

# Topic III:

## Principles of Data Reduction

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# Data Reduction

In statistics, one of the central tasks is to turn the large amount of data in a sample  $\mathbf{X} = \{X_1, \dots, X_n\}$  into inferences about the world, e.g. an unknown parameter  $\theta$  in a family of distributions.

- Do we have to keep ALL data in order to make a good inference?

**Example:** Consider a  $\text{Uniform}([0, \theta])$  random sample, suppose we observed the following data

$$[2.16, 0.72, 9.75, 0.89, 2.21].$$

What can we say about  $\theta$ ?

**Not all data are relevant** to a particular statistical problem.

- A data reduction procedure that discards irrelevant data  $\Rightarrow$  results in a simpler inference procedure.

### Definition (Statistic)

A **statistic**  $T(\mathbf{X})$  is a function of the data. It does not depend on any unknown parameters.

**Example:** In the  $\text{Uniform}([0, \theta])$  example,  $X_{(n)} = \max\{X_1, \dots, X_n\}$  is a statistic.

- If  $T$  is not one-to-one, it defines a form of data reduction.
- A “good” statistic should preserve information about the unknown parameter  $\theta$ .

**Key question:** Is there a statistic that contains all the information in the sample about  $\theta$ ?

If so, a reduction or compression of the original data to this statistic without loss of information is possible.

# Sufficient Statistics

## Definition (Sufficient Statistics)

A statistic is sufficient<sup>a</sup> for a model  $\mathcal{P} = \{P_\theta : \theta \in \Theta\}$  if for any given  $t$ , the conditional distribution of  $X$  under  $T(\mathbf{X}) = t$  does not depend on  $\theta$ .

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<sup>a</sup>This concept was introduced by R. A. Fisher in 1922.

- The concept of sufficiency depends on the model  $\mathcal{P}$ , i.e., the parameter  $\theta$ .
- Intuitively speaking, if we know the value of a sufficient statistic  $T$ , then we can do just as good a job of estimating the unknown parameter  $\theta$  as someone who knows the entire data.

To see this, we can consider the full data as “dummy” data generated using  $T$ .

- Instead of directly simulating  $\mathbf{X}$ , we are given an observation

$$T(\mathbf{X}) \sim \mathbb{P}_\theta(T(\mathbf{X}) = t).$$

- We then generate independent conditional r.v.  $\mathbf{X}|T(\mathbf{X})$ , which has the same distribution as the full data:

$$\mathbb{P}_\theta(\mathbf{X} = \mathbf{x}) = \mathbb{P}_\theta(\mathbf{X} = \mathbf{x} \mid T(\mathbf{X}) = T(\mathbf{x}))\mathbb{P}_\theta(T(\mathbf{X}) = T(\mathbf{x})).$$

- By sufficiency,  $\mathbf{X}|T(\mathbf{X})$  does not depend on  $\theta$ , all the information about  $\theta$  is contained in  $T(\mathbf{X})$ .

## Examples

**Example:** Bernoulli. Let  $X_1, \dots, X_n$  be random sample from  $\text{Bernoulli}(\theta)$ . Is the number of heads  $T = \sum X_i$  sufficient?

$$\begin{aligned}\mathbb{P}_\theta(\mathbf{X} = \mathbf{x}) &= \theta^{\sum_i x_i} (1 - \theta)^{n - \sum_i x_i} \\ \mathbb{P}_\theta(\mathbf{X} = \mathbf{x} \mid T(\mathbf{X}) = t) &= \frac{\mathbb{P}_\theta(\mathbf{X} = \mathbf{x}, T(\mathbf{X}) = t)}{\mathbb{P}_\theta(T(\mathbf{X}) = t)} \\ &= \frac{\theta^{\sum_i x_i} (1 - \theta)^{n - \sum_i x_i} \mathbb{1}(t = \sum x_i)}{\binom{n}{t} \theta^t (1 - \theta)^{n-t}} \\ &= \frac{\mathbb{1}(t = \sum x_i)}{\binom{n}{t}}, \quad \text{for all } x_i \in \{0, 1\}.\end{aligned}$$

This does not depend on  $\theta$ , by definition  $\sum X_i$  is sufficient for  $\theta$ .

How to understand  $\mathbb{P}_\theta(\mathbf{X} = \mathbf{x} \mid T(\mathbf{X}) = t)$  here?

**Example:**  $\text{Uniform}([0, \theta])$ . Conditioning on  $T(\mathbf{X}) = X_{(n)} = t$ , the remaining  $n - 1$  numbers behave like random sample from  $\text{Uniform}([0, t])$ , independent of  $\theta$ .

$$\begin{aligned} & \mathbb{P}_\theta(X_1 \leq x_1, \dots, X_{n-1} \leq x_{n-1} \mid X_n = X_{(n)} = t) \\ &= \frac{\mathbb{P}_\theta(X_1 \leq x_1, \dots, X_{n-1} \leq x_{n-1}, X_n = X_{(n)} = t)}{\mathbb{P}_\theta(X_n = X_{(n)} = t)} \\ &= \frac{\mathbb{P}_\theta(X_1 \leq x_1 \wedge t, \dots, X_{n-1} \leq x_{n-1} \wedge t, X_n = t)}{\mathbb{P}_\theta(X_1 \leq t, \dots, X_{n-1} \leq t, X_n = t)} \\ &= \frac{\mathbb{P}_\theta(X_1 \leq x_1 \wedge t) \dots \mathbb{P}_\theta(X_{n-1} \leq x_{n-1} \wedge t) \mathbb{P}_\theta(X_n = t)}{\mathbb{P}_\theta(X_1 \leq t) \dots \mathbb{P}_\theta(X_{n-1} \leq t) \mathbb{P}_\theta(X_n = t)} \\ &= \prod_{i=1}^{n-1} \frac{x_i \wedge t}{t} \mathbf{1}(x_i \geq 0) \stackrel{iid}{\sim} \text{Uniform}([0, t]). \end{aligned}$$

Here  $a \wedge b = \min\{a, b\}$ . Recall that for the indicator function, we have  $\mathbf{1}_A \mathbf{1}_B = \mathbf{1}_{A \cap B}$ .



Hence

$$\begin{aligned} & \mathbb{P}_\theta(X_1 \leq x_1, \dots, X_n \leq x_n \mid X_{(n)} = t) \\ &= \sum_{i=1}^n \mathbb{P}_\theta(X_1 \leq x_1, \dots, X_n \leq x_n, X_i = X_{(n)} \mid X_{(n)} = t) \\ &= \sum_{i=1}^n \mathbb{P}_\theta(X_1 \leq x_1, \dots, X_n \leq x_n \mid X_i = X_{(n)} = t) \times \mathbb{P}_\theta(X_i = X_{(n)} \mid X_{(n)} = t) \\ &= \sum_{i=1}^n \prod_{j \neq i} \frac{x_j \wedge t}{t} \mathbb{1}(x_j \geq 0) \times \frac{1}{n}. \end{aligned}$$

This does not depend on  $\theta$ , by definition  $X_{(n)}$  is a sufficient statistic for  $\theta$ .

**Example:** Normal. Let  $X_1, \dots, X_n$  be i.i.d.  $\mathcal{N}(\mu, \sigma^2)$  r.v.'s with known  $\sigma$ . Consider  $T(\mathbf{X}) = \bar{X} = (X_1 + \dots + X_n)/n$ .

$$\mathbb{P}_\theta(\mathbf{X} = \mathbf{x} | T(\mathbf{X}) = T(\mathbf{x})) = \frac{\mathbb{P}_\theta(\mathbf{X} = \mathbf{x}, T(\mathbf{X}) = T(\mathbf{x}))}{\mathbb{P}_\theta(T(\mathbf{X}) = T(\mathbf{x}))} = \frac{\mathbb{P}_\theta(\mathbf{X} = \mathbf{x})}{\mathbb{P}_\theta(T(\mathbf{X}) = T(\mathbf{x}))} = \frac{f(\mathbf{x} | \mu)}{q(T(\mathbf{x}) | \mu)}$$

where

$$\begin{aligned} f(\mathbf{x} | \mu) &= \frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left(-\frac{\sum_i (x_i - \mu)^2}{2\sigma^2}\right) \\ &= \frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left(-\frac{\sum_i (x_i - \bar{x})^2 + n(\bar{x} - \mu)^2}{2\sigma^2}\right) \\ q(T(\mathbf{x}) | \mu) &= q(\bar{x} | \mu) = \frac{1}{\sqrt{2\pi} \frac{\sigma}{\sqrt{n}}} \exp\left(-\frac{n(\bar{x} - \mu)^2}{2\sigma^2}\right) \end{aligned}$$

$\bar{X}$  is sufficient for  $\mu$ , but not  $\sigma$ .

**Example:** Order statistic. Let  $X_1, \dots, X_n$  be a random sample from pdf  $f$ . Consider  $T(\mathbf{X}) = (X_{(1)}, \dots, X_{(n)})$ .

$$\mathbb{P}_\theta(\mathbf{X} = \mathbf{x} | T(\mathbf{X}) = T(\mathbf{x})) = \frac{f(\mathbf{x})}{q(T(\mathbf{x}))} = \frac{\prod_i f(x_i)}{\prod_i n! f(x_{(i)})} = \frac{1}{n!},$$

for any  $\mathbf{x} = \pi(\mathbf{X})$ , i.e., a permutation of  $X_1, \dots, X_n$ .

- Non-parametric example: the “parameter” here is the distribution function  $f$ .
- Notice that there is not much data reduction.
- Outside the exponential family, it is rare to have sufficient statistics that are of lower dimension than the sample size.

## Factorization Theorem

It can be complicated to use the definition to

- find a candidate sufficient statistic; and
- check if a statistic is sufficient.

Luckily, there is a theorem that makes both tasks easy.

### Theorem (Factorization theorem)

Let  $f(\mathbf{x}|\theta)$  denote the joint pdf/pmf of a sample  $\mathbf{X}$ . A statistic  $T(\mathbf{X})$  is a sufficient statistic for  $\theta$  **if and only if** there exist functions  $g(t|\theta)$  and  $h(\mathbf{x})$  such that, for all sample points  $\mathbf{x}$  and all parameter  $\theta$ ,

$$f(\mathbf{x}|\theta) = h(\mathbf{x})g(T(\mathbf{x})|\theta).$$

## Remarks

$$\begin{aligned}
 T &\xrightarrow{s} S = s(T(x)). \\
 T &= s^{-1}(S(x)) \\
 f(x) &= h(x) g(T(x) | \theta) \\
 &= h(x) g(s^{-1}(S(x)) | \theta)
 \end{aligned}$$

- The function  $h$  can depend on the full random sample  $x$ , but not on the unknown parameter  $\theta$ .
- The function  $g$  can depend on  $\theta$ , but can depend on the random sample only through the value of  $t = T(x)$ .
- It is easy to see that if  $s(t)$  is a one to one function and  $T$  is a sufficient statistic, then  $s(T)$  is a sufficient statistic.

**Example:** In the order statistic example, equivalently, the empirical cdf  $F_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{1}(X_i \leq x)$  is sufficient.

## Proof

- “ $\Rightarrow$ ” If sufficient, let  $h(\mathbf{x}) = \mathbb{P}(\mathbf{X} = \mathbf{x} | T(\mathbf{X}) = T(\mathbf{x}))$ , then

$$f(\mathbf{x}|\theta) = \mathbb{P}_\theta(\mathbf{X} = \mathbf{x}) = \mathbb{P}(\mathbf{X} = \mathbf{x} | T(\mathbf{X}) = T(\mathbf{x})) \mathbb{P}_\theta(T(\mathbf{X}) = T(\mathbf{x}))$$

- “ $\Leftarrow$ ” (in the case of discrete r.v.) If factorization, then let  $q(T(\mathbf{x})|\theta)$  be the pmf of  $T(\mathbf{X})$  and  $A_{T(\mathbf{x})} = \{\mathbf{y} : T(\mathbf{y}) = T(\mathbf{x})\}$ .

$$\begin{aligned} \mathbb{P}(\mathbf{X} = \mathbf{x} \mid T = t) &= \frac{\mathbb{P}(\mathbf{X} = \mathbf{x}, T = t)}{\mathbb{P}(T = t)} = \frac{f(\mathbf{x}|\theta) \mathbb{1}(T(\mathbf{x}) = t)}{\sum_{A_{T(\mathbf{x})}} f(\mathbf{y}|\theta)} \\ &= \frac{g(T(\mathbf{x})|\theta) h(\mathbf{x}) \mathbb{1}(T(\mathbf{x}) = t)}{\sum_{A_{T(\mathbf{x})}} g(T(\mathbf{y})|\theta) h(\mathbf{y})} = \frac{h(\mathbf{x}) \mathbb{1}(T(\mathbf{x}) = t)}{\sum_{A_{T(\mathbf{x})}} h(\mathbf{y})} \end{aligned}$$

- For a complete proof, see *Testing Statistical Hypothesis* (2015) by E. Lehmann and J. Romano, Section 2.6.

## Examples Revisited

**Example:** Uniform( $[0, \theta]$ ) revisited. We can write down the pdf of the full data as

$$f(\mathbf{x}) = 1/\theta^n \prod_i \mathbb{1}(0 \leq X_i \leq \theta) = 1/\theta^n \mathbb{1}(\max_i \{X_i\} \leq \theta) \prod_i \mathbb{1}(X_i \geq 0)$$

- By the factorization theorem, a sufficient statistic is  $T(\mathbf{X}) = \max_i X_i = X_{(n)}$ .
- The sample mean is not a sufficient statistic for  $\mathbb{E}[X] = \theta/2$ .

**Example:** Normal mean revisited. Consider a normal random sample  $\mathcal{N}(\mu, \sigma^2)$  with known  $\sigma$ .

$$f(\mathbf{x}|\mu) = \frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left(-\frac{\sum_i (x_i - \bar{x})^2}{2\sigma^2}\right) \exp\left(-\frac{n(\bar{x} - \mu)^2}{2\sigma^2}\right)$$

Then  $T(\mathbf{X}) = \bar{X}$  and  $g(t|\mu) = \exp\left(-\frac{n(t-\mu)^2}{2\sigma^2}\right)$ .



## Remarks

### Definition (Multi-dimensional case)

The statistics  $\mathbf{T} = (T_1, \dots, T_k)$  are jointly sufficient if for each  $\mathbf{t} = (t_1, \dots, t_k)$ , the conditional distribution of  $\mathbf{X} = (X_1, \dots, X_n)$  given  $\mathbf{T}$  does not depend on  $\theta$ .

- The factorization theorem applies to multi-dimensional parameter and statistic.

**Example:** Normal mean and variance. What if  $\theta = (\mu, \sigma)$  is unknown?

Let  $T_1(\mathbf{x}) = \bar{x}$  and  $T_2(\mathbf{x}) = s^2$ .

$$g(\mathbf{t}|\theta) = g(t_1, t_2|\theta) = \frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left(-\frac{(n-1)t_2}{2\sigma^2}\right) \exp\left(-\frac{n(t_1 - \mu)^2}{2\sigma^2}\right)$$

Here  $h(\mathbf{x}) = 1$ . We see that  $(T_1(\mathbf{x}), T_2(\mathbf{x}))$  is sufficient for  $(\mu, \sigma)$ .

If  $\theta \in \mathbb{R}^k$  and  $f(t)$  is a one to one function on  $\mathbb{R}^k$  and  $T$  is a sufficient statistic for  $\theta$ , then  $f(T)$  is also a sufficient statistic. More generally,

$$S \xrightarrow{\psi} T = \psi(S)$$

If  $T$  is sufficient and  $T = \psi(S)$ , where  $\psi$  is a (measurable) function and  $S$  is a statistic, then  $S$  is sufficient.

**Example:** Normal.  $T_1 = \bar{X}, T_2 = (X_1, \sum_{i=2}^n X_i), T_3 = \mathbf{X}$  are all sufficient statistics for  $\mu$ .

## Remarks – Sufficiency

Any statistic  $T$  will induce a partition of the sample space according to the its value

$$\mathcal{A}(T) = \{A_t\}, \quad A_t = \{\mathbf{x} : T(\mathbf{x}) = t\}.$$

**Example:** Uniform(0,  $\theta$ ). Consider sample size of 2.

- For a statistic to be sufficient, the partition should be fine enough to distinguish information about different  $\theta$ .
- If  $T$  is sufficient, we should draw identical statistical conclusions about  $\theta$  inside each region.
- It is this partition, rather than the particular statistic inducing the partition, that is the fundamental object. This idea is formalized using  $\sigma$ -algebras in measure theory.

# Exponential Families

A family of pdf or pmf is called a  $k$ -parameter exponential family if it can be written as

$$f(x|\boldsymbol{\theta}) = h(x)c(\boldsymbol{\theta}) \exp \left( \sum_{i=1}^k w_i(\boldsymbol{\theta}) t_i(x) \right).$$

This special form is chosen for mathematical convenience.

**Example:** Binomial( $n, p$ ).

$$f(x|p) = \binom{n}{x} p^x (1-p)^{n-x} = \binom{n}{x} (1-p)^n \left( \frac{p}{1-p} \right)^x = \binom{n}{x} (1-p)^n \exp \left( \log \left( \frac{p}{1-p} \right) x \right)$$

**Example:** Normal  $N(\mu, \sigma^2)$ .

$$f(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(\mu)^2}{2\sigma^2}} \exp \left( -\frac{1}{2\sigma^2} x^2 + \frac{\mu}{\sigma^2} x \right)$$

**Example:** Counterexample. The shifted exponential distributions does not form an exponential family

$$f(x|\theta) = \frac{1}{\theta} \exp \left( \frac{\theta - x}{\theta} \right) \mathbb{1}(x \geq \theta)$$

## Natural Parameters of the Exponential Family

A exponential family is sometimes reparameterized as

$$f(x|\boldsymbol{\eta}) = h(x)c^*(\boldsymbol{\eta}) \exp \left( \sum_{i=1}^k \eta_i t_i(x) \right).$$

where  $\boldsymbol{\eta} = (w_1(\theta), w_2(\theta), \dots, w_k(\theta))$  is called the natural parameter. This is called the **canonical form** of the exponential family.

### Natural Parameter Space

$$\mathcal{H} = \left\{ \boldsymbol{\eta} = (\eta_1, \dots, \eta_k) : \int_{-\infty}^{\infty} h(x) \exp \left( \sum_{i=1}^k \eta_i t_i(x) \right) ds < \infty, \text{ or } \sum_x \dots < \infty \right\}$$

**Example:** For exponential distribution, we have  $\mathcal{H} = \{\eta > 0\}$ .

Using Hölder's inequality, one can prove that  $\mathcal{H}$  is a convex set.

## Natural Sufficient Statistics

Suppose  $X_1, \dots, X_n$  is a random sample from

$$f(x|\boldsymbol{\eta}) = h(x)c^*(\boldsymbol{\eta}) \exp \left( \sum_{i=1}^k \eta_i t_i(x) \right).$$

Define statistics  $\mathbf{T} = (T_1(\mathbf{X}), \dots, T_k(\mathbf{X}))$ , where

$$T_i(\mathbf{X}) = \sum_{j=1}^n t_i(X_j).$$

In matrix form

$$f_{\mathbf{X}}(\mathbf{x}|\boldsymbol{\eta}) = \left( \prod_i h(x_i) \right) [c^*(\boldsymbol{\eta})]^n \exp(\boldsymbol{\eta}^T \mathbf{T}(\mathbf{x}))$$

## Natural sufficient statistics

By the factorization theorem, the natural statistics are sufficient for  $\boldsymbol{\eta}$

$$\mathbf{T}(\mathbf{X}) = \left( \sum_{j=1}^n t_1(X_j), \dots, \sum_{j=1}^n t_k(X_j) \right)$$

Moreover,  $\mathbf{T}$  still belongs to an exponential family

$$f_T(\mathbf{u}|\theta) = \tilde{h}(\mathbf{u})[c^*(\boldsymbol{\eta})]^n \exp(\boldsymbol{\eta}^T \mathbf{u}).$$



**Example:** Bernoulli( $p$ ).

$$f(x|p) = p^x(1-p)^{1-x} = (1-p) \exp \left( \log \left( \frac{p}{1-p} \right) x \right)$$

So  $k = 1$ ,  $t_1(x) = x$  and  $\eta = \log \left( \frac{p}{1-p} \right)$ .

$$T = T_1(X_1, \dots, X_n) = X_1 + \dots + X_n.$$

$T$  is Binomial ( $n, p$ )

$$f(x|p) = \binom{n}{x} (1-p)^n \exp \left( \log \left( \frac{p}{1-p} \right) x \right) = \binom{n}{x} (1-p)^{n-x} p^x$$

# Minimal Sufficient Statistics

For a given parameter, there are many sufficient statistics.

- The concept of sufficiency implies no loss of information for  $\theta$ .
- The concept of sufficiency, by itself, does not imply data reduction. (E.g. the full data  $\mathbf{X}$  is sufficient statistic for any parameter  $\theta$ .)

Is there a sufficient statistic that provides “maximal” reduction of data?

## Definition (Minimal Sufficient Statistics)

A sufficient statistic  $T(\mathbf{X})$  is called a minimal sufficient statistic if, for **any** other sufficient statistic  $S(\mathbf{X})$ , there is a (measurable) function such that  $T = \psi(S)$  (a.s. for any  $\mathbb{P}_\theta$ ).

Recall the partition induced by a statistic

$$\mathcal{A}(T) = \{A_t\}, \quad A_t = \{\mathbf{x} : T(\mathbf{x}) = t\}$$

Minimal sufficiency of  $T$  implies that

For any sufficient statistic  $S$ , if  $S(\mathbf{x}) = S(\mathbf{y})$ , then  $T(\mathbf{x}) = T(\mathbf{y})$ .

Then the partition  $\mathcal{A}(T)$  is coarser than  $\mathcal{A}(S)$ .

The simpler the partition is, the more data reduction we have.

While retaining all information of  $\theta$ , minimal sufficiency identifies

- the maximal reduction of the data;
- the coarsest partition of the sample space; and
- \*the coarsest  $\sigma$ -algebra.

## Remarks

### One-to-one mapping

Any one-to-one function of a minimal sufficient statistic is minimal sufficient.

This can be proved using factorization theorem and the definition of minimality.

### Uniqueness

Minimal statistic is unique in the sense that two statistics that are one-to-one measurable functions of each other can be treated as the same.

- The partitions induced are the same.
- It is this partition that is the fundamental object.

## Minimal Sufficient Statistics

**Example:** Normal sufficient statistic for  $\mu$  with known  $\sigma$ . Consider two sufficient statistics:

$$T(X) = \bar{X}, \quad T'(X) = (\bar{X}, S^2)$$

Recall that  $\bar{X}$  and  $S^2$  are independent. So  $T'(X)$  can not be written as function of  $T(X)$ , and hence is not minimal.

How to check if  $\bar{X}$  is minimal?

## Minimal Sufficient Statistics

### Theorem (Checking Rule)

Let  $f(x|\theta)$  be the pmf/pdf of a sample  $\mathbf{X}$ . Suppose there exists a statistic  $T(\cdot)$  such that, for every two sample realizations  $\mathbf{x}$  and  $\mathbf{y}$ ,

$$\frac{f(\mathbf{x}|\theta)}{f(\mathbf{y}|\theta)} \text{ does not depend on } \theta \Leftrightarrow T(\mathbf{x}) = T(\mathbf{y}).$$

Then  $T(\mathbf{X})$  is a minimal sufficient statistic for  $\theta$ .

**Example:** Normal minimal sufficient statistic for  $\theta = \mu, \sigma^2, (\mu, \sigma^2)$ .

$$\frac{f(\mathbf{x}|\mu, \sigma)}{f(\mathbf{y}|\mu, \sigma)} = \frac{\frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left(-\frac{(n-1)s_{\mathbf{x}}^2}{2\sigma^2}\right) \exp\left(-\frac{n(\bar{x}-\mu)^2}{2\sigma^2}\right)}{\frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left(-\frac{(n-1)s_{\mathbf{y}}^2}{2\sigma^2}\right) \exp\left(-\frac{n(\bar{y}-\mu)^2}{2\sigma^2}\right)}$$

## Proof of the Checking Rule

- Sufficiency. Given  $T(\mathbf{x}) = T(\mathbf{y})$ , then  $f(\mathbf{x}|\theta)/f(\mathbf{y}|\theta)$  does not depend on  $\theta$ . Hence  $f(\mathbf{x}|\theta)$  is a constant function in  $\theta$  on  $A_t = \{\mathbf{x} : T(\mathbf{x}) = t\}$ . Let  $g(t|\theta) = f(\mathbf{x}|\theta)$  for any  $\mathbf{x} \in A_t$ . Let  $h(\mathbf{x}) = f(\mathbf{x}|\theta)/g(T(\mathbf{x})|\theta)$ . Note that  $h$  does not depend on  $\theta$ . Sufficiency follows from the factorization theorem.
- Minimality. Let  $T'(\mathbf{X})$  be a sufficient statistic, which has factorization  $f(\mathbf{x}|\theta) = g'(T'(\mathbf{x})|\theta)h'(\mathbf{x})$ . If  $\mathbf{x}$  and  $\mathbf{y}$  are two sample realizations such that  $T'(\mathbf{x}) = T'(\mathbf{y})$ , then

$$\frac{f(\mathbf{x}|\theta)}{f(\mathbf{y}|\theta)} = \frac{g'(T'(\mathbf{x})|\theta)h'(\mathbf{x})}{g'(T'(\mathbf{y})|\theta)h'(\mathbf{y})} = \frac{h'(\mathbf{x})}{h'(\mathbf{y})} \Rightarrow T(\mathbf{x}) = T(\mathbf{y})$$

$T(\mathbf{x})$  is a function of  $T'(\mathbf{x})$ .

# Uniform Distribution

**Example:** Consider  $X_1, \dots, X_n$  are uniform distributed r.v. in  $[\theta, \theta + 1]$ .

- Remember the indicator function:

$$\frac{f(\mathbf{x}|\theta)}{f(\mathbf{y}|\theta)} = \frac{\mathbb{1}_{\theta \leq x_{(1)} \leq x_{(n)} \leq \theta+1}}{\mathbb{1}_{\theta \leq y_{(1)} \leq y_{(n)} \leq \theta+1}}$$

- By the checking rule,  $T(\mathbf{X}) = (X_{(1)}, X_{(n)})$  is minimal sufficient.
- Notice that the sufficient static is of dimension 2, compared to the parameter ( $1D$ ) and the sample ( $nD$ ).



# Ancillary Statistics

## Definition (Ancillary Statistic)

A statistic  $V(\mathbf{X})$  whose distribution does not depend on the parameter  $\theta$  is called an ancillary statistic.

**Example:** (Location family ancillary statistic) Suppose  $F(\cdot)$  is a cdf, let  $X_1, \dots, X_n$  be a sample from  $F(x - \theta)$ .  $R = X_{(n)} - X_{(1)}$  is ancillary.

$$P_\theta(R \leq r) = P_\theta(\max_i X_i - \min_i X_i \leq r) = P_\theta(\max_i (X_i - \theta) - \min_i (X_i - \theta) \leq r)$$

Recall the previous uniform example.

**Example:** (Scale family ancillary statistic) let  $X_1, \dots, X_n$  be a sample from  $F(x/\sigma)$ .  $X_1/X_n, \dots, X_{n-1}/X_n$  is ancillary.  $X_i = \sigma Z_i$  with  $Z_i \sim F$ .

## Remarks

- The simplest ancillary statistic is the constant statistic  $V(\mathbf{X}) \equiv c$ .
- A non-trivial ancillary statistic  $V(\mathbf{X})$  identifies a partition  $\mathcal{A}(V) = \{\{\mathbf{x} : V(\mathbf{x}) = v\} : v\}$  that does not contain any information about  $\theta$ .
- Suppose that  $T(\mathbf{X})$  is a statistic and  $V(T(\mathbf{X}))$  is a non-trivial ancillary statistic, then the partition  $\mathcal{A}(T)$  contains a coarser partition that does not contain any information about  $\theta$ .
- This indicates that we may need further data reduction than  $T$ .
- A sufficient statistic seems to be the most “successful” in data reduction if no nonconstant function of it is ancillary.

**Question:** Recall that minimal sufficient statistics indicates a maximal data reduction while keeping the information of  $\theta$ . Is minimal sufficient statistics “successful” in the above sense?

Ancillary statistics may be a component of the minimal sufficient statistic.

**Example:** Let  $X_1, \dots, X_n$  be a sample from Uniform  $(\theta, \theta + 1)$ .

- $R = X_{(n)} - X_{(1)}$  is ancillary.
- We know that  $(X_{(1)}, X_{(n)})$  is minimal sufficient, hence

$(X_{(n)} - X_{(1)}, X_{(n)} + X_{(1)})$  is a minimal sufficient statistic.

Therefore,

- There exist nonconstant function of minimal sufficient statistic that is ancillary  $\Rightarrow$  minimal sufficient statistics is not “successful.”
- Ancillary statistics is not always independent of minimal sufficient statistic.

This inspires the definition of **completeness**.

# Completeness

## Definition (Complete statistic)

Let  $\mathbf{X}$  be i.i.d. from pdf/pmf  $f(\cdot|\theta)$ . A statistic  $T(\mathbf{X})$  is said to be complete for  $\theta$ , if any (measurable) function  $g$  not depending on  $\theta$  satisfies that

$$\mathbb{E}_{\theta}[g(T(\mathbf{X}))] = 0 \text{ for all } \theta \Rightarrow \mathbb{P}_{\theta}(g(T(\mathbf{X})) = 0) = 1 \text{ for all } \theta.$$

- Complete if there is no non-trivial unbiased estimator for 0 based on  $T(\mathbf{X})$ .
- Completeness implies that unbiased estimator of  $\theta$  based on  $T$  is unique.
- A minimal sufficient statistic is not necessarily complete. E.g.  $\text{Uniform}([\theta, \theta + 1])$ .
- Complete statistic is not necessarily sufficient. See example below.

## Complete Statistics – Examples

**Example:**  $\text{Uniform}(\theta, \theta + 1)$  re-visited.  $T(X) = (X_{(1)}, X_{(n)})$  is a minimal sufficient statistic. However,  $X_{(n)} - X_{(1)} - \mathbb{E}[X_{(n)} - X_{(1)}]$  has mean 0, but is not 0 a.s., thus both  $T(X)$  and  $X_{(n)} - X_{(1)}$  are not complete. It is important here that  $g(\cdot)$  does not depend on  $\theta$ .

The range  $R = X_{(n)} - X_{(1)}$  itself does not contain any information about  $\theta$ , but combined with the sufficient statistics, it does! (See C-B Example 6.2.20.)

**Example:**  $\text{Normal}(0, \sigma^2)$  with  $\theta = \sigma$  and  $T = \bar{X}$ . Let  $g(x) = x$ , then  $\mathbb{E}[g(\bar{X})] = 0$  but  $\mathbb{P}(g(\bar{X}) = 0) \neq 1$ . Not complete.

**Example:**  $\text{Normal}(\mu, 1)$  with  $\theta = \mu$  and  $T = \bar{X}$ . If  $\mathbb{E}_\theta[g(\bar{X})] = 0$  for all  $\theta$ , then  $g \equiv 0$  with probability 1. Complete.

**Example:**  $\text{Normal}(\mu, \sigma^2)$  and  $T = \bar{X}$ .  $T$  is complete for  $\theta = \mu$  and  $\theta = (\mu, \sigma^2)$ , but not  $\theta = \sigma^2$ . Completeness does not imply sufficiency.

**Example:** Bernoulli complete statistic. For a Bernoulli random sample with success probability  $\theta = p$ ,  $0 < p < 1$ . A minimal sufficient statistic is  $T(\mathbf{X}) = \sum X_i \sim \text{Binomial}(n, p)$ . Suppose

$$0 = \mathbb{E}_p[g(T)] = \sum_{t=0}^n g(t) \binom{n}{t} p^t (1-p)^{n-t} = (1-p)^n \sum_{t=0}^n g(t) \binom{n}{t} \phi^t.$$

where  $\phi = \frac{p}{1-p}$ , so  $\phi \in (0, \infty)$ . Note that  $(1-p)^n > 0$ . For a polynomial (in  $\phi$ ) to be a constant 0, every coefficient has to be 0. Complete!

## Completeness Implies Minimality

### Theorem

- *If a minimal sufficient statistic exists, then any complete sufficient statistic is also a minimal sufficient statistic.*
- *A finite dimensional complete sufficient statistic is also minimal sufficient.*

The theorem states that under mild conditions, a complete sufficient statistic is all you need. It implies minimal sufficiency.

Converse is not true: in the  $\text{Uniform}(\theta, \theta + 1)$  example,  $(X_{(n)} - X_{(1)}, X_{(n)} + X_{(1)})$  is a minimal sufficient statistic for  $\theta$ , but not complete.

If a minimal sufficient statistic  $T$  is not complete, then there does not exist any complete statistic.



## Order Statistic Re-Visited

**Example:** We have argued that the order statistics  $\mathbf{T}$  are sufficient for  $\theta = f \in \Theta = \{\text{All dist. with a density.}\}$ . We now show that it is also complete for  $\theta \in \Theta$ .

- First, note that  $\delta$  is a function of  $\mathbf{T}$  iff it is symmetric in its arguments, i.e.  $\delta(\mathbf{x}) = \delta(\pi\mathbf{x})$  for any permutation  $\pi$ .
- Consider a family of distributions  $f = \sum_{i=1}^n \alpha_i f_i \in \Theta$  for  $\alpha_i > 0$ ,  $\sum_i \alpha_i = 1$  and  $f_i$  to be specified.  $\mathbb{E}_F[h(T(\mathbf{X}))] \equiv \mathbb{E}_F[\delta(\mathbf{X})] = 0$  implies that

$$0 = \int \cdots \int \delta(\mathbf{x}) \prod_{j=1}^n f(x_j) d\mathbf{x} = \int \cdots \int \delta(\mathbf{x}) \prod_{j=1}^n \left( \sum_{i=1}^n \alpha_i f_i(x_j) \right) d\mathbf{x}$$

- The RHS is a polynomial of  $\alpha$ . Hence all coefficients must be zero.

- Consider the coefficient of  $\prod_i \alpha_i$

$$\begin{aligned} 0 &= \sum_{\pi} \int \cdots \int \delta(\mathbf{x}) \prod_{i=1}^n f_i(x_{\pi(i)}) d\mathbf{x} \\ &= \sum_{\pi} \int \cdots \int \delta(\pi^{-1} \mathbf{x}) \prod_{i=1}^n f_i(x_i) d\mathbf{x} = \sum_{\pi} \int \cdots \int \delta(\mathbf{x}) \prod_{i=1}^n f_i(x_i) d\mathbf{x} \\ &= n! \int \cdots \int \delta(\mathbf{x}) \prod_{i=1}^n f_i(x_i) d\mathbf{x} \end{aligned}$$

- Now, let  $f_i$  be uniform on interval  $[a_i, b_i]$ , then

$$\int_{a_1}^{b_1} \cdots \int_{a_n}^{b_n} \delta(\mathbf{x}) d\mathbf{x} = 0 \Rightarrow \delta(\mathbf{x}) = 0, a.s.$$

Complete!

## Order Statistic Cont.

**Example:** Now that the ordered statistic  $\mathbf{T}$  is complete and sufficient, consider the ranks of the observations

$$\mathbf{R} = (R_1, \dots, R_n)$$

where  $R_i \equiv \{\# \text{ of } X_j\text{'s} \leq X_i\}$ . Then  $\mathbb{P}(\mathbf{R} = \pi(1, \dots, n)) = 1/n!$ ,  $\mathbf{R}$  is ancillary!

In fact,  $\mathbf{T}$  and  $\mathbf{R}$  are independent

$$\mathbb{P}(\mathbf{T} = \mathbf{t}, \mathbf{R} = \mathbf{r}) = \frac{1}{n!} \times n! \prod_i f(t_i).$$

# Complete Statistics

## Theorem (Basu's)

*If  $T(\mathbf{X})$  is a complete and sufficient for  $\mathcal{P} = \{\mathbb{P}_\theta : \theta \in \Omega\}$ , if  $V(\mathbf{X})$  is ancillary, then  $T(\mathbf{X})$  and  $V(\mathbf{X})$  are independent under  $\mathbb{P}_\theta$  for any  $\theta$ .*

*Proof.* Define  $q_A(t) = \mathbb{P}_\theta(V \in A | T(\mathbf{X}) = t)$  and  $p_A = P_\theta(V \in A)$ . Let  $g(t) = q_A(t) - p_A$ . We have  $g(T(\mathbf{X}))$  non-trivial and  $g(t)$  does not depend on  $\theta$  (by sufficiency and ancillarity). Now, note that

$$\mathbb{E}_\theta[g(T(\mathbf{X}))] = \mathbb{E}_\theta[\mathbb{P}_\theta(V \in A | T(\mathbf{X}))] - p_A = \mathbb{P}_\theta(V \in A) - p_A = 0.$$

By completeness,  $q_A(T) = p_A$ , *a.s.*

$$\begin{aligned}\mathbb{P}_\theta(T \in A, V \in B) &= \mathbb{E}_\theta[\mathbf{1}_A(T)\mathbf{1}_B(V)] \\ &= \mathbb{E}_\theta[\mathbb{E}_\theta[\mathbf{1}_A(T)\mathbf{1}_B(V) | T]] \\ &= \mathbb{E}_\theta[\mathbf{1}_A(T)\mathbb{E}_\theta[\mathbf{1}_B(V) | T]] \\ &= \mathbb{E}_\theta[\mathbf{1}_A(T)q_A(T)] \\ &= \mathbb{E}_\theta[\mathbf{1}_A(T)p_A] \\ &= \mathbb{P}_\theta(T \in A)\mathbb{P}_\theta(V \in B)\end{aligned}$$

Hence,  $T$  and  $V$  are independent.

## Complete Statistics for Exponential Family

- Basu's theorem allows us to deduce the independence of two statistics. But how to show completeness?
- Luckily, for exponential family, we know how to do it.
- Let  $X_1, \dots, X_n$  a sample from a pdf/pmf that belongs to an  $k$ -parameter canonical exponential family given by

$$f(x|\boldsymbol{\eta}) = h(x)c^*(\boldsymbol{\eta}) \exp \left( \sum_{i=1}^k \eta_i t_i(x) \right),$$

where  $\boldsymbol{\eta} \in \Xi \subset \mathcal{H}$  is the parameter set.

# Minimal Exponential Families

## Minimal exponential family

An exponential family parameterize by its natural parameters  $\mathcal{P} = \{\mathbb{P}_\eta : \eta \in \mathcal{H}\}$  is **minimal** if

- ① there is no set of coefficients  $\boldsymbol{\lambda} \in \mathbb{R}^{k+1}, \boldsymbol{\lambda} \neq \mathbf{0}$ , such that  $\sum_i \lambda_i \eta_i = \lambda_0$ ;
- ② there is no set of coefficients  $\boldsymbol{\lambda} \in \mathbb{R}^{k+1}, \boldsymbol{\lambda} \neq \mathbf{0}$ , such that  $\sum_i \lambda_i T_i(\mathbf{x}) = \lambda_0$ .

- The first condition rules out possibility to transform the  $k$ -dimensional exponential family into an exponential family of smaller dimension.
- The second condition rules out cases where the model is **unidentifiable** (i.e., exist  $\eta_1 \neq \eta_2$  such that  $\mathbb{P}_{\eta_1} = \mathbb{P}_{\eta_2}$ .) **Example:**  $X \sim \text{Exp}(\eta_1, \eta_2)$ , where  $p(x, \eta_1, \eta_2) = \exp(-\eta_1 x - \eta_2 x + \log(\eta_1 + \eta_2)) \mathbb{1}(x \geq 0)$ .

# Curved Exponential Family

## Curved exponential family

Suppose  $\mathcal{P} = \{\mathbb{P}_\eta : \eta \in \Xi\}$  is an  $k$ -parameter **minimal** canonical exponential family. If  $\Xi$  contains an  $k$ -dimensional open set, then  $\mathcal{P}$  is called **full-rank**. Otherwise,  $\mathcal{P}$  is **curved**.

In curved exponential family, the  $\eta_i$ 's are related in a non-linear way.



## Examples

Consider Normal  $(\mu, \sigma^2)$ ,

$$f(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(\mu)^2}{2\sigma^2}} \exp\left(\frac{\mu}{\sigma^2}x - \frac{1}{2\sigma^2}x^2\right)$$

- **Example:** Minimal and full-rank.  $\eta_1 = \frac{\mu}{\sigma^2}$  and  $\eta_2 = -\frac{1}{2\sigma^2}$ .
- **Example:** Non-minimal. When we restrict  $\mu = \sigma^2 = \theta$ , then  $\eta_1 = 1$  and  $\eta_2 = -\frac{1}{2\theta}$ .
- **Example:** Minimal and curved. When we restrict  $\mu = \sigma = \theta$ , then  $\eta_1 = 1/\theta$  and  $\eta_2 = -1/(2\theta^2)$ .
  - $T = (\bar{X}, S^2)$  is a sufficient statistic for  $\theta$ , but it is not complete for  $\theta$ .
  - To show it is not complete, need to find a nonzero function of  $T$  such that  $\mathbb{E}[g(\bar{X}, S^2)] = 0$  for all  $\theta$ . Let  $g(\bar{X}, S^2) = n\bar{X}^2/(n+1) - S^2$ .

# Completeness and Exponential Family

## Theorem

Suppose  $\mathcal{P} = \{\mathbb{P}_\eta : \eta \in \Xi\}$  is an  $k$ -parameter minimal canonical exponential family of full-rank, then

$$T(\mathbf{X}) = \left( \sum_{j=1}^n t_1(X_j), \dots, \sum_{j=1}^n t_k(X_j) \right)$$

is complete.

## Application of Basu's Theorem

**Example:** Let  $X_1, \dots, X_n$  be a sample from  $\text{Exponential}(\theta)$ . The following two are independent

$$g(\mathbf{X}) = \frac{X_n}{X_1 + \dots + X_n}, \quad T(\mathbf{X}) = X_1 + \dots + X_n.$$

- Exponential is a scale family, so  $g(\mathbf{X})$  is ancillary.
- Exponential is a minimal 1-parameter exponential family of full-rank, so  $T(\mathbf{X})$  is complete and sufficient.
- Easy to verify minimality using the checking rule, but unnecessarily!
- So  $\mathbb{E}_\theta[g(\mathbf{X})] = 1/n$ .

**Example:** If we consider  $N(\mu, \sigma^2)$  for a known  $\sigma$ ,  $\bar{X}$  and  $S^2$  are independent.

**Example:** For  $N(\mu, \sigma^2)$  with known  $\sigma$ .  $\bar{X}$  is a sufficient and complete statistic and  $med(\mathbf{X}) - \bar{X}$  is ancillary. So  $\text{Cov}(\bar{X}, med(\mathbf{X})) = \sigma^2/n$ .

## Summary

Consider two experiments

- Observe  $X \sim \mathbb{P}_{X|\theta}$ .
- Observe  $T \sim \mathbb{P}_{T|\theta}$ , then  $X|T = t \sim \mathbb{P}_{X|t}$ .

Then

- $X$  in both experiments share the same dist., thus inference about  $\theta$  should be the same in both cases.
- If  $T$  is sufficient, only the experiment of observing  $T$  is informative about  $\theta$ .
  - $T$  induce partitions on which identical statistical conclusions are drawn.
  - It is this partition (or  $\sigma$ -algebra), rather than the particular statistic inducing the partition, that is the fundamental object.
- If no coarser partition of the sample space that retains sufficiency is possible, then  $T$  is called minimal sufficient.

We will learn more about completeness next week.

## Reading Materials

### Same level

- Robert W. Keener, Theoretical Statistics, Chapter 2 and 3.
- (Not recommended) Casella and Berger, Statistical Inference, Section 6.2.

### Measure theoretic

- Jun Shao, Mathematical Statistics, Section 2.2.
- Lehmann and Romano, Testing Statistical Hypothesis, Section 1.9 and 2.6.