubuntu 20.04/Linux 5.10
I/O	Gigabit Ethernet x 2 USB 3.1 Gen1 Type-A x 4 Micro USB 2.0 x 1 Micro HDMI x 1 Digital In (5V) x 4 Digital Output x 4 Power LED x 1 PCIe NVMe SSD (internal M.2) x 1 Debug UART (internal) x 1 DC-in (12~19V)
Dimension	94mm(W)X157mm(L)X70.75mm(H)
Weight	888g+-5g
Temperature	-20~60 °C (Operation)
Button/Key	1 x Power Button 1 x Recovery Button 1 x Reset Button

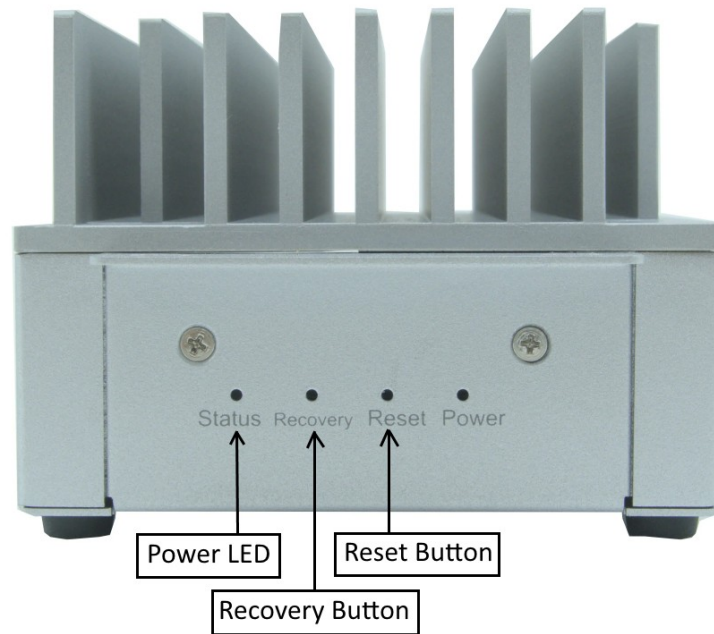
2. System Architecture



AIM-Edge psoc/psom Block Diagram

3. I/O Port Overview





4. Getting Started

4.1. Power Up

1. Connect a USB keyboard to the USB Type A connector of your device.
2. Connect an HDMI-compatible display to the micro HDMI connector on your device.
3. Connect the DC 12~19V adapter to the DC-in connector of your device.
4. Plug the power adapter into an appropriately rated electrical outlet. The system should power on directly. If not, press and release the power button in the device by paperclip.
5. When prompted, enter username and password (Username: **aim** /Password: **aim12345**).
6. Because of security concern, **user will be asked to change the password on the first login.**

```
WARNING: Your password has expired.
You must change your password now and log
Changing password for aim.
Current password: |
```

4.2. Enter Force USB Recovery Mode

To update your device, you must be in Force USB Recovery Mode so that you can transfer system image to the Jetson device. To place device in Force USB Recovery Mode,

1. Power down the device. If connected, remove the DC power from the device. The device must be powered OFF, and not in a suspend or sleep state.
2. Connect the Micro-B plug on the USB cable to the Recovery (USB Micro-B) Port on the device and the other end to an available USB port on the host PC.
3. Connect the power adapter to the device.
4. With the system powered on:
 - Press and hold the RECOVERY button with paperclip.
 - While pressing the RECOVERY button, press and release the RESET button with paperclip.
 - Wait 2 seconds and release the RECOVERY button.
5. After psux/psun enter Force USB Recovery Mode, if it connected to Linux Host PC/NB already, execute “lsusb” command on Host PC/NB, a “0955:7323 NVidia Corp.” device will appear. If not, perform Step 4 above again.

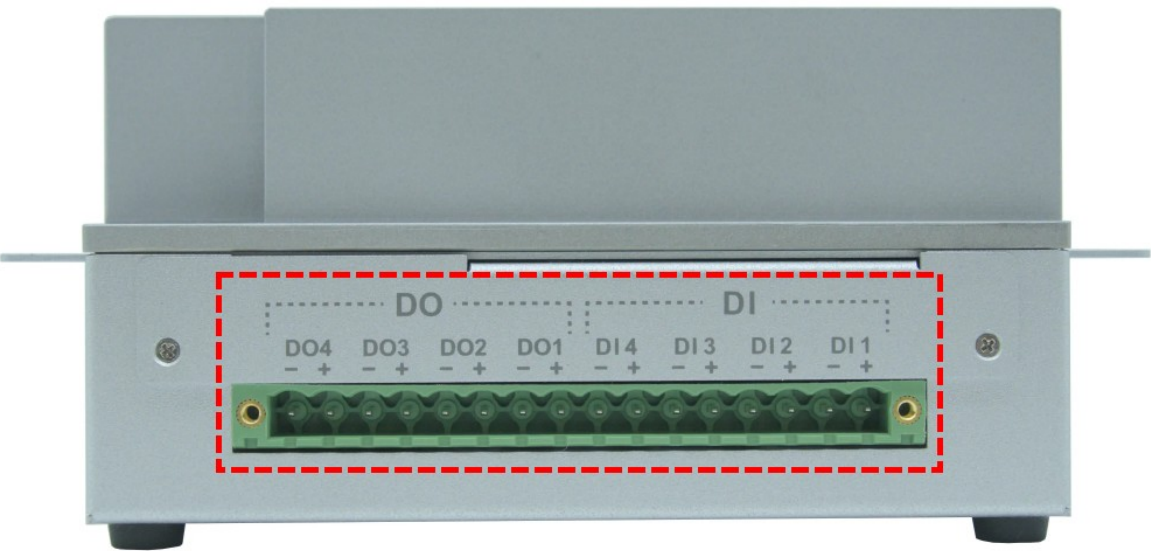
```
Bus 002 Device 001: ID 1d6b:0003 Linux Foundation 3.0 root hub
Bus 001 Device 074: ID 0955:7323 NVidia Corp.
Bus 001 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub
```

Jetson SoM	USB ID
Orin NX 16GB	0955:7323

Orin NX 8GB	0955:7423
Orin Nano 8GB	0955:7523
Orin Nano 4GB	0955:7623

4.3. DI/DO Pin Definition And Mapping

The DI/DO pin definition and mapping as below.



Pin mapping

DI1	PZ.03
DI2	PZ.04
DI3	PZ.05
DI4	PZ.06
DO1	PY.00
DO2	PY.01
DO3	PY.02
DO4	PY.03

Please use Linux kernel sysfs to control gpio.

Example for DI:

```
echo PZ.03 > /sys/class/gpio/export

echo in > /sys/class/gpio/PZ.03/direction

cat /sys/class/gpio/PZ.03/value

echo PZ.03 > /sys/class/gpio/unexport
```

Example for DO:

```
echo PY.00 > /sys/class/gpio/export

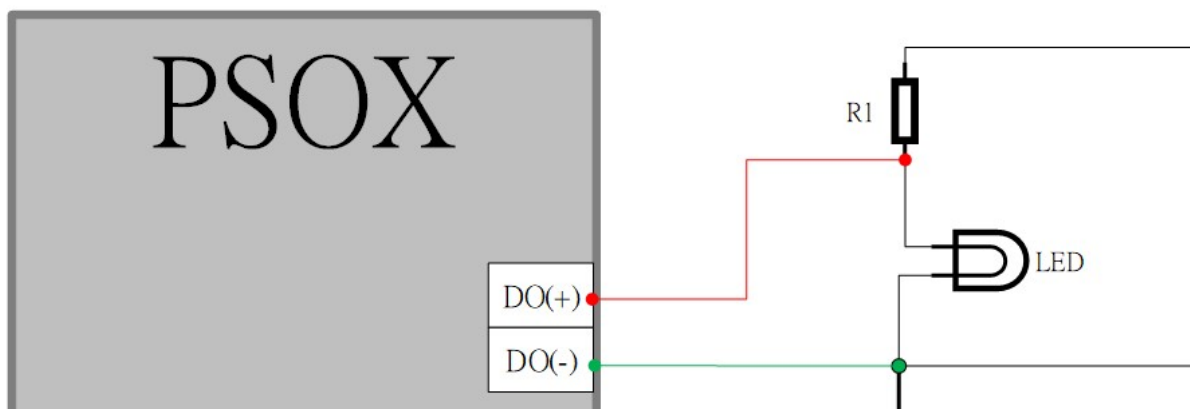
echo out > /sys/class/gpio/PY.00/direction

echo 1 > /sys/class/gpio/PY.00/value

echo 0 > /sys/class/gpio/PY.00/value

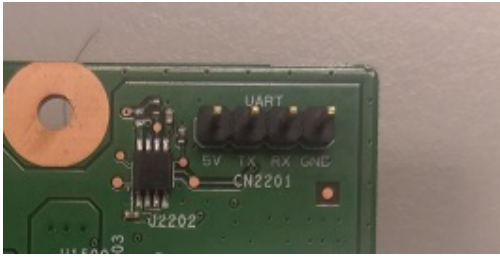
echo PY.00 > /sys/class/gpio/unexport
```

Reference schematic of DO (open drain/isolation):



Each DO port is capable of driving relay coils rated up to 150mA at 12V, 24V or 40V.

4.4. Use Serial Debug Console (Internal only)



Any serial port console program should work as a debug console. Examples are PuTTY, gtkTerm, and minicom. Connection speed is 115200, with 8 bits, no parity, and 1 stop bit (115200 8N1). Flow control will be RTS/CTS.

4.5. AIMobile Container Usage

Please check [readme.txt](#) on Ubuntu desktop about pre-installed AIMobile container usage including how to relocate the container image.

The AIMobile container image is pre-installed to root file system, it takes around 13GB, and it can be removed with “[docker system prune -af](#)” command.

```
aim@AIM-dev-4737:~$ docker images
REPOSITORY          TAG         IMAGE ID      CREATED       SIZE
aimobile/l4t-jetpack r35.4.1     353b9824dd21 2 weeks ago   12.9GB
```

