

# Trust your Tesla

## Collision Course Prediction for Simulated Autonomous Vehicles

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### Motivation

#### Societal trust in autonomous vehicles.



Improving autonomous vehicles' ability to predict collisions could save countless lives.

### The Problem

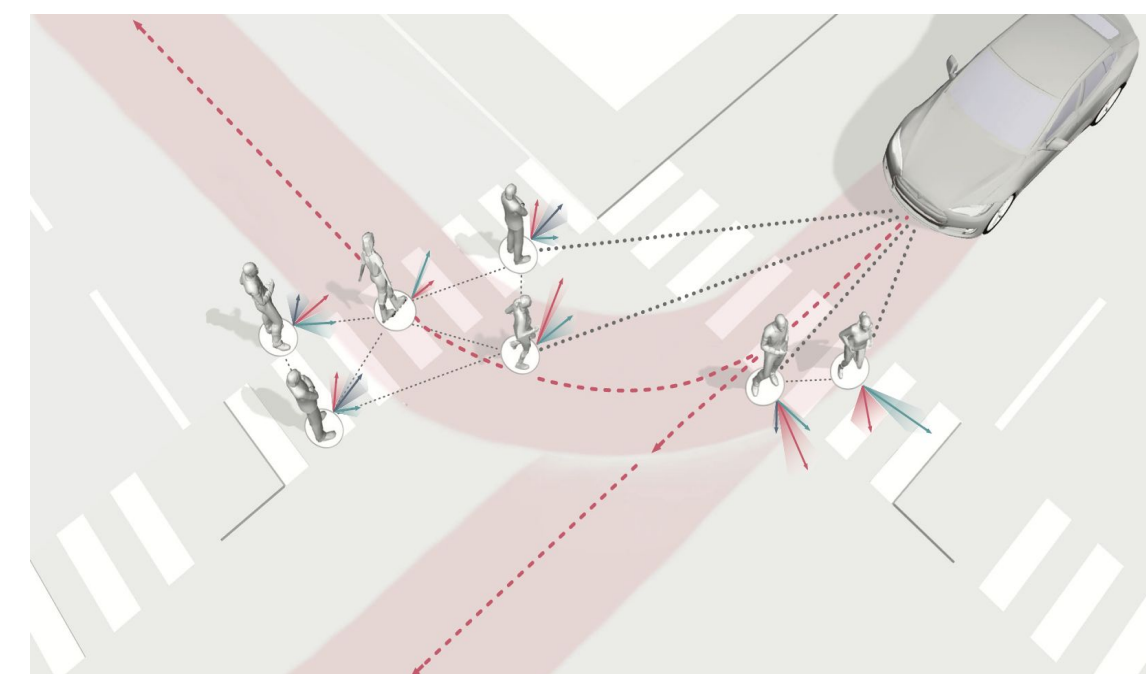
#### Collision Prediction

Predict riskiness of a vehicle's trajectory at a moment's notice.



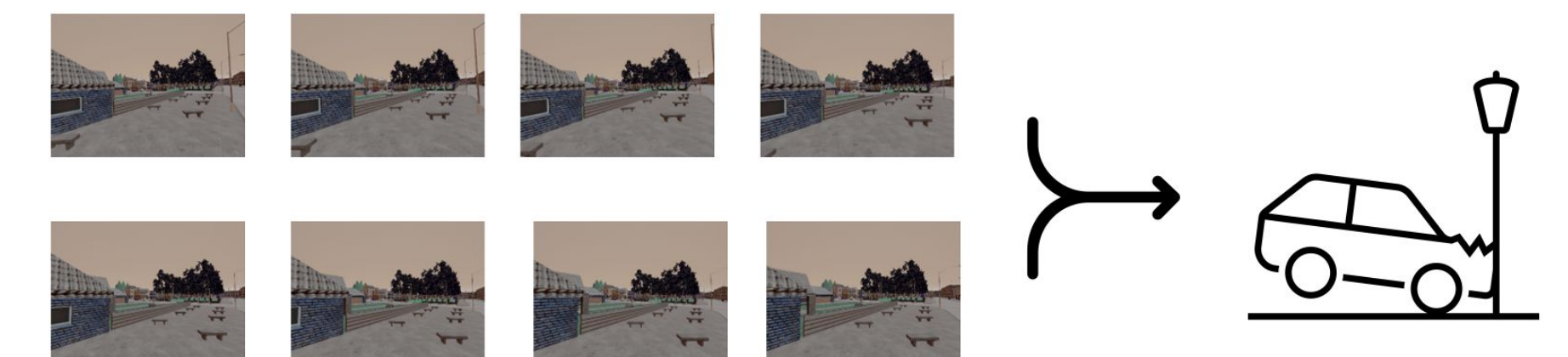
#### Time Series Data

Train on sequences of images to predict collision in real-time.



### Goal

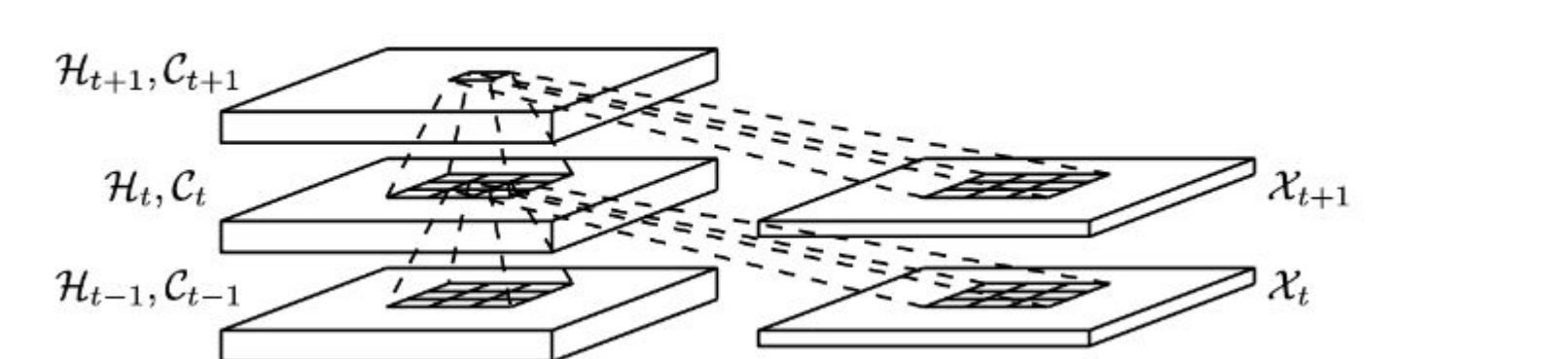
1. Given a sequence of 8 images of a simulated car's environment, accurately predict a collision course.
2. Achieve a testing accuracy of at least 75% if not higher.



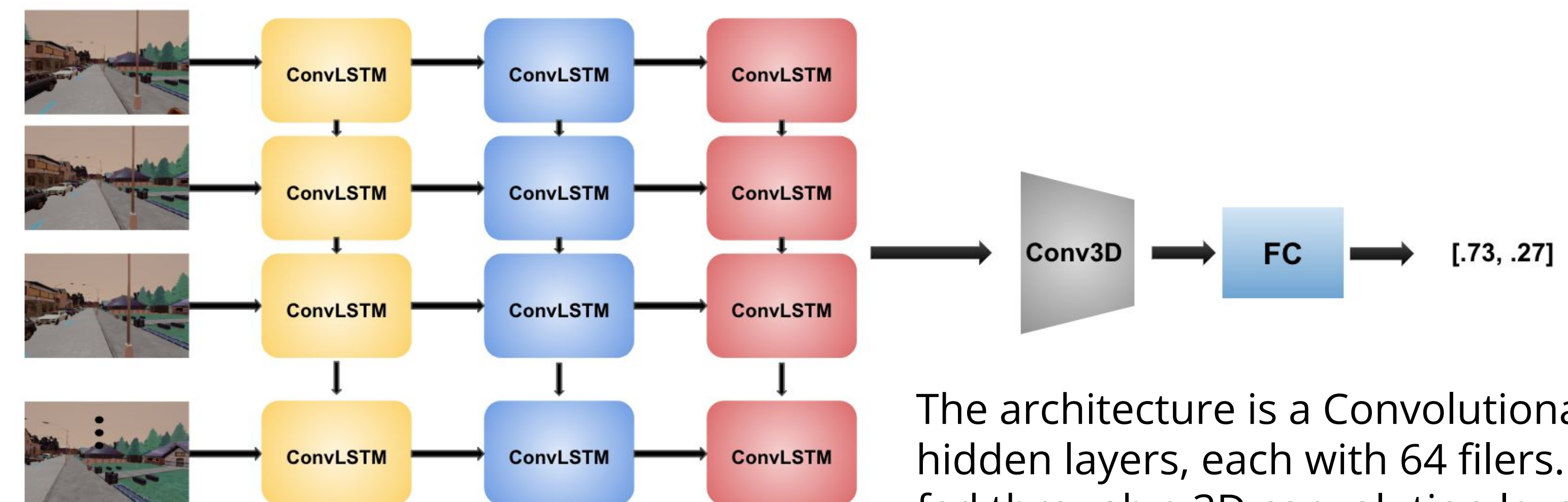
### Key Insights

#### The ConvLSTM Unit

The ConvLSTM is similar to the Fully Connected LSTM, but replaces matrix multiplication of weights and inputs with convolution. Combining convolution with the memory gated structure of the LSTM allows for better hidden spatio-temporal representations which leads to better predictions.

$$\begin{aligned}
 i_t &= \sigma(W_{xi} * X_t + W_{hi} * H_{t-1} + W_{ci} \circ C_{t-1} + b_i) \\
 f_t &= \sigma(W_{xf} * X_t + W_{hf} * H_{t-1} + W_{cf} \circ C_{t-1} + b_f) \\
 C_t &= f_t \circ C_{t-1} + i_t \circ \tanh(W_{xc} * X_t + W_{hc} * H_{t-1} + b_c) \\
 o_t &= \sigma(W_{xo} * X_t + W_{ho} * H_{t-1} + W_{co} \circ C_t + b_o) \\
 H_t &= o_t \circ \tanh(C_t)
 \end{aligned}$$


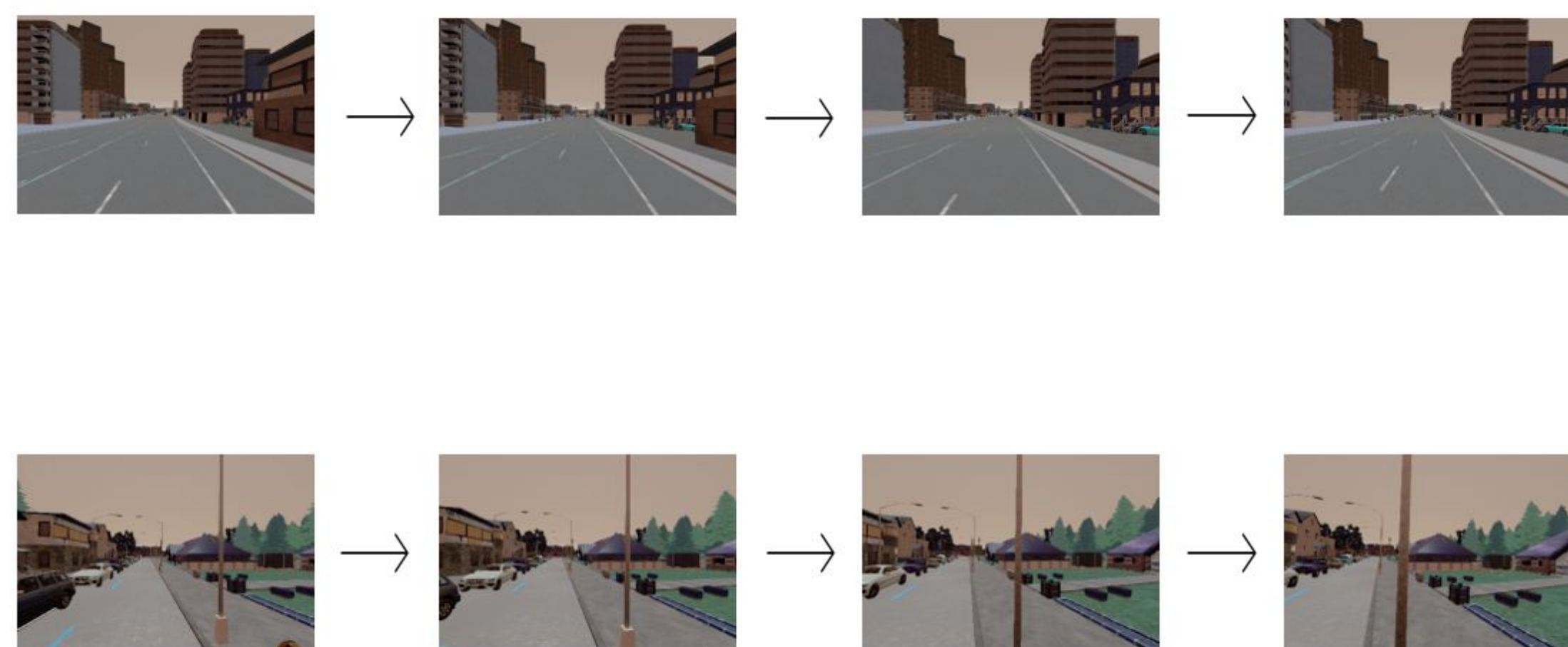
### Model Architecture



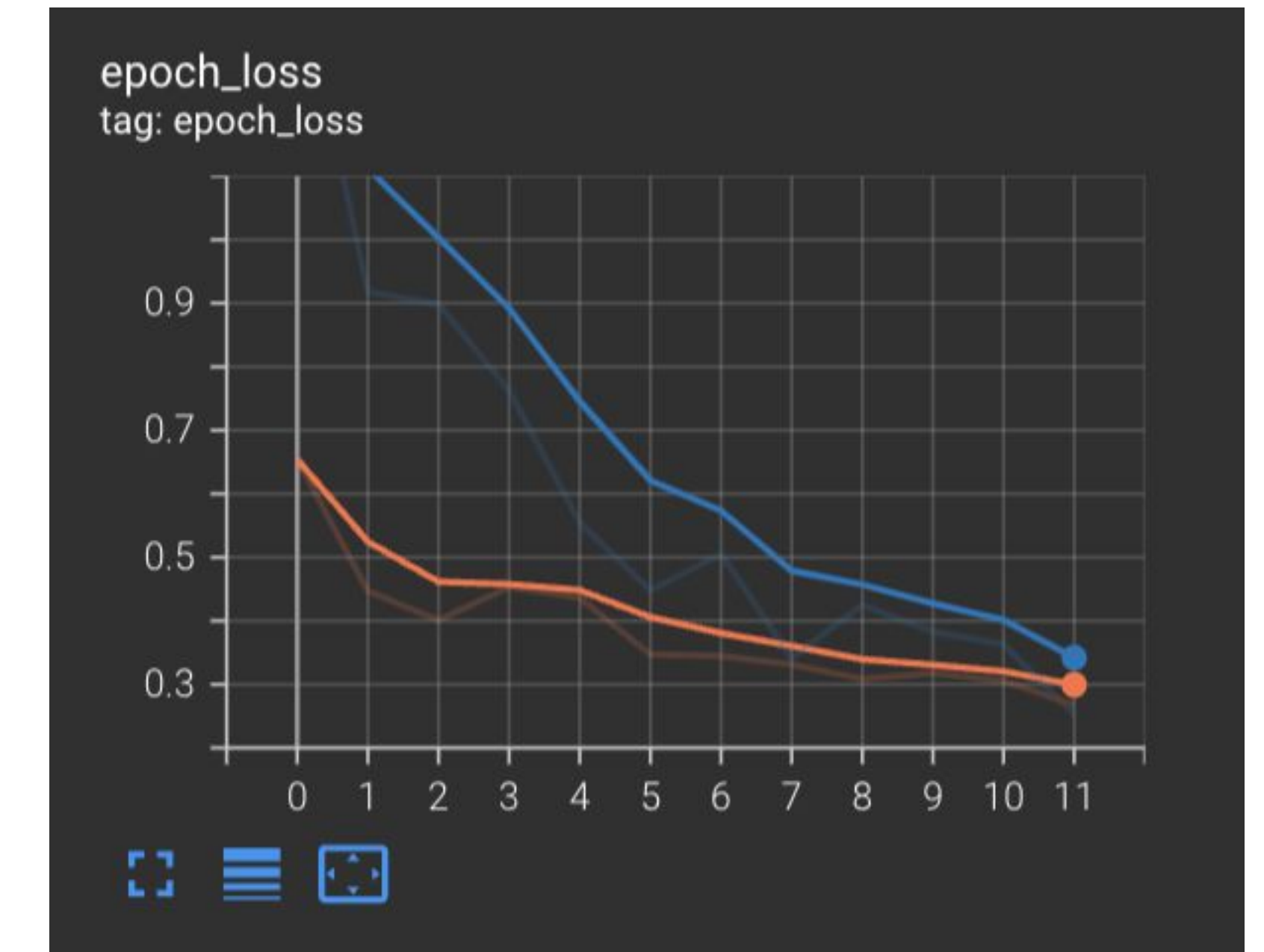
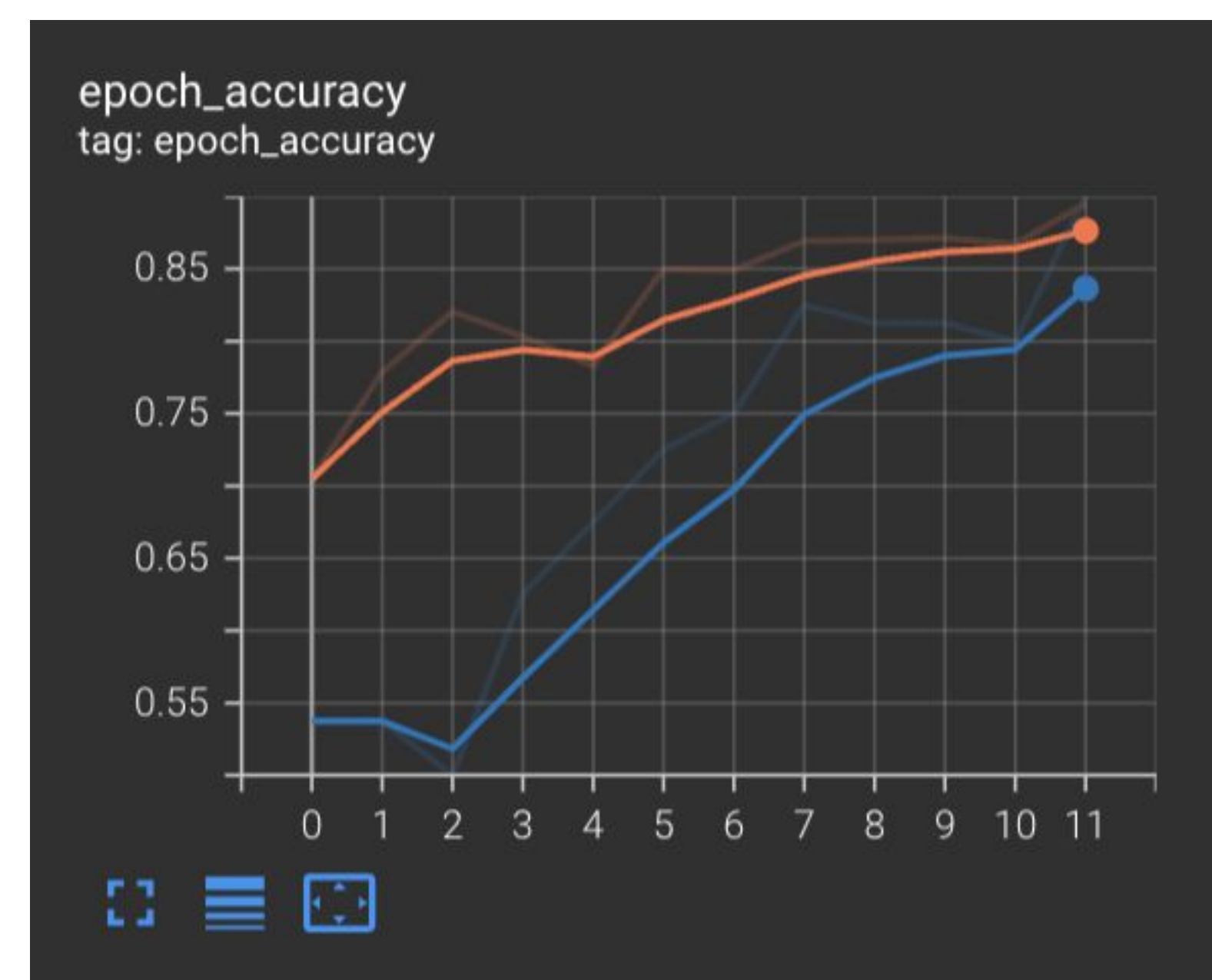
The architecture is a Convolutional LSTM with 3 hidden layers, each with 64 filters. The output is fed through a 3D convolution layer and then fully connected layers for classification

- Best results when Conv3D had 1 filter

### Results



### More Results



### References and Acknowledgments

- [1] Shi, Xingjian et al. "Convolutional LSTM Network: A Machine Learning Approach for Precipitation Nowcasting." *arXiv:1506.04214*.
- [2] N. Srivastava, E. Mansimov, R. Salakhutdinov, "Unsupervised Learning of Video Representations using LSTMs." *arXiv:1502.04681*
- [3] Opera, S. et. al., "A Review on Deep Learning Techniques for Video Prediction." *arXiv: 2004.05214*
- [4] Paarvendhan., "https://github.com/perseus784/Vehicle\_Collision\_Prediction\_Using\_CNN-LSTMs".

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Architecture	Train Accuracy	Validation Accuracy	Testing Accuracy
ConvLSTM(3 x 64)-Conv3D(32)-FC	0.8312	0.7375	0.7872
ConvLSTM(3 x 64)-Conv3D(1)-FC	0.8951	0.9000	0.9170