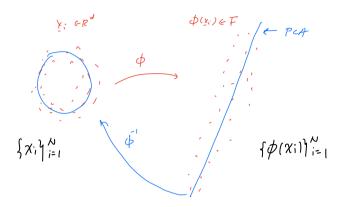
Kornel PCA - Making PCA non-linear



PCA on $\{\phi(\mathbf{x}_i)\}_{i=1}^N$ in the feature space F:

Suppose for the moment that the dataset is centered in F,

$$\sum_{i=0}^{N} \phi(\mathbf{x}_i) = 0.$$

• The sample covariance matrix is

$$C = \frac{1}{N} \sum_{i=1}^{N} \phi(\mathbf{x}_i) \phi(\mathbf{x}_i)^{T}.$$

• The principal components in *F* are the eigenvectors of *C*:

$$C\mathbf{v}_j = \lambda_j \mathbf{v}_j, \quad j = 1, \cdots, p$$

where the eigenvalues $\lambda_1 \geq \lambda_2 \geq \cdots$.

Finding the eigenvectors of C in F:

Using the definition of the covariant matrix, we have

$$\sum_{i=1}^{N} \left(\underbrace{\underbrace{\tilde{\mathbf{z}}_{i}^{N} i \cdot \tilde{\mathbf{x}}_{i}^{N}}_{i}}_{i} \right) \overset{\checkmark}{\mathbf{y}_{i}^{N}} \overset{\checkmark}{\mathbf{y}_{i}^{N}} = \overset{\checkmark}{\mathbf{y}_{i}^{N}} \qquad \underbrace{\frac{1}{N} \sum_{i=1}^{N} \phi(\mathbf{x}_{i}) \underbrace{\phi(\mathbf{x}_{i})}^{T} \mathbf{v}_{j}}_{i} = \lambda_{j} \mathbf{v}_{j}. \tag{1}$$

• \mathbf{v}_{j} is a linear combination of the features $\{\phi(\mathbf{x}_{i})\}_{i=1}^{N}$:

$$\mathbf{v}_{j} = \sum_{i=1}^{N} a_{ji} \phi(\mathbf{x}_{i}). \tag{2}$$

Next, we find a_{ji} . $\left\{ \begin{array}{c} a_{ji} \\ a_{ji} \end{array} \right\}_{i>j}^{j} \implies \forall j$

Substitute (3) Timbo(1):
$$\frac{1}{N} \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \phi(x_{1}) \phi(x_{1})^{T} \left(\stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \partial_{j} e \phi(x_{1}) \right) = \lambda_{j} \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \partial_{j} e \phi(x_{1})$$

$$\frac{1}{N} \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \phi(x_{1}) \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \partial_{j} e \phi(x_{1})^{T} \phi(x_{1}) = \lambda_{j} \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \partial_{j} e \phi(x_{1})^{T} \phi(x_{1})$$

$$\frac{1}{N} \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \phi(x_{1}) \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \partial_{j} e \phi(x_{1})^{T} \phi(x_{1}) = \lambda_{j} \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \partial_{j} e \phi(x_{1})^{T} \phi(x_{1})$$

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$$\frac{1}{N} \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} (x_{1}) \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \partial_{j} e \phi(x_{1})^{T} \phi(x_{1}) = \lambda_{j} \stackrel{\mathcal{L}}{\stackrel{!}{\rightleftharpoons}} \partial_{j} e \phi(x_{1})^{T} \phi(x_{1})$$

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 $\frac{1}{N}(KK) = \frac{1}{N} = \frac{1}{N} + \frac{1}{N} =$

Good:
$$\forall j - pc \text{ of } |p(x_i)| \text{ in } F$$
 $\forall j = \sum_{i=1}^{N} \alpha_j |p(x_i)|$
 $|\alpha_j|_{i=1}^{N} \text{ can be obtained by solving } |k\alpha_j = N \rangle_j \alpha_j$

Normalize $\forall j : 1 = || \forall j ||_i =$

Solve aj from Kaj = Nijaj with Nijajaj = 1 (Normalization andition)

Summary:

 \bullet The principal components in the feature space ${\it F}$ are given by

$$\mathbf{v}_j = \sum_{i=1}^N a_{ji} \phi(\mathbf{x}_i), \quad j = 1, \cdots, p$$

 The coefficients a_{jj} are computed from the eigenvectors of the kernel matrix K.

$$K\mathbf{a}_{j} = N\lambda_{j}\mathbf{a}_{j}, \quad j = 1, \cdots, p$$

with the constraint

$$N\lambda_i \mathbf{a}_i^T \mathbf{a}_i = 1$$

project
$$\phi(\underline{X}i)$$
 onto $\underline{Y}j: [\phi(\underline{X}i)^T\underline{Y}j]\underline{Y}j$

principal component score

$$\psi(\underline{x}_i)^T \underline{y}_j = \psi(\underline{x}_i)^T \underbrace{\sum_{i=1}^N a_j e}_{\neq i} \phi(\underline{x}_i) = \underbrace{\sum_{i=1}^N a_j e}_{\neq i} \phi(\underline{x}_i)^T \phi(\underline{x}_i) = \underbrace{\sum_{i=1}^N a_$$

To find the principal score along y_j , all we need are the wefficients $\{\underline{d}_j\}_{i=1}^N$ and the kernels $K(\underline{X},\underline{X}_i)$

- So far, we have assumed the features $\{\phi(\mathbf{x}_i)\}_{i=1}^N$ are centered. In general, however, the features $\{\phi(\mathbf{x}_i)\}_{i=1}^N$ may not be centered, even if $\{\mathbf{x}_i\}_{i=1}^N$ is centered.
- Center the features:

$$\tilde{\phi}_i = \phi_i - \frac{1}{N} \sum_{k=1}^N \phi_k,$$

where $\phi_i = \phi(\mathbf{x}_i)$. Then the kernel matrix of the centered features is given by

$$\tilde{K} = K - \frac{1}{N} \frac{1}{1} K - \frac{1}{N} K \mathbf{1} + \frac{1}{N^2} \mathbf{1} K \mathbf{1}$$

where **1** is the $N \times N$ matrix of all 1's and K is the kernel matrix of $\{\phi(\mathbf{x}_i)\}_{i=1}^N$.

$$\widetilde{\mathcal{K}} = \left(\widetilde{\phi}(\widetilde{x}_i)^{\top}\widetilde{\phi}(\widetilde{x}_j)\right)_{N\times N} \qquad \mathcal{K} = \left(\phi(\widetilde{x}_i)^{\top}\phi(\widetilde{x}_j)\right)_{N\times N}$$

Summary of kernel PCA:

1) Pick a kernel

$$k(\mathbf{x}_i,\mathbf{x}_i): R^d \times R^d \to R.$$

2) Construct the kernel matrix K:

$$(K)_{ij} = k(\mathbf{x}_i, \mathbf{x}_i), \quad i, j = 1, \cdots, N$$

Construct the centered kernel matrix \tilde{K} :

$$\tilde{K} = K - \frac{1}{N} 1K - \frac{1}{N} K 1 + \frac{1}{N^2} 1K 1$$

3) Compute the first p eigenvectors of \tilde{K} :

$$\tilde{K}$$
a_i = $N\lambda_i$ **a**_i, $j = 1, \cdots, p$

with the normalization constraint $N\lambda_j \mathbf{a}_i^T \mathbf{a}_j = 1$.

4) Given a data point **x**, its principal component scores along the principal component axis in the feature space are

$$y_j = \sum_{i=1}^N a_{ji} \tilde{k}(\mathbf{x}, \mathbf{x}_i), \quad j = 1, \cdots, p$$

where

$$\tilde{k}(\mathbf{x}, \mathbf{x}_i) = k(\mathbf{x}, \mathbf{x}_i) - \frac{1}{N} \sum_{l=1}^{N} k(\mathbf{x}, \mathbf{x}_l) - \frac{1}{N} \sum_{n=1}^{N} k(\mathbf{x}_n, \mathbf{x}_i) + \frac{1}{N^2} \sum_{n=1}^{N} \sum_{l=1}^{N} k(\mathbf{x}_n, \mathbf{x}_l).$$

In this algorithm, we projected the data $\{\phi(\mathbf{x}_i)\}$ onto p principal components in the feature space.