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Team Reference Document for ICPC WORLD FINALS, EGYPT

Updated: April 2024

Contents

1 DP

1.1 CHT

```cpp
/*
 *   Lines should be added non-increasing order of m
 ↪   for minimizing
 Non-decreasing order of m for maximizing
 *   Intersection point of two lines (m1,c1) , (m2,c2)
 ↪   is
 x = (c2-c1)/(m1-m2)
 */
ll M[MAX] , C[MAX];
struct CHT {
  int len , cur;
  void init() {
    len = 0 ,cur = 0;
  }
  // returns true if line[len-1] is unnecessary when
   ↪  we add line(nm,nc)
  inline bool isBad(ll nm,ll nc) {
    return ( (C[len-1]-C[len-2])/(double)(M[len-2]-M[l
        en-1]) >= (nc-C[len-2])/(double)(M[len-2]-nm)
    ↪   );
    //return ( (C[len-1]-C[len-2])*(M[len-2]-nm) >=
    ↪   (M[len-2]-M[len-1])*(nc-C[len-2]) );
  }
  inline void addLine(ll nm,ll nc) {
    if(len == 0) M[len] = nm , C[len] = nc , ++len;
    else if( M[len-1] == nm ) {
      if(C[len-1] <= nc) return; // <= to minimize, >=
      ↪   to maximize
      else C[len-1] = nc;
    }
    else {
      while(len >= 2 && isBad(nm,nc)) --len;
      M[len] = nm , C[len] = nc , ++len;
    }
  }
  inline ll getY(int id , ll x) {
    return ( M[id]*x + C[id] );
  }
  inline ll sortedQuery( ll x ) {
```

```
    if(cur >= len ) cur = len-1;
    while( cur < len-1 && getY(cur+1,x) >= getY(cur,x) ) cur++; // <= to minimize, >= to maximize
    return getY(cur,x);
  }
  inline ll TS( ll x ) {
    int low = 0, high = len-1 , mid ;
    while( high - low > 1 ) {
      mid = low + high >> 1;
      if(getY(mid,x) < getY(mid+1,x)) low = mid + 1; // > to minimize , < to maximize
      else high = mid;
    }
    return max(getY(low,x),getY(high,x)); // adjust min/max
  }
};
CHT cht;
cht.init();
```

1.2 DC_Optimization

```
void compute(int L, int R, int optL, int optR){
  if(L > R) return;
  int M = L + R >> 1;
  pair<ll, int> best(1LL << 60, -1);
  for(int k = optL; k <= min(M, optR); k++){
    best = min(best, {dp[prv][k] + C[k + 1][M], k});
  }
  dp[now][M] = best.ff;
  compute(L, M - 1, optL, best.ss);
  compute(M + 1, R, best.ss, optR);
}
```

1.3 SOS_DP

```
/*
    S(mask,i) denotes those submasks of mask which differ
    from mask only in the least significant i+1 bits ( 0, 1, 2, ...., i --> 0 based indexing)
    Example : S(1011010,3) = {1011010,1010010,1011000,1010000}

    if(bit i is on)
        S(mask, i) = S(mask, i - 1) U S(mask ^ (1<<i), i - 1)
    else
        S(mask, i) = S(mask, i - 1)

    Let Sum(mask,i) denote the sum of the all A[x] where x element of S(mask,i)
    So, Sum(mask,N-1) will contain SOS DP result for a particular mask
    Recurrence :
    if(i'th bit is on)
        Sum(mask, i) = Sum(mask, i-1) + Sum(mask ^ (1<<i), i-1)
    else
        Sum(mask, i) = Sum(mask, i-1)
*/
    for(int mask = 0; mask < (1<<N); ++mask){
        dp[mask][-1] = A[mask];
        for(int i = 0;i < N; ++i){
            if(mask & (1<<i)) dp[mask][i] = dp[mask][i-1] + dp[mask ^ (1<<i)][i-1];
            else dp[mask][i] = dp[mask][i-1];
        }
        F[mask] = dp[mask][N-1];
    }
    for(int i = 0; i<(1<<N); ++i) F[i] = A[i];
    for(int i = 0;i < N; ++i)
        for(int mask = 0; mask < (1<<N); ++mask){
            if(mask & (1<<i))
                F[mask] += F[mask^(1<<i)];
        }

/*
 * c = x&-x, r = x+c; (((r^x) >> 2)/c) | r is the next number after x with the same number of bits set.
 */
```

1.4 dynamic_cht

```
//add lines with -m and -b and return -ans to
//make this code work for minimums.(not -x)
const ll inf = -(1LL << 62);
struct line {
  ll m, b;
  mutable function<const line*() > succ;
  bool operator < (const line& rhs) const {
    if (rhs.b != inf) return m < rhs.m;
    const line* s = succ();
    if (!s) return 0;
    ll x = rhs.m;
    return b - s->b < (s->m - m) * x;
  }
};
struct CHT : public multiset<line> {
  bool bad(iterator y) {
    auto z = next(y);
    if (y == begin()) {
      if (z == end()) return 0;
      return y -> m == z -> m && y -> b <= z -> b;
    }
    auto x = prev(y);
    if (z == end()) return y -> m == x -> m && y -> b <= x -> b;
    return 1.0 * (x -> b - y -> b) * (z -> m - y -> m) >= 1.0 * (y -> b - z -> b) * (y -> m - x -> m);
  }
  void add(ll m, ll b) {
    auto y = insert({ m, b });
    y->succ = [ = ] { return next(y) == end() ? 0 : &*next(y); };
    if (bad(y)) {
      erase(y);
      return;
    }
    while (next(y) != end() && bad(next(y))) erase(next(y));
    while (y != begin() && bad(prev(y))) erase(prev(y));
  }
  ll query(ll x) {
    auto l = *lower_bound((line) {
      x, inf
    });
    return l.m * x + l.b;
  }
};
CHT* cht;
ll a[N], b[N];
int32_t main() {
  ios_base::sync_with_stdio(0);
  cin.tie(0);
  int n;
  cin >> n;
  for(int i = 0; i < n; i++) cin >> a[i];
  for(int i = 0; i < n; i++) cin >> b[i];
  cht = new CHT();
  cht -> add(-b[0], 0);
  ll ans = 0;
  for(int i = 1; i < n; i++) {
    ans = -cht -> query(a[i]);
    cht -> add(-b[i], -ans);
  }
  cout << ans << nl;
  return 0;
}
```

2 Data_Structure

2.1 2D_segtree

```
struct Point {
    int x, y, mx;
    Point() {}
    Point(int x, int y, int mx) : x(x), y(y), mx(mx) {}
    bool operator < (const Point& other) const {
        return mx < other.mx;
    }
};
struct Segtree2d {
    // I didn't calculate the exact size needed in terms of 2D container size.
    // If anyone, please edit the answer.
    // It's just a safe size to store nodes for MAX * MAX 2D grids which won't cause stack overflow :)
    Point T[500000]; // TODO: calculate the accurate space needed
    int n, m;
    // initialize and construct segment tree
    void init(int n, int m) {
        this -> n = n;
        this -> m = m;
        build(1, 1, 1, n, m);
    }
    // build a 2D segment tree from data [ (a1, b1), (a2, b2) ]
    // Time: O(n logn)
    Point build(int node, int a1, int b1, int a2, int b2) {
        // out of range
        if (a1 > a2 or b1 > b2)
            return def();
        // if it is only a single index, assign value to node
        if (a1 == a2 and b1 == b2)
            return T[node] = Point(a1, b1, P[a1][b1]);
        // split the tree into four segments
        T[node] = def();
        T[node] = maxNode(T[node], build(4 * node - 2, a1, b1, (a1 + a2) / 2, (b1 + b2) / 2 ) );
        T[node] = maxNode(T[node], build(4 * node - 1, (a1 + a2) / 2 + 1, b1, a2, (b1 + b2) / 2 ));
        T[node] = maxNode(T[node], build(4 * node + 0, a1, (b1 + b2) / 2 + 1, (a1 + a2) / 2, b2) );
        T[node] = maxNode(T[node], build(4 * node + 1, (a1 + a2) / 2 + 1, (b1 + b2) / 2 + 1, a2, b2) );
        return T[node];
    }
    // helper function for query(int, int, int, int);
    Point query(int node, int a1, int b1, int a2, int b2, int x1, int y1, int x2, int y2) {
        // if we out of range, return dummy
        if (x1 > a2 or y1 > b2 or x2 < a1 or y2 < b1 or a1 > a2 or b1 > b2)
            return def();
        // if it is within range, return the node
        if (x1 <= a1 and y1 <= b1 and a2 <= x2 and b2 <= y2)
            return T[node];
        // split into four segments
```

```
        Point mx = def();
        mx = maxNode(mx, query(4 * node - 2, a1, b1,
            (a1 + a2) / 2, (b1 + b2) / 2, x1, y1, x2,
         ↪  y2) );
        mx = maxNode(mx, query(4 * node - 1, (a1 + a2)
            / 2 + 1, b1, a2, (b1 + b2) / 2, x1, y1,
         ↪  x2, y2) );
        mx = maxNode(mx, query(4 * node + 0, a1, (b1 +
            b2) / 2 + 1, (a1 + a2) / 2, b2, x1, y1,
         ↪  x2, y2) );
        mx = maxNode(mx, query(4 * node + 1, (a1 + a2)
            / 2 + 1, (b1 + b2) / 2 + 1, a2, b2, x1,
         ↪  y1, x2, y2));
        // return the maximum value
        return mx;
    }
    // query from range [ (x1, y1), (x2, y2) ]
    // Time: O(logn)
    Point query(int x1, int y1, int x2, int y2) {
        return query(1, 1, 1, n, m, x1, y1, x2, y2);
    }
    // helper function for update(int, int, int);
    Point update(int node, int a1, int b1, int a2, int
     ↪  b2, int x, int y, int value) {
        if (a1 > a2 or b1 > b2)
            return def();
        if (x > a2 or y > b2 or x < a1 or y < b1)
            return T[node];
        if (x == a1 and y == b1 and x == a2 and y ==
         ↪  b2)
            return T[node] = Point(x, y, value);
        Point mx = def();
        mx = maxNode(mx, update(4 * node - 2, a1, b1,
            (a1 + a2) / 2, (b1 + b2) / 2, x, y, value)
         ↪  );
        mx = maxNode(mx, update(4 * node - 1, (a1 +
            a2) / 2 + 1, b1, a2, (b1 + b2) / 2, x, y,
         ↪  value));
        mx = maxNode(mx, update(4 * node + 0, a1, (b1
            + b2) / 2 + 1, (a1 + a2) / 2, b2, x, y,
         ↪  value));
        mx = maxNode(mx, update(4 * node + 1, (a1 +
            a2) / 2 + 1, (b1 + b2) / 2 + 1, a2, b2, x,
         ↪  y, value) );
        return T[node] = mx;
    }
    // update the value of (x, y) index to 'value'
    // Time: O(logn)
    Point update(int x, int y, int value) {
        return update(1, 1, 1, n, m, x, y, value);
    }
    // utility functions; these functions are virtual
     ↪  because they will be overridden in child class
    virtual Point maxNode(Point a, Point b) {
        return max(a, b);
    }
    // dummy node
    virtual Point def() {
        return Point(0, 0, -INF);
    }
};
/* 2D Segment Tree for range minimum query; a override
 ↪  of Segtree2d class */
struct Segtree2dMin : Segtree2d {
    // overload maxNode() function to return minimum
     ↪  value
    Point maxNode(Point a, Point b) {
        return min(a, b);
    }
    Point def() {
        return Point(0, 0, INF);
    }
};
```

2.2 Segtree_beats_desc

```
/*
Description: For update Ai  Ai mod x and similar, keep
 ↪  range min,
max in node and lazily update whenever min = max. For
 ↪  update
Ai  min(Ai, x) and similar, keep range max, second max
 ↪  in node and
lazily update whenever x > second max.
Time: O(log^2 N), (log N)
 */
```

2.3 gp_hash_table

```
using namespace __gnu_pbds;
const int RANDOM = chrono::high_resolution_clock::now(
 ↪  ).time_since_epoch().count();
using namespace __gnu_pbds;
struct chash {
  const int RANDOM = (long
      long)(make_unique<char>().get()) ^
      chrono::high_resolution_clock::now().time_since_
   ↪  epoch().count();
  static unsigned long long hash_f(unsigned long long
   ↪  x) {
    x += 0x9e3779b97f4a7c15;
    x = (x ^ (x >> 30)) * 0xbf58476d1ce4e5b9;
    x = (x ^ (x >> 27)) * 0x94d049bb133111eb;
    return x ^ (x >> 31);
  }
  static unsigned hash_combine(unsigned a, unsigned b)
   ↪  { return a * 31 + b; }
  ll operator()(ll x) const { return hash_f(x)^RANDOM;
   ↪  }
};
gp_hash_table<key, long long, chash> table;
```

2.4 iterative_segtree

```
const int N = 500010;
int n, a[N], tree[N << 1];
void init() {
    for (int i = 0; i < n; ++i) tree[n + i] = a[i];
    for (int i = n - 1; i >= 0; --i) {
        tree[i] = min(tree[i << 1], tree[i << 1 | 1]);
    }
}
void update(int p, int v) {
    for (tree[p += n] = v; p > 1; p >>= 1) {
        tree[p >> 1] = min(tree[p], tree[p ^ 1]);
    }
}
int query(int l, int r) {
    int ret = INT_MAX;
    for (l += n, r += n; l < r; l >>= 1, r >>= 1) {
        if (l & 1) ret = min(ret, tree[l++]);
        if (r & 1) ret = min(ret, tree[--r]);
    }
    return ret;
}
```

2.5 mos_algo

```
struct data{
  int l, r, id, bn;
  data() {}
  data(int _l, int _r, int _id){
    l = _l, r = _r, id = _id;
    bn = l / block_sz;
  }
  bool operator < (const data& other) const{
    if (bn != other.bn) return (bn < other.bn);
    return ((bn & 1) ? (r < other.r) : (r > other.r));
  }
}
int curL = 0, curR = -1;
for(int i = 0; i < Q.sz; i++){
  while(curL > Q[i].L){
    curL--; add(curL);
  }
  while(curR < Q[i].R){
    curR++; add(curR);
  }
  while(curL < Q[i].L){
    remove(curL); curL++;
  }
  while(curR > Q[i].R){
    remove(curR); curR--;
  }
}
```

2.6 ordered_set

```
using namespace std;
using namespace __gnu_pbds;
typedef tree<
    int ,
    null_type ,
    less < int > , // "less_equal<int>," for multiset
    rb_tree_tag,
    tree_order_statistics_node_update > ordered_set;
ordered_set OS;
```

2.7 persistant_segtree

```
/* Persistent Segment Tree using static Array
  Point Update, Range Sum
  Initialize ncnt to 0 in every test case */
const int MAX = 100010;
int ncnt = 0;
struct node {
  int sum;
  int left,right;
  node() {}
  node(int val) {
    sum = val;
    left = right = -1;
  }
} tree[ ? ];
int ara[MAX];
int version[MAX];
void build(int n,int st,int ed) {
  if (st==ed) {
    tree[n] = node(ara[st]);
    return;
  }
  int mid = (st+ed) / 2;
  tree[n].left = ++ncnt;
  tree[n].right = ++ncnt;
  build(tree[n].left, st, mid);
  build(tree[n].right, mid+1, ed);
  tree[n].sum = tree[tree[n].left].sum +
   ↪  tree[tree[n].right].sum;
}
void update(int prev,int cur,int st,int ed,int id, int
 ↪  val)
{
```

```cpp
  if (id > ed or id < st) return;
  if (st == ed) {
    tree[cur] = node(val);
    return;
  }
  int mid = (st+ed) / 2;
  if (id <= mid) {
    tree[cur].right = tree[prev].right;
    tree[cur].left = ++ncnt;
    update(tree[prev].left,tree[cur].left, st, mid,
      id, val);
  }
  else {
    tree[cur].left = tree[prev].left;
    tree[cur].right = ++ncnt;
    update(tree[prev].right, tree[cur].right, mid+1,
      ed, id, val);
  }
  tree[cur].sum = tree[tree[cur].left].sum +
    tree[tree[cur].right].sum;
}
int query(int n,int st,int ed,int i,int j){
  if(st>=i && ed<=j) return tree[n].sum;
  int mid = (st+ed)/2;
  if(mid<i) return query(tree[n].right,mid+1,ed,i,j);
  else if(mid>=j) return
    query(tree[n].left,st,mid,i,j);
  else return query(tree[n].left,st,mid,i,j) +
    query(tree[n].right,mid+1,ed,i,j);
}
int main() {
  int n,q,l,r,k;
  sii(n,q);
  version[0] = ++ncnt;
  build(version[0],1,n);
  version[1] = ++ncnt;
  update(version[0],version[1],1,n,id,val);
  query(version[0],1,n,id,id);
  query(version[1],1,n,id,id);
  return 0;
}
```

2.8 segment_tree

```cpp
int ara[MAX];
struct node {
  int sum;
} tree[4 * MAX];
int lazy[4 * MAX];
node Merge(node a, node b) {
  node ret;
  ret.sum = a.sum + b.sum;
  return ret;
}
void lazyUpdate(int n, int st, int ed) {
  if(lazy[n] != 0){
    tree[n].sum += ((ed - st + 1) * lazy[n]);
    if(st != ed){
      lazy[2 * n] += lazy[n];
      lazy[2 * n + 1] += lazy[n];
    }
    lazy[n] = 0;
  }
}
void build(int n, int st, int ed) {
  lazy[n] = 0;
  if(st == ed){
    tree[n].sum = ara[st];
    return;
  }
  int mid = (st + ed) / 2;
  build(2 * n, st, mid);
  build(2 * n + 1, mid + 1, ed);
  tree[n] = Merge(tree[2 * n], tree[2 * n + 1]);
}
void update(int n, int st, int ed, int i, int j, int
  v) {
  lazyUpdate(n, st, ed);
  if(st > j or ed < i) return;
  if(st >= i and ed <= j){
    lazy[n] += v;
    lazyUpdate(n, st, ed);
    return;
  }
  int mid = (st + ed) / 2;
  update(2 * n, st, mid, i, j, v);
  update(2 * n + 1, mid+1, ed, i, j, v);
  tree[n] = Merge(tree[2 * n], tree[2 * n + 1]);
}
node query(int n, int st, int ed, int i, int j) {
  lazyUpdate(n, st, ed);
  if(st >= i and ed <= j) return tree[n];
  int mid = (st + ed) / 2;
  if(mid < i) return query(2 * n + 1, mid + 1, ed, i,
    j);
  else if(mid >= j) return query(2 * n, st, mid, i, j);
  else return Merge(query(2 * n, st, mid, i, j),
    query(2 * n + 1, mid + 1, ed, i, j));
}
```

2.9 sparse_table

```cpp
int st[K + 1][MAXN];
void build() {
  std::copy(array.begin(), array.end(), st[0]);
  for (int i = 1; i <= K; i++)
    for (int j = 0; j + (1 << i) <= N; j++)
      st[i][j] = f(st[i - 1][j], st[i - 1][j + (1 <<
        (i - 1))]);
}
```

3 Geometry

3.1 2D Primitive

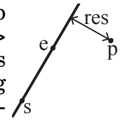
3.1.1 Angle

A class for ordering angles (as represented by int points and a number of rotations around the origin). Useful for rotational sweeping. Sometimes also represents points or vectors.

```cpp
/* Usage:
 *  vector<Angle> v = {w[0], w[0].t360() ...}; //
    sorted
 *  int j = 0; rep(i,0,n) { while (v[j] < v[i].t180())
    ++j; }
 *  // sweeps j such that (j-i) represents the number
    of positively oriented triangles with vertices at
    0 and i
*/
struct Angle {
  int x, y;
  int t;
  Angle(int x, int y, int t=0) : x(x), y(y), t(t) {}
  Angle operator-(Angle b) const { return {x-b.x,
    y-b.y, t}; }
  int half() const {
    assert(x || y);
    return y < 0 || (y == 0 && x < 0);
  }
  Angle t90() const { return {-y, x, t + (half() && x
    >= 0)}; }
  Angle t180() const { return {-x, -y, t + half()}; }
  Angle t360() const { return {x, y, t + 1}; }
};
bool operator<(Angle a, Angle b) {
  // add a.dist2() and b.dist2() to also compare
    distances
  return make_tuple(a.t, a.half(), a.y * (ll)b.x) <
    make_tuple(b.t, b.half(), a.x * (ll)b.y);
}
// Given two points, this calculates the smallest
  angle between
// them, i.e., the angle that covers the defined line
  segment.
pair<Angle, Angle> segmentAngles(Angle a, Angle b) {
  if (b < a) swap(a, b);
  return (b < a.t180() ? make_pair(a, b) :
    make_pair(b, a.t360()));
}
Angle operator+(Angle a, Angle b) { // point a +
  vector b
  Angle r(a.x + b.x, a.y + b.y, a.t);
  if (a.t180() < r) r.t--;
  return r.t180() < a ? r.t360() : r;
}
Angle angleDiff(Angle a, Angle b) { // angle b - angle
  a
  int tu = b.t - a.t; a.t = b.t;
  return {a.x*b.x + a.y*b.y, a.x*b.y - a.y*b.x, tu -
    (b < a)};
}
```

3.1.2 Line Distance

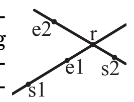
Returns the signed distance between point p and the line containing points a and b. Positive value on left side and negative on right as seen from a towards b. a==b gives nan. P is supposed to be Point<T> or Point3D<T> where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long. Using Point3D will always give a non-negative distance. For Point3D, call .dist on the result of the cross product.




```cpp
#include "Point.h"
template<class P>
double lineDist(const P& a, const P& b, const P& p) {
  return (double)(b-a).cross(p-a)/(b-a).dist();
}
```

3.1.3 Line Intersection

If a unique intersection point of the lines going through s1,e1 and s2,e2 exists {1, point} is returned. If no intersection point exists {0, (0,0)} is returned and if infinitely many exists {-1, (0,0)} is returned. The wrong position will be returned if P is Point<ll> and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or ll.

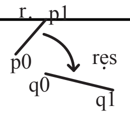



```cpp
/* Usage:
 *  auto res = lineInter(s1,e1,s2,e2);
 *  if (res.first == 1)
 *    cout << "intersection point at " << res.second
      << endl;
 */
#pragma once
#include "Point.h"
template<class P>
pair<int, P> lineInter(P s1, P e1, P s2, P e2) {
  auto d = (e1 - s1).cross(e2 - s2);
  if (d == 0) // if parallel
    return {-(s1.cross(e1, s2) == 0), P(0, 0)};
```

```
  auto p = s2.cross(e1, e2), q = s2.cross(e2, s1);
  return {1, (s1 * p + e1 * q) / d};
}
```

3.1.4 Linear Transformation

Apply the linear transformation (translation, rotation and scaling) which takes line p0-p1 to line q0-q1 to point r.




```
#include "Point.h"
typedef Point<double> P;
P linearTransformation(const P& p0, const P& p1, const P& q0, const P& q1, const P& r) {
  P dp = p1-p0, dq = q1-q0, num(dp.cross(dq), dp.dot(dq));
  return q0 + P((r-p0).cross(num), (r-p0).dot(num))/dp.dist2();
}
```

3.1.5 On Segment

```
/* Description: Returns true iff p lies on the line segment from s to e.
 * Use \texttt{(segDist(s,e,p)<=epsilon)} instead when using Point<double>.
 */
#include "Point.h"
template<class P> bool onSegment(P s, P e, P p) {
  return p.cross(s, e) == 0 && (s - p).dot(e - p) <= 0;
}
```

3.1.6 Point Sort

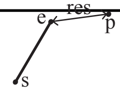
```
// sort the points in counterclockwise order that starts from the half line x0,y=0.
using namespace std;
typedef long long ll;
typedef pair <ll, ll> point;
#define x first
#define y second
int main() {
  int n; cin >> n;
  vector <point> p(n);
  for (auto &it : p) scanf("%lld %lld", &it.x, &it.y);
  sort(p.begin(), p.end(), [] (point a, point b) {
    return atan2l(a.y, a.x) < atan2l(b.y, b.x);
  });
  for (auto it : p) printf("%lld %lld\n", it.x, it.y);
  return 0;
}
```

3.1.7 Point

```
// Class to handle points in the plane. T can be e.g. double or long long. (Avoid int.)
template <class T> int sgn(T x) { return (x > 0) - (x < 0); }
template<class T>
struct Point {
 typedef Point P;
 T x, y;
 explicit Point(T x=0, T y=0) : x(x), y(y) {}
 bool operator<(P p) const { return tie(x,y) < tie(p.x,p.y); }
 bool operator==(P p) const { return tie(x,y)==tie(p.x,p.y); }
 P operator+(P p) const { return P(x+p.x, y+p.y); }
 P operator-(P p) const { return P(x-p.x, y-p.y); }
 P operator*(T d) const { return P(x*d, y*d); }
 P operator/(T d) const { return P(x/d, y/d); }
 T dot(P p) const { return x*p.x + y*p.y; }
 T cross(P p) const { return x*p.y - y*p.x; }
 T cross(P a, P b) const { return (a-*this).cross(b-*this); }
 T dist2() const { return x*x + y*y; }
 double dist() const { return sqrt((double)dist2()); }
 // angle to x-axis in interval [-pi, pi]
 double angle() const { return atan2(y, x); }
 P unit() const { return *this/dist(); } // makes dist()=1
 P perp() const { return P(-y, x); } // rotates +90 degrees
 P normal() const { return perp().unit(); }
 // returns point rotated 'a' radians ccw around the origin
 P rotate(double a) const {
  return P(x*cos(a)-y*sin(a),x*sin(a)+y*cos(a)); }
 friend ostream& operator<<(ostream& os, P p) {
  return os << "(" << p.x << "," << p.y << ")"; }
};
```

3.1.8 Segment Distance

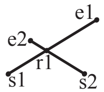
Returns the shortest distance between point p and the line segment from point s to e.




```
/* Usage:
 *  Point<double> a, b(2,2), p(1,1);
 *  bool onSegment = segDist(a,b,p) < 1e-10;
 * Status: tested
 */
#pragma once
#include "Point.h"
typedef Point<double> P;
double segDist(P& s, P& e, P& p) {
  if (s==e) return (p-s).dist();
  auto d = (e-s).dist2(), t = min(d,max(.0,(p-s).dot(e-s)));
  return ((p-s)*d-(e-s)*t).dist()/d;
}
```

3.1.9 Segment Intersection

If a unique intersection point between the line segments going from s1 to e1 and from s2 to e2 exists then it is returned. If no intersection point exists an empty vector is returned. If infinitely many exist a vector with 2 elements is returned, containing the endpoints of the common line segment. The wrong position will be returned if P is Point<ll> and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or long long.




```
/* Usage:
 * vector<P> inter = segInter(s1,e1,s2,e2);
 * if (sz(inter)==1)
 *   cout << "segments intersect at " << inter[0] << endl;
 * Status: stress-tested, tested on kattis:intersection
 */
#include "Point.h"
#include "OnSegment.h"
template<class P> vector<P> segInter(P a, P b, P c, P d) {
  auto oa = c.cross(d, a), ob = c.cross(d, b),
       oc = a.cross(b, c), od = a.cross(b, d);
  // Checks if intersection is single non-endpoint point.
  if (sgn(oa) * sgn(ob) < 0 && sgn(oc) * sgn(od) < 0)
    return {(a * ob - b * oa) / (ob - oa)};
  set<P> s;
  if (onSegment(c, d, a)) s.insert(a);
  if (onSegment(c, d, b)) s.insert(b);
  if (onSegment(a, b, c)) s.insert(c);
  if (onSegment(a, b, d)) s.insert(d);
  return {all(s)};
}
```

3.1.10 Side Of

Returns where p is as seen from s towards e. 1/0/-1 ⇔ left/on line/right. If the optional argument eps is given 0 is returned if p is within distance eps from the line. P is supposed to be Point<T> where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long.

```
/* Usage:
 *  bool left = sideOf(p1,p2,q)==1;
 * Status: tested
 */
#include "Point.h"
template<class P>
int sideOf(P s, P e, P p) { return sgn(s.cross(e, p)); }
template<class P>
int sideOf(const P& s, const P& e, const P& p, double eps) {
  auto a = (e-s).cross(p-s);
  double l = (e-s).dist()*eps;
  return (a > l) - (a < -l);
}
```

3.2 3D

3.2.1 3D Convex Hull

```
#define ll long long
#define sz(x) ((int) (x).size())
#define all(x) (x).begin(), (x).end()
#define vi vector<int>
#define pii pair<int, int>
#define rep(i, a, b) for(int i = (a); i < (b); i++)
using namespace std;
template<typename T>
using minpq = priority_queue<T, vector<T>, greater<T>>;
typedef long double ftype;
struct pt3 {
  ftype x, y, z;
  pt3(ftype x = 0, ftype y = 0, ftype z = 0) : x(x), y(y), z(z) {}
  pt3 operator-(const pt3 &o) const {
    return pt3(x - o.x, y - o.y, z - o.z);
  }
  pt3 cross(const pt3 &o) const {
    return pt3(y * o.z - z * o.y, z * o.x - x * o.z, x * o.y - y * o.x);
  }
  ftype dot(const pt3 &o) const {
    return x * o.x + y * o.y + z * o.z;
  }
};
// A face is represented by the indices of its three points a, b, c.
// It also stores an outward-facing normal vector q
struct face {
  int a, b, c;
  pt3 q;
};
// modify this depending on the coordinate sizes in your use case
const ftype EPS = 1e-9;
vector<face> hull3(const vector<pt3> &p) {
  int n = sz(p);
  assert(n >= 3);
  vector<face> f;
```

```
  // Consider an edge (a->b) dead if it is not a CCW edge of some current face
  // If an edge is alive but not its reverse, this is an exposed edge.
  // We should add new faces on the exposed edges.
  vector<vector<bool>> dead(n, vector<bool>(n, true));
  auto add_face = [&](int a, int b, int c) {
    f.push_back({a, b, c, (p[b] - p[a]).cross(p[c] - p[a])});
    dead[a][b] = dead[b][c] = dead[c][a] = false;
  };
  // Initialize the convex hull of the first 3 points as a
  // triangular disk with two faces of opposite orientation
  add_face(0, 1, 2);
  add_face(0, 2, 1);
  rep(i, 3, n) {
    // f2 will be the list of faces invisible to the added point p[i]
    vector<face> f2;
    for(face &F : f) {
      if((p[i] - p[F.a]).dot(F.q) > EPS) {
        // this face is visible to the new point, so mark its edges as dead
        dead[F.a][F.b] = dead[F.b][F.c] = dead[F.c][F.a] = true;
      }else {
        f2.push_back(F);
      }
    }
    // Add a new face for each exposed edge.
    // Only check edges of alive faces for being exposed.
    f.clear();
    for(face &F : f2) {
      int arr[3] = {F.a, F.b, F.c};
      rep(j, 0, 3) {
        int a = arr[j], b = arr[(j + 1) % 3];
        if(dead[b][a]) {
          add_face(b, a, i);
        }
      }
    }
    f.insert(f.end(), all(f2));
  }
  return f;
}
```

3.2.2 Point3D

Class to handle points in 3D space.T can be e.g. double or long long.

```
template<class T> struct Point3D {
  typedef Point3D P;
  typedef const P& R;
  T x, y, z;
  explicit Point3D(T x=0, T y=0, T z=0) : x(x), y(y), z(z) {}
  bool operator<(R p) const {
    return tie(x, y, z) < tie(p.x, p.y, p.z); }
  bool operator==(R p) const {
    return tie(x, y, z) == tie(p.x, p.y, p.z); }
  P operator+(R p) const { return P(x+p.x, y+p.y, z+p.z); }
  P operator-(R p) const { return P(x-p.x, y-p.y, z-p.z); }
  P operator*(T d) const { return P(x*d, y*d, z*d); }
  P operator/(T d) const { return P(x/d, y/d, z/d); }
  T dot(R p) const { return x*p.x + y*p.y + z*p.z; }
  P cross(R p) const {
    return P(y*p.z - z*p.y, z*p.x - x*p.z, x*p.y - y*p.x);
  }
  T dist2() const { return x*x + y*y + z*z; }
  double dist() const { return sqrt((double)dist2()); }
  //Azimuthal angle (longitude) to x-axis in interval [-pi, pi]
  double phi() const { return atan2(y, x); }
  //Zenith angle (latitude) to the z-axis in interval [0, pi]
  double theta() const { return atan2(sqrt(x*x+y*y),z); }
  P unit() const { return *this/(T)dist(); } //makes dist()=1
  //returns unit vector normal to *this and p
  P normal(P p) const { return cross(p).unit(); }
  //returns point rotated 'angle' radians ccw around axis
  P rotate(double angle, P axis) const {
    double s = sin(angle), c = cos(angle); P u = axis.unit();
    return u*dot(u)*(1-c) + (*this)*c - cross(u)*s;
  }
};
```

3.2.3 Polyhedron Volume

Description: Magic formula for the volume of a polyhedron. Faces should point outwards.

```
template<class V, class L>
double signedPolyVolume(const V& p, const L& trilist) {
  double v = 0;
  for (auto i : trilist) v += p[i.a].cross(p[i.b]).dot(p[i.c]);
  return v / 6;
}
```

3.2.4 Spherical Distance

Returns the shortest distance on the sphere with radius radius between the points with azimuthal angles (longitude) f1 (ϕ_1) and f2 (ϕ_2) from x axis and zenith angles (latitude) t1 (θ_1) and t2 (θ_2) from z axis (0 = north pole). All angles measured in radians. The algorithm starts by converting the spherical coordinates to cartesian coordinates so if that is what you have you can use only the two last rows. dx*radius is then the difference between the two points in the x direction and d*radius is the total distance between the points.

```
double sphericalDistance(double f1, double t1,
    double f2, double t2, double radius) {
  double dx = sin(t2)*cos(f2) - sin(t1)*cos(f1);
  double dy = sin(t2)*sin(f2) - sin(t1)*sin(f1);
  double dz = cos(t2) - cos(t1);
  double d = sqrt(dx*dx + dy*dy + dz*dz);
  return radius*2*asin(d/2);
}
```

3.3 Circle

3.3.1 Circle Intersection

Computes the pair of points at which two circles intersect. Returns false in case of no intersection.

```
#include "Point.h"
typedef Point<double> P;
bool circleInter(P a,P b,double r1,double r2,pair<P, P>* out) {
  if (a == b) { assert(r1 != r2); return false; }
  P vec = b - a;
  double d2 = vec.dist2(), sum = r1+r2, dif = r1-r2,
         p = (d2 + r1*r1 - r2*r2)/(d2*2), h2 = r1*r1 - p*p*d2;
  if (sum*sum < d2 || dif*dif > d2) return false;
  P mid = a + vec*p, per = vec.perp() * sqrt(fmax(0, h2) / d2);
  *out = {mid + per, mid - per};
  return true;
}
```

3.3.2 Circle Polygon Intersection

Returns the area of the intersection of a circle with a ccw polygon.
Time: $O(n)$

```
#include "Point.h"
typedef Point<double> P;
#define arg(p, q) atan2(p.cross(q), p.dot(q))
double circlePoly(P c, double r, vector<P> ps) {
  auto tri = [&](P p, P q) {
    auto r2 = r * r / 2;
    P d = q - p;
    auto a = d.dot(p)/d.dist2(), b = (p.dist2()-r*r)/d.dist2();
    auto det = a * a - b;
    if (det <= 0) return arg(p, q) * r2;
    auto s = max(0., -a-sqrt(det)), t = min(1., -a+sqrt(det));
    if (t < 0 || 1 <= s) return arg(p, q) * r2;
    P u = p + d * s, v = p + d * t;
    return arg(p,u) * r2 + u.cross(v)/2 + arg(v,q) * r2;
  };
  auto sum = 0.0;
  rep(i,0,sz(ps))
    sum += tri(ps[i] - c, ps[(i + 1) % sz(ps)] - c);
  return sum;
}
```

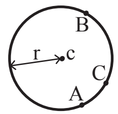
3.3.3 Circle Tangents

Finds the external tangents of two circles, or internal if r2 is negated. Can return 0, 1, or 2 tangents – 0 if one circle contains the other (or overlaps it, in the internal case, or if the circles are the same); 1 if the circles are tangent to each other (in which case .first = .second and the tangent line is perpendicular to the line between the centers). .first and .second give the tangency points at circle 1 and 2 respectively. To find the tangents of a circle with a point set r2 to 0.

```
#include "Point.h"
template<class P>
vector<pair<P, P>> tangents(P c1, double r1, P c2, double r2) {
  P d = c2 - c1;
  double dr = r1 - r2, d2 = d.dist2(), h2 = d2 - dr * dr;
  if (d2 == 0 || h2 < 0)  return {};
  vector<pair<P, P>> out;
  for (double sign : {-1, 1}) {
    P v = (d * dr + d.perp() * sqrt(h2) * sign) / d2;
    out.push_back({c1 + v * r1, c2 + v * r2});
  }
  if (h2 == 0) out.pop_back();
  return out;
}
```

3.3.4 CircumCircle

The circumcirle of a triangle is the circle intersecting all three vertices. ccRadius returns the radius of the circle going through points A, B and C and ccCenter returns the center of the same circle.




```
#include "Point.h"
typedef Point<double> P;
double ccRadius(const P& A, const P& B, const P& C) {
  return (B-A).dist()*(C-B).dist()*(A-C).dist()/
      abs((B-A).cross(C-A))/2;
```

```
}
P ccCenter(const P& A, const P& B, const P& C) {
  P b = C-A, c = B-A;
  return A +
  ↪ (b*c.dist2()-c*b.dist2()).perp()/b.cross(c)/2;
}
```

3.4 Polygon

3.4.1 Hull Diameter

Returns the two points with max distance on a convex hull (ccw, no duplicate/collinear points).

```
#include "Point.h"
typedef Point<ll> P;
array<P, 2> hullDiameter(vector<P> S) {
  int n = sz(S), j = n < 2 ? 0 : 1;
  pair<ll, array<P, 2>> res({0, {S[0], S[0]}});
  rep(i,0,j)
    for (;; j = (j + 1) % n) {
      res = max(res, {(S[i] - S[j]).dist2(), {S[i],
      ↪ S[j]}});
      if ((S[(j + 1) % n] - S[j]).cross(S[i + 1] -
      ↪ S[i]) >= 0)
        break;
    }
  return res.second;
}
```

3.4.2 Line Hull Intersection

Line-convex polygon intersection. The polygon must be ccw and have no collinear points. lineHull(line, poly) returns a pair describing the intersection of a line with the polygon:

$(-1,-1)$ if no collision,

$(i,-1)$ if touching the corner i,

(i,i) if along side $(i,i+1)$,

(i,j) if crossing sides $(i,i+1)$ and $(j,j+1)$. In the last case, if a corner i is crossed, this is treated as happening on side $(i,i+1)$. The points are returned in the same order as the line hits the polygon. `extrVertex` returns the point of a hull with the max projection onto a line.
Time: $O(\log n)$

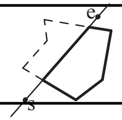
```
#include "Point.h"
#define cmp(i,j)
↪ sgn(dir.perp().cross(poly[(i)%n]-poly[(j)%n]))
#define extr(i) cmp(i + 1, i) >= 0 && cmp(i, i - 1 +
↪ n) < 0
template <class P> int extrVertex(vector<P>& poly, P
↪ dir) {
  int n = sz(poly), lo = 0, hi = n;
  if (extr(0)) return 0;
  while (lo + 1 < hi) {
    int m = (lo + hi) / 2;
    if (extr(m)) return m;
    int ls = cmp(lo + 1, lo), ms = cmp(m + 1, m);
    (ls < ms || (ls == ms && ls == cmp(lo, m)) ? hi :
    ↪ lo) = m;
  }
  return lo;
}
#define cmpL(i) sgn(a.cross(poly[i], b))
template <class P>
array<int, 2> lineHull(P a, P b, vector<P>& poly) {
  int endA = extrVertex(poly, (a - b).perp());
  int endB = extrVertex(poly, (b - a).perp());
  if (cmpL(endA) < 0 || cmpL(endB) > 0)
    return {-1, -1};
  array<int, 2> res;
  rep(i,0,2) {
    int lo = endB, hi = endA, n = sz(poly);
    while ((lo + 1) % n != hi) {
      int m = ((lo + hi + (lo < hi ? 0 : n)) / 2) % n;
      (cmpL(m) == cmpL(endB) ? lo : hi) = m;
    }
    res[i] = (lo + !cmpL(hi)) % n;
    swap(endA, endB);
  }
  if (res[0] == res[1]) return {res[0], -1};
  if (!cmpL(res[0]) && !cmpL(res[1]))
    switch ((res[0] - res[1] + sz(poly) + 1) %
    ↪ sz(poly)) {
      case 0: return {res[0], res[0]};
      case 2: return {res[1], res[1]};
    }
  return res;
}
```

3.4.3 Polygon Center

Returns the center of mass for a polygon.
Time: $O(n)$

```
#include "Point.h"
typedef Point<double> P;
P polygonCenter(const vector<P>& v) {
  P res(0, 0); double A = 0;
  for (int i = 0, j = sz(v) - 1; i < sz(v); j = i++) {
    res = res + (v[i] + v[j]) * v[j].cross(v[i]);
    A += v[j].cross(v[i]);
  }
  return res / A / 3;
}
```

3.4.4 Polygon Cut



Returns a vector with the vertices of a polygon with everything to the left of the line going from s to e cut away.

```
/* Usage:
 *  vector<P> p = ...;
 *  p = polygonCut(p, P(0,0), P(1,0));
 * Status: tested but not extensively
 */
#include "Point.h"
#include "lineIntersection.h"
typedef Point<double> P;
vector<P> polygonCut(const vector<P>& poly, P s, P e) {
  vector<P> res;
  rep(i,0,sz(poly)) {
    P cur = poly[i], prev = i ? poly[i-1] :
    ↪ poly.back();
    bool side = s.cross(e, cur) < 0;
    if (side != (s.cross(e, prev) < 0))
      res.push_back(lineInter(s, e, cur, prev).second);
    if (side)
      res.push_back(cur);
  }
  return res;
}
```

3.5 Closest Pair

Finds the closest pair of points.
Time: $O(n \log n)$

```
#include "Point.h"
typedef Point<ll> P;
pair<P, P> closest(vector<P> v) {
  assert(sz(v) > 1);
  set<P> S;
  sort(all(v), [](P a, P b) { return a.y < b.y; });
  pair<ll, pair<P, P>> ret{LLONG_MAX, {P(), P()}};
  int j = 0;
  for (P p : v) {
    P d{1 + (ll)sqrt(ret.first), 0};
    while (v[j].y <= p.y - d.x) S.erase(v[j++]);
    auto lo = S.lower_bound(p - d), hi =
    ↪ S.upper_bound(p + d);
    for (; lo != hi; ++lo)
      ret = min(ret, {(*lo - p).dist2(), {*lo, p}});
    S.insert(p);
  }
  return ret.second;
}
```

3.6 Convex Hull

```
typedef long long ll;
typedef pair <ll, ll> point;
#define x first
#define y second
inline ll area (point a, point b, point c) {
  return (b.x - a.x) * (c.y - a.y) - (b.y - a.y) *
  ↪ (c.x - a.x);
}
vector <point> convexHull (vector <point> p) {
  int n = p.size(), m = 0;
  if (n < 3) return p;
  vector <point> hull(n + n);
  sort(p.begin(), p.end());
  for (int i = 0; i < n; ++i) {
    while (m > 1 and area(hull[m - 2], hull[m - 1],
    ↪ p[i]) <= 0) --m;
    hull[m++] = p[i];
  }
  for (int i = n - 2, j = m + 1; i >= 0; --i) {
    while (m >= j and area(hull[m - 2], hull[m - 1],
    ↪ p[i]) <= 0) --m;
    hull[m++] = p[i];
  }
  hull.resize(m - 1); return hull;
}
```

3.7 Minimum Enclosing Circle

```
// Expected runtime: O(n)
// Solves Gym 102299J
using namespace std;
typedef long double ld;
typedef pair <ld, ld> point;
#define x first
#define y second
point operator + (const point &a, const point &b) {
  return point(a.x + b.x, a.y + b.y);
}
point operator - (const point &a, const point &b) {
  return point(a.x - b.x, a.y - b.y);
}
point operator * (const point &a, const ld &b) {
  return point(a.x * b, a.y * b);
}
point operator / (const point &a, const ld &b) {
  return point(a.x / b, a.y / b);
}
const ld EPS = 1e-8;
const ld INF = 1e20;
const ld PI = acosl(-1);
inline ld dist (point a, point b) {
  return hypotl(a.x - b.x, a.y - b.y);
}
inline ld sqDist (point a, point b) {
  return (a.x - b.x) * (a.x - b.x) + (a.y - b.y) *
  ↪ (a.y - b.y);
```

```
}
inline ld dot (point a, point b) {
  return a.x * b.x + a.y * b.y;
}
inline ld cross (point a, point b) {
  return a.x * b.y - a.y * b.x;
}
inline ld cross (point a, point b, point c) {
  return cross(b - a, c - a);
}
inline point perp (point a) {
  return point(-a.y, a.x);
}
// circle through 3 points
pair <point, ld> getCircle (point a, point b, point c)
  {
  pair <point, ld> ret;
  ld den = (ld) 2 * cross(a, b, c);
  ret.x.x = ((c.y - a.y) * (dot(b, b) - dot(a, a)) -
    (b.y - a.y) * (dot(c, c) - dot(a, a))) / den;
  ret.x.y = ((b.x - a.x) * (dot(c, c) - dot(a, a)) -
    (c.x - a.x) * (dot(b, b) - dot(a, a))) / den;
  ret.y = dist(ret.x, a);
  return ret;
}
pair <point, ld> minCircleAux (vector <point> &s,
  point a, point b, int n) {
  ld lo = -INF, hi = INF;
  for (int i = 0; i < n; ++i) {
    auto si = cross(b - a, s[i] - a);
    if (fabs(si) < EPS) continue;
    point m = getCircle(a, b, s[i]).x;
    auto cr = cross(b - a, m - a);
    si < 0 ? hi = min(hi, cr) : lo = max(lo, cr);
  }
  ld v = 0 < lo ? lo : hi < 0 ? hi : 0;
  point c = (a + b) * 0.5 + perp(b - a) * v /
    sqDist(a, b);
  return {c, sqDist(a, c)};
}
pair <point, ld> minCircle (vector <point> &s, point
  a, int n) {
  random_shuffle(s.begin(), s.begin() + n);
  point b = s[0], c = (a + b) * 0.5;
  ld r = sqDist(a, c);
  for (int i = 1; i < n; ++i) {
    if (sqDist(s[i], c) > r * (1 + EPS)) {
      tie(c, r) = n == s.size() ? minCircle(s, s[i],
        i) : minCircleAux(s, a, s[i], i);
    }
  }
  return {c, r};
}
pair <point, ld> minCircle (vector <point> s) {
  assert(!s.empty());
  if (s.size() == 1) return {s[0], 0};
  return minCircle(s, s[0], s.size());
}
int n; vector <point> p;
int main() {
  cin >> n;
  while (n--) {
    double x, y;
    scanf("%lf %lf", &x, &y);
    p.emplace_back(x, y);
  }
  pair <point, ld> circ = minCircle(p);
  printf("%0.12f %0.12f %0.12f\n", (double) circ.x.x,
    (double) circ.x.y, (double) (0.5 * circ.y));
  return 0;
}
```

3.8 Point In Polygon

```
// Test if a point is inside a convex polygon in O(lg
  n) time
// Solves SPOJ INOROUT
typedef long long ll;
typedef pair <ll, ll> point;
#define x first
#define y second
struct segment {
  point P1, P2;
  segment () {}
  segment (point P1, point P2) : P1(P1), P2(P2) {}
};
inline ll ccw (point A, point B, point C) {
  return (B.x - A.x) * (C.y - A.y) - (C.x - A.x) *
    (B.y - A.y);
}
inline bool pointOnSegment (segment S, point P) {
  ll x = P.x, y = P.y, x1 = S.P1.x, y1 = S.P1.y, x2 =
    S.P2.x, y2 = S.P2.y;
  ll a = x - x1, b = y - y1, c = x2 - x1, d = y2 - y1,
    dot = a * c + b * d, len = c * c + d * d;
  if (x1 == x2 and y1 == y2) return x1 == x and y1 ==
    y;
  if (dot < 0 or dot > len) return 0;
  return x1 * len + dot * c == x * len and y1 * len +
    dot * d == y * len;
}
const int M = 17;
const int N = 10010;
struct polygon {
  int n; // n > 1
  point p[N]; // clockwise order
  polygon () {}
  polygon (int _n, point *T) {
    n = _n;
    for (int i = 0; i < n; ++i) p[i] = T[i];
  }
  bool contains (point P, bool strictlyInside) {
    int lo = 1, hi = n - 1;
    while (lo < hi){
      int mid = lo + hi >> 1;
      if (ccw(p[0], P, p[mid]) > 0) lo = mid + 1;
      else hi = mid;
    }
    if (ccw(p[0], P, p[lo]) > 0) lo = 1;
    if (!strictlyInside and
      pointOnSegment(segment(p[0], p[n - 1]), P))
      return 1;
    if (!strictlyInside and
      pointOnSegment(segment(p[lo], p[lo - 1]), P))
      return 1;
    if (lo == 1 or ccw(p[0], P, p[n - 1]) == 0) return
      0;
    return ccw(p[lo], P, p[lo - 1]) < 0;
  }
};
```

3.9 near_pair

```
struct pt {
  int x, y, id;
};
struct cmp_x {
  bool operator()(const pt & a, const pt & b) const {
    return a.x < b.x || (a.x == b.x && a.y < b.y);
  }
};
struct cmp_y {
  bool operator()(const pt & a, const pt & b) const {
    return a.y < b.y;
  }
};
int n;
vector<pt> a;
double mindist;
pair<int, int> best_pair;
void upd_ans(const pt & a, const pt & b) {
  double dist = sqrt((a.x - b.x)*(a.x - b.x) + (a.y -
    b.y)*(a.y - b.y));
  if (dist < mindist) {
    mindist = dist;
    best_pair = {a.id, b.id};
  }
}
vector<pt> t;
void rec(int l, int r) {
  if (r - l <= 3) {
    for (int i = l; i < r; ++i) {
      for (int j = i + 1; j < r; ++j) {
        upd_ans(a[i], a[j]);
      }
    }
    sort(a.begin() + l, a.begin() + r, cmp_y());
    return;
  }
  int m = (l + r) >> 1;
  int midx = a[m].x;
  rec(l, m);
  rec(m, r);
  merge(a.begin() + l, a.begin() + m, a.begin() + m,
    a.begin() + r, t.begin(), cmp_y());
  copy(t.begin(), t.begin() + r - l, a.begin() + l);
  int tsz = 0;
  for (int i = l; i < r; ++i) {
    if (abs(a[i].x - midx) < mindist) {
      for (int j = tsz - 1; j >= 0 && a[i].y - t[j].y
        < mindist; --j)
        upd_ans(a[i], t[j]);
      t[tsz++] = a[i];
    }
  }
}
void solve(int n)
{
  t.resize(n);
  sort(a.begin(), a.end(), cmp_x());
  mindist = 1E20;
  rec(0, n);
}
```

3.10 sweep

```
const double EPS = 1E-9;
struct pt {
  double x, y;
};
struct seg {
  pt p, q;
  int id;
  double get_y(double x) const {
    if (abs(p.x - q.x) < EPS)
      return p.y;
    return p.y + (q.y - p.y) * (x - p.x) / (q.x - p.x);
  }
};
bool intersect1d(double l1, double r1, double l2,
  double r2) {
```

```
  if (l1 > r1)
    swap(l1, r1);
  if (l2 > r2)
    swap(l2, r2);
  return max(l1, l2) <= min(r1, r2) + EPS;
}
int vec(const pt& a, const pt& b, const pt& c) {
  double s = (b.x - a.x) * (c.y - a.y) - (b.y - a.y) *
   ↪ (c.x - a.x);
  return abs(s) < EPS ? 0 : s > 0 ? +1 : -1;
}
bool intersect(const seg& a, const seg& b)
{
  return intersect1d(a.p.x, a.q.x, b.p.x, b.q.x) &&
    intersect1d(a.p.y, a.q.y, b.p.y, b.q.y) &&
    vec(a.p, a.q, b.p) * vec(a.p, a.q, b.q) <= 0 &&
    vec(b.p, b.q, a.p) * vec(b.p, b.q, a.q) <= 0;
}
bool operator<(const seg& a, const seg& b)
{
  double x = max(min(a.p.x, a.q.x), min(b.p.x, b.q.x));
  return a.get_y(x) < b.get_y(x) - EPS;
}
struct event {
  double x;
  int tp, id;
  event() {}
  event(double x, int tp, int id) : x(x), tp(tp),
   ↪ id(id) {}
  bool operator<(const event& e) const {
    if (abs(x - e.x) > EPS)
      return x < e.x;
    return tp > e.tp;
  }
};
set<seg> s;
vector<set<seg>::iterator> where;
set<seg>::iterator prev(set<seg>::iterator it) {
  return it == s.begin() ? s.end() : --it;
}
set<seg>::iterator next(set<seg>::iterator it) {
  return ++it;
}
pair<int, int> solve(const vector<seg>& a) {
  int n = (int)a.size();
  vector<event> e;
  for (int i = 0; i < n; ++i) {
    e.push_back(event(min(a[i].p.x, a[i].q.x), +1, i));
    e.push_back(event(max(a[i].p.x, a[i].q.x), -1, i));
  }
  sort(e.begin(), e.end());
  s.clear();
  where.resize(a.size());
  for (size_t i = 0; i < e.size(); ++i) {
    int id = e[i].id;
    if (e[i].tp == +1) {
      set<seg>::iterator nxt = s.lower_bound(a[id]),
       ↪ prv = prev(nxt);
      if (nxt != s.end() && intersect(*nxt, a[id]))
        return make_pair(nxt->id, id);
      if (prv != s.end() && intersect(*prv, a[id]))
        return make_pair(prv->id, id);
      where[id] = s.insert(nxt, a[id]);
    } else {
      set<seg>::iterator nxt = next(where[id]), prv =
       ↪ prev(where[id]);
      if (nxt != s.end() && prv != s.end() &&
       ↪ intersect(*nxt, *prv))
        return make_pair(prv->id, nxt->id);
      s.erase(where[id]);
    }
  }
  return make_pair(-1, -1);
}
```

4 Graph

4.1 2Sat

```
namespace sat{
  const int MAX = 200010;
  bool vis[MAX];
  vector <int> ed[MAX], rev[MAX];
  int n, m, ptr, dfs_t[MAX], ord[MAX], par[MAX];
  inline int inv(int x){
    return ((x) <= n ? (x + n) : (x - n));
  }
  void init(int vars){
    n = vars, m = vars << 1;
    for (int i = 1; i <= m; i++){
      ed[i].clear();
      rev[i].clear();
    }
  }
  inline void add(int a, int b){
    ed[a].push_back(b);
    rev[b].push_back(a);
  }
  inline void OR(int a, int b){
    add(inv(a), b);
    add(inv(b), a);
  }
  inline void AND(int a, int b){
    add(a, b);
    add(b, a);
  }
  void XOR(int a,int b){
    add(inv(b), a);
    add(a, inv(b));
    add(inv(a), b);
    add(b, inv(a));
  }
  inline void XNOR(int a, int b){
    add(a,b);
    add(b,a);
    add(inv(a), inv(b));
    add(inv(b), inv(a));
  }
  inline void force_true(int x){
    add(inv(x), x);
  }
  inline void topsort(int s){
    vis[s] = true;
    for(int x : rev[s]) if(!vis[x]) topsort(x);
    dfs_t[s] = ++ptr;
  }
  inline void dfs(int s, int p){
    par[s] = p;
    vis[s] = true;
    for(int x : ed[s]) if (!vis[x]) dfs(x, p);
  }
  void build(){
    CLR(vis);
    ptr = 0;
    for(int i=m;i>=1;i--) {
      if (!vis[i]) topsort(i);
      ord[dfs_t[i]] = i;
    }
    CLR(vis);
    for (int i = m; i >= 1; i--){
      int x = ord[i];
      if (!vis[x]) dfs(x, x);
    }
  }
  bool satisfy(vector <int>& res){
    build();
    CLR(vis);
    for (int i = 1; i <= m; i++){
      int x = ord[i];
      if (par[x] == par[inv(x)]) return false;
      if (!vis[par[x]]){
        vis[par[x]] = true;
        vis[par[inv(x)]] = false;
      }
    }
    res.clear();
    for (int i = 1; i <= n; i++){
      if (vis[par[i]]) res.push_back(i);
    }
    return true;
  }
}
```

4.2 Centroid_decomp

```
vector <int> ed[MAX];
bool isCentroid[MAX];
int sub[MAX], cpar[MAX], clevel[MAX];
int dis[20][MAX];
void calcSubTree(int s,int p) {
  sub[s] = 1;
  for(int x : ed[s]) {
    if(x == p or isCentroid[x]) continue;
    calcSubTree(x,s);
    sub[s] += sub[x];
  }
}
int nn;
int getCentroid(int s,int p) {
  for(int x : ed[s]) {
    if(!isCentroid[x] && x!=p && sub[x]>(nn/2)) return
     ↪ getCentroid(x,s);
  }
  return s;
}
void setDis(int s, int from, int p, int lev) {
  dis[from][s] = lev;
  for(int x : ed[s]) {
    if(x == p or isCentroid[x] )  continue;
    setDis(x, from, s, lev+1);
  }
}
void decompose(int s,int p,int lev) {
  calcSubTree(s,p);
  nn = sub[s];
  int c = getCentroid(s,p);
  setDis(c,lev,p,0);
  isCentroid[c] = true;
  cpar[c] = p;
  clevel[c] = lev;
  for(int x : ed[c]) {
    if(!isCentroid[x]) decompose(x,c,lev+1);
  }
}
int ans[MAX];
inline void update(int v) {
  int u = v;
  while(u!=-1) {
    ans[u] = min(ans[u], dis[clevel[u]][v]);
    u = cpar[u];
  }
}
```

```
inline int query(int v) {
  int ret = INF;
  int u = v;
  while(u != -1) {
    ret = min(ret, dis[clevel[u]][v]+ans[u]);
    u = cpar[u];
  }
  return ret;
}
int main() {
  decompose(1,-1,0);
  for(int i=1; i<=n; i++) ans[i] = INF;
  update(v);
  query(v));
  return 0;
}
```

4.3 articulation_point

```
using namespace std;
const int N = 1e5 + 10;
vector<int> g[N];
int vis[N], low[N], cut[N], now = 0, n, m;
void dfs(int u, int p) {
  low[u] = vis[u] = ++now; int ch = 0;
  for(int v : g[u]){
    if(v ^ p) {
      if(vis[v]) low[u] = min(low[u], vis[v]);
      else {
        ch++; dfs(v, u);
        low[u] = min(low[u], low[v]);
        if(p + 1 && low[v] >= vis[u]) cut[u] = 1;
        if(low[v] > vis[u]) {
          printf("Bridge %d -- %d\n", u, v);
        }
      }
    }
  } if(p == -1 && ch > 1) cut[u] = 1;
}
void ArticulationPointAndBridge() {
  now = 0;
  for(int i = 0; i < n; i++) {
    if(!vis[i]) dfs(i, -1);
  }
}
```

4.4 bcc

```
// clear ed[] every test case
// tot -> total number of components
// bcc[i] contains the nodes of the i'th component
// any self loop or multiple edge?
const int MAX = ?;
vector <int> ed[MAX];
bool cut[MAX];
int tot, Time, low[MAX], st[MAX];
vector <int> bcc[MAX];
stack <int> S;
void popBCC(int s,int x) {
  cut[s] = 1;
  bcc[++tot].pb(s);
  while(bcc[tot].back() ^ x) {
    bcc[tot].pb(S.top());
    S.pop();
  }
}
void dfs(int s, int p = -1) {
  S.push(s);
  int ch = 0;
  st[s] = low[s] = ++Time;
  for(int x : ed[s]) {
    if(!st[x]) {
      ch++;
      dfs(x,s);
      low[s] = min(low[s],low[x]);
      if(p != -1 and low[x] >= st[s]) popBCC(s,x);
      else if(p == -1) if(ch > 1) popBCC(s,x);
    }
    else if(p != x) low[s] = min(low[s],st[x]);
  }
  if(p == -1 && ch > 1) cut[s] = 1;
}
void processBCC(int n) {
  for(int i=1;i<=n;i++) bcc[i].clear();
  CLR(st); CLR(cut);
  Time = tot = 0;
  for(int i=1; i<=n; i++) {
    if(!st[i]) {
      dfs(i,-1);
      if(!S.empty()) ++tot;
      while(!S.empty()) {
        bcc[tot].push_back(S.top());
        S.pop();
      }
    }
  }
}
```

4.5 bridge_tree

```
const int MAXN = ?;
const int MAXE = ?;
struct edges {
  int u,v;
} ara[MAXE];
vector <int> ed[MAXN];
vector <int> isBridge[MAXN];
vector <int> brTree[MAXN];
bool vis[MAXN];
int st[MAXN], low[MAXN], Time = 0;
int cnum;
int comp[MAXN];
void findBridge(int s,int par) {
  int i,x,child = 0,j;
  vis[s] = 1;
  Time++;
  st[s] = low[s] = Time;
  for(i=0; i<ed[s].size(); i++) {
    x = ed[s][i];
    if(!vis[x]) {
      child++;
      findBridge(x,s);
      low[s] = min(low[s],low[x]);
      if(low[x] > st[s]) {
        isBridge[s][i] = 1;
        j = lower_bound(ed[x].begin(),ed[x].end(),s)-e
        ↪ d[x].begin();
        isBridge[x][j] = 1;
      }
    }
    else if(par!=x)
      low[s] = min(low[s],st[x]);
  }
}
void dfs(int s) {
  int i,x;
  vis[s] = 1;
  comp[s] = cnum;
  for(i=0; i<ed[s].size(); i++) {
    if(!isBridge[s][i]) {
      x = ed[s][i];
      if(!vis[x]) dfs(x);
    }
  }
}
void processBridge(int n,int m) {
  CLR(vis);
  Time = 0;
  for(int i=1; i<=n; i++) if(!vis[i]) findBridge(i,-1);
  cnum = 0;
  CLR(vis);
  for(int i=1; i<=n; i++) {
    if(!vis[i]) {
      cnum++;
      dfs(i);
    }
  }
  n = cnum;
  for(int i=1; i<=m; i++) {
    if(comp[ara[i].u] != comp[ara[i].v]) {
      brTree[comp[ara[i].u]].pb(comp[ara[i].v]);
      brTree[comp[ara[i].v]].pb(comp[ara[i].u]);
    }
  }
}
int main() {
  int n,m,u,v;
  scanf("%d %d",&n,&m);
  for(int i=1; i<=m; i++) {
    sii(u,v);
    ed[u].pb(v);
    ed[v].pb(u);
    isBridge[u].pb(0);
    isBridge[v].pb(0);
    ara[i].u = u;
    ara[i].v = v;
  }
  for(int i=1; i<=n; i++) sort(all(ed[i]));
  processBridge(n,m);
  return 0;
}
```

4.6 dinic

```
namespace dinic {
  using T = int;
  const T INF = 0x3f3f3f3f;
  const int MAXN = 5010;
  int n, src, snk, work[MAXN];
  T dist[MAXN];
  struct Edge{
    int to, rev_pos;
    T c, f;
  };
  vector <Edge> ed[MAXN];
  void init(int _n, int _src, int _snk) {
    n = _n, src = _src, snk = _snk;
    for(int i=1;i<=n;i++) ed[i].clear();
  }
  inline void addEdge(int u, int v, T c, T rc = 0) {
    Edge a = {v, (int)ed[v].size(), c, 0};
    Edge b = {u, (int)ed[u].size(), rc, 0};
    ed[u].push_back(a);
    ed[v].push_back(b);
  }
  bool dinic_bfs() {
    SET(dist);
    dist[src] = 0;
    queue <int> q;
    q.push(src);
    while(!q.empty()){
      int u = q.front(); q.pop();
      for(Edge &e : ed[u]){
        if(dist[e.to] == -1 and e.f < e.c) {
          dist[e.to] = dist[u] + 1;
```

```
        q.push(e.to);
      }
    }
  }
  return (dist[snk]>=0);
}
T dinic_dfs(int u, T fl){
  if (u == snk) return fl;
  for (; work[u] < (int)ed[u].size(); work[u]++) {
    Edge &e = ed[u][work[u]];
    if (e.c <= e.f) continue;
    int v = e.to;
    if (dist[v] == dist[u] + 1){
      T df = dinic_dfs(v, min(fl, e.c - e.f));
      if (df > 0){
        e.f += df;
        ed[v][e.rev_pos].f -= df;
        return df;
      }
    }
  }
  return 0;
}
T solve() {
  T ret = 0;
  while (dinic_bfs()) {
    CLR(work);
    while (T delta = dinic_dfs(src, INF)) ret +=
      ↪ delta;
  }
  return ret;
}
}
int main() {
  int n, m, u, v, c;
  cin >> n >> m;
  dinic::init(n, 1, n);
  while(m--) {
    cin >> u >> v >> c;
    dinic::addEdge(u, v, c, c);
  }
  cout << dinic::solve() << '\n';
  return 0;
}
```

4.7 dsu_on_tree

```
void calcSubSize(int s,int p) {
  sub[s] = 1;
  for(int x : G[s]) {
    if(x==p) continue;
    calcSubSize(x,s);
    sub[s] += sub[x];
  }
}
void add(int s,int p,int v,int bigchild = -1) {
  freq[color[s]] += v;
  for(int x : G[s]) {
    if(x==p || x==bigchild) continue;
    add(x,s,v);
  }
}
void dfs(int s,int p,bool keep) {
  int bigChild = -1;
  for(int x : G[s]) {
    if(x==p) continue;
    if(bigChild==-1 || sub[bigChild] < sub[x] )
      ↪ bigChild = x;
  }
  for(int x : G[s]) {
    if(x==p || x==bigChild) continue;
    dfs(x,s,0);
  }
  if(bigChild!=-1) dfs(bigChild,s,1);
  add(s,p,1,bigChild);
  if(keep==0)
    add(s,p,-1);
}
```

4.8 euler_path

```
vector <int> ed[MAX+5], sltn;
int inDeg[MAX+5], outDeg[MAX+5];
bool vis[MAX+5];
void dfs(int nd) {
  vis[nd] = true;
  while(ed[nd].size()) {
    int v = ed[nd].back();
    ed[nd].pop_back();
    dfs(v);
  }
  sltn.pb(nd);
}
int findEuler (int n) {
  int src , snk , ret = 1;
  bool found_src = false, found_snk = false;
  CLR(inDeg); CLR(outDeg);
  for(int u = 1; u <= n; u++) {
    for(int i = 0; i<ed[u].size(); i++) {
      int v = ed[u][i];
      outDeg[u]++;
      inDeg[v]++;
    }
  }
  int diff;
  for(int i = 1; i<=n; i++) {
    diff = outDeg[i] - inDeg[i];
    if(diff == 1) {
      if(found_src) return 0;
      found_src = true;
      src = i;
    }
    else if (diff == -1) {
      if(found_snk) return 0;
      found_snk = true;
      snk = i;
    }
    else if(diff != 0) return 0;
  }
  if(!found_src) {
    ret = 2;
    for(int i = 1 ; i <= n ; i++) {
      if( outDeg[i] ) {
        found_src = true;
        src = i;
        break;
      }
    }
  }
  if(!found_src) return ret;
  CLR(vis);
  sltn.clear();
  dfs(src);
  for(int i = 1; i<=n; i++) {
    if(outDeg[i] && !vis[i]) return 0;
  }
  for(int i = (int)sltn.size()-1; i>=0; i--)
    ↪ printf("%d ",sltn[i]);
  puts("");
  return ret;
}
```

4.9 hld

```
const int N = 3e4 + 5;
vector<int> G[N];
int sz[N], H[N], P[N];
void dfs(int cur, int h)
{
    sz[cur] = 1;
    H[cur] = h;
    for(int& to : G[cur]) {
        G[to].erase(find(G[to].begin(), G[to].end(),
          ↪ cur));
        P[to] = cur;
        dfs(to, h + 1);
        sz[cur] += sz[to];
        if(sz[to] > sz[G[cur][0]]) swap(G[cur][0], to);
    }
}
int base[N], pos[N], head[N];
int ptr = 0;
void hld(int cur)
{
    pos[cur] = ++ptr;
    base[ptr] = cur;
    for(int to : G[cur]) {
        head[to] = (to == G[cur][0] ? head[cur] : to);
        hld(to);
    }
}
segtree ST;
int query(int u, int v)
{
    int ret = 0;
    while(head[u] != head[v]) {
        if(H[head[u]] > H[head[v]]) swap(u, v);
        ret += ST.query(pos[head[v]], pos[v]);
        v = P[head[v]];
    }
    if(H[u] > H[v]) swap(u, v);
    ret += ST.query(pos[u], pos[v]);
    return ret;
}
void update(int u, int val) {
    ST.update(pos[u], val);
}
void build(int n, int root)
{
    ptr = 0;
    dfs(root, 0);
    head[root] = root;
    hld(root);
    ST = segtree(n);
}
/*
 * clear graph
 * call build
 * Prob : sum of values from u to v
 */
```

4.10 hopcroft_karp

```
struct HopcroftKarp {
  const int N, M;
  std::vector<std::vector<int>> adj_left;
  std::vector<int> matchL, matchR;
  HopcroftKarp(int N, int M, const
    ↪ std::vector<std::pair<int, int>>& edge)
      : N(N), M(M), matchL(N, -1), matchR(M, -1),
        ↪ adj_left(N) {
    for (auto [l, r] : edge)
      adj_left[l].push_back(r);
  }
  int maxmatching() {
    int sz = 0;
    for (bool updated = true; updated;) {
```

```cpp
      updated = false;
      static std::vector<int> root(N), prev(N), qq(N);
      static int qi, qj;
      // std::queue<int> q;
      qi = qj = 0;
      std::fill(root.begin(), root.end(), -1),
      std::fill(prev.begin(), prev.end(), -1);
      for (int i = 0; i < N; i++)
        if (matchL[i] == -1)
          qq[qj++] = i, root[i] = i, prev[i] = i;
      // q.push(i), root[i] = i;
      while (qi < qj) {
        int u = qq[qi++];
        // int u = q.front(); q.pop();
        if (matchL[root[u]] != -1) continue;
        for (int v : adj_left[u]) {
          if (matchR[v] == -1) {
            while (v != -1)
              matchR[v] = u, std::swap(matchL[u], v), u = prev[u];
            updated = true, sz++;
            break;
          }
          if (prev[matchR[v]] == -1)
            v = matchR[v], prev[v] = u, root[v] = root[u], qq[qj++] = v;
          // v = matchR[v], prev[v] = u, root[v] = root[u], q.push(v);
        }
      }
    }
    return sz;
  }
};
```

4.11 hungarian

```cpp
// Given NN matrix A[i][j]. Calculate a permutation p[i] that minimize A[i][p[i]].
template <typename T>
pair <T, vector <int>> Hungarian (int n, int m, T c[N][N]) {
  vector <T> v(m), dist(m);
  vector <int> L(n, -1), R(m, -1);
  vector <int> index(m), prev(m);
  auto residue = [&] (int i, int j) {return c[i][j] - v[j];};
  iota(index.begin(), index.end(), 0);
  for (int f = 0; f < n; ++f) {
    for (int j = 0; j < m; ++j) {
      dist[j] = residue(f, j), prev[j] = f;
    }
    T w; int i, j, l, s = 0, t = 0;
    while (true) {
      if (s == t) {
        l = s, w = dist[index[t++]];
        for (int k = t; k < m; ++k) {
          j = index[k]; T h = dist[j];
          if (h <= w) {
            if (h < w) t = s, w = h;
            index[k] = index[t], index[t++] = j;
          }
        }
        for (int k = s; k < t; ++k) {
          j = index[k];
          if (R[j] < 0) goto augment;
        }
      }
      int q = index[s++], i = R[q];
      for (int k = t; k < m; ++k) {
        j = index[k];
        T h = residue(i, j) - residue(i, q) + w;
        if (h < dist[j]) {
          dist[j] = h, prev[j] = i;
          if (h == w) {
            if (R[j] < 0) goto augment;
            index[k] = index[t], index[t++] = j;
          }
        }
      }
    }
  augment:
    for (int k = 0; k < l; ++k) v[index[k]] += dist[index[k]] - w;
    do {
      R[j] = i = prev[j], swap(j, L[i]);
    } while (i ^ f);
  }
  T ret = 0;
  for (int i = 0; i < n; ++i) ret += c[i][L[i]];
  return {ret, L};
}
```

4.12 kuhn

```cpp
namespace bpm{
  const int L = 105;
  const int R = 105;
  vector <int> G[L];
  int matchR[R], matchL[L], vis[L], it;
  void init(int n) {
    SET(matchL), SET(matchR), CLR(vis);
    it = 1;
    for(int i=1;i<=n;i++) G[i].clear();
  }
  inline void addEdge(int u,int v) { G[u].pb(v); }
  bool dfs(int s) {
    vis[s] = it;
    for(auto x : G[s]) {
      if( matchR[x] == -1 or (vis[matchR[x]] != it and dfs(matchR[x])) ) {
        matchL[s] = x; matchR[x] = s;
        return true;
      }
    }
    return false;
  }
  int solve() {
    int cnt = 0;
    for(int i=1;i<=n;i++) {
      if(dfs(i)) cnt++, it++;
    }
    return cnt;
  }
}
```

4.13 lca

```cpp
// Don't forget to clear ed after test case ends(vt, cost are cleared inside)
using namespace std;
const int MAX = 100010;
int LG;
int dep[MAX], par[MAX][21];
vector <int> ed[MAX];
void dfs(int s, int p, int d) {
  dep[s] = d, par[s][0] = p;
  for(int x : ed[s]) {
    if(x == p) continue;
    dfs(x, s, d+1);
  }
}
void preprocess(int root, int n) {
  LG = __lg(n);
  memset(par, -1, sizeof(par));
  dfs(root, -1, 0);
  for(int j=1;j<=LG;j++) {
    for(int i=1;i<=n;i++) {
      if(par[i][j-1] != -1) par[i][j] = par[par[i][j-1]][j-1];
    }
  }
}
int getLCA(int u, int v) {
  if(dep[u] < dep[v]) swap(u, v);
  for(int i=LG;i>=0;i--) {
    if(dep[u] - (1<<i) >= dep[v]) u = par[u][i];
  }
  if(u == v) return u;
  for(int i=LG;i>=0;i--) {
    if (par[u][i] != -1 and par[u][i] - par[v][i]) {
      u = par[u][i], v = par[v][i];
    }
  }
  return par[u][0];
}
```

4.14 manhattan_MST

```cpp
using namespace std;
using ll = long long;
struct UnionFind {
    vector<int> UF;
    int cnt;
    UnionFind(int N) : UF(N, -1), cnt(N) {}
    int find(int v) { return UF[v] < 0 ? v : UF[v] = find(UF[v]); }
    bool join(int v, int w) {
        if ((v = find(v)) == (w = find(w))) return false;
        if (UF[v] > UF[w]) swap(v, w);
        UF[v] += UF[w];
        UF[w] = v;
        cnt--;
        return true;
    }
    bool connected(int v, int w) {
        return find(v) == find(w);
    }
    int getSize(int v) { return -UF[find(v)]; }
};
template <class T>
struct KruskalMST {
    using Edge = tuple<int, int, T>;
    T mstWeight;
    vector<Edge> mstEdges;
    UnionFind uf;
    KruskalMST(int V, vector<Edge> edges) : mstWeight(), uf(V) {
        sort(edges.begin(), edges.end(), [&](const Edge &a, const Edge &b) {
            return get<2>(a) < get<2>(b);
        });
        for (auto &&e : edges) {
            if (int(mstEdges.size()) >= V - 1) break;
            if (uf.join(get<0>(e), get<1>(e))) {
                mstEdges.push_back(e);
                mstWeight += get<2>(e);
            }
        }
    }
};
template <class T>
struct ManhattanMST : public KruskalMST<T> {
```

```
    using Edge = typename KruskalMST<T>::Edge;
    static vector<Edge>
    ↪ generateCandidates(vector<pair<T, T>>, P) {
        vector<int> id(P.size());
        iota(id.begin(), id.end(), 0);
        vector<Edge> ret;
        ret.reserve(P.size() * 4);
        for (int h = 0; h < 4; h++) {
            sort(id.begin(), id.end(), [&](int i, int
            ↪ j) {
                return P[i].first - P[j].first <
                ↪ P[j].second - P[i].second;
            });
            map<T, int> M;
            for (int i : id) {
                auto it = M.lower_bound(-P[i].second);
                for (; it != M.end(); it =
                ↪ M.erase(it)) {
                    int j = it->second;
                    T dx = P[i].first - P[j].first, dy
                    ↪ = P[i].second, - P[j].second;
                    if (dy > dx) break;
                    ret.emplace_back(i, j, dx + dy);
                }
                M[-P[i].second] = i;
            }
            for (auto &&p : P) {
                if (h % 2)
                    p.first = -p.first;
                else
                    swap(p.first, p.second);
            }
        }
        return ret;
    }
    ManhattanMST(const vector<pair<T, T>> &P)
        : KruskalMST<T>(P.size(),
        ↪ generateCandidates(P)) {}
};
int main() {
    int N;
    cin >> N;
    vector<pair<ll, ll>> P(N);
    for (auto &&p : P) cin >> p.first >> p.second;
    ManhattanMST mst(P);
    cout << mst.mstWeight << '\n';
    for (auto &&[v, w, weight] : mst.mstEdges) cout <<
    ↪ v << ' , ' << w << '\n'; return 0;
}
```

4.15 mcmf

```
namespace mcmf {
  using T = int;
  const T INF = ?; // 0x3f3f3f3f or
  ↪ 0x3f3f3f3f3f3f3f3fLL
  const int MAX = ?; // maximum number of nodes
  int  n, src, snk;
  T dis[MAX], mCap[MAX];
  int par[MAX], pos[MAX];
  bool vis[MAX];
  struct Edge{
    int to, rev_pos;
    T cap, cost, flow;
  };
  vector <Edge> ed[MAX];
  void init(int _n, int _src, int _snk) {
    n = _n, src = _src, snk = _snk;
    for(int i=1;i<=n;i++) ed[i].clear();
  }
  void addEdge(int u, int v, T cap, T cost) {
    Edge a = {v, (int)ed[v].size(), cap, cost, 0};
    Edge b = {u, (int)ed[u].size(), 0, -cost, 0};
    ed[u].pb(a);
    ed[v].pb(b);
  }
  inline bool SPFA(){
    CLR(vis);
    for(int i=1; i<=n; i++) mCap[i] = dis[i] = INF;
    queue <int> q;
    dis[src] = 0;
    vis[src] = true;
    q.push(src);
    while(!q.empty()){
      int u = q.front();
      q.pop();
      vis[u] = false;
      for(int i=0; i<(int)ed[u].size(); i++) {
        Edge &e = ed[u][i];
        int v = e.to;
        if(e.cap > e.flow && dis[v] > dis[u] + e.cost){
          dis[v] = dis[u] + e.cost;
          par[v] = u;
          pos[v] = i;
          mCap[v] = min(mCap[u],e.cap - e.flow);
          if(!vis[v]) {
            vis[v] = true;
            q.push(v);
          }
        }
      }
    }
    return (dis[snk] != INF);
  }
  inline pair <T, T> solve() {
    T F = 0, C = 0, f;
    int u, v;
    while(SPFA()){
      u = snk;
      f = mCap[u];
      F += f;
      while(u!=src){
        v = par[u];
        ed[v][pos[u]].flow += f; // edge of v-->u
        ↪ increases
        ed[u][ed[v][pos[u]].rev_pos].flow -= f;
        u = v;
      }
      C += dis[snk] * f;
    }
    return make_pair(F,C);
  }
}
```

4.16 tree_hash_all_root

```
/*Description : Find hashes of a tree when rooted at
↪ each possible
node(unrooted tree isomorphism test).Time : O(n)*/
const int sz = 2e5 + 5,mod = 1e9 + 7;
ll hval[sz], h[sz], dp[sz], rans[sz];
void dfs(vector<vector<int>> &g, int u = 0, int p =
↪ -1, int val = 0, int up = 0) {
    vector<int> cv, cht;  // current child values &
    ↪ heights
    if (u > 0) {
        cv.push_back(val);
        cht.push_back(up);
    }
    for (int v : g[u])
        if (v - p) {
            cv.push_back(dp[v]);
            cht.push_back(1 + h[v]);
        }
    sort(cht.begin(), cht.end(), greater<int>());
    if (cv.size() > 1) {
        ll ret[] = {1, 1};  // for biggest &
        ↪ 2nd-biggest heights
        for (int i = 0; i < 2; i++)
            for (int value : cv)
                ret[i] = ret[i] * (hval[cht[i]] +
                ↪ value) % mod;
        rans[u] = ret[0];  // biggest is hash for this
        ↪ root
        for (int v : g[u])
            if (v - p) {
                int id = 1;
                if (cht[0] - 1 - h[v]) id = 0;  // v
                ↪ is not on the biggest height path
                val = ret[id] * invmod((hval[cht[id]]
                ↪ + dp[v]) % mod) % mod;
                /* division of v subtree hash value */
                dfs(g, v, u, val, cht[id] + 1);
            }
    } else if (cv.size()) {  // Leaf node u OR vertex
    ↪ - 1 has only one child
        if (!up)
            val = 1;
        else
            val = (val + hval[up]) % mod;
        rans[u] = val;
        for (int v : g[u])
            if (v - p) dfs(g, v, u, val, up + 1);
    }
}
ll get(vector<vector<int>> &g, int u = 0, int p = -1) {
    h[u] = 0;
    vector<ll> childs;
    for (int v : g[u])
        if (v - p) {
            childs.push_back(get(g, v, u));
            h[u] = max(h[u], 1 + h[v]);
        }
    ll ret = 1;
    for (int value : childs) ret = ret * (hval[h[u]] +
    ↪ value) % mod;
    return dp[u] = ret;
}
int main() {  // can remove the g as param, can change
↪ to 1-index, multi-test works, no further change
    get(g);
    dfs(g);
    tree[k] = rans[0] = dp[0];
    // rans[i] = tree hash with i as root
}
```

5 Math

5.1 FWHT

```
const int N = 1 << 20;
// apply modulo if necessary
void fwht_xor(int *a, int n, int dir = 0) {
    for (int h = 1; h < n; h <<= 1) {
        for (int i = 0; i < n; i += h << 1) {
            for (int j = i; j < i + h; ++j) {
                int x = a[j], y = a[j + h];
                a[j] = x + y, a[j + h] = x - y;
                if (dir) a[j] >>= 1, a[j + h] >>= 1;
            }
        }
    }
}
void fwht_or(int *a, int n, int dir = 0) {
    for (int h = 1; h < n; h <<= 1) {
        for (int i = 0; i < n; i += h << 1) {
```

```
            for (int j = i; j < i + h; ++j) {
                int x = a[j], y = a[j + h];
                a[j] = x, a[j + h] = dir ? y - x : x + y;
            }
        }
    }
}
void fwht_and(int *a, int n, int dir = 0) {
    for (int h = 1; h < n; h <<= 1) {
        for (int i = 0; i < n; i += h << 1) {
            for (int j = i; j < i + h; ++j) {
                int x = a[j], y = a[j + h];
                a[j] = dir ? x - y : x + y, a[j + h] = y;
            }
        }
    }
}
```

5.2 FloorSum

```
// O(log a) sum^n floor(ax + b / c) = f
long long FloorSumAP(long long a, long long b, long long c, long long n){
  if(!a) return (b / c) * (n + 1);
  if(a >= c or b >= c) return ( ( n * (n + 1) ) / 2) * (a / c) + (n + 1) * (b / c) + FloorSumAP(a % c, b % c, c, n);
  long long m = (a * n + b) / c;
  return m * n - FloorSumAP(c, c - b - 1, a, m - 1);
}
// O(log a) sum^n x * floor(ax + b / c) = g, sum^n floro(ax + b / c)^2 = h
struct dat {
  long long f, g, h;
  dat(long long f = 0, long long g = 0, long long h = 0) : f(f), g(g), h(h) {};
};
long long mul(long long a, long long b){
  return (a * b) % MOD;
}
dat query(long long a, long long b, long long c, long long n){
  if(!a) return {mul(n + 1, b / c), mul(mul(mul(b / c, n), n + 1), inv2), mul(mul(n + 1, b / c), b /c)};
  long long f, g, h;
  dat nxt;
  if(a >= c or b >= c){
    nxt = query(a % c, b % c, c, n);
    f = (nxt.f + mul(mul(mul(n, n + 1), inv2), a / c) + mul(n + 1, b / c)) % MOD;
    g = (nxt.g + mul(a / c, mul(mul(n, n + 1), mul(2 * n + 1, inv6))) + mul(mul(b / c, mul(n, n + 1)), inv2)) % MOD;
    h = (nxt.h + 2 * mul(b / c, nxt.f) + 2 * mul(a / c, nxt.g) + mul(mul(a / c, a / c), mul(mul(n, n + 1), mul(2 * n + 1, inv6))) + mul(mul(b / c, b / c), n + 1) + mul(mul(a / c, b / c), mul(n, n + 1)) ) % MOD;
    return {f, g, h};
  }
  long long m = (a * n + b ) / c;
  nxt = query(c, c - b - 1, a, m - 1);
  f = (mul(m, n) - nxt.f) % MOD;
  g = mul( mul(m, mul(n, n + 1)) - nxt.h - nxt.f, inv2);
  h = (mul(n, mul(m, m + 1)) - 2 * nxt.g - 2 * nxt.f - f) % MOD;
  return {f, g, h};
}
```

5.3 NOD

```
N = input()
primes = array containing primes till 10^6
ans = 1
for all p in primes :
    if p*p*p > N:
        break
    count = 1
    while N divisible by p:
        N = N/p
        count = count + 1
    ans = ans * count
if N is prime:
    ans = ans * 2
else if N is square of a prime:
    ans = ans * 3
else if N != 1:
    ans = ans * 4
```

5.4 Pollard Rho

```
we#include <bits/stdc++.h>
using namespace std;
typedef long long ll;
typedef unsigned long long ull;
namespace Rho {
  ull mul (ull a, ull b, ull mod) {
    ll ret = a * b - mod * (ull) (1.L / mod * a * b);
    return ret + mod * (ret < 0) - mod * (ret >= (ll) mod);
  }
  ull bigMod (ull a, ull e, ull mod) {
    ull ret = 1;
    while (e) {
      if (e & 1) ret = mul(ret, a, mod);
      a = mul(a, a, mod), e >>= 1;
    }
    return ret;
  }
  bool isPrime (ull n) {
    if (n < 2 or n % 6 % 4 != 1) return (n | 1) == 3;
    ull a[] = {2, 325, 9375, 28178, 450775, 9780504, 1795265022};
    ull s = __builtin_ctzll(n - 1), d = n >> s;
    for (ull x : a) {
      ull p = bigMod(x % n, d, n), i = s;
      while (p != 1 and p != n - 1 and x % n and i--) p = mul(p, p, n);
      if (p != n - 1 and i != s) return 0;
    }
    return 1;
  }
  ull pollard (ull n) {
    auto f = [&] (ull x) {return mul(x, x, n) + 1;};
    ull x = 0, y = 0, t = 0, prod = 2, i = 1, q;
    while (t++ % 40 or __gcd(prod, n) == 1) {
      if (x == y) x = ++i, y = f(x);
      if ((q = mul(prod, max(x, y) - min(x, y), n))) prod = q;
      x = f(x), y = f(f(y));
    }
    return __gcd(prod, n);
  }
  vector <ull> factor (ull n) {
    if (n == 1) return {};
    if (isPrime(n)) return {n};
    ull x = pollard(n);
    auto l = factor(x), r = factor(n / x);
    l.insert(l.end(), r.begin(), r.end());
    return l;
  }
};
int t; ll n;
int main() {
  cin >> t;
  while (t--) {
    scanf("%lld", &n);
    vector <ull> facs = Rho::factor(n);
    sort(facs.begin(), facs.end());
    printf("%d", (int) facs.size());
    for (auto it : facs) printf(" %llu", it);
    puts("");
  }
  return 0;
}
```

5.5 catalan

```
//Recursive
const int MOD = ....
const int MAX = ....
int catalan[MAX];
void init() {
    catalan[0] = catalan[1] = 1;
    for (int i=2; i<=n; i++) {
        catalan[i] = 0;
        for (int j=0; j < i; j++) {
            catalan[i] += (catalan[j] * catalan[i-j-1]) % MOD;
            if (catalan[i] >= MOD) {
                catalan[i] -= MOD;
            }
        }
    }
}
//Analytical formula:
ans = ncr(2*n,n)-ncr(2*n,n-1)= ncr(2*n,n)/(n+1)
```

5.6 crt

```
//r[i][j]= inverse of p[i] modulo p[j]
//ans= x[0]+x[1]*p[0]+x[2]*(p[0]*p[1])+...+x[k-1]*(p[0]*p[1]*p[2]*...*p[k-2])
//ans %= ((p[0]*p[1]*p[2]*...*p[k-1])
for (int i = 0; i < k; ++i) {
    x[i] = a[i];
    for (int j = 0; j < i; ++j) {
        x[i] = r[j][i] * (x[i] - x[j]);
        x[i] = x[i] % p[i];
        if (x[i] < 0)
            x[i] += p[i];
    }
}
ll mul= p[0],res=x[0],tot=1;
F(i,0,k)tot *= p[i];
F(i,1,k){
 res+= x[i]*mul;
 res %= tot;
 mul *= p[i];
}
res %= mul;
return res;
```

5.7 derangement

```
int derangement(int n)
{
if(!n) return n;
if(n <= 2) return n-1;
return (n-1)*(derangement(n-1) + derangement(n-2));
}
```

5.8 diophantine

```
void print_solution(int a, int b, int c)
{
    int x, y;
    if (a == 0 && b == 0) {
        if (c == 0) {
            cout << "Infinite Solutions Exist" << endl;
        }
        else {
            cout << "No Solution exists" << endl;
        }
    }
    int gcd = gcd_extend(a, b, x, y);
    if (c % gcd != 0) {
        cout<< "No Solution exists"<< endl;
    }
    else {
        cout << "x = " << x * (c / gcd)<< ", y = " <<
         y * (c / gcd)<< endl;
    }
}
```

5.9 discrete_log

```
// Returns minimum x for which a ^ x % m = b % m, a
 and m are coprime.
int solve(int a, int b, int m) {
    a %= m, b %= m;
    int n = sqrt(m) + 1;
    int an = 1;
    for (int i = 0; i < n; ++i)
        an = (an * 1ll * a) % m;
    unordered_map<int, int> vals;
    for (int q = 0, cur = b; q <= n; ++q) {
        vals[cur] = q;
        cur = (cur * 1ll * a) % m;
    }
    for (int p = 1, cur = 1; p <= n; ++p) {
        cur = (cur * 1ll * an) % m;
        if (vals.count(cur)) {
            int ans = n * p - vals[cur];
            return ans;
        }
    }
    return -1;
}
```

5.10 factorial_mod_p

```
// O(log_p(n)) gives me n! % p for large n, p
int factmod(int n, int p) {
    vector<int> f(p);
    f[0] = 1;
    for (int i = 1; i < p; i++)
        f[i] = f[i-1] * i % p;
    int res = 1;
    while (n > 1) {
        if ((n/p) % 2)
            res = p - res;
        res = res * f[n%p] % p;
        n /= p;
    }
    return res;
}
```

5.11 fft

```
typedef complex<double> base;
#define PI acos(-1)
void fft(vector<base> &a, bool invert){
    int n = (int)a.size();
    for (int i = 1, j = 0; i < n; ++i){
        int bit = n >> 1;
        for (; j >= bit; bit >>= 1) j -= bit;
        j += bit;
        if (i < j)swap(a[i], a[j]);
    }
    for (int len = 2; len <= n; len <<= 1){
        double ang = 2 * PI / len * (invert ? -1 : 1);
        base wlen(cos(ang), sin(ang));
        for (int i = 0; i < n; i += len){
            base w(1);
            for (int j = 0; j < len / 2; ++j){
                base u = a[i + j], v = a[i + j + len /
                 2] * w;
                a[i + j] = u + v;
                a[i + j + len / 2] = u - v;
                w *= wlen;
            }
        }
    }
    if (invert) for (int i = 0; i < n; ++i) a[i] /= n;
}
void multiply(const vector<int> &a, const vector<int>
 &b, vector<int> &res){
    vector<base> fa(a.begin(), a.end()), fb(b.begin(),
     b.end());
    size_t n = 1;
    while (n < max(a.size(), b.size())) n <<= 1;
    n <<= 1;
    fa.resize(n), fb.resize(n);
    fft(fa, false), fft(fb, false);
    for (size_t i = 0; i < n; ++i) fa[i] *= fb[i];
    fft(fa, true); res.resize(n);
    for (size_t i = 0; i < n; ++i) res[i] =
     int(fa[i].real() + 0.5);
}
```

5.12 find_roots

```
/*Description: Finds the real roots to a polynomial.
Usage: polyRoots({{2,-3,1}},-1e9,1e9) // solve x2-3x+2
 = 0
Time: O(n^2log(1/)))*/
struct Poly {
    vector<double> a;
    double operator()(double x) const {
        double val = 0;
        for (int i = a.size(); i--;) (val *= x) +=
         a[i];
        return val;
    }
    void diff() {
        for (int i = 1; i < a.size(); ++i) a[i - 1] =
         i * a[i];
        a.pop_back();
    }
    void divroot(double x0) {
        double b = a.back(), c;
        a.back() = 0;
        for (int i = a.size() - 1; i--;) c = a[i],
         a[i] = a[i + 1] * x0 + b, b = c;
        a.pop_back();
    }
};
vector<double> polyRoots(Poly p, double xmin = -1e9,
 double xmax = 1e9) {
    if (p.a.size() == 2) {
        return {-p.a[0] / p.a[1]};
    }
    vector<double> ret;
    Poly der = p;
    der.diff();
    auto dr = polyRoots(der, xmin, xmax);
    dr.push_back(xmin - 1);
    dr.push_back(xmax + 1);
    sort(dr.begin(), dr.end());
    for (int i = 0; i < dr.size() - 1; ++i) {
        double l = dr[i], h = dr[i + 1];
        bool sign = p(l) > 0;
        if (sign ^ (p(h) > 0)) {
            for (int it = 0; it < 60; ++it) {  //
             while (h-l > 1e-8)
                double m = (l + h) / 2, f = p(m);
                if ((f <= 0) ^ sign)
                    l = m;
                else
                    h = m;
            }
            ret.push_back((l + h) / 2);
        }
    }
    return ret;
}
```

5.13 gauss_eliminition

```
const double EPS = 1e-9;
const int INF = 2; // it doesn't actually have to be
 infinity or a big number
int gauss (vector < vector<double> > a, vector<double>
 & ans) {
    int n = (int) a.size();
    int m = (int) a[0].size() - 1;
    vector<int> where (m, -1);
    for (int col=0, row=0; col<m && row<n; ++col) {
        int sel = row;
        for (int i=row; i<n; ++i)
            if (abs (a[i][col]) > abs (a[sel][col]))
                sel = i;
        if (abs (a[sel][col]) < EPS)
            continue;
        for (int i=col; i<=m; ++i)
            swap (a[sel][i], a[row][i]);
        where[col] = row;
        for (int i=0; i<n; ++i)
            if (i != row) {
                double c = a[i][col] / a[row][col];
                for (int j=col; j<=m; ++j)
                    a[i][j] -= a[row][j] * c;
            }
        ++row;
    }
    ans.assign (m, 0);
    for (int i=0; i<m; ++i)
        if (where[i] != -1)
            ans[i] = a[where[i]][m] / a[where[i]][i];
    for (int i=0; i<n; ++i) {
        double sum = 0;
        for (int j=0; j<m; ++j)
            sum += ans[j] * a[i][j];
        if (abs (sum - a[i][m]) > EPS)
            return 0;
    }
    for (int i=0; i<m; ++i)
        if (where[i] == -1)
            return INF;
    return 1;
}
//modular
int gauss (vector < bitset<N> > a, int n, int m,
 bitset<N> & ans) {
    vector<int> where (m, -1);
    for (int col=0, row=0; col<m && row<n; ++col) {
        for (int i=row; i<n; ++i)
            if (a[i][col]) {
                swap (a[i], a[row]);
                break;
```

```
        }
        if (! a[row][col])
            continue;
        where[col] = row;
        for (int i=0; i<n; ++i)
            if (i != row && a[i][col])
                a[i] ^= a[row];
        ++row;
    }
    // The rest of implementation is the same as
     ↪ above
}
//rank
const double EPS = 1E-9;
int compute_rank(vector<vector<double>> A) {
    int n = A.size();
    int m = A[0].size();
    int rank = 0;
    vector<bool> row_selected(n, false);
    for (int i = 0; i < m; ++i) {
        int j;
        for (j = 0; j < n; ++j) {
            if (!row_selected[j] && abs(A[j][i]) > EPS)
                break;
        }
        if (j != n) {
            ++rank;
            row_selected[j] = true;
            for (int p = i + 1; p < m; ++p)
                A[j][p] /= A[j][i];
            for (int k = 0; k < n; ++k) {
                if (k != j && abs(A[k][i]) > EPS) {
                    for (int p = i + 1; p < m; ++p)
                        A[k][p] -= A[j][p] * A[k][i];
                }
            }
        }
    }
    return rank;
}
```

5.14 gen_all_k_combs

```
vector<int> ans;
void gen(int n, int k, int idx, bool rev) {
    if (k > n || k < 0)
        return;
    if (!n) {
        for (int i = 0; i < idx; ++i) {
            if (ans[i])
                cout << i + 1;
        }
        cout << "\n";
        return;
    }
    ans[idx] = rev;
    gen(n - 1, k - rev, idx + 1, false);
    ans[idx] = !rev;
    gen(n - 1, k - !rev, idx + 1, true);
}
void all_combinations(int n, int k) {
    ans.resize(n);
    gen(n, k, 0, false);
}
```

5.15 integrate_adaptive

```
/*Description: Fast integration using an adaptive
 ↪ Simpsons rule.
Usage: double sphereVolume = quad(-1, 1, [](double x) {
return quad(-1, 1, [&](double y) {
return quad(-1, 1, [&](double z) {
return x*x + y*y + z*z < 1; });});});*/
typedef double d;
#define S(a, b) (f(a) + 4 * f((a + b) / 2) + f(b)) *
 ↪ (b - a) / 6
template <class F>
d rec(F& f, d a, d b, d eps, d S) {
    d c = (a + b) / 2;
    d S1 = S(a, c), S2 = S(c, b), T = S1 + S2;
    if (abs(T - S) <= 15 * eps || b - a < 1e-10)
        return T + (T - S) / 15;
    return rec(f, a, c, eps / 2, S1) + rec(f, c, b,
     ↪ eps / 2, S2);
}
template <class F>
d quad(d a, d b, F f, d eps = 1e-8) {
    return rec(f, a, b, eps, S(a, b));
}
```

5.16 lagrange_interpolation

```
/*Description: A polynomial of degree d can be
 ↪ uniquely identified
given its values on d + 1 unique points. O(n) to
 ↪ pre-calculate given
the first n points (x=0 to n-1) of the polynomial.
 ↪ Then answer each
query to interpolate the xth term in O(n). All values
 ↪ are done modulo
mod, which needs to be a prime as we need its inverse
 ↪ modulo. Also
includes an additional helper function called
 ↪ find_degree(terms, mod).
Given at least the first d+2 points of a polynomial of
 ↪ degree d, it finds
d in roughly O(n log d). Note, n should not exceed mod
 ↪ due to the
way modular inverse is used. In such cases, we can use
 ↪ interpolation
without modulo in big integers and take the remainder
 ↪ later
Time: O (n) */
using namespace std;
struct Lagrange {
    vector<int> terms, dp;
    int mod, n;
    Lagrange() {}
    Lagrange(const vector<int>& terms, int mod) :
     ↪ terms(terms), mod(mod) {
        n = terms.size();
        assert(n <= mod);
        int i, v, f;
        for (f = 1, i = 1; i < n; i++) f = (long
         ↪ long)f * i % mod;
        v = expo(f, mod - 2);
        vector<int> inv(n, v);
        for (i = n - 1; i > 0; i--) {
            inv[i - 1] = (long long)inv[i] * i % mod;
        }
        dp.resize(n, 1);
        for (i = 0; i < n; i++) {
            dp[i] = (long long)inv[i] * inv[n - i - 1]
             ↪ % mod;
            dp[i] = (long long)dp[i] * terms[i] % mod;
        }
    }
    int expo(int a, int b) {
        int res = 1;
        while (b) {
            if (b & 1) res = (long long)res * a % mod;
            a = (long long)a * a % mod;
            b >>= 1;
        }
        return res;
    }
    int interpolate(long long x) {
        if (x < n) return terms[x] % mod;
        x %= mod;
        int i, w;
        vector<int> X(n, 1), Y(n, 1);
        for (i = 1; i < n; i++) {
            X[i] = (long long)X[i - 1] * (x - i + 1) %
             ↪ mod;
            if (X[i] < 0) X[i] += mod;
        }
        for (i = n - 2; i >= 0; i--) {
            Y[i] = (long long)Y[i + 1] * (x - i - 1) %
             ↪ mod;
            if (Y[i] < 0) Y[i] += mod;
        }
        long long res = 0;
        for (i = 0; i < n; i++) {
            w = ((long long)X[i] * Y[i] % mod) * dp[i]
             ↪ % mod;
            if ((n - i + 1) & 1) w = mod - w;
            res += w;
        }
        return res % mod;
    }
};
vector<int> get_terms(const vector<int>& terms, int
 ↪ mod, int l, int r) {
    auto lagrange = Lagrange(terms, mod);
    vector<int> res;
    for (int i = l; i <= r; i++) {
        res.push_back(lagrange.interpolate(i));
    }
    return res;
}
int find_degree(const vector<int>& terms, int mod) {
    long long v = mod;
    int k = 1, n = terms.size();
    while (v < INT_MAX) {
        v *= mod;
        k++;
    }
    int l = 1 << 30, r = l + k - 1;
    auto expected = get_terms(terms, mod, l, r);
    int low = 1, high = n - 1;
    while ((low + 1) < high) {
        int mid = (low + high) >> 1;
        vector<int> v(terms.begin(), terms.begin() +
         ↪ mid);
        if (get_terms(v, mod, l, r) == expected)
            high = mid;
        else
            low = mid;
    }
    for (int d = low; d <= high; d++) {
        vector<int> v(terms.begin(), terms.begin() +
         ↪ d);
        if (get_terms(v, mod, l, r) == expected)
         ↪ return d - 1;
    }
    return -1;
}
int main() {
    const int mod = 1000000007;
    vector<int> terms = vector<int>{0, 1, 5, 14, 30};
    auto lagrange = Lagrange(terms, mod);
    assert(lagrange.interpolate(5) == 55);
    assert(lagrange.interpolate(6) == 91);
    assert(lagrange.interpolate(1 << 30) == 300663155);
    assert(lagrange.interpolate(1LL << 60) ==
     ↪ 717860166);
    assert(find_degree(terms, mod) == 3);
```

```
    terms.pop_back();
    assert(find_degree(terms, mod) == -1);
    return 0;
}
```

5.17 matrix_expo

```
ll mod=(1e9)+7;
struct Matrix{
    int row, col;
    vector<vector<ll>> mat;
    Matrix(int x, int y){
        row=x;
        col=y;
        mat.assign(row,vector<ll>(col,0));
    }
    Matrix operator *(Matrix &other){
        assert(col==other.row);
        Matrix product(row,other.col);
        for(int i=0;i<row;i++){
            for(int j=0;j<col;j++){
                for(int k=0;k<other.col;k++){
                    product.mat[i][k]=(product.mat[i][
                        k]+(mat[i][j]*other.mat[j][k])
                        %mod)%mod;
                }
            }
        }
        return product;
    }
};
Matrix expo(Matrix &m, ll n){
    assert(m.row==m.col);
    Matrix ret(m.row,m.col);
    for(int i=0;i<m.row;i++) ret.mat[i][i]=1;
    while(n){
        if(n&1) ret=ret*m;
        n/=2;
        m=m*m;
    }
    return ret;
}
```

5.18 next_lexicographical_k_comb

```
bool next_combination(vector<int>& a, int n) {
    int k = (int)a.size();
    for (int i = k - 1; i >= 0; i--) {
        if (a[i] < n - k + i + 1) {
            a[i]++;
            for (int j = i + 1; j < k; j++)
                a[j] = a[j - 1] + 1;
            return true;
        }
    }
    return false;
}
```

5.19 ntt

```
const int mod = 998244353;
const int root = 15311432;
const int k = 1 << 23;
int root_1;
vector<int> rev;
void pre(int sz){
    root_1 = bigmod(root, mod - 2, mod);
    if (rev.size() == sz) return;
    rev.resize(sz);
    rev[0] = 0;
    int lg_n = __builtin_ctz(sz);
    for (int i = 1; i < sz; ++i)
        rev[i]=(rev[i>>1]>>1)|((i&1)<<(lg_n-1));
}
void fft(vector<int> &a, bool inv){
    int n = a.size();
    for (int i = 1; i < n - 1; ++i) if (i < rev[i])
        swap(a[i], a[rev[i]]);
    for (int len = 2; len <= n; len <<= 1) {
        int wlen = inv ? root_1 : root;
        for (int i = len; i < k; i <<= 1) wlen = 1ll *
            wlen * wlen % mod;
        for (int st = 0; st < n; st += len){
            int w = 1;
            for (int j = 0; j < len / 2; j++){
                int ev = a[st + j];
                int od = 1ll * a[st + j + len / 2] * w
                    % mod;
                a[st + j] = ev + od < mod ? ev + od :
                    ev + od - mod;
                a[st + j + len / 2] = ev - od >= 0 ?
                    ev - od : ev - od + mod;
                w = 1ll * w * wlen % mod;
            }
        }
    }
    if (inv){
        int n_1 = bigmod(n, mod - 2, mod);
        for (int &x : a) x = 1ll * x * n_1 % mod;
    }
}
vector<int> mul(vector<int> &a, vector<int> &b){
    int n = a.size(), m = b.size(), sz = 1;
    while (sz < n + m - 1) sz <<= 1;
    vector<int> x(sz), y(sz), z(sz);
    for (int i = 0; i < sz; ++i){
        x[i] = i < n ? a[i] : 0;
        y[i] = i < m ? b[i] : 0;
    }
    pre(sz);fft(x, 0);fft(y, 0);
    for (int i = 0; i < sz; ++i) z[i] = 1ll * x[i] *
        y[i] % mod;
    fft(z, 1);z.resize(n + m - 1);
    return z;
}
```

5.20 seg_sieve

```
/*
Segmented Sieve
This code was for 1 <= a <= b <= 2^31-1
Change variable types appropriately.
*/
bool notPrime[ ? ];
void segmented_sieve(int a, int b)
{
    int p, f;
    mem(notPrime, 0);
    for (int i = 0; i < tot_prime; i++)
    {
        p = prime[i];
        if (a % p == 0)
            f = a;
        else
            f = (a - (a % p) + p);
        f = max(p * p, f);
        for (unsigned j = f; j <= b; j += p)
            notPrime[j - a] = true;
    }
    if (a == 1)
        notPrime[0] = 1;
}
```

5.21 stirling

```
that no box is empty□.
int stirling2(int n, int k)
{
 if(n < k)
 return 0;
 if(k == 1)
 return 1;
 if(dp[n][k] == dp[n][k])
 return dp[n][k];
 return dp[n][k] = stirling2(n-1,k-1) +
    stirling2(n-1,k)*k;
}
is empty
int stirling1(int n, int k)
{
 dp[n][k] = stirling1(n-1,k-1) + stirling(n-1,k)*n-1;
}
```

5.22 stirling_number_of_the_second_kind

```
// 1 / k! * sum (-1)^i nCr(k, i) * (k - i) ^ n
ll f(int n, int k) {
    ll res = 0;
    for (int i = 0; i < k; ++i) {
        if (i & 1) res = (res - nCr(k, i) * bp(k - i,
            n, mod) % mod + mod) % mod;
        else res = (res + nCr(k, i) * bp(k - i, n,
            mod) % mod) % mod;
    }
    if (res < 0) res += mod;
    return res * ifac[k] % mod;
}
```

5.23 sum_of_totient

```
using namespace __gnu_pbds;
const int N = 3e5 + 9, mod = 998244353;
template <const int32_t MOD>
struct modint {
    int32_t value;
    modint() = default;
    modint(int32_t value_) : value(value_) {}
    inline modint<MOD> operator+(modint<MOD> other)
        const {
        int32_t c = this->value + other.value;
        return modint<MOD>(c >= MOD ? c - MOD : c);
    }
    inline modint<MOD> operator-(modint<MOD> other)
        const {
        int32_t c = this->value - other.value;
        return modint<MOD>(c < 0 ? c + MOD : c);
    }
    inline modint<MOD> operator*(modint<MOD> other)
        const {
        int32_t c = (int64_t)this->value * other.value
            % MOD;
        return modint<MOD>(c < 0 ? c + MOD : c);
    }
    inline modint<MOD> &operator+=(modint<MOD> other) {
        this->value += other.value;
        if (this->value >= MOD)
            this->value -= MOD;
        return *this;
    }
    inline modint<MOD> &operator-=(modint<MOD> other) {
        this->value -= other.value;
        if (this->value < 0)
            this->value += MOD;
        return *this;
    }
    inline modint<MOD> &operator*=(modint<MOD> other) {
        this->value = (int64_t)this->value *
            other.value %
```

```cpp
        MOD;
    if (this->value < 0) this->value += MOD;
    return *this;
  }
  inline modint<MOD> operator-() const { return
    modint<MOD>(this->value ? MOD - this->value :
    0); }
  modint<MOD> pow(uint64_t k) const {
    modint<MOD> x =
                *this,
            y = 1;
    for (; k; k >>= 1) {
      if (k & 1) y *= x;
      x *= x;
    }
    return y;
  }
  modint<MOD> inv() const { return pow(MOD - 2); }
   // MOD must be a prime
  inline modint<MOD> operator/(modint<MOD> other)
   const { return *this * other.inv(); }
  inline modint<MOD> operator/=(modint<MOD> other) {
   return *this *= other.inv(); }
  inline bool operator==(modint<MOD> other) const {
   return value == other.value; }
  inline bool operator!=(modint<MOD> other) const {
   return value != other.value; }
  inline bool operator<(modint<MOD> other) const {
   return value < other.value; }
  inline bool operator>(modint<MOD> other) const {
   return value > other.value; }
};
template <int32_t MOD>
modint<MOD> operator*(int64_t value, modint<MOD> n) {
 return modint<MOD>(value) * n; }
template <int32_t MOD>
modint<MOD> operator*(int32_t value, modint<MOD> n) {
 return modint<MOD>(value % MOD) * n; }
template <int32_t MOD>
istream &operator>>(istream &in, modint<MOD> &n) {
 return in >> n.value; }
template <int32_t MOD>
ostream &operator<<(ostream &out, modint<MOD> n) {
 return out << n.value; }
using mint = modint<mod>;
namespace Dirichlet {
// solution for f(x) = phi(x)
const int T = 1e7 + 9;
long long phi[T];
gp_hash_table<long long, mint> mp;
mint dp[T], inv;
int sz, spf[T], prime[T];
void init() {
  memset(spf, 0, sizeof spf);
  phi[1] = 1;
  sz = 0;
  for (int i = 2; i < T; i++) {
    if (spf[i] == 0) phi[i] = i - 1, spf[i] = i,
     prime[sz++] = i;
    for (int j = 0; j < sz && i * prime[j] < T &&
     prime[j] <= spf[i]; j++) {
      spf[i * prime[j]] = prime[j];
      if (i % prime[j] == 0)
        phi[i * prime[j]] = phi[i] * prime[j];
      else
        phi[i * prime[j]] = phi[i] * (prime[j]
         - 1);
    }
  }
  dp[0] = 0;
  for (int i = 1; i < T; i++) dp[i] = dp[i - 1] +
   phi[i] % mod;
  inv = 1;  // g(1)
}
mint p_c(long long n) {
  if (n % 2 == 0) return n / 2 % mod * ((n + 1) %
   mod) % mod;
  return (n + 1) / 2 % mod * (n % mod) % mod;
}
mint p_g(long long n) {
  return n % mod;
}
mint solve(long long x) {
  if (x < T) return dp[x];
  if (mp.find(x) != mp.end()) return mp[x];
  mint ans = 0;
  for (long long i = 2, last; i <= x; i = last + 1) {
    last = x / (x / i);
    ans += solve(x / i) * (p_g(last) - p_g(i - 1));
  }
  ans = p_c(x) - ans;
  ans /= inv;
  return mp[x] = ans;
}
};  // namespace Dirichlet
```

5.24 totient

```cpp
int phi(int n) {
  int result = n;
  for (int i = 2; i * i <= n; i++) {
    if (n % i == 0) {
      while (n % i == 0)
        n /= i;
      result -= result / i;
    }
  }
  if (n > 1)
    result -= result / n;
  return result;
}
void phi_1_to_n(int n) {
  vector<int> phi(n + 1);
  phi[0] = 0;
  phi[1] = 1;
  for (int i = 2; i <= n; i++)
    phi[i] = i;
  for (int i = 2; i <= n; i++) {
    if (phi[i] == i) {
      for (int j = i; j <= n; j += i)
        phi[j] -= phi[j] / i;
    }
  }
}
```

5.25 xor_basis

```cpp
int basis[d]; // basis[i] keeps the mask of the vector
 whose f value is i
int sz;
void insertVector(int mask) {
 for (int i = 0; i < d; i++) {
  if ((mask & 1 << i) == 0) continue;
  if (!basis[i]) { // If there is no basis vector with
     the i'th bit set, then insert this vector into
     the basis
   basis[i] = mask;
   ++sz;
   return;
  }
  mask ^= basis[i]; // Otherwise subtract the basis
   vector from this vector
 }
}
```

6 Misc

6.1 check

```bash
g++ a.cpp -o a.out && g++ ac.cpp -o ac.out && g++
 gen.cpp -o gen && for ((i=0;i<1000;i++)) \
do
echo $i
./gen > in
./a.out < inp > out
./ac.out < inp > out1
diff out1 out2
if [ $? -ne 0 ]
then
echo "-----Input----"
cat in
echo "------Output----"
cat out
echo "-----Accepted----"
cat out1
break
fi
done
```

6.2 debug

```cpp
struct debug {
#define contPrint { *this << "["; \
        int f = 0; for(auto it : x) { *this << (f?",
         ":""); *this << it; f = 1;} \
        *this << "]"; return *this;}
    ~debug(){cerr << endl;}
    template<class c> debug& operator<<(c x) {cerr <<
     x; return *this;}
    template<class c, class d>
    debug& operator<<(pair<c, d> x) {*this << "(" <<
     x.first << ", " << x.second << ")";
        return *this;}
    template<class c> debug& operator<<(vector<c> x)
     contPrint;
#undef contPrint
};
#define dbg(x) "[" << #x << ": " << x << "]  "
#define Wa() cerr << "[LINE: " << __LINE__ << "] -> ";
 debug() <<
```

6.3 flags

```bash
g++ -std=c++17  -Wall -Wextra -pedantic -Wshadow
    -Wformat=2 -Wfloat-equal -Wconversion -Wlogical-op
    -Wshift-overflow=2 -Wduplicated-cond -Wcast-qual
    -Wcast-align -D_GLIBCXX_DEBUG
    -D_GLIBCXX_DEBUG_PEDANTIC -D_FORTIFY_SOURCE=2
    -fsanitize=address -fsanitize=undefined
    -fno-sanitize-recover -fstack-protector -o $1
    -Wno-unused-result $1.cpp
```

6.4 interval_container

```cpp
/* Description: Add and remove intervals from a set of
    disjoint intervals. Will merge the added interval
    with any overlapping intervals in
the set when adding. Intervals are [inclusive,
 exclusive).
Time: O (log N)
 */
set<pii>::iterator addInterval(set<pii>& is, int L,
 int R) {
    if (L == R) return is.end();
    auto it = is.lower_bound({L, R}), before = it;
    while (it != is.end() && it->first <= R) {
        R = max(R, it->second);
        before = it = is.erase(it);
```

```cpp
    }
    if (it != is.begin() && (--it)->second >= L) {
        L = min(L, it->first);
        R = max(R, it->second); is.erase(it);
    }
    return is.insert(before, {L, R});
}
void removeInterval(set<pii>& is, int L, int R) {
    if (L == R) return;
    auto it = addInterval(is, L, R);
    auto r2 = it->second;
    if (it->first == L)
        is.erase(it);
    else
        (int&)it->second = L;
    if (R != r2) is.emplace(R, r2);
}
```

6.5 interval_cover

```cpp
template <class T>
vi cover(pair<T, T> G, vector<pair<T, T>> I) {
    vi S(sz(I)), R;
    iota(all(S), 0);
    sort(all(S), [&](int a, int b) { return I[a] < I[b]; });
    T cur = G.first;
    int at = 0;
    while (cur < G.second) {  // (A)
        pair<T, int> mx = make_pair(cur, -1);
        while (at < sz(I) && I[S[at]].first <= cur) {
            mx = max(mx, make_pair(I[S[at]].second, S[at]));
            at++;
        }
        if (mx.second == -1) return {};
        cur = mx.first;
        R.push_back(mx.second);
    }
    return R;
}
```

6.6 pragma

```cpp
// Pragmas
#pragma comment(linker, "/stack:200000000")
#pragma GCC optimize("O3,unroll-loops")
#pragma GCC target("avx,avx2,fma")
```

6.7 random

```cpp
// shuffle(v.begin(), v.end(), default_random_engine(rnd(1, 1000)));
mt19937 rng(chrono::steady_clock::now().time_since_epoch().count());
ll rnd(ll l, ll r) {
    return uniform_int_distribution<ll>(l, r) (rng);
}
```

6.8 vimrc

```vim
imap jk <Esc>
set nu
set mouse=a
set autoindent
set tabstop=4
set shiftwidth=4
set smartindent
set relativenumber
set laststatus=2
set hlsearch
let mapleader = " "
nnoremap <leader>s :w<Enter>
nnoremap <leader>y ggVG"+y<CR>
syntax on
vnoremap <leader>/ :s!^!//!<CR> :noh <CR>
vnoremap <leader>u :s!^//!!<CR>
nnoremap <leader>/ :s!^!//!<CR> :noh <CR>
nnoremap <leader>u :s!^//!!<CR>
```

7 Notes

7.1 Counting

1. **Lucas Theorem**
For non-negative integers m and n and a prime p, the following congruence relation holds: :

$$\binom{m}{n} \equiv \prod_{i=0}^{k} \binom{m_i}{n_i} \pmod p, \tag{1}$$

where :

$$m = m_k p^k + m_{k-1}p^{k-1} + \cdots + m_1 p + m_0,$$

and :

$$n = n_k p^k + n_{k-1}p^{k-1} + \cdots + n_1 p + n_0$$

are the base p expansions of m and n respectively. This uses the convention that $\binom{m}{n} = 0$ if $m \le n$.

2. **Stirling Numbers of the first kind**
$S(n,k)$ counts the number of permutations of n elements with k disjoint cycles.

$$S(n,k) = (n-1)\cdot S(n-1,k) + S(n-1,k-1) \tag{2}$$

where, $S(0,0) = 1, S(n,0) = S(0,n) = 0$

$$\sum_{k=0}^{n} S(n,k) = n! \tag{3}$$

3. **Stirling Numbers of the second kind**
$S(n,k)\cdot k!$ = number of ways to color n nodes using colors from 1 to k such that each color is used at least once.
An r-associated Stirling number of the second kind is the number of ways to partition a set of n objects into k subsets, with each subset containing at least r elements. It is denoted by $S_r(n,k)$ and obeys the recurrence relation.

$$S_r(n+1,k) = kS_r(n,k) + \binom{n}{r-1} S_r(n-r+1,k-1) \tag{4}$$

4. **Bell Numbers**
Counts the number of partitions of a set.

$$B_{n+1} = \sum_{k=0}^{n} \binom{n}{k} \cdot B_k \tag{5}$$

$B_n = \sum_{k=0}^{n} S(n,k)$, where $S(n,k)$ is stirling number of second kind.

5. **Some identities**
Vandermonde's Identify: $\sum_{k=0}^{r} \binom{m}{k}\binom{n}{r-k} = \binom{m+n}{r}$

Hockey-Stick Identify: $n,r \in N, n > r, \sum_{i=r}^{n} \binom{i}{r} = \binom{n+1}{r+1}$

Involutions: permutations such that p^2 = identity permutation. $a_0 = a_1 = 1$ and $a_n = a_{n-1} + (n-1)a_{n-2}$ for $n > 1$.

7.2 Fibonacci

Let A, B and n be integer numbers.

$$k = A - B$$

$$F_A F_B = F_{k+1}F_A^2 + F_k F_A F_{A-1} \tag{6}$$

$$\sum_{i=0}^{n} F_i^2 = F_{n+1}F_n \tag{7}$$

$$\sum_{i=0}^{n} F_i F_{i+1} = F_{n+1}^2 - (-1)^n \tag{8}$$

$$\sum_{i=0}^{n} F_i F_{i-1} = \sum_{i=0}^{n-1} F_i F_{i+1} \tag{9}$$

$$GCD(F_m, F_n) = F_{GCD(m,n)} \tag{10}$$

$$\sum_{0 \le k \le n} \binom{n-k}{k} = Fib_{n+1} \tag{11}$$

$$\gcd(F_n, F_{n+1}) = \gcd(F_n, F_{n+2}) = \gcd(F_{n+1}, F_{n+2}) = 1 \tag{12}$$

7.3 Notes

7.4 Geometry

7.4.1 Triangles

Circumradius: $R = \dfrac{abc}{4A}$, Inradius: $r = \dfrac{A}{s}$
Length of median (divides triangle into two equal-area triangles): $m_a = \frac{1}{2}\sqrt{2b^2 + 2c^2 - a^2}$

Length of bisector (divides angles in two): $s_a = \sqrt{bc\left[1 - \left(\dfrac{a}{b+c}\right)^2\right]}$

Law of tangents: $\dfrac{a+b}{a-b} = \dfrac{\tan\dfrac{\alpha+\beta}{2}}{\tan\dfrac{\alpha-\beta}{2}}$

7.4.2 Quadrilaterals

With side lengths a, b, c, d, diagonals e, f, diagonals angle θ, area A and magic flux $F = b^2 + d^2 - a^2 - c^2$:

$$4A = 2ef \cdot \sin\theta = F\tan\theta = \sqrt{4e^2f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is 180°, $ef = ac + bd$, and $A = \sqrt{(p-a)(p-b)(p-c)(p-d)}$.

7.4.3 Spherical coordinates

$$x = r\sin\theta\cos\phi \qquad r = \sqrt{x^2 + y^2 + z^2}$$
$$y = r\sin\theta\sin\phi \qquad \theta = \operatorname{acos}(z/\sqrt{x^2 + y^2 + z^2})$$
$$z = r\cos\theta \qquad \phi = \operatorname{atan2}(y, x)$$

7.5 Sums

$1^2 + 2^2 + 3^2 + \cdots + n^2 = \frac{n(2n+1)(n+1)}{6}$

$1^3 + 2^3 + 3^3 + \cdots + n^3 = \frac{n^2(n+1)^2}{4}$

$1^4 + 2^4 + 3^4 + \cdots + n^4 = \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}$

$\sum_{i=1}^{n} i^m = \frac{1}{m+1}\left[(n+1)^{m+1} - 1 - \sum_{i=1}^{n}\left((i+1)^{m+1} - i^{m+1} - (m+1)i^m\right)\right]$

$\sum_{i=1}^{n-1} i^m = \frac{1}{m+1}\sum_{k=0}^{m}\binom{m+1}{k}B_k n^{m+1-k}$

$\sum_{k=0}^{n} kx^k = (x - (n+1)x^{n+1} + nx^{n+2})/(x-1)^2$

7.6 Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \ldots, (-\infty < x < \infty)$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \ldots, (-1 < x \le 1)$$

$$\sqrt{1+x} = 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{2x^3}{32} - \frac{5x^4}{128} + \ldots, (-1 \le x \le 1)$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \ldots, (-\infty < x < \infty)$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \ldots, (-\infty < x < \infty)$$

$$(x+a)^{-n} = \sum_{k=0}^{\infty} (-1)^k \binom{n+k-1}{k} x^k a^{-n-k}$$

7.7 Pythagorean Triples

The Pythagorean triples are uniquely generated by

$$a = k\cdot(m^2 - n^2),\ b = k\cdot(2mn),\ c = k\cdot(m^2+n^2),$$

with $m > n > 0$, $k > 0$, $m \perp n$, and either m or n even.

7.8 Number Theory

7.8.1 Primes

$p = 962592769$ is such that $2^{21} \mid p-1$, which may be useful. For hashing use 970592641 (31-bit number), 31443539979727 (45-bit), 3006703054056749 (52-bit). There are 78498 primes less than 1 000 000.

Primitive roots exist modulo any prime power p^a, except for $p = 2, a > 2$, and there are $\phi(\phi(p^a))$ many. For $p = 2, a > 2$, the group $\mathbb{Z}_{2^a}^{\times}$ is instead isomorphic to $\mathbb{Z}_2 \times \mathbb{Z}_{2^{a-2}}$.

7.8.2 Estimates

$\sum_{d|n} d = O(n \log\log n)$.

The number of divisors of n is at most around 100 for $n < 5e4$, 500 for $n < 1e7$, 2000 for $n < 1e10$, 200 000 for $n < 1e19$.

7.8.3 Perfect numbers

$n > 1$ is called perfect if it equals sum of its proper divisors and 1. Even n is perfect iff $n = 2^{p-1}(2^p - 1)$ and $2^p - 1$ is prime (Mersenne's). No odd perfect numbers are yet found.

7.8.4 Carmichael numbers

A positive composite n is a Carmichael number ($a^{n-1} \equiv 1 \pmod n$ for all a: $\gcd(a,n) = 1$), iff n is square-free, and for all prime divisors p of n, $p-1$ divides $n-1$.

7.8.5 Mobius function

$\mu(1) = 1$. $\mu(n) = 0$, if n is not squarefree. $\mu(n) = (-1)^s$, if n is the product of s distinct primes. Let f, F be functions on positive integers. If for all $n \in N$, $F(n) = \sum_{d|n} f(d)$, then $f(n) = \sum_{d|n} \mu(d) F(\frac{n}{d})$, and vice versa. $\phi(n) = \sum_{d|n} \mu(d)\frac{n}{d}$. $\sum_{d|n} \mu(d) = 1$.

If f is multiplicative, then $\sum_{d|n} \mu(d) f(d) = \prod_{p|n}(1 - f(p))$, $\sum_{d|n} \mu(d)^2 f(d) = \prod_{p|n}(1 + f(p))$.

7.8.6 Legendre symbol

If p is an odd prime, $a \in \mathbb{Z}$, then $\left(\frac{a}{p}\right)$ equals 0, if $p|a$; 1 if a is a quadratic residue modulo p; and -1 otherwise. Euler's criterion: $\left(\frac{a}{p}\right) = a^{\left(\frac{p-1}{2}\right)} \pmod p$.

7.8.7 Jacobi symbol

If $n = p_1^{a_1}\cdots p_k^{a_k}$ is odd, then $\left(\frac{a}{n}\right) = \prod_{i=1}^{k}\left(\frac{a}{p_i}\right)^{k_i}$.

7.8.8 Primitive roots

If the order of g modulo m (min $n > 0$: $g^n \equiv 1 \pmod m$) is $\phi(m)$, then g is called a primitive root. If Z_m has a primitive root, then it has $\phi(\phi(m))$ distinct primitive roots. Z_m has a primitive root iff m is one of 2, 4, p^k, $2p^k$, where p is an odd prime. If Z_m has a primitive root g, then for all a coprime to m, there exists unique integer $i = \mathrm{ind}_g(a)$ modulo $\phi(m)$, such that $g^i \equiv a \pmod m$. $\mathrm{ind}_g(a)$ has logarithm-like properties: $\mathrm{ind}(1) = 0$, $\mathrm{ind}(ab) = \mathrm{ind}(a) + \mathrm{ind}(b)$.

If p is prime and a is not divisible by p, then congruence $x^n \equiv a \pmod p$ has $\gcd(n, p-1)$ solutions if $a^{(p-1)/\gcd(n,p-1)} \equiv 1 \pmod p$, and no solutions otherwise. (Proof sketch: let g be a primitive root, and $g^i \equiv a \pmod p$, $g^u \equiv x \pmod p$. $x^n \equiv a \pmod p$ iff $g^{nu} \equiv g^i \pmod p$ iff $nu \equiv i \pmod p$.)

7.8.9 Discrete logarithm problem

Find x from $a^x \equiv b \pmod m$. Can be solved in $O(\sqrt{m})$ time and space with a meet-in-the-middle trick. Let $n = \lceil\sqrt{m}\rceil$, and $x = ny - z$. Equation becomes $a^{ny} \equiv ba^z \pmod m$. Precompute all values that the RHS can take for $z = 0, 1, \ldots, n-1$, and brute force y on the LHS, each time checking whether there's a corresponding value for RHS.

7.8.10 Pythagorean triples

Integer solutions of $x^2 + y^2 = z^2$ All relatively prime triples are given by: $x = 2mn, y = m^2 - n^2, z = m^2 + n^2$ where $m > n, \gcd(m,n) = 1$ and $m \not\equiv n \pmod 2$. All other triples are multiples of these. Equation $x^2 + y^2 = 2z^2$ is equivalent to $(\frac{x+y}{2})^2 + (\frac{x-y}{2})^2 = z^2$.

7.8.11 Postage stamps/McNuggets problem

Let a, b be relatively-prime integers. There are exactly $\frac{1}{2}(a-1)(b-1)$ numbers *not* of form $ax + by$ $(x, y \ge 0)$, and the largest is $(a-1)(b-1) - 1 = ab - a - b$.

7.8.12 Fermat's two-squares theorem

Odd prime p can be represented as a sum of two squares iff $p \equiv 1 \pmod 4$. A product of two sums of two squares is a sum of two squares. Thus, n is a sum of two squares iff every prime of form $p = 4k+3$ occurs an even number of times in n's factorization.

7.9 Permutations

7.9.1 Factorial

n	1	2	3	4	5	6	7	8	9	10
$n!$	1	2	6	24	120	720	5040	40320	362880	3628800
n	11	12	13	14	15	16	17			
$n!$	4.0e7	4.8e8	6.2e9	8.7e10	1.3e12	2.1e13	3.6e14			
n	20	25	30	40	50	100	150	171		
$n!$	2e18	2e25	3e32	8e47	3e64	9e157	6e262	>DBL_MAX		

7.9.2 Cycles

Let $g_S(n)$ be the number of n-permutations whose cycle lengths all belong to the set S. Then

$$\sum_{n=0}^{\infty} g_S(n)\frac{x^n}{n!} = \exp\left(\sum_{n\in S}\frac{x^n}{n}\right)$$

7.9.3 Derangements

Permutations of a set such that none of the elements appear in their original position.

$$D(n) = (n-1)(D(n-1) + D(n-2)) = nD(n-1) + (-1)^n = \left\lfloor\frac{n!}{e}\right\rceil$$

7.9.4 Burnside's lemma

Given a group G of symmetries and a set X, the number of elements of X *up to symmetry* equals

$$\frac{1}{|G|}\sum_{g\in G}|X^g|,$$

where X^g are the elements fixed by g $(g.x = x)$.

If $f(n)$ counts "configurations" (of some sort) of length n, we can ignore rotational symmetry using $G = \mathbb{Z}_n$ to get

$$g(n) = \frac{1}{n}\sum_{k=0}^{n-1} f(\gcd(n,k)) = \frac{1}{n}\sum_{k|n} f(k)\phi(n/k)$$

7.10 Partitions and subsets

7.10.1 Partition function

Number of ways of writing n as a sum of positive integers, disregarding the order of the summands.

$$p(0) = 1,\ p(n) = \sum_{k\in\mathbb{Z}\setminus\{0\}} (-1)^{k+1} p(n - k(3k-1)/2)$$

$$p(n) \sim 0.145/n \cdot \exp(2.56\sqrt{n})$$

n	0	1	2	3	4	5	6	7	8	9	20	50	100
$p(n)$	1	1	2	3	5	7	11	15	22	30	627	~2e5	~2e8

7.11 General purpose numbers

7.11.1 Stirling numbers of the first kind

Number of permutations on n items with k cycles.

$$c(n,k) = c(n-1,k-1) + (n-1)c(n-1,k),\ c(0,0) = 1$$
$$\textstyle\sum_{k=0}^{n} c(n,k)x^k = x(x+1)\ldots(x+n-1)$$

$c(8,k) = 8, 0, 5040, 13068, 13132, 6769, 1960, 322, 28, 1$
$c(n,2) = 0, 0, 1, 3, 11, 50, 274, 1764, 13068, 109584, \ldots$

7.11.2 Eulerian numbers

Number of permutations $\pi \in S_n$ in which exactly k elements are greater than the previous element. k j:s s.t. $\pi(j) > \pi(j+1)$, $k+1$ j:s s.t. $\pi(j) \ge j$, k j:s s.t. $\pi(j) > j$.

$$E(n,k) = (n-k)E(n-1,k-1) + (k+1)E(n-1,k)$$

$$E(n,0) = E(n,n-1) = 1$$

$$E(n,k) = \sum_{j=0}^{k}(-1)^j\binom{n+1}{j}(k+1-j)^n$$

7.11.3 Stirling numbers of the second kind

Partitions of n distinct elements into exactly k groups.

$$S(n,k) = S(n-1,k-1) + kS(n-1,k)$$

$$S(n,1) = S(n,n) = 1$$

$$S(n,k) = \frac{1}{k!}\sum_{j=0}^{k}(-1)^{k-j}\binom{k}{j}j^n$$

7.11.4 Bell numbers

Total number of partitions of n distinct elements. $B(n) = 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, \ldots$. For p prime,

$$B(p^m + n) \equiv mB(n) + B(n+1) \pmod p$$

7.11.5 Bernoulli numbers

$\sum_{j=0}^{m}\binom{m+1}{j}B_j = 0$. $B_0 = 1, B_1 = -\frac{1}{2}$. $B_n = 0$, for all odd $n \neq 1$.

7.11.6 Catalan numbers

$$C_n = \frac{1}{n+1}\binom{2n}{n} = \binom{2n}{n} - \binom{2n}{n+1} = \frac{(2n)!}{(n+1)!n!}$$

$$C_0 = 1,\ C_{n+1} = \frac{2(2n+1)}{n+2}C_n,\ C_{n+1} = \sum C_i C_{n-i}$$

$C_n = 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, \ldots$

- sub-diagonal monotone paths in an $n \times n$ grid.
- strings with n pairs of parenthesis, correctly nested.
- binary trees with with $n+1$ leaves (0 or 2 children).
- ordered trees with $n+1$ vertices.
- ways a convex polygon with $n+2$ sides can be cut into triangles by connecting vertices with straight lines.
- permutations of $[n]$ with no 3-term increasing subseq.

7.12 Inequalities

7.12.1 Titu's Lemma

For positive reals $a_1, a_2, \ldots, a_n$ and $b_1, b_2, \ldots, b_n$,

$$\frac{{a_1}^2}{b_1} + \frac{{a_2}^2}{b_2} + \ldots + \frac{{a_n}^2}{b_n} \geq \frac{{a_1 + a_2 + \ldots + a_n}^2}{b_1 + b_2 + \ldots + b_n}$$

Equality holds if and only if $a_i = kb_i$ for a non-zero real constant k.

7.13 Games

7.13.1 Grundy numbers

For a two-player, normal-play (last to move wins) game on a graph (V, E): $G(x) = \text{mex}(\{G(y) : (x, y) \in E\})$, where $\text{mex}(S) = \min\{n \geq 0 : n \notin S\}$. x is losing iff $G(x) = 0$.

7.13.2 Sums of games

- *Player chooses a game and makes a move in it* Grundy number of a position is xor of grundy numbers of positions in summed games.
- *Player chooses a non-empty subset of games (possibly, all) and makes moves in all of them* A position is losing iff each game is in a losing position.
- *Player chooses a proper subset of games (not empty and not all), and makes moves in all chosen ones.* A position is losing iff grundy numbers of all games are equal.
- *Player must move in all games, and loses if can't move in some game* A position is losing if any of the games is in a losing position.

7.13.3 Misère Nim

A position with pile sizes $a_1, a_2, \ldots, a_n \geq 1$, not all equal to 1, is losing iff $a_1 \oplus a_2 \oplus \cdots \oplus a_n = 0$ (like in normal nim.) A position with n piles of size 1 is losing iff n is *odd*.

7.14 NumberTheory

$$\sum_{k=1}^{n} \frac{1}{\gcd(k,n)} = \sum_{d|n} \frac{1}{d} \cdot \phi\left(\frac{n}{d}\right) = \frac{1}{n} \sum_{d|n} d \cdot \phi(d) \tag{13}$$

$$\sum_{k=1}^{n} \frac{k}{\gcd(k,n)} = \frac{n}{2} \cdot \frac{1}{n} \cdot \sum_{d|n} d \cdot \phi(d) \tag{14}$$

$$\sum_{k=1}^{n} \frac{n}{\gcd(k,n)} = 2 * \sum_{k=1}^{n} \frac{k}{\gcd(k,n)} - 1, \text{ for, } n > 1 \tag{15}$$

$$\sum_{i=1}^{n} \sum_{j=1}^{n} [\gcd(i,j) = 1] = \sum_{d=1}^{n} \mu(d) \left\lfloor \frac{n}{d} \right\rfloor^2 \tag{16}$$

$$\sum_{i=1}^{n} \sum_{j=1}^{n} \gcd(i,j) = \sum_{d=1}^{n} \phi(d) \left\lfloor \frac{n}{d} \right\rfloor^2 \tag{17}$$

$$\sum_{i=1}^{n} \sum_{j=1}^{n} i \cdot j [\gcd(i,j) = 1] = \sum_{i=1}^{n} \phi(i) i^2 \tag{18}$$

$$\sum_{i=1}^{n} \sum_{j=1}^{n} \text{lcm}(i,j) = \sum_{l=1}^{n} \left(\frac{\left(1 + \left\lfloor \frac{n}{l} \right\rfloor\right)\left(\left\lfloor \frac{n}{l} \right\rfloor\right)}{2} \right)^2 = \sum_{d|l} \mu(d) l d \tag{19}$$

7.15 troubleshoot

```
General:
Write down most of your thoughts, even if you're not
 ↪ sure
whether they're useful.
Give your variables (and files) meaningful names.
Stay organized and don't leave papers all over the
 ↪ place!
You should know what your code is doing ...
Pre-submit:
Write a few simple test cases if sample is not enough.
Are time limits close? If so, generate max cases.
Is the memory usage fine?
Could anything overflow?
Remove debug output.
Make sure to submit the right file.
Wrong answer:
Print your solution! Print debug output as well.
Read the full problem statement again.
Have you understood the problem correctly?
Are you sure your algorithm works?
Try writing a slow (but correct) solution.
Can your algorithm handle the whole range of input?
Did you consider corner cases (ex. n=1)?
Is your output format correct? (including whitespace)
Are you clearing all data structures between test
 ↪ cases?
Any uninitialized variables?
Any undefined behavior (array out of bounds)?
Any overflows or NaNs (or shifting ll by >=64 bits)?
Confusing N and M, i and j, etc.?
Confusing ++i and i++?
Return vs continue vs break?
Are you sure the STL functions you use work as you
 ↪ think?
Add some assertions, maybe resubmit.
Create some test cases to run your algorithm on.
Go through the algorithm for a simple case.
Go through this list again.
Explain your algorithm to a teammate.
Ask the teammate to look at your code.
Go for a small walk, e.g. to the toilet.
Rewrite your solution from the start or let a teammate
 ↪ do it.
Geometry:
Work with ints if possible.
Correctly account for numbers close to (but not) zero.
 ↪ Related:
for functions like acos make sure absolute val of
 ↪ input is not
(slightly) greater than one.
Correctly deal with vertices that are collinear,
 ↪ concyclic,
coplanar (in 3D), etc.
Subtracting a point from every other (but not itself)?
Runtime error:
Have you tested all corner cases locally?
Any uninitialized variables?
Are you reading or writing outside the range of any
 ↪ vector?
Any assertions that might fail?
Any possible division by 0? (mod 0 for example)
Any possible infinite recursion?
Invalidated pointers or iterators?
Are you using too much memory?
Debug with resubmits (e.g. remapped signals, see
 ↪ Various).
Time limit exceeded:
Do you have any possible infinite loops?
What's your complexity? Large TL does not mean that
 ↪ something
simple (like NlogN) isn't intended.
Are you copying a lot of unnecessary data? (References)
Avoid vector, map. (use arrays/unordered_map)
How big is the input and output? (consider FastIO)
What do your teammates think about your algorithm?
Calling count() on multiset?
Memory limit exceeded:
What is the max amount of memory your algorithm should
 ↪ need?
Are you clearing all data structures between test
 ↪ cases?
If using pointers try BumpAllocator.
```

8 String

8.1 aho_corasick

```
using namespace std;
const int N = ?;
const int A = ?;
struct AC {
  int nd, pt;
  int next[N][A], link[N], out_link[N], cnt[N], ans[N];
  vector <int> ed[N], out[N];
  AC(): nd(0), pt(0) { node(); }
  int node() {
    memset(next[nd], 0, sizeof next[nd]);
    link[nd] = out_link[nd] = cnt[nd] = 0;
    ed[nd].clear(), out[nd].clear();
    return nd++;
  }
  void clear() {
    nd = pt = 0;
    node();
  }
  inline int get(char c) { return c - 'a'; }
  void insert(const string &T) {
    int u = 0;
    for (char c : T) {
      if (!next[u][get(c)]) next[u][get(c)] = node();
      u = next[u][get(c)];
    }
    ans[pt] = 0;
    out[u].push_back(pt++);
  }
  void build() {
    queue <int> q;
    for (q.push(0); !q.empty(); ) {
      int u = q.front();
      q.pop();
      for (int c = 0; c < A; ++c) {
        int v = next[u][c];
        if (!v) next[u][c] = next[link[u]][c];
        else {
          link[v] = u ? next[link[u]][c] : 0;
          out_link[v] = out[link[v]].empty() ?
           ↪ out_link[link[v]] : link[v];
          ed[link[v]].push_back(v);
          q.push(v);
        }
      }
```

```
    }
  }
  void dfs(int s) {
    for(int x : ed[s]) dfs(x), cnt[s] += cnt[x];
    for(int e : out[s]) ans[e] = cnt[s];
  }
  void traverse(const string &S) {
    int u = 0;
    for (char c : S) {
      u = next[u][get(c)];
      cnt[u]++;
    }
    dfs(0);
  }
};
char str[1000010], pat[505];
int main() {
  //    freopen("in.txt","r",stdin);
  AC aho;
  int t,T;
  scanf("%d",&T);
  for(int t=1;t<=T;t++) {
    int n;
    scanf("%d",&n);
    scanf("%s",str);
    for(int i=1;i<=n;i++) {
      scanf("%s",pat);
      aho.insert(pat);
    }
    aho.build();
    aho.traverse(str);
    printf("Case %d:\n",t);
    for(int i=0;i<n;i++) {
      printf("%d\n",aho.ans[i]);
    }
    aho.clear();
  }
  return 0;
}
```

8.2 fft_match

```
using ld = double;
using cd = complex<ld>;
const ld PI = acos(-1.0);
const ld eps = 1e-6;
void fft(vector<cd>& a, bool invert)
{
    int n = (int)a.size();
    for(int i = 1, j = 0; i < n; i++) {
        int bit = n >> 1;
        for(; j & bit; bit >>= 1) j ^= bit;
        j ^= bit;
        if(i < j) swap(a[i], a[j]);
    }
    for(int len = 2; len <= n; len <<= 1) {
        ld ang = 2 * PI / len * (invert ? -1 : 1);
        cd wlen(cosl(ang), sinl(ang));
        for(int i = 0; i < n; i += len) {
            cd w(1);
            for(int j = 0; j < len / 2; j++) {
                cd u = a[i + j], v = a[i + j + len/2]
                  * w;
                a[i + j] = u + v;
                a[i + j + len/2] = u - v;
                w *= wlen;
            }
        }
    }
    if(invert) {
        for(cd& x : a) {
            x /= n;
        }
    }
}
vector<i64> multiply(vector<cd> const& a, vector<cd>
  const& b) {
    vector<cd> fa(a.begin(), a.end()), fb(b.begin(),
      b.end());
    int n = 1;
    while(n < (int)a.size() + b.size()) {
        n <<= 1;
    }
    fa.resize(n);
    fb.resize(n);
    fft(fa, false);
    fft(fb, false);
    for(int i = 0; i < n; i++) fa[i] *= fb[i];
    fft(fa, true);
    vector<i64> res(n);
    for(int i = 0; i < n; i++) {
        if(abs(fa[i].imag()) < eps) {
            res[i] = round(fa[i].real());
            if(abs(res[i] - fa[i].real()) > eps) {
                res[i] = -1;
            }
        } else {
            res[i] = -1;
        }
    }
    return res;
}
int main()
{
    /*
        |t| <= |s|
        Want to check if t occurs as a substring of s
    */
    string s, t; cin >> s >> t;
    vector <cd> sa(s.size()), ta(t.size());
    for (int i = 0; i < s.size(); ++i) {
        ld ang = 2 * PI * (s[i] - 'a' + 1) / 27;
        sa[i] = cd(cosl(ang), sin(ang));
    }
    for (int i = 0; i < t.size(); ++i) {
        ld ang = 2 * PI * (t[i] - 'a' + 1) / 27;
        ta[t.size() - 1 - i] = cd(cosl(ang),
          -sin(ang));
    }
    vector<i64> mul = multiply(sa, ta);
    for (int i = 0; i < sa.size(); ++i) {
        if (mul[i] == ta.size()) {
            cout << i - ta.size() + 1 << ' ';
        }
    }
    cout << '\n';
}
```

8.3 hash

```
struct Hash {
  struct base {
    string s; int b, mod;
    vector<int> hash, p;
    void init(string &_s, int _b, int _mod) { // b >
      26, prime.
      s = _s; b = _b, mod = _mod;
      hash.resize(s.size());
      p.resize(s.size());
      hash[0] = s[0] - 'A' + 1; p[0] = 1;
      for(int i = 1; i < s.size(); ++i) {
        hash[i] = (ll) hash[i - 1] * b % mod;
        hash[i] += s[i] - 'A' + 1;
        if(hash[i] >= mod) hash[i] -= mod;
        p[i] = (ll) p[i - 1] * b % mod;
      }
    }
    int get(int l, int r) {
      int ret = hash[r];
      if(l) ret -= (ll) hash[l - 1] * p[r - l + 1] %
        mod;
      if(ret < 0) ret += mod;
      return ret;
    }
  } h[2];
  void init(string &s) {
    h[0].init(s, 29, 1e9+7);
    h[1].init(s, 31, 1e9+9);
  }
  pair<int, int> get(int l, int r) {
    return { h[0].get(l, r), h[1].get(l, r) };
  }
} H;
```

8.4 hash_segtree

```
#define INVALID_CHAR        -1
namespace strhash {
  int n;
  const int MAX = 100010;
  int ara[MAX];
  const int MOD[] = {1067737007, 1069815139};
  const int BASE[] = {982451653, 984516781};
  int BP[2][MAX], CUM[2][MAX];
  void init(char *str) {
    n = strlen(str);
    for(int i=0;i<n;i++) ara[i] = str[i]-'0'+1;
  }
  void precal() {
    BP[0][0] = BP[1][0] = 1;
    CUM[0][0] = CUM[1][0] = 1;
    for(int i=1;i<MAX;i++) {
      BP[0][i] = ( BP[0][i-1] * (long long) BASE[0] )
        % MOD[0];
      BP[1][i] = ( BP[1][i-1] * (long long) BASE[1] )
        % MOD[1];
      CUM[0][i] = ( CUM[0][i-1] + (long long) BP[0][i]
        ) % MOD[0];
      CUM[1][i] = ( CUM[1][i-1] + (long long) BP[1][i]
        ) % MOD[1];
    }
  }
  struct node {
    int sz;
    int h[2];
    node() {}
  } tree[4*MAX];
  int lazy[4*MAX];
  inline void lazyUpdate(int n,int st,int ed) {
    if(lazy[n]!=INVALID_CHAR){
      tree[n].h[0] = (lazy[n] * (long long)
        CUM[0][ed-st]) % MOD[0];
      tree[n].h[1] = (lazy[n] * (long long)
        CUM[1][ed-st]) % MOD[1];
      if(st!=ed){
        lazy[2*n] = lazy[n];
        lazy[2*n+1] = lazy[n];
      }
      lazy[n] = INVALID_CHAR;
    }
  }
  inline node Merge(node a,node b) {
    node ret;
    ret.h[0] = ( ( a.h[0] * (long long) BP[0][b.sz] )
      + b.h[0] ) % MOD[0];
```

```
  ret.h[1] = ( ( a.h[1] * (long long) BP[1][b.sz] )
  ↪ + b.h[1] ) % MOD[1];
  ret.sz = a.sz + b.sz;
  return ret;
}
inline void build(int n,int st,int ed) {
  lazy[n] = INVALID_CHAR;
  if(st==ed) {
    tree[n].h[0] = tree[n].h[1] = ara[st];
    tree[n].sz = 1;
    return;
  }
  int mid = (st+ed)>>1;
  build(n+n,st,mid);
  build(n+n+1,mid+1,ed);
  tree[n] = Merge(tree[n+n],tree[n+n+1]);
}
inline void update(int n,int st,int ed,int i,int
↪ j,int v) {
  lazyUpdate(n,st,ed);
  if(st>j or ed<i) return;
  if(st>=i and ed<=j) {
    lazy[n] = v;
    lazyUpdate(n,st,ed);
    return;
  }
  int mid = (st+ed)>>1;
  update(n+n,st,mid,i,j,v);
  update(n+n+1,mid+1,ed,i,j,v);
  tree[n] = Merge(tree[n+n],tree[n+n+1]);
}
inline node query(int n,int st,int ed,int i,int j){
  lazyUpdate(n,st,ed);
  if(st>=i and ed<=j) return tree[n];
  int mid = (st+ed)/2;
  if(mid<i) return query(n+n+1,mid+1,ed,i,j);
  else if(mid>=j) return query(n+n,st,mid,i,j);
  else return Merge(query(n+n,st,mid,i,j),query(n+n+
  ↪ 1,mid+1,ed,i,j));
}
}
```

8.5 kmp

```
// returns the longest proper prefix array of pattern p
// where lps[i]=longest proper prefix which is also
↪ suffix of p[0...i]
vector<int> build_lps(string p) {
  int sz = p.size();
  vector<int> lps;
  lps.assign(sz + 1, 0);
  int j = 0;
  lps[0] = 0;
  for(int i = 1; i < sz; i++) {
    while(j >= 0 && p[i] != p[j]) {
      if(j >= 1) j = lps[j - 1];
      else j = -1;
    }
    j++;
    lps[i] = j;
  }
  return lps;
}
vector<int>ans;
// returns matches in vector ans in 0-indexed
void kmp(vector<int> lps, string s, string p) {
  int psz = p.size(), sz = s.size();
  int j = 0;
  for(int i = 0; i < sz; i++) {
    while(j >= 0 && p[j] != s[i])
      if(j >= 1) j = lps[j - 1];
      else j = -1;
    j++;
    if(j == psz) {
      j = lps[j - 1];
      // pattern found in string s at position i-psz+1
      ans.push_back(i - psz + 1);
    }
    // after each loop we have j=longest common suffix
    ↪ of s[0..i] which is also prefix of p
  }
}
```

8.6 manachar

```
vector<int> d1(n);  // maximum odd length palindrome
↪ centered at i
                    // here d1[i]=the palindrome has
                    ↪ d1[i]-1 right characters from i
                    // e.g. for aba, d1[1]=2;
for (int i = 0, l = 0, r = -1; i < n; i++) {
  int k = (i > r) ? 1 : min(d1[l + r - i], r - i);
  while (0 <= i - k && i + k < n && s[i - k] == s[i +
  ↪ k]) {
    k++;
  }
  d1[i] = k--;
  if (i + k > r) {
    l = i - k;
    r = i + k;
  }
}
vector<int> d2(n);  // maximum even length palindrome
↪ centered at i
                    // here d2[i]=the palindrome has
                    ↪ d2[i]-1 right characters from i
                    // e.g. for abba, d2[2]=2;
for (int i = 0, l = 0, r = -1; i < n; i++) {
  int k = (i > r) ? 0 : min(d2[l + r - i + 1], r - i +
  ↪ 1);
  while (0 <= i - k - 1 && i + k < n && s[i - k - 1]
  ↪ == s[i + k]) {
    k++;
  }
  d2[i] = k--;
  if (i + k > r) {
    l = i - k - 1;
    r = i + k ;
  }
}
```

8.7 palindromic_tree

```
const int A = 26;
const int N = 300010;
char s[N]; long long ans;
int last, ptr, nxt[N][A], link[N], len[N], occ[N];
void feed (int at) {
  while (s[at - len[last] - 1] != s[at]) last =
  ↪ link[last];
  int ch = s[at] - 'a', temp = link[last];
  while (s[at - len[temp] - 1] != s[at]) temp =
  ↪ link[temp];
  if (!nxt[last][ch]) {
    nxt[last][ch] = ++ptr, len[ptr] = len[last] + 2;
    link[ptr] = len[ptr] == 1 ? 2 : nxt[temp][ch];
  }
  last = nxt[last][ch], ++occ[last];
}
int main() {
  len[1] = -1, len[2] = 0, link[1] = link[2] = 1, last
  ↪ = ptr = 2;
  scanf("%s", s + 1);
  for (int i = 1, n = strlen(s + 1); i <= n; ++i)
  ↪ feed(i);
  for (int i = ptr; i > 2; --i) ans = max(ans, len[i]
  ↪ * 1LL * occ[i]), occ[link[i]] += occ[i];
  printf("%lld\n", ans);
  return 0;
}
```

8.8 persistant_trie

```
const int MAX = 200010;
const int B = 19;
int root[MAX], ptr = 0;
struct node {
  int ara[2], sum;
  node() {}
} tree[ MAX * (B+1) ];
void insert(int prevnode, int &curRoot, int val) {
  curRoot = ++ptr;
  int curnode = curRoot;
  for(int i = B; i >= 0; i--) {
    bool bit = val & (1 << i);
    tree[curnode] = tree[prevnode];
    tree[curnode].ara[bit] = ++ptr;
    tree[curnode].sum += 1;
    prevnode = tree[prevnode].ara[bit];
    curnode = tree[curnode].ara[bit];
  }
  tree[curnode] = tree[prevnode];
  tree[curnode].sum += 1;
}
int find_xor_max(int prevnode, int curnode, int x) {
  int ans = 0;
  for(int i = B; i >= 0; i--) {
    bool bit = x & (1 << i);
    if(tree[tree[curnode].ara[bit ^ 1]].sum >
    ↪ tree[tree[prevnode].ara[bit ^ 1]].sum) {
      curnode = tree[curnode].ara[bit ^ 1];
      prevnode = tree[prevnode].ara[bit ^ 1];
      ans = ans | (1 << i);
    }
    else {
      curnode = tree[curnode].ara[bit];
      prevnode = tree[prevnode].ara[bit];
    }
  }
  return ans;
}
void solve() {
  int n, q, L, R, K;
  cin >> n;
  for(int i=1;i<=n;i++) cin >> ara[i];
  for(int i=1;i<=q;i++) {
    cin >> L >> R >> K;
    cout << find_xor_max(root[L-1],root[R],K) << endl;
  }
}
```

8.9 suffix_array

```
// Everything is 0-indexed
char s[N]; // Suffix array will be built for this
↪ string
int SA[N], iSA[N]; // SA is the suffix array, iSA[i]
↪ stores the rank of the i'th suffix
int cnt[N], nxt[N]; // Internal stuff
bool bh[N], b2h[N]; // Internal stuff
int lcp[N]; // Stores lcp of SA[i] and SA[i + 1];
↪ lcp[n - 1] = 0
int lcpSparse[LOGN][N]; // lcpSparse[i][j] =
↪ min(lcp[j], ..., lcp[j - 1 + (1 << i)])
```

```
void buildSA(int n) {
  for (int i = 0; i < n; i++) SA[i] = i;
  sort(SA, SA + n, [](int i, int j) { return s[i] <
  ↪  s[j]; });
  for (int i = 0; i < n; i++) {
    bh[i] = i == 0 || s[SA[i]] != s[SA[i - 1]];
    b2h[i] = 0;
  }
  for (int h = 1; h < n; h <<= 1) {
    int tot = 0;
    for (int i = 0, j; i < n; i = j) {
      j = i + 1;
      while (j < n && !bh[j]) j++;
      nxt[i] = j; tot++;
    } if (tot == n) break;
    for (int i = 0; i < n; i = nxt[i]) {
      for (int j = i; j < nxt[i]; j++) iSA[SA[j]] = i;
      cnt[i] = 0;
    }
    cnt[iSA[n - h]]++;
    b2h[iSA[n - h]] = 1;
    for (int i = 0; i < n; i = nxt[i]) {
      for (int j = i; j < nxt[i]; j++) {
        int s = SA[j] - h;
        if (s < 0) continue;
        int head = iSA[s];
        iSA[s] = head + cnt[head]++;
        b2h[iSA[s]] = 1;
      }
      for (int j = i; j < nxt[i]; j++) {
        int s = SA[j] - h;
        if (s < 0 || !b2h[iSA[s]]) continue;
        for (int k = iSA[s] + 1; !bh[k] && b2h[k];
         ↪  k++) b2h[k] = 0;
      }
    }
    for (int i = 0; i < n; i++) {
      SA[iSA[i]] = i;
      bh[i] |= b2h[i];
    }
  }
  for (int i = 0; i < n; i++) iSA[SA[i]] = i;
}
void buildLCP(int n) {
  for (int i = 0, k = 0; i < n; i++) {
    if (iSA[i] == n - 1) {
      k = 0;
      lcp[n - 1] = 0;
      continue;
    }
    int j = SA[iSA[i] + 1];
    while (i + k < n && j + k < n && s[i + k] == s[j +
     ↪  k]) k++;
    lcp[iSA[i]] = k;
    if (k) k--;
  }
}
void buildLCPSparse(int n) {
  for (int i = 0; i < n; i++) lcpSparse[0][i] = lcp[i];
  for (int i = 1; i < LOGN; i++) {
    for (int j = 0; j < n; j++) {
      lcpSparse[i][j] = min(lcpSparse[i - 1][j],
        lcpSparse[i - 1][min(n - 1, j + (1 << (i -
     ↪  1)))]);
    }
  }
}
pair<int, int> minLCPRange(int n, int from, int
 ↪  minLCP) {
  int r = from;
  for (int i = LOGN - 1; i >= 0; i--) {
    int jump = 1 << i;
    if (r + jump < n and lcpSparse[i][r] >= minLCP) r
     ↪  += jump;
  }
  int l = from;
  for (int i = LOGN - 1; i >= 0; i--) {
    int jump = 1 << i;
    if (l - jump >= 0 and lcpSparse[i][l - jump] >=
     ↪  minLCP) l -= jump;
  }
  return make_pair(l, r);
}
```

8.10 suffix_automata

```
namespace sa{
  const int MAXN = 100005 << 1;
  const int MAXC = 26;
  char str[MAXN];
  int n, sz, last;
  int len[MAXN], link[MAXN], ed[MAXN][MAXC], cnt[MAXN];
  bool terminal[MAXN];
  vector <int> G[MAXN];
  void init() {
    SET(ed[0]);
    len[0] = 0, link[0] = -1, sz = 1, last = 0,
     ↪  terminal[0] = false;
  }
  inline int scale(char c) { return c-'a'; }
  void extend(char c) {
    int cur = sz++;
    terminal[cur] = false;
    cnt[cur] = 1;
    SET(ed[cur]);
    len[cur] = len[last] + 1;
    int p = last;
    while (p != -1 && ed[p][c]==-1) {
      ed[p][c] = cur;
      p = link[p];
    }
    if (p == -1) link[cur] = 0;
    else {
      int q = ed[p][c];
      if (len[p] + 1 == len[q]) link[cur] = q;
      else {
        int clone = sz++;
        len[clone] = len[p] + 1;
        memcpy(ed[clone],ed[q],sizeof(ed[q]));
        link[clone] = link[q];
        while (p != -1 && ed[p][c] == q) {
          ed[p][c] = clone;
          p = link[p];
        }
        link[q] = link[cur] = clone;
        cnt[clone] = 0;
        terminal[clone] = false;
      }
    }
    last = cur;
  }
  void dfs(int s) {
    for(auto x : G[s]) dfs(x), cnt[s] += cnt[x];
  }
  void build() {
    init();
    int n = strlen(str);
    for(int i=0;i<n;i++) extend(scale(str[i]));
    for(int i=1;i<sz;i++) G[link[i]].pb(i);
    dfs(0);
    for(int i=0;i<sz;i++) G[i].clear();
    for(int i=last;i!=-1;i=link[i]) terminal[i] = true;
  }
}
```

8.11 trie

```
#define N       200000
#define S       26
int root,now;
int nxt[N][S], cnt[N];
void init(){
  root = now = 1;
  CLR(nxt),CLR(cnt);
}
inline int scale(char ch) { return (ch - 'a'); }
inline void Insert(char s[],int sz){
  int cur = root, to;
  for(int i=0 ; i< sz ; i++){
    to = scale(s[i]) ;
    if( !nxt[cur][to] ) nxt[cur][to] = ++now;
    cur = nxt[cur][to];
  }
  cnt[cur]++;
}
inline bool Find(char s[],int sz){
  int cur = root, to;
  for(int i=0 ; i<sz ; i++){
    to = scale(s[i]) ;
    if( !nxt[cur][to] ) return false;
    cur = nxt[cur][to];
  }
  return (cnt[cur]!=0);
}
inline void Delete(char s[],int sz){
  int cur = root, to;
  for(int i=0 ; i<sz ; i++){
    to = scale(s[i]) ;
    cur = nxt[cur][to];
  }
  cnt[cur]--;
}
```

8.12 z_algo

```
const int N = 100010;
char s[N];
int t, n, z[N];
int main() {
  scanf("%s", s);
  n = strlen(s), z[0] = n;
  int L = 0, R = 0;
  for (int i = 1; i < n; ++i) {
    if (i > R) {
      L = R = i;
      while (R < n && s[R - L] == s[R]) ++R;
      z[i] = R - L; --R;
    } else {
      int k = i - L;
      if (z[k] < R - i + 1) z[i] = z[k];
      else {
        L = i;
        while (R < n && s[R - L] == s[R]) ++R;
        z[i] = R - L; --R;
      }
    }
  }
}
```