

Data acquisition with the ADS1115 on the raspberry PI

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Chapter 1

rpi_ads1115

Raspberry PI C++ library for the ADS1115

github: https://github.com/berndporr/rpi_ads1115

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

[ADS1115rpi](#)

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[ADS1115settings](#)

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Chapter 3

Class Documentation

3.1 ADS1115rpi Class Reference

This class reads data from the ADS1115 in the background (separate thread) and calls a callback function whenever data is available.

```
#include <ads1115rpi.h>
```

Public Member Functions

- `~ADS1115rpi ()`
Destructor which makes sure the data acquisition stops on exit.
- virtual void `hasSample (float sample)=0`
Called when a new sample is available.
- void `setChannel (ADS1115settings::Input channel)`
Selects a different channel at the multiplexer while running.
- void `start (ADS1115settings settings=ADS1115settings())`
Starts the data acquisition in the background and the callback is called with new samples.
- void `stop ()`
Stops the data acquisition.

3.1.1 Detailed Description

This class reads data from the ADS1115 in the background (separate thread) and calls a callback function whenever data is available.

3.1.2 Member Function Documentation

3.1.2.1 hasSample()

```
virtual void ADS1115rpi::hasSample (  
    float sample ) [pure virtual]
```

Called when a new sample is available.

This needs to be implemented in a derived class by the client. Defined as abstract.

Parameters

<i>sample</i>	Voltage from the selected channel.
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3.1.2.2 setChannel()

```
void ADS1115rpi::setChannel (
    ADS1115settings::Input channel )
```

Selects a different channel at the multiplexer while running.

Call this in the callback handler [hasSample\(\)](#) to cycle through different channels.

Parameters

<i>channel</i>	Sets the channel from A0..A3.
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3.1.2.3 start()

```
void ADS1115rpi::start (
    ADS1115settings settings = ADS1115settings() )
```

Starts the data acquisition in the background and the callback is called with new samples.

Parameters

<i>settings</i>	A struct with the settings.
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The documentation for this class was generated from the following file:

- ads1115rpi.h

3.2 ADS1115settings Struct Reference

ADS1115 initial settings when starting the device.

```
#include <ads1115rpi.h>
```

Public Types

- enum [SamplingRates](#) {
FS8HZ = 0, **FS16HZ** = 1, **FS32HZ** = 2, **FS64HZ** = 3,
FS128HZ = 4, **FS250HZ** = 5, **FS475HZ** = 6, **FS860HZ** = 7 }
Sampling rates.
- enum [PGA](#) { **FSR2_048** = 2, **FSR1_024** = 3, **FSR0_512** = 4, **FSR0_256** = 5 }
Full scale range: 2.048V, 1.024V, 0.512V or 0.256V.
- enum [Input](#) { **AIN0** = 0, **AIN1** = 1, **AIN2** = 2, **AIN3** = 3 }
Channel indices.

Public Attributes

- int [i2c_bus](#) = 1
I2C bus used (99% always set to one)
- uint8_t [address](#) = DEFAULT_ADS1115_ADDRESS
I2C address of the ads1115.
- [SamplingRates](#) [samplingRate](#) = FS8HZ
Sampling rate requested.
- [PGA](#) [pgaGain](#) = FSR2_048
Requested full scale range.
- [Input](#) [channel](#) = AIN0
Requested input channel (AIN0..AIN3)
- bool [initPIGPIO](#) = true
If set to true the pigpio will be initialised.
- int [drdy_gpio](#) = DEFAULT_ALERT_RDY_TO_GPIO
GPIO pin connected to ALERT/RDY.

3.2.1 Detailed Description

ADS1115 initial settings when starting the device.

The documentation for this struct was generated from the following file:

- ads1115rpi.h

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