## Linear Algebra MATH 325: Assignment 4

(Due in class, February 11)

Problem 1: Determine the eigenvalues and the eigenspaces of the following two matrices

$$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$
 and  $\begin{pmatrix} 2 & 1 \\ -1 & 4 \end{pmatrix}$ ,

and if one of them is not diagonalizable give a Jordan basis for it.

**Solution.** Set  $A := \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$  and  $B := \begin{pmatrix} 2 & 1 \\ -1 & 4 \end{pmatrix}$ . We first compute the characteristic polynomials:

$$P_A(T) = T^2 + 1 = (T - i) \cdot (T + i),$$

where  $i = \sqrt{-1}$  is square root of -1, and

$$P_B(T) = T^2 - 6T + 9 = (T - 3)^2$$
.

Therefore A is diagonalizable with eigenvalues i and -i; in particular both eigenspaces of A have dimension 1 and are generated by an eigenvector. One checks a vector  $\begin{pmatrix} i \\ 1 \end{pmatrix}$  is an eigenvector for i, and  $\begin{pmatrix} -i \\ 1 \end{pmatrix}$  is an eigenvector for -i. Hence

$$E_i = \mathbb{C} \cdot \left( \begin{array}{c} i \\ 1 \end{array} \right)$$

and

$$E_{-i} = \mathbb{C} \cdot \left( \begin{array}{c} -i \\ 1 \end{array} \right).$$

The matrix B has only one eigenvalue 3 and is not diagonalizable. Indeed, assume that B is diagonalizable. Then there would be a matrix S such that

$$S^{-1}BS = \left(\begin{array}{cc} a & 0\\ 0 & b \end{array}\right).$$

where a, b are eigenvalues of B. But B has only one eigenvalue 3. It follows that a = b = 3, implying  $S^{-1}BS$  is a scalar matrix. As we explained in class this forces B to be a scalar matrix as well – a contradiction.

One checks that a vector  $\begin{pmatrix} 1\\1 \end{pmatrix}$  is an eigenvector for  $\lambda=3$  which generates the 1-dimensional eigenspace:

$$E_1 = \mathbb{C} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$
.

To get a Jordan basis one first extends this eigenvector to a basis of  $\mathbb{C}^2$ : Set

$$v := \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$
 and  $w' := \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ .

Then

$$B \cdot w' = \begin{pmatrix} 2 \\ -1 \end{pmatrix} = (-1) \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 3 \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

So in basis  $\{v.w'\}$  the corresponding linear map has the matrix

$$\left(\begin{array}{cc} 3 & -1 \\ 0 & 3 \end{array}\right).$$

Replacing w' by  $w = -w' = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$  one gets a Jordan basis v, w for B.

**Problem 2:** Let 
$$A = \begin{pmatrix} 3 & 2 & 0 \\ 0 & 1 & -1 \\ 1 & 1 & 1 \end{pmatrix}$$
.

- (i) Show that 1 and 2 are eigenvalues of A and that A is not diagonalizable.
- (ii) Decompose the two vectors  $v = \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix}$  into a sum of generalized eigenvectors.

## Solution.

(i) We compute first the characteristic polynomial:

$$P_A(T) = T^3 - 5T^2 + 8T - 4 = (T - 1) \cdot (T - 2)^2$$
.

Hence  $\lambda_1 = 1$  and  $\lambda_2 = 2$  are the eigenvalues of A. The matrix A is not diagonalizable since one checks that the dimension of the eigenspace  $E_2$  for the eigenvalue 2 is 1. (Recall that if a matrix of size  $n \times n$  is diagonalizable, then on the diagonal we have its eigenvalues, say  $\lambda_1, \ldots, \lambda_l$ , and

$$\dim(E_{\lambda_1}) + \cdots + \dim(E_{\lambda_l}) = n.$$

In our case we have n = 3,  $\lambda_1 = 1$ ,  $\lambda_2 = 2$  and  $\dim(E_1) = 1$ ,  $\dim(E_2) = 1$ .)

(ii) In the notation of the course notes we have  $f_1(T) = (T - \lambda_2)^2 = (T - 2)^2$  and  $f_2(T) = (T - \lambda_1) = T - 1$ . We have

$$1 = (T-2)^2 - (T-3) \cdot (T-1),$$

and so  $I_3 = (A-2\cdot I_3)^2 - (A-3\cdot I_3)\cdot (A-I_3)$  from which we get

$$v = (A - 2 \cdot I_3)^2 \cdot v - (A - 3 \cdot I_3) \cdot (A - I_3) \cdot v = v_1 + v_2$$

for all  $v \in \mathbb{C}^3$ . The vector

$$v_1 := (A - 2 \cdot \mathbf{I}_3)^2 \cdot v$$

is in the generalized eigenspace for  $\lambda_1 = 1$ , and the vector

$$v_2 := -(A - 3 \cdot \mathbf{I}_3) \cdot (A - \mathbf{I}_3) \cdot v$$

is in the generalized eigenspace for  $\lambda_2 = 2$ .

To compute the corresponding summands for the given vector v we first compute

$$(A - 2 \cdot I_3)^2 = \begin{pmatrix} 1 & 0 & -2 \\ -1 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix},$$

and

$$-(A-3\cdot I_3)\cdot (A-I_3) = \begin{pmatrix} 0 & 0 & 2 \\ 1 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix}.$$

Then  $v = v_1 + v_2$  with

$$v_1 = (A - 2 \cdot I_3)^2 \cdot v = \begin{pmatrix} 1 & 0 & -2 \\ -1 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} -5 \\ 5 \\ 0 \end{pmatrix} \in K_1(A),$$

and

$$v_2 = -(A - 3 \cdot I_3) \cdot (A - I_3) \cdot v = \begin{pmatrix} 0 & 0 & 2 \\ 1 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 6 \\ -4 \\ 3 \end{pmatrix} \in K_{2(A)}.$$

**Problem 3:** Show that the  $4 \times 4$ -matrix  $\begin{pmatrix} 2 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix}$  is not diagonalizable.

**Solution.** The characteristic polynomial of

$$A = \begin{pmatrix} 2 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

is  $P_A(T) = (T-2)^4$  and so 2 is the only eigenvalue of A. Hence A is diagonalizable if and only if the corresponding eigenspace  $E_2$  is the whole space  $\mathbb{C}^4$ . But this is not the case since

for instance  $\begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$  is not an eigenvector and so dimension  $E_2 \leq 3$ . (In fact, the dimension

of  $E_2$  is 1 since the rank of  $A-2\cdot I_4$  is obviously 3.)

**Problem 4:** Recall that the trace tr(A) of a  $n \times n$ -matrix  $A = (a_{ij})$  is defined as

$$\operatorname{tr}(A) := \sum_{i=1}^{n} a_{ii}.$$

Show that  $tr(A \cdot B) = tr(B \cdot A)$  for all  $n \times n$ -matrices A, B.

**Solution.** Let  $A = (a_{ij})$ ,  $B = (b_{ij})$ ,  $C = (c_{ij}) = A \cdot B$ , and  $D = (d_{ij}) = B \cdot A$ . Then

$$c_{ij} = \sum_{k=1}^{n} a_{ik} \cdot b_{kj}$$
 and  $d_{ij} = \sum_{k=1}^{n} b_{ik} \cdot a_{kj}$ .

Therefore

$$tr(A \cdot B) = \sum_{l=1}^{n} c_{ll} = \sum_{l=1}^{n} \sum_{k=1}^{n} a_{lk} \cdot b_{kl}$$
$$= \sum_{k=1}^{n} \sum_{l=1}^{n} b_{kl} \cdot a_{lk} = \sum_{k=1}^{n} d_{kk}$$
$$= tr(B \cdot A).$$