

Hybrid Programming



Hybrid Programming

- Hybrid programming here stands for the interaction of OpenMP with a lower-level programming model, e.g.
 - OpenCL
 - CUDA
 - HIP



Hybrid Programming

- Hybrid programming here stands for the interaction of OpenMP with a lower-level programming model, e.g.
 - OpenCL
 - CUDA
 - HIP
- OpenMP supports these interactions
 - Calling low-level kernels from OpenMP application code
 - Calling OpenMP kernels from low-level application code



Example: Calling saxpy

```
void example(){
 float a = 2.0;
 float * x;
 float * y;
 // allocate the device memory
 #pragma omp target data map(to:x[0:count]) map(tofrom:y[0:count])
  compute_{1}(n, x);
  compute_2(n, y);
          saxpy(n, a, x, y)
  compute_3(n, y);
```



Example: Calling saxpy

```
void example(){
 float a = 2.0;
 float * x;
 float * y;
 // allocate the device memory
 #pragma omp target data map(to:x[0:count]) map(tofrom:y[0:count])
                                                                 void saxpy(size__t n, float a,
  compute__(n, x);
                                                                     float * x, float * y) {
                                                                 #pragma omp target teams distribute \
   compute 2(n, v):
                                                                         parallel for simd
           $axpy(n, a, x, y)
                                                                   for (size__t i = 0; i < n; ++i) {
   compute__3(n, y);
                                                                    y[i] = a * x[i] + y[i];
```



Example: Calling saxpy

```
void example(){
 float a = 2.0;
                                                                                      Let's assume that we want to
 float * x;
                                                                                     implement the saxpy() function
 float * y;
                                                                                          in a low-level language.
 // allocate the device memory
 #pragma omp target data map(to:x[0:count]) map(tofrom:y[0:count])
                                                               void saxpy(size__t n, float a,
  compute__(n, x);
                                                                   float * x, float * y) {
                                                               #pragma omp target teams distribute \
   compute 2(n, v):
                                                                      parallel for simd
           $axpy(n, a, x, y)
                                                                 for (size__t i = 0; i < n; ++i) {
  compute__3(n, y);
                                                                  y[i] = a * x[i] + y[i];
```



HIP Kernel for saxpy()

```
___global___void saxpy__kernel(size__tn, float a, float * x, float * y) {
    size__ti = threadIdx.x + blockIdx.x * blockDim.x;
    y[i] = a * x[i] + y[i];
}

void saxpy__hip(size__tn, float a, float * x, float * y) {
    assert(n % 256 == 0);
    saxpy__kernel<<<<n/>/256,256,0,NULL>>>(n, a, x, y);
}
```



HIP Kernel for saxpy()

These are device pointers!



HIP Kernel for saxpy()

Assume a HIP version of the SAXPY kernel:

 We need a way to translate the host pointer that was mapped by OpenMP directives and retrieve the associated device pointer.



- When creating the device data environment, OpenMP creates a mapping between
 - the (virtual) memory pointer on the host and
 - the (virtual) memory pointer on the target device.

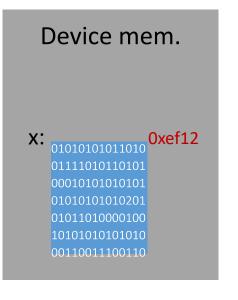
Host memory



- When creating the device data environment, OpenMP creates a mapping between
 - the (virtual) memory pointer on the host and
 - the (virtual) memory pointer on the target device.
- This mapping is established through the data-mapping directives and their clauses.

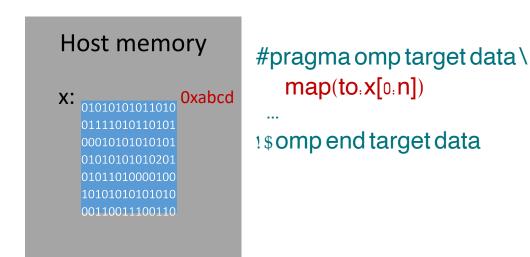


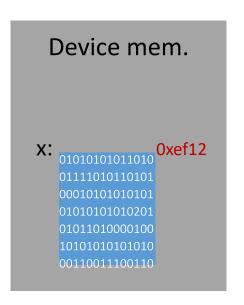
- When creating the device data environment, OpenMP creates a mapping between
 - the (virtual) memory pointer on the host and
 - the (virtual) memory pointer on the target device.
- This mapping is established through the data-mapping directives and their clauses.

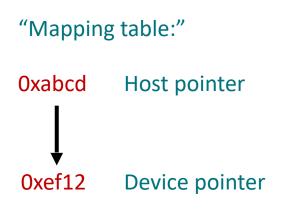




- When creating the device data environment, OpenMP creates a mapping between
 - the (virtual) memory pointer on the host and
 - the (virtual) memory pointer on the target device.
- This mapping is established through the data-mapping directives and their clauses.



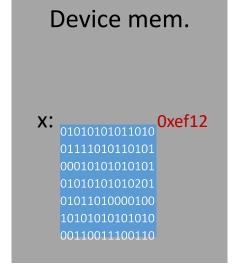


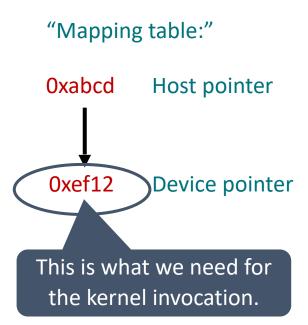




- When creating the device data environment, OpenMP creates a mapping between
 - the (virtual) memory pointer on the host and
 - the (virtual) memory pointer on the target device.
- This mapping is established through the data-mapping directives and their clauses.

#pragma omp target data\
 map(to:x[0:n])
...
!\$omp end target data







- The target data construct defines the use__device__ptr clause to perform pointer translation.
 - The OpenMP implementation searches for the host pointer in its internal mapping tables.
 - The associated device pointer is then returned.

```
type * x = oxabcd;
#pragma omp target data use__device__ptr(x)
{
    example__func(x); // x == oxefiz
}
```

 Note: the pointer variable shadowed within the target data construct for the translation.



Putting it Together...

```
void example(){
 float a = 2.0;
 float * x = ...; // assume: x = 0xabcd
 float * y = ...;
 // allocate the device memory
 #pragma omp target data map(to:x[0:count]) map(tofrom:y[0:count])
  compute___(n, x); // mapping table. x.[oxabcd,oxefiz], x = oxabcd
  compute_2(n, y);
  #pragma omp target data use__device__ptr(x,y)
            saxpy_hip(n, a, x, y) // mapping table: x = [0xabcd, 0xefi2], x = 0xefi2
  compute_3(n, y);
```



Advanced Task Synchronization



Asynchronous API Interaction

- Some APIs are based on asynchronous operations
 - MPI asynchronous send and receive
 - Asynchronous I/O
 - HIP, CUDA and OpenCL stream-based offloading
 - In general: any other API/model that executes asynchronously with OpenMP (tasks)



Asynchronous API Interaction

- Some APIs are based on asynchronous operations
 - MPI asynchronous send and receive
 - Asynchronous I/O
 - HIP, CUDA and OpenCL stream-based offloading
 - In general: any other API/model that executes asynchronously with OpenMP (tasks)
- Example: HIP memory transfers

```
do_something();
hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
do_something_else();
hipStreamSynchronize(stream);
do_other_important_stuff(dst);
```



Asynchronous API Interaction

- Some APIs are based on asynchronous operations
 - MPI asynchronous send and receive
 - Asynchronous I/O
 - HIP, CUDA and OpenCL stream-based offloading
 - In general: any other API/model that executes asynchronously with OpenMP (tasks)
- Example: HIP memory transfers

```
do_something();
hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
do_something_else();
hipStreamSynchronize(stream);
do_other_important_stuff(dst);
```

- Programmers need a mechanism to marry asynchronous APIs with the parallel task model of OpenMP
 - How to synchronize completions events with task execution?



Try 1: Use just OpenMP Tasks

```
void hip__example() {
#pragma omp task // task A
  do_something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
 #pragma omp task // task B
  do__something__else();
 #pragma omp task // task C
  hipStreamSynchronize(stream);
  do__other__important__stuff(dst);
```



Try 1: Use just OpenMP Tasks

```
void hip__example() {
#pragma omp task // task A
  do_something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
                                           Race condition between the tasks A & C,
 #pragma omp task // task B
                                           task C may start execution before
  do__something__else();
                                           task A enqueues memory transfer.
 #pragma omp task // task C
  hipStreamSynchronize(stream);
  do__other__important__stuff(dst);
```



Try 1: Use just OpenMP Tasks

```
void hip__example(){
#pragma omp task // task A
  do_something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
                                           Race condition between the tasks A & C,
 #pragma omp task // task B
                                           task C may start execution before
  do__something__else();
                                           task A enqueues memory transfer.
 #pragma omp task // task C
  hipStreamSynchronize(stream);
  do__other__important__stuff(dst);
```

This solution does not work!



Try 2: Use just OpenMP Tasks Dependences

```
void hip__example(){
#pragma omp task depend(out.stream) // task A
  do_something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
 #pragma omp task
                        //taskB
  do_something_else();
 #pragma omp task depend(in:stream) // task C
  hipStreamSynchronize(stream);
  do__other__important__stuff(dst);
```



Try 2: Use just OpenMP Tasks Dependences

```
void hip__example(){
#pragma omp task depend(out.stream) // task A
  do__something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHos, stream);
 #pragma omp task
                        //taskB
  do_something_else();
 #pragma omp task depend(in stream) // task C
  hipStreamSynchronize(stream);
  do__other__important__stuff(dst);
```

Synchronize execution of tasks through dependence. May work, but task C will be blocked waiting for the data transfer to finish



Try 2: Use just OpenMP Tasks Dependences

```
void hip__example(){
#pragma omp task depend(out.stream) // task A
  do__something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHos, stream);
                                                              Synchronize execution of tasks through dependence.
 #pragma omp task
                        //taskB
                                                             May work, but task C will be blocked waiting for
  do_something_else();
                                                             the data transfer to finish
 #pragma omp task depend(in stream) // task C
  hipStreamSynchronize(stream);
  do__other__important__stuff(dst);
```

- This solution may work, but
 - takes a thread away from execution while the system is handling the data transfer.
 - may be problematic if called interface is not thread-safe



- OpenMP 5.0 introduces the concept of a detachable task
 - Task can detach from executing thread without being "completed"
 - Regular task synchronization mechanisms can be applied to await completion of a detached task
 - Runtime API to complete a task



- OpenMP 5.0 introduces the concept of a detachable task
 - Task can detach from executing thread without being "completed"
 - Regular task synchronization mechanisms can be applied to await completion of a detached task
 - Runtime API to complete a task

Detached task events: omp__event__t datatype



- OpenMP 5.0 introduces the concept of a detachable task
 - Task can detach from executing thread without being "completed"
 - Regular task synchronization mechanisms can be applied to await completion of a detached task
 - Runtime API to complete a task

- Detached task events: omp__event__t datatype
- Detached task clause: detach(event)



- OpenMP 5.0 introduces the concept of a detachable task
 - Task can detach from executing thread without being "completed"
 - Regular task synchronization mechanisms can be applied to await completion of a detached task
 - Runtime API to complete a task

- Detached task events: omp__event__t datatype
- Detached task clause: detach(event)
- Runtime API: void omp__fulfill__event(omp__event__t *event)



```
omp__event__t *event;
void detach__example() {
    #pragma omp task detach(event)
    {
        important__code();
    }

    #pragma omp taskwait
}
```



```
omp__event__t *event;
void detach__example() {
    #pragma omp task detach(event)
    {
        important__code();
    }
    #pragma omp taskwait
}
```

1. Task detaches



```
omp__event__t *event;
void detach__example(){
#pragma omp task detach(event)
    {
      important__code();
    }
    #pragma omp taskwait
}
```

- Task detaches
- 2. taskwait construct cannot complete



```
omp_event_t*event;
void detach_example() {
    #pragma omp task detach(event)
    {
        important_code();
    }
    #pragma omp taskwait
}
Some other thread/task:

omp_fulfill_event(event);

3
```

- Task detaches
- 2. taskwait construct cannot complete

3. Signal event for completion



```
omp_event_t*event;
void detach_example() {
    #pragma omp task detach(event)
    {
        important_code();
    }
    #pragma omp taskwait
    }
    **gragma omp taskwait
}

Some other thread/task:
    omp_fulfill_event(event);
    3
```

- Task detaches
- 2. taskwait construct cannot complete

- 3. Signal event for completion
- 4. Task completes and taskwait can continue



Putting It All Together

```
void callback(hipStream__t stream, hipError__t status, void *cb__dat) {
   omp__fulfill__event((omp__event__t*) cb__data);
void hip__example() {
 omp__event__t*hip__event;
#pragma omp task detach(hip_event) // task A
  do_something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
  hipStreamAddCallback(stream, callback, hip__event, 0);
#pragma omp task
                       //taskB
  do__something__else();
#pragma omp taskwait
#pragma omp task
                       //task C
  do__other__important__stuff(dst);
} }
```



```
void callback(hipStream__t stream, hipError__t status, void *cb__dat) {
   omp__fulfill__event((omp__event__t*) cb__data);
void hip__example(){
 omp__event__t*hip__event;
#pragma omp task detach(hip_event) // task A
  do_something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
  hipStreamAddCallback(stream, callback, hip_event, 0);
#pragma omp task
                       //taskB
  do__something__else();
                                                                   Task A detaches
#pragma omp taskwait
#pragma omp task
                       //task C
  do__other__important__stuff(dst);
} }
```



```
void callback(hipStream__t stream, hipError__t status, void *cb__dat) {
   omp__fulfill__event((omp__event__t*) cb__data);
void hip__example(){
 omp__event__t*hip__event;
#pragma omp task detach(hip_event) // task A
  do_something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
  hipStreamAddCallback(stream, callback, hip_event, 0);
#pragma omp task
                       //taskB
  do__something__else();
                                                                   Task A detaches
#pragma omp taskwait
                                                                   taskwait does not continue
#pragma omp task
  do__other__important__stuff(dst);
} }
```



} }

```
void callback(hipStream__t stream, hipError__t status, void *cb__dat) {
  p_fulfill_event((omp_event_t*)cb_data);
void hip__example() {
 omp__event__t*hip__event;
#pragma omp task detach(hip_event) // task A
  do_something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
  hipStreamAddCallback(stream, callback, hip_event, 0);
#pragma omp task
                       //taskB
  do__something__else();
                                                                  Task A detaches
#pragma omp taskwait
                                                                 taskwait does not continue
#pragma omp task
                                                                  When memory transfer completes, callback is
                                                                  invoked to signal the event for task completion
  do_other_important_stuff(dst);
```



```
void callback(hipStream__t stream, hipError__t status, void *cb__dat) {
  p_fulfill_event((omp_event_t*) cb_data);
void hip__example(){
 omp__event__t*hip__event;
#pragma omp task detach(hip_event) // task A
  do_something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
  hipStreamAddCallback(stream, callback, hip_event, 0);
#pragma omp task
                       //taskB
  do__something__else();
#pragma omp taskwait
#pragma omp task
  do_other_important_stuff(dst);
} }
```

- Task A detaches
- taskwait does not continue
- When memory transfer completes, callback is invoked to signal the event for task completion
- taskwait continues, task C executes



```
void callback(hipStream__t stream, hipError__t status, void *cb__dat) {
   omp__fulfill__event((omp__event__t*) cb__data);
void hip__example() {
 omp__event__t*hip__event;
#pragma omp task depend(out.dst) detach(hip_event) // task A
  do__something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
  hipStreamAddCallback(stream, callback, hip_event, 0);
#pragma omp task
                        //taskB
  do__something__else();
#pragma omp task depend(in.dst) // task C
  do__other__important__stuff(dst);
} }
```



```
void callback(hipStream__t stream, hipError__t status, void *cb__dat) {
   omp__fulfill__event((omp__event__t*) cb__data);
void hip__example(){
 omp__event__t*hip__event;
#pragma omp task depend(out.dst) detach(hip_event) // task A
  do__something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
  hipStreamAddCallback(stream, callback, hip_event, 0);
#pragma omp task
                        //taskB
  do__something__else();
                                                                    Task A detaches and task C will not execute because
                                                                    of its unfulfilled dependency on A
#pragma omp task depend(in.dst) // task C
  do__other__important__stuff(dst);
} }
```



```
void callback(hipStream__t stream, hipError__t status, void *cb__dat) {
         _fulfill__event((omp__event__t*)cb__data);
void hip__example() {
 omp__event__t*hip__event;
#pragma omp task depend(out.dst) detach(hip_event) // task A
  do__something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
   hipStreamAddCallback(stream, callback, hip_event, 0);
#pragma omp task
                        //taskB
  do_something_else();
#pragma omp task depend(in.dst) // task C
  do__other__important__stuff(dst);
} }
```

- Task A detaches and task C will not execute because of its unfulfilled dependency on A
- When memory transfer completes, callback is invoked to signal the event for task completion



```
void callback(hipStream_t stream, hipError_t status, void *cb__dat) {
         _fulfill__event((omp__event__t*)cb__data);
void hip__example(){
 omp__event__t*hip__event;
#pragma omp task depend(out.dst) detach(hip_event) // task A
  do__something();
  hipMemcpyAsync(dst, src, nbytes, hipMemcpyDeviceToHost, stream);
   hipStreamAddCallback(stream, callback, hip_event, 0);
#pragma omp task
                        //taskB
  do__something__else();
#pragma omp task depend(in.dst) // task C
  do_other_important_stuff(dst);
} }
```

- Task A detaches and task C will not execute because of its unfulfilled dependency on A
- 2. When memory transfer completes, callback is invoked to signal the event for task completion
- 3. Task A completes and C's dependency is fulfilled



Case Study: NWChem TCE CCSD(T)

TCE: Tensor Contraction Engine

CCSD(T): Coupled-Cluster with Single, Double,

and perturbative Triple replacements



NWChem

- Computational chemistry software package
 - Quantum chemistry
 - Molecular dynamics
- Designed for large-scale supercomputers
- Developed at the EMSL at PNNL
 - EMSL: Environmental Molecular Sciences Laboratory
 - PNNL: Pacific Northwest National Lab
- URL: http://www.nwchem-sw.org



Finding Offload Candidates

- Requirements for offload candidates
 - Compute-intensive code regions (kernels)
 - Highly parallel
 - Compute scaling stronger than data transfer, e.g., compute O(n³) vs. data size O(n²)



Example Kernel (1 of 27 in total)

```
subroutine sd_t_di_i(h3d,h2d,hid,p6d,p5d,p4d,
       h7d,triplesx,t2sub,v2sub)
c Declarations omitted.
  double precision triplesx(h3d*h2d,hid,p6d,p5d,p4d)
  double precision t2sub(h7d,p4d,p5d,hid)
  double precision v2sub(h3d*h2d,p6d,h7d)
1$omp target "presence?(triplesx,t2sub,v2sub)"
1$ omp teams distribute parallel do private(p4,p5,p6,h2,h3,h1,h7)
  do p4=1,p4d
  do p5=1,p5d
  do p6=1,p6d
  do hi=i,hid
  do h7=1,h7d
  do h_2h_3=1,h_3d*h_2d
  triplesx(h_2h_3,h_1,p_6,p_5,p_4)=triplesx(h_2h_3,h_1,p_6,p_5,p_4)
 1 - t2sub(h7,p4,p5,h1)*v2sub(h2h3,p6,h7)
  end do
  end do
  end do
  end do
  end do
  end do
1$ omp end teams distribute parallel do
1$ omp end target
  end subroutine
```

- All kernels have the same structure
- 7 perfectly nested loops
- Some kernels contain inner product loop (then, 6 perfectly nested loops)
- Trip count per loop is equal to "tile size" (20-30 in production)



Example Kernel (1 of 27 in total)

```
subroutine sd_t_di_i(h3d,h2d,hid,p6d,p5d,p4d,
       h7d,triplesx,t2sub,v2sub)
c Declarations omitted.
 double precision triplesx(h3d*h2d,hid,p6d,p5d,p4d)
 double precision t2sub(h7d,p4d,p5d,hid)
 double precision v2sub(h3d*h2d,p6d,h7d)
1$omp target "presence?(triplesx,t2sub,v2sub)"
1$ omp teams distribute parallel do private(p4,p5,p6,h2,h3,h1,h7)
 do p4=1,p4d
 do p5=1,p5d
 do p6=1,p6d
 do hi=i,hid
 do h7=1,h7d
 do h_2h_3=1,h_3d*h_2d
  triplesx(h_2h_3,h_1,p_6,p_5,p_4)=triplesx(h_2h_3,h_1,p_6,p_5,p_4)
 1 - t2sub(h7,p4,p5,h1)*v2sub(h2h3,p6,h7)
 end do
 end do
 end do
 end do
 end do
 end do
1$ omp end teams distribute parallel do
1$ omp end target
 end subroutine
```

- All kernels have the same structure
- 7 perfectly nested loops
- Some kernels contain inner product loop (then, 6 perfectly nested loops)
- Trip count per loop is equal to "tile size" (20-30 in production)
- Naïve data allocation (tile size 24)
 - Per-array transfer for each target construct
 - triplesx: 1458 MB
 - t2sub, v2sub: 2.5 MB each



Example Kernel (1 of 27 in total)

```
subroutine sd_t_di_i(h3d,h2d,hid,p6d,p5d,p4d,
       h7d,triplesx,t2sub,v2sub)
c Declarations omitted.
 double precision triplesx(h3d*h2d,hid,p6d,p5d,p4d)
 double precision t2sub(h7d,p4d,p5d,hid)
 double precision v2sub(h3d*h2d,p6d,h7d)
1$omp target "presence?(triplesx,t2sub,v2sub)"
1$ omp teams distribute parallel do private(p4,p5,p6,h2,h3,h1,h7)
 do p4=1,p4d
 do p5=1,p5d
                                    1.5GB data transferred
 do p6=1,p6d
 do hi=i,hid
                                         (host to device)
 do h7=1,h7d
 do h_2h_3=1,h_3d*h_2d
  triplesx(h_2h_3,h_1,p_6,p_5,p_4)=triplesx(h_2h_3,h_1,p_6,p_5,p_4)
 1 - t2sub(h7,p4,p5,h1)*v2sub(h2h3,p6,h7)
 end do
 end do
                              1.5GB data transferred
 end do
 end do
                                   (device to host)
 end do
 end do
1$ omp end teams distribut parallel do
1$ omp end target
 end subroutine
```

- All kernels have the same structure
- 7 perfectly nested loops
- Some kernels contain inner product loop (then, 6 perfectly nested loops)
- Trip count per loop is equal to "tile size" (20-30 in production)
- Naïve data allocation (tile size 24)
 - Per-array transfer for each target construct
 - triplesx: 1458 MB
 - t2sub, v2sub: 2.5 MB each



Simplified pseudo-code

```
1$ omp target enter data map(alloc.triplesx(I:tr_size))
c for all tiles
  do...
  call zero__triplesx(triplesx)
  do...
   call comm_and_sort(t2sub, v2sub)
1$ omp target data map(to:t2sub(t2_size)) map(to:v2sub(v2_size))
   if (...)
    call sd_t_dı__(h3d,h2d,hid,p6d,p5d,p4d,h7,triplesx,t2sub,v2sub)
   end if
    same for sd_t_di_2 until sd_t_di_9
1$ omp target end data
  end do
  do...
    Similar structure for sd_t_d2_1 until sd_t_d2_9, incl. target data
  end do
  call sum_energy(energy, triplesx)
  end do
1$ omp target exit data map(release:triplesx(I.size))
```

Reduced data transfers:



Simplified pseudo-code

```
1$ omp target enter data map(alloc.triplesx(I:tr_size))
c for all tiles
  do...
  call zero__triplesx(triplesx)
                                                               Allocate 1.5GB data once,
  do...
                                                                     stays on device.
   call comm_and_sort(t2sub, v2sub)
1$ omp target data map(to:t2sub(t2_size)) map(to:v2sub(v2_size))
   if (...)
    call sd_t_dı__(h3d,h2d,hid,p6d,p5d,p4d,h7,triplesx,t2sub,v2sub)
   end if
    same for sd_t_di_2 until sd_t_di_9
1$ omp target end data
  end do
  do...
    Similar structure for sd_t_d2_1 until sd_t_d2_9, incl. target data
  end do
  call sum_energy(energy, triplesx)
  end do
1$ omp target exit data map(release:triplesx(I.size))
```

- Reduced data transfers:
 - triplesx:
 - allocated once
 - always kept on the target



Simplified pseudo-code

```
1$ omp target enter data map(alloc:triplesx(1:tr_size))
c for all tiles
  do...
  call zero__triplesx(triplesx)
                                                              Allocate 1.5GB data once,
  do...
                                                                    stays on device.
   call comm_and_sort(t2sub, v2sub)
1$ omp target data map(to:t2sub(t2_size)) map(to:v2sub(v2_size))
   if (...)
    call sd_t_di_i(h3d,h2d,hid,p6d,p5d,p4d,h7,triplesx,t2st
   end if
                                                              Update 2x2.5MB of data for
    same for sd_t_di_2 until sd_t_di_9
1$ omp target end data
                                                              (potentially) multiple kernels.
  end do
  do...
    Similar structure for sd_t_d2_1 until sd_t_d2_9, incl. target data
  end do
  call sum_energy(energy, triplesx)
  end do
1$ omp target exit data map(release:triplesx(I.size))
```

Reduced data transfers:

- triplesx:
 - allocated once
 - always kept on the target
- t2sub, v2sub:
 - allocated after comm.
 - kept for (multiple) kernel invocations



