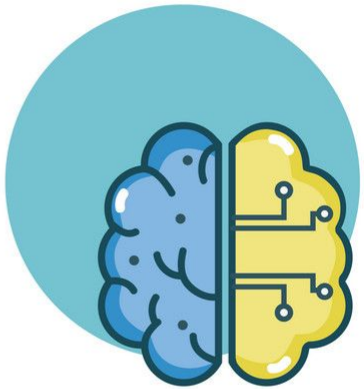
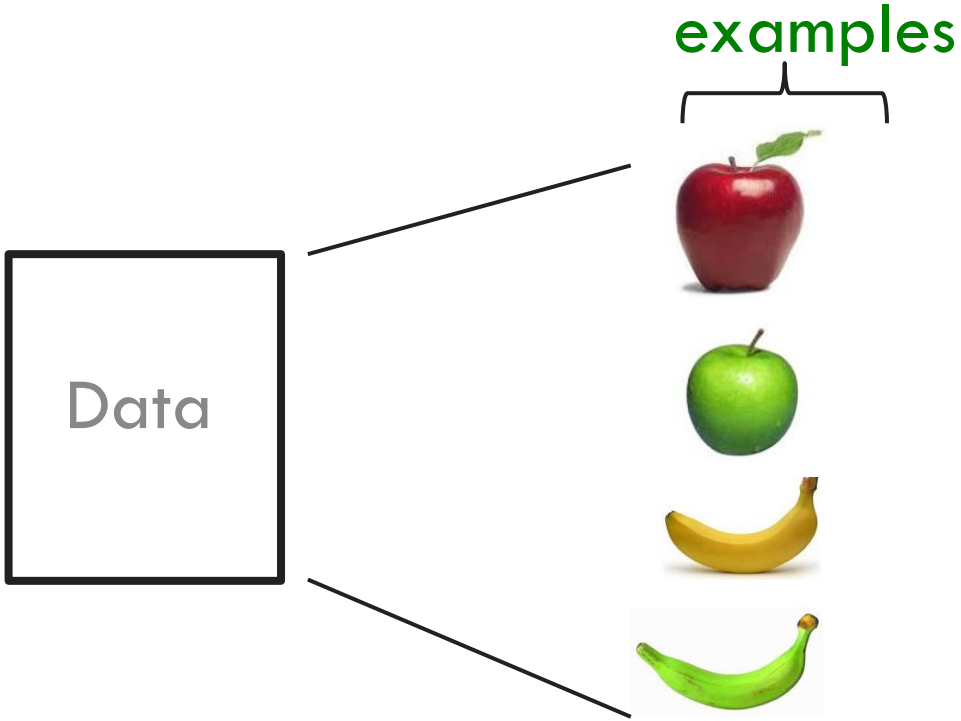
INTRODUCTION TO MACHINE LEARNING

K-Nearest neighbor

Elisa Ricci



Recap: Data



Recap: Representing examples

examples

What is an example?

How is it represented?

Recap: Features

examples

features

$f_1, f_2, f_3, \ldots, f_n$

$f_1, f_2, f_3, \ldots, f_n$

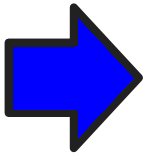
$f_1, f_2, f_3, \ldots, f_n$

$f_1, f_2, f_3, \ldots, f_n$

How our algorithms actually "view" the data

Recap: Features

examples



features

red, round, leaf, 3oz, …

green, round, no leaf, 4oz, …

yellow, curved, no leaf, 8oz, …

green, curved, no leaf, 7oz, …

How our algorithms actually "view" the data

Features are the questions we can ask about the examples

Features in generally are represented with vectors

Apples vs. Bananas

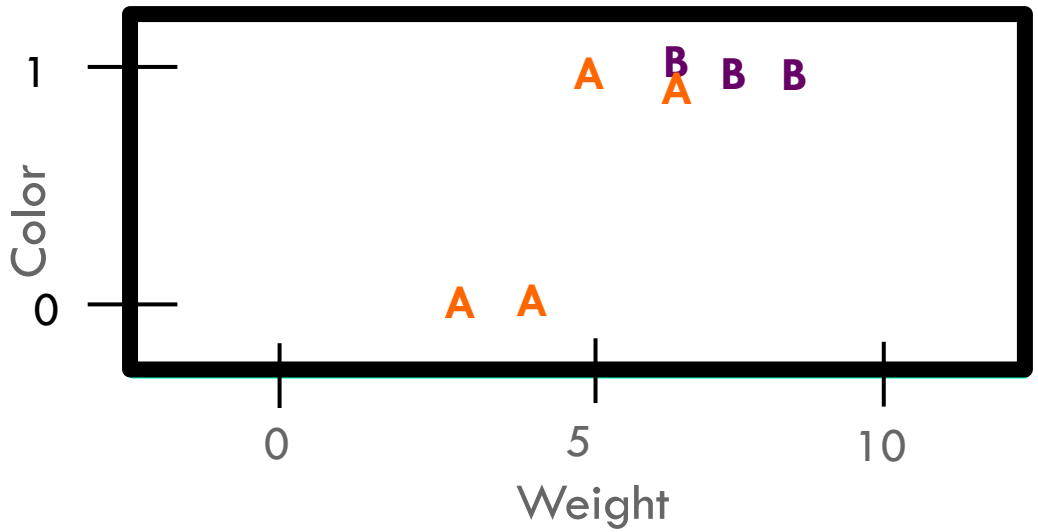
Weight	Color	Label
4	Red	Apple
5	Yellow	Apple
6	Yellow	Banana
3	Red	Apple
7	Yellow	Banana
8	Yellow	Banana
6	Yellow	Apple

Can we visualize this data?

Apples vs. Bananas

We can turn features into numerical values

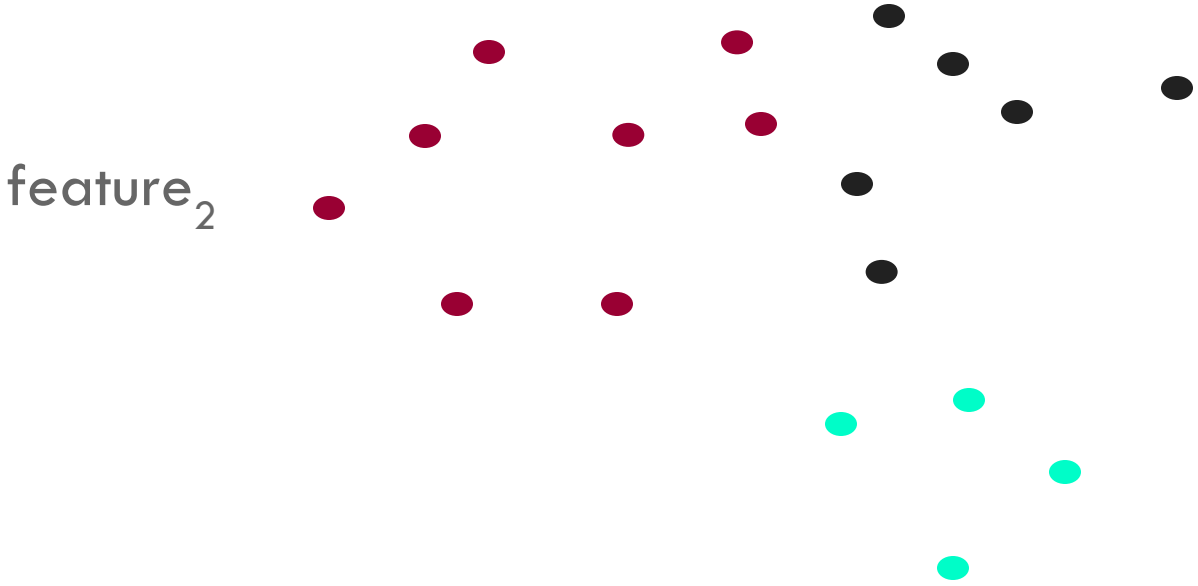
Weight	Color	Label
4	0	Apple
5	1	Apple
6	1	Banana
3	0	Apple
7	1	Banana
8	1	Banana
6	1	Apple



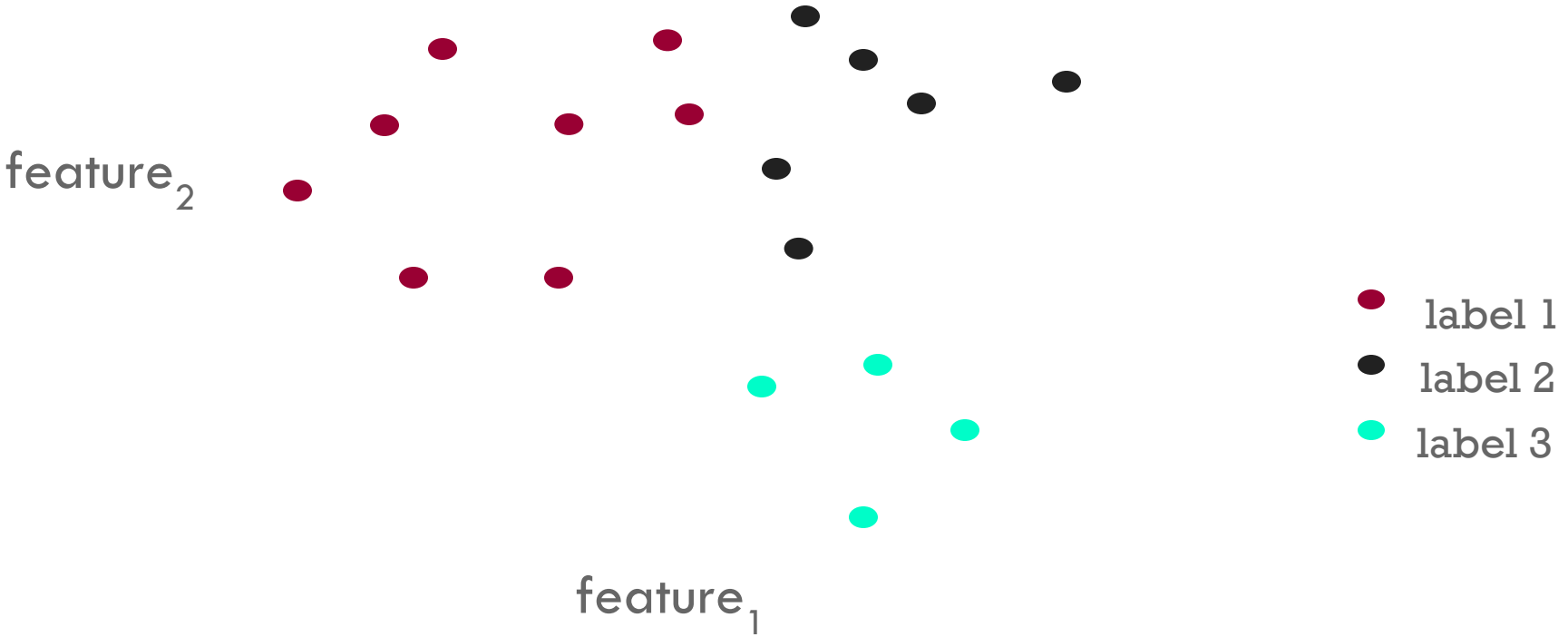
Examples are points in an *n*-dimensional space where *n* is the number of features

Examples in a feature space

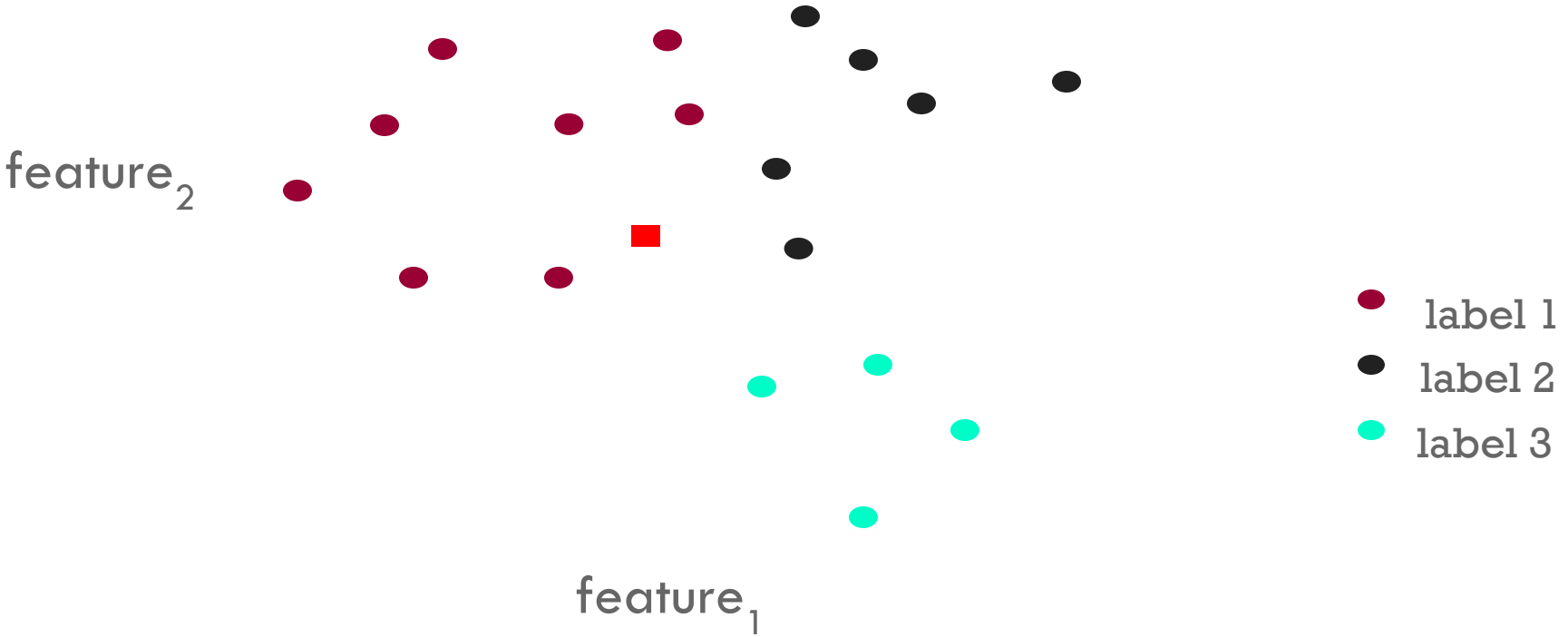
We can imagine to have 3 categories of interest



Training set



Test example: which class?



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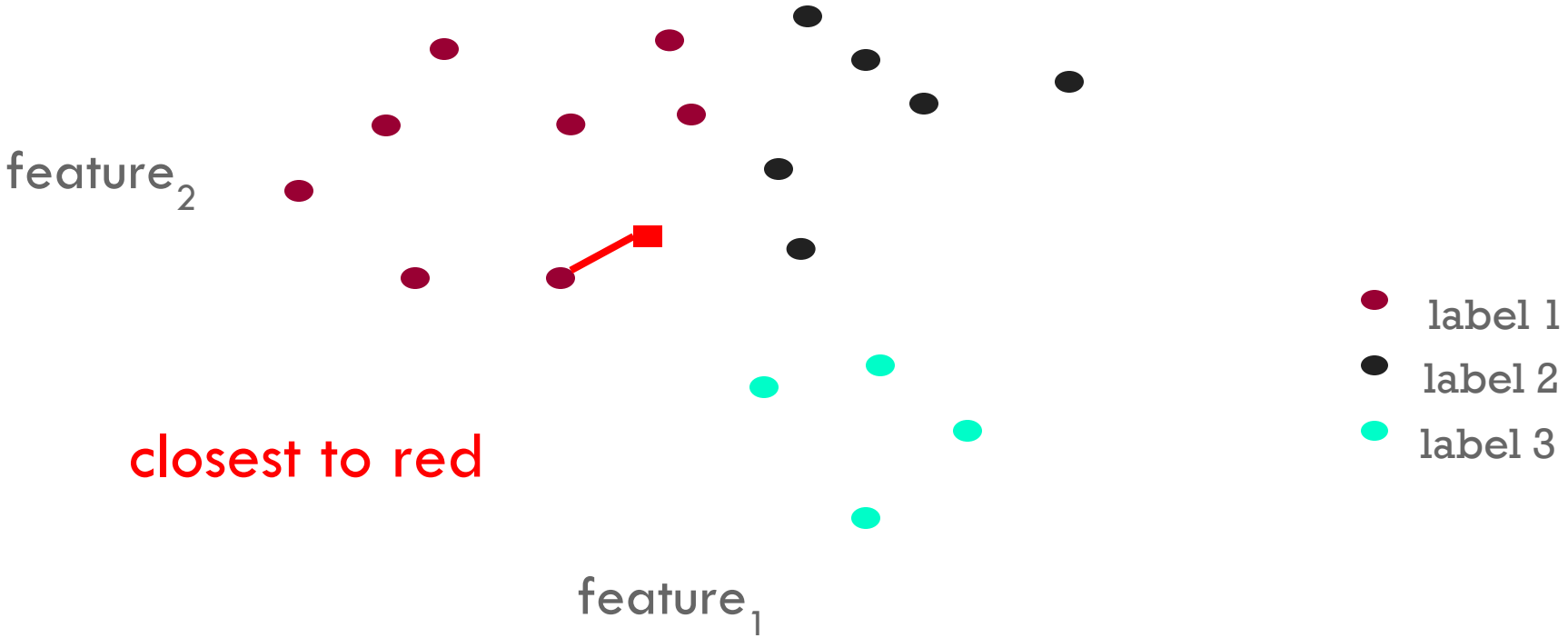
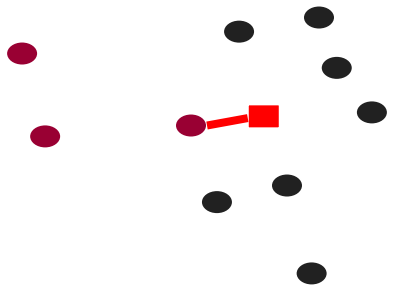


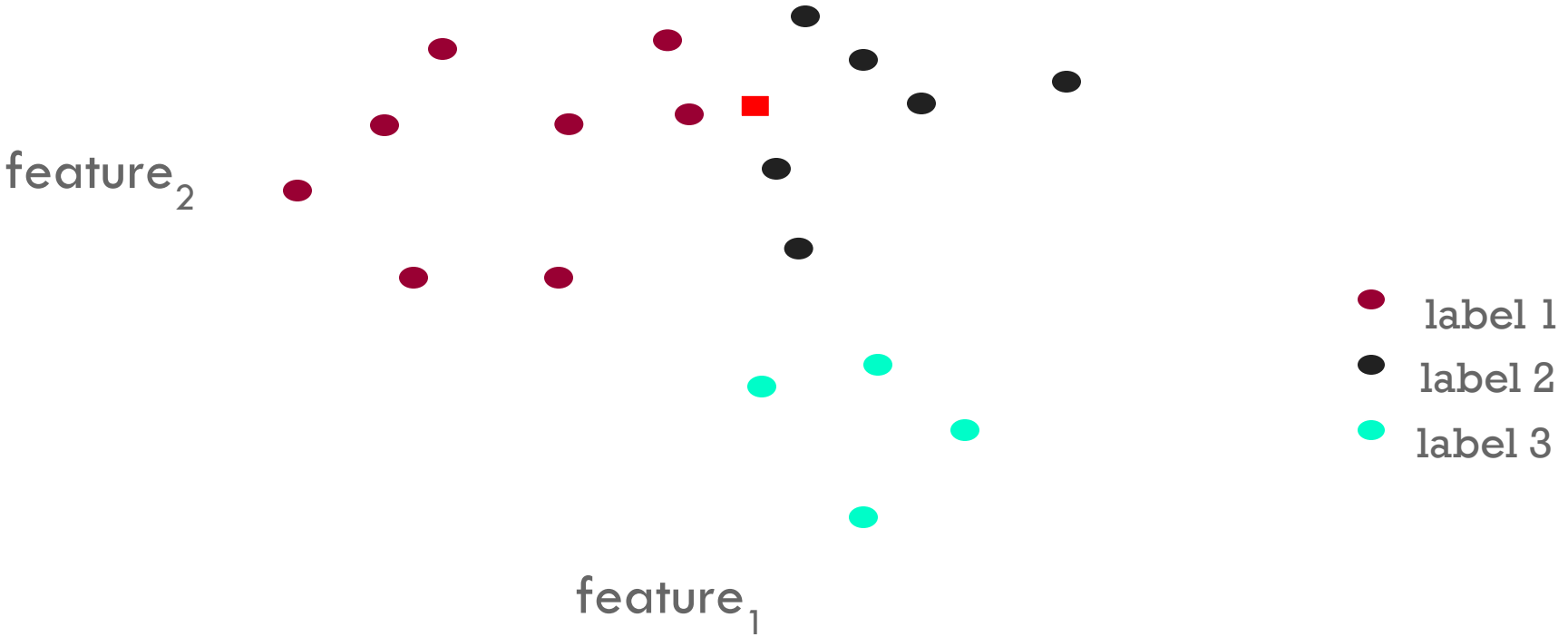
A classification algorithm?

To classify an example ***d***:

Label ***d*** with the label of the closest example to ***d*** in the training set



What about this example?



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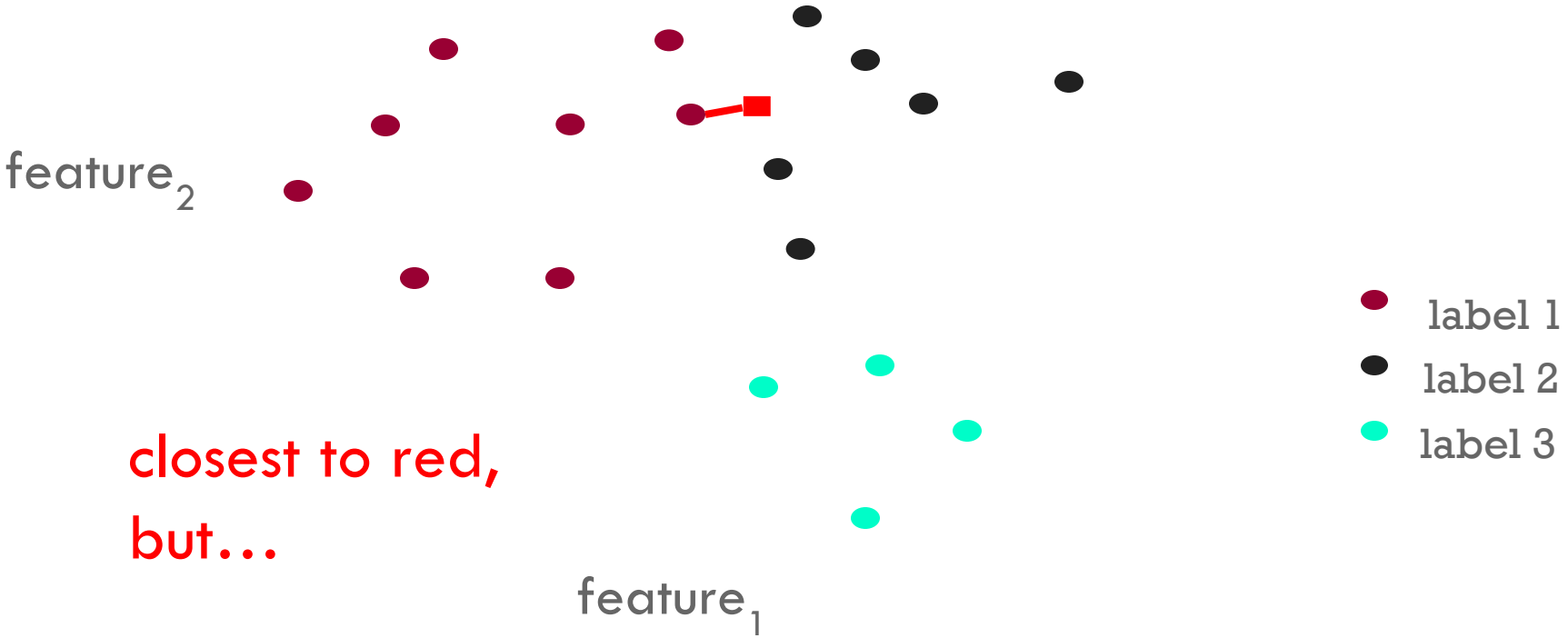

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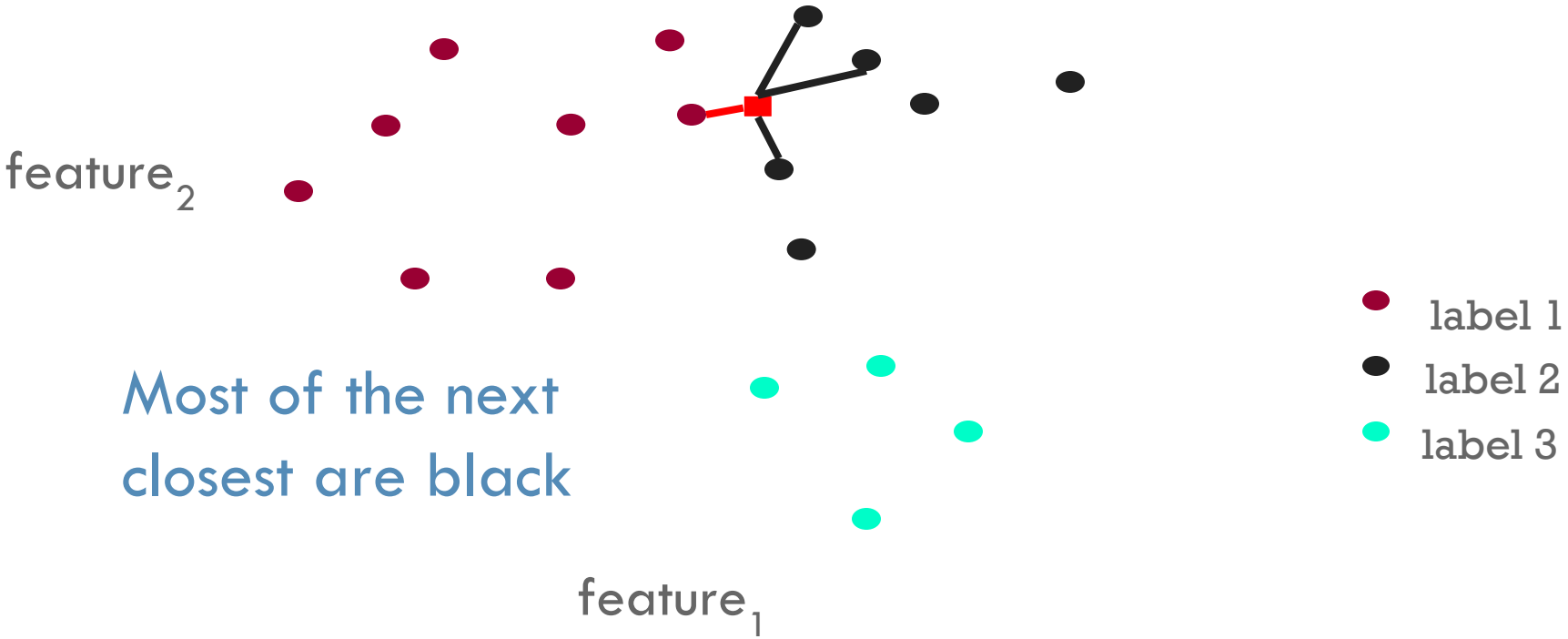


K-Nearest Neighbor (K-NN)

To classify an example ***d***:

- Find ***k*** nearest neighbors of ***d***
- Choose as the label the majority label within the ***k*** nearest neighbors

Robust to noisy data by considering k-nearest neighbors

K-Nearest Neighbor (K-NN)

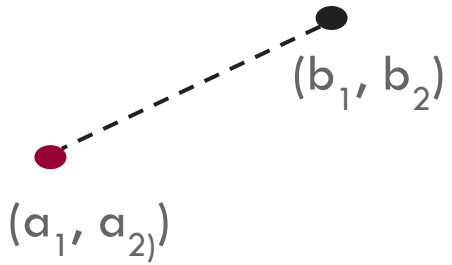
To classify an example ***d***:

- Find ***k*** ***nearest*** neighbors of ***d***
- Choose as the label the majority label within the ***k*** nearest neighbors

How do we measure "nearest"?

Euclidean distance

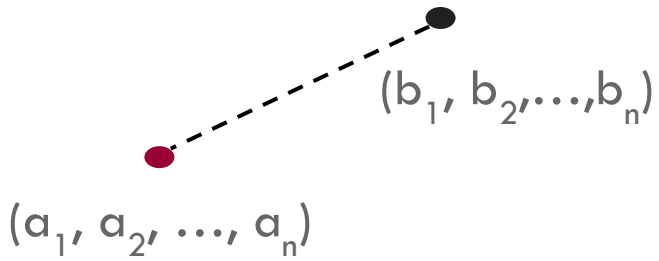
In two dimensions, how do we compute the distance?



$$D(a,b) = \sqrt{(a_1 - b_1)^2 + (a_2 - b_2)^2}$$

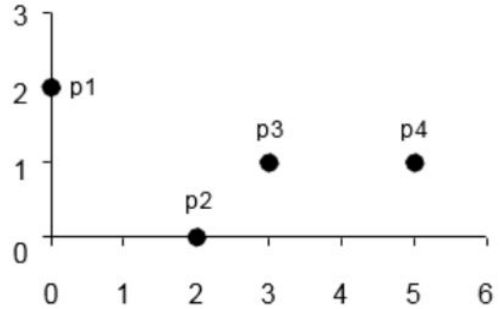
Euclidean distance

In n-dimensions, how do we compute the distance?



$$D(a,b) = \sqrt{(a_1 - b_1)^2 + (a_2 - b_2)^2 + \ldots + (a_n - b_n)^2}$$

Euclidean Distance: Example



point	x	y
p1	0	2
p2	2	0
p3	3	1
p4	5	1

	p1	p2	p3	p4
p1	0	2.828	3.162	5.099
p2	2.828	0	1.414	3.162
p3	3.162	1.414	0	2
p4	5.099	3.162	2	0

Euclidean distance

- Euclidean Distance makes sense when different features are comparable (e.g. each is variable measured in the same units).
    - For instance, if the measurements are different, say length and weight, it is not clear.
- **Standardization**: When features are not comparable we can standardize them by dividing by their corresponding standard deviation. This makes them all equally important.

Standardization & Scaling

- **Standardization or Z-score normalization**
  - Rescale the data so that the mean is 0 and the standard deviation from the mean (standard scores) is 1

$$x_{norm} = \frac{x - \mu}{\sigma}$$

μ is mean, σ is a standard deviation from the mean (standard score)

- **Min-Max scaling**
  - Scale the data to a fixed range – between 0 and 1

$$x_{morm} = \frac{x - x_{min}}{x_{max} - x_{min}}$$

Distance and Similarity

- Measuring distance/similarity is a domain-specific problem and there are many, many different variations
- Similarity
  - Numerical measure of how alike two data objects are.
  - Is higher when objects are more alike.
  - Often falls in the range [0,1]
- Distance
  - Numerical measure of how different are two data objects
  - Lower when objects are more alike
  - Minimum dissimilarity is often 0
  - Upper limit varies

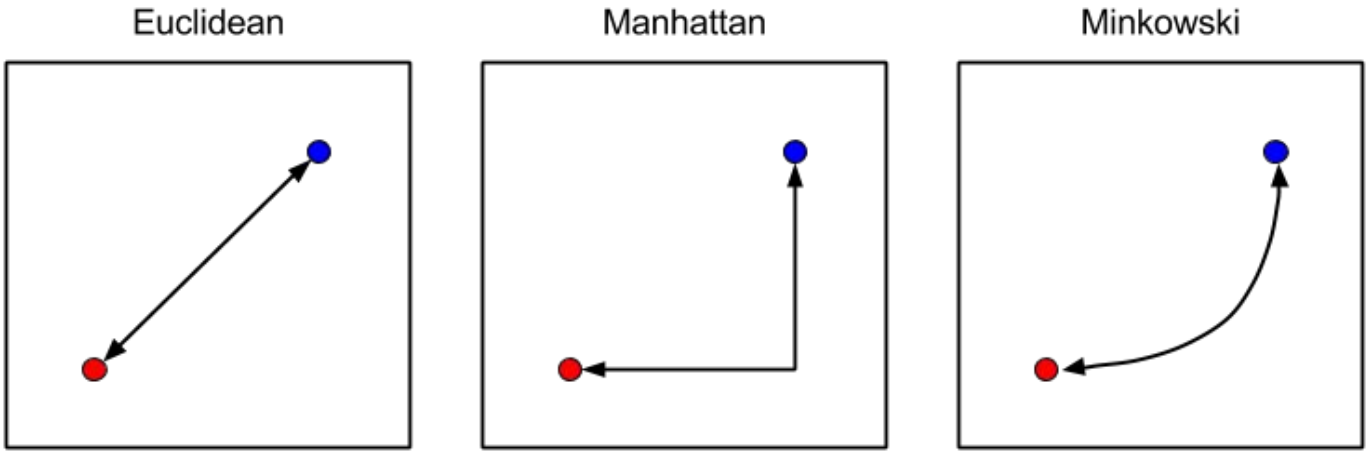
Minkowski Distance

- Minkowski Distance is a generalization of Euclidean Distance

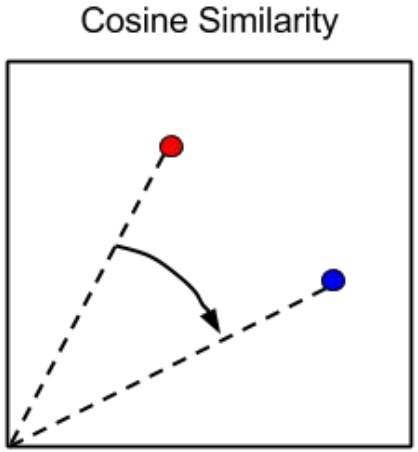
$$D(a,b) = \left(\sum_{k=1}^{p} |a_k - b_k|^r \right)^{1/r}$$

- r is a parameter, p is the number of dimensions
- $r = 1$. City block (Manhattan, L1 norm) distance.
- $r = 2$. Euclidean distance
- $r \to \infty$. "supremum" (L_∞ norm) distance.
    - This is the maximum difference between any component of the vectors

Distances



Cosine Similarity



Given two document vectors:

$$\cos(d_1, d_2) = (d_1 \cdot d_2) / ||d_1|| \, ||d_2||,$$

Where $\cdot$ indicates vector dot product and $||d||$ is the length of vector d.

Example:

$d_1 = 3\ 2\ 0\ 5\ 0\ 0\ 0\ 2\ 0\ 0$

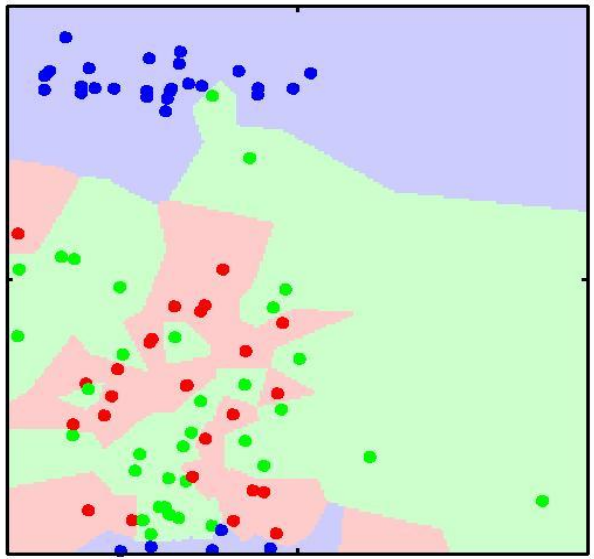
$d_2 = 1\ 0\ 0\ 0\ 0\ 0\ 0\ 1\ 0\ 2$

$d_1 \cdot d_2 = 3*1 + 2*0 + 0*0 + 5*0 + 0*0 + 0*0 + 0*0 + 2*1 + 0*0 + 0*2 = 5$

$||d_1||$ = (3*3+2*2+0*0+5*5+0*0+0*0+0*0+2*2+0*0+0*0)**0.5**= (42)^**0.5**= 6.481

$||d_1||$ = (1*1+0*0+0*0+0*0+0*0+0*0+0*0+1*1+0*0+2*2)**0.5**= (6)^**0.5**= 2.245

cos(*d1*, *d2*) = .3150

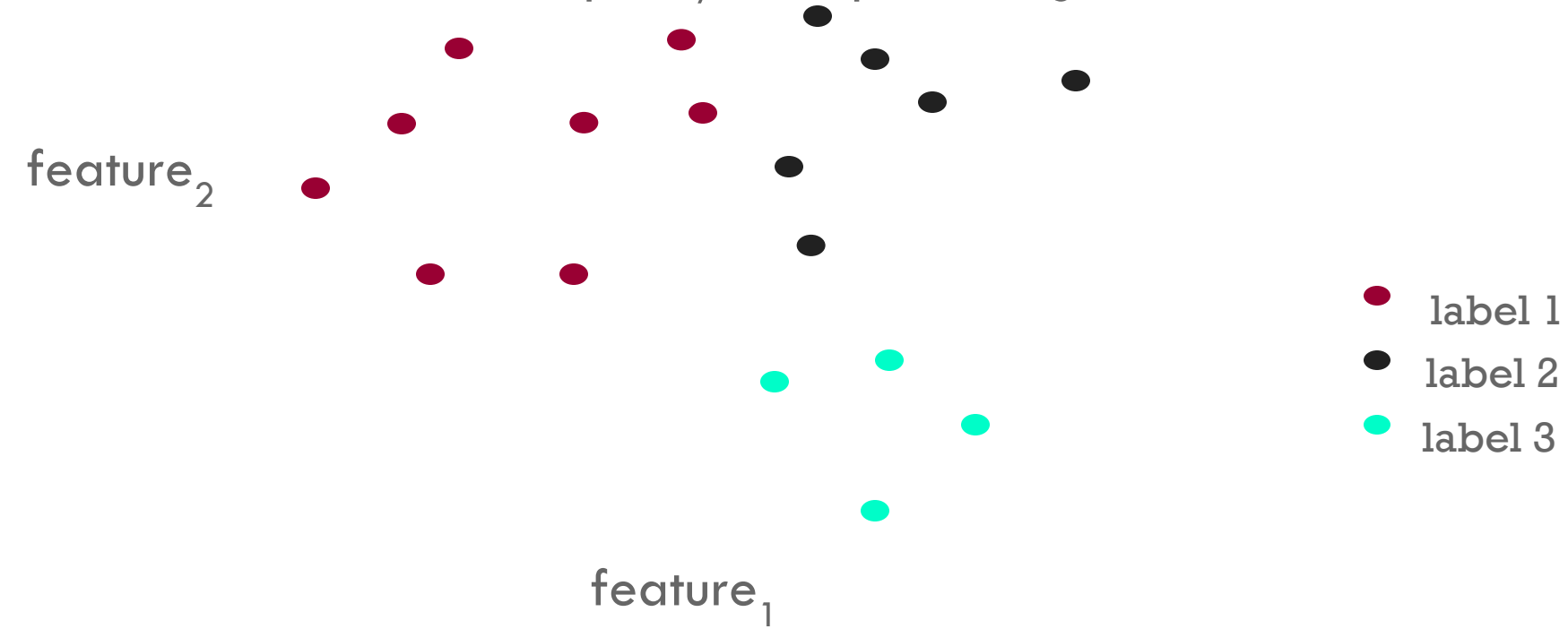


Decision Boundaries

Hyper-parameters

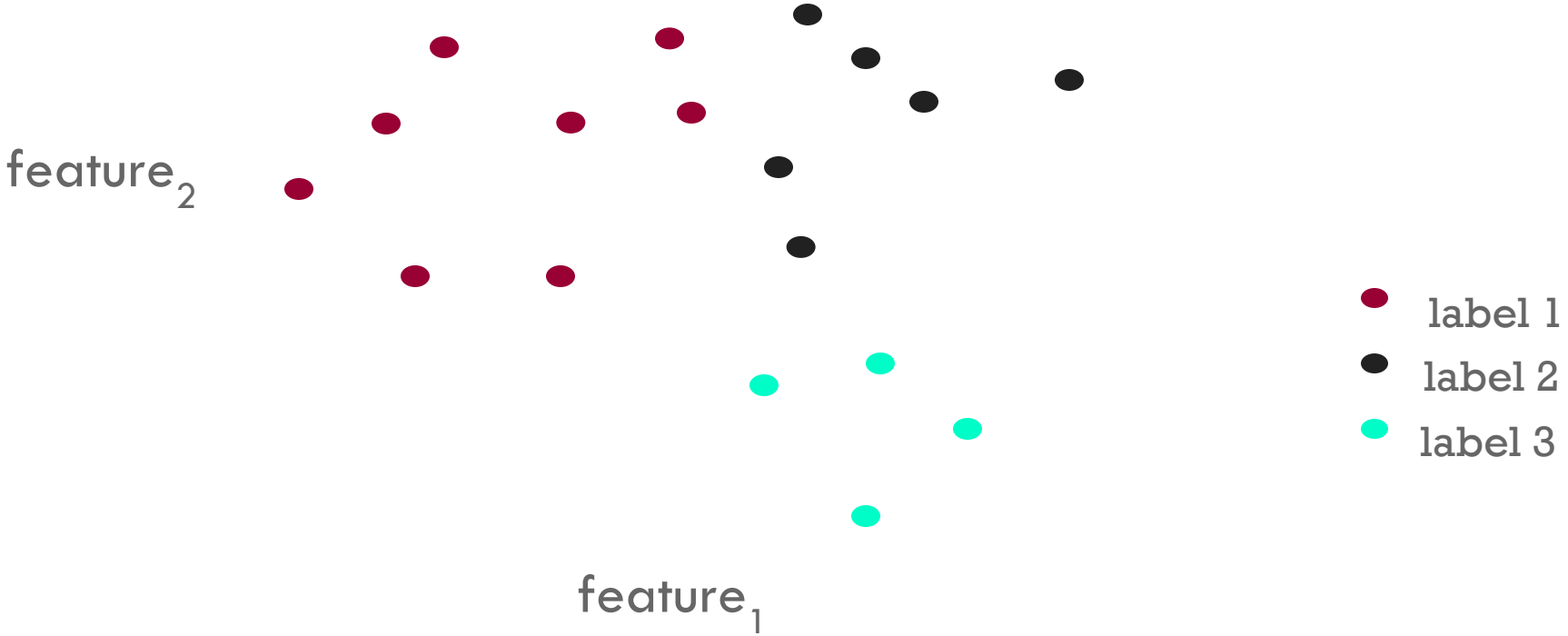
Decision boundaries

The **decision boundaries** are places in the features space where the classification of a point/example changes



Decision boundaries

Where are the decision boundaries for k-NN?



Decision boundaries

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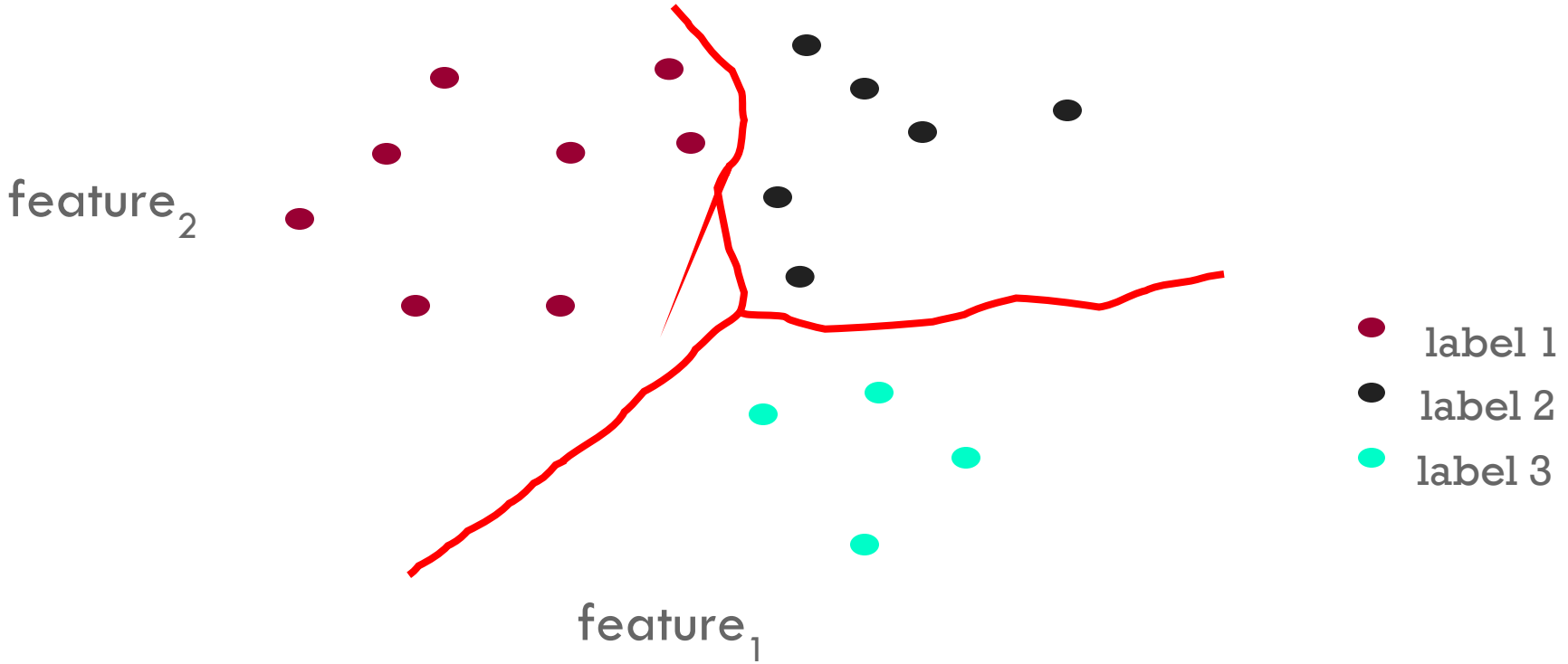
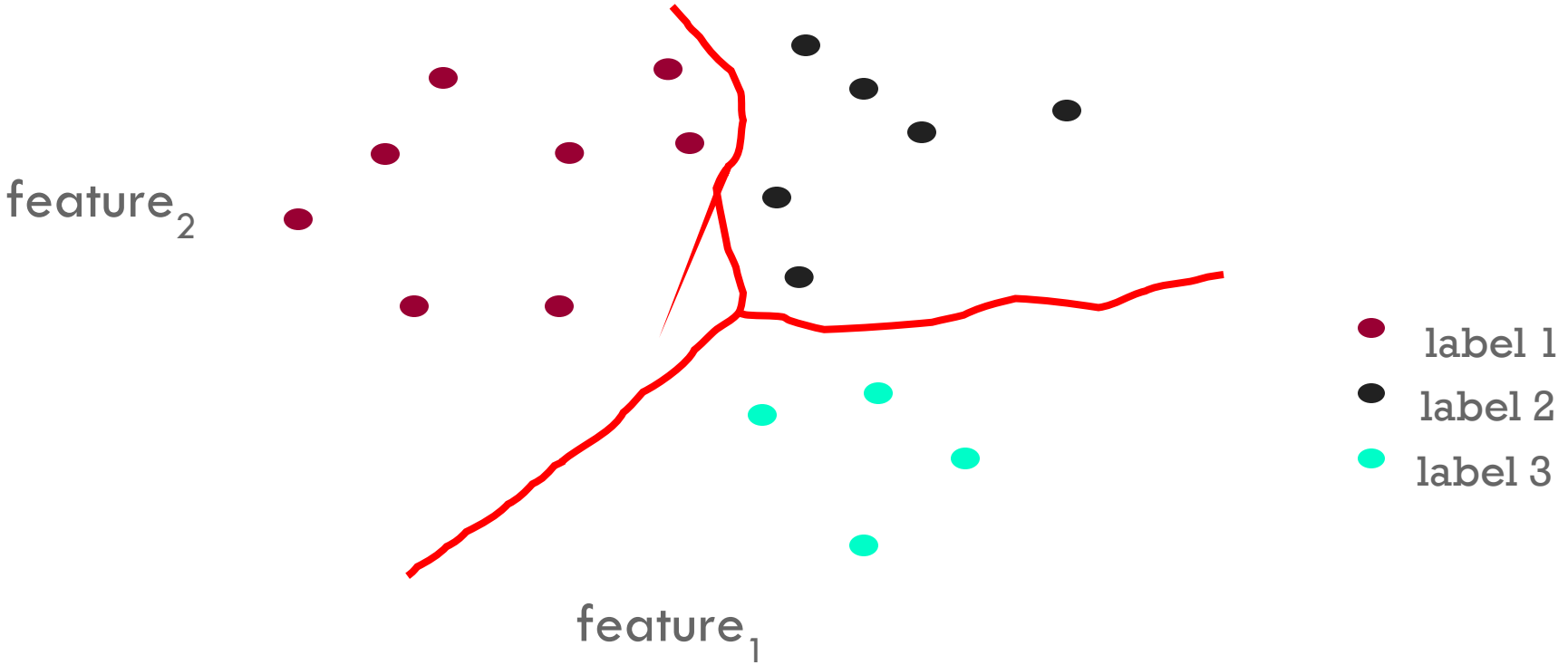


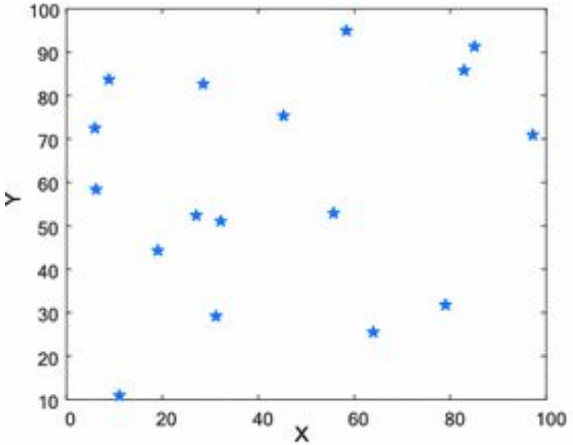
Decision boundaries

k-NN gives **locally** defined decision boundaries between classes

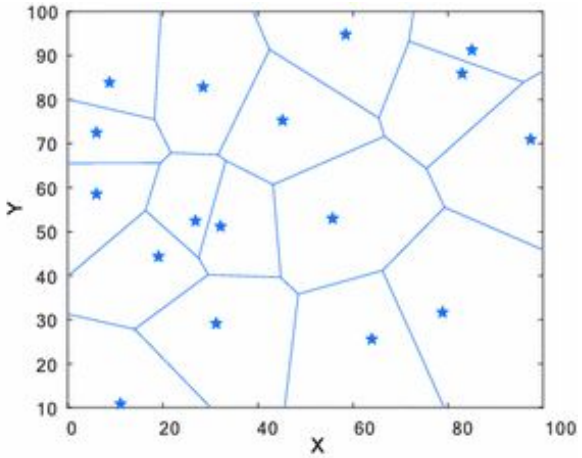


Voronoi Diagram

- Describes the areas that are nearest to any given point, given a set of data.
- Each line segment is equidistant between two points



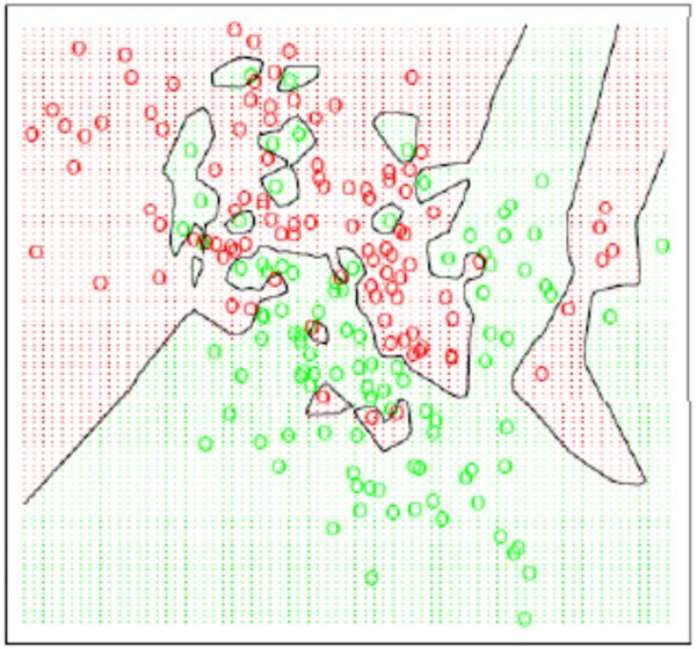
(a) Initial points distribution



(b) Voronoi diagram by initial points

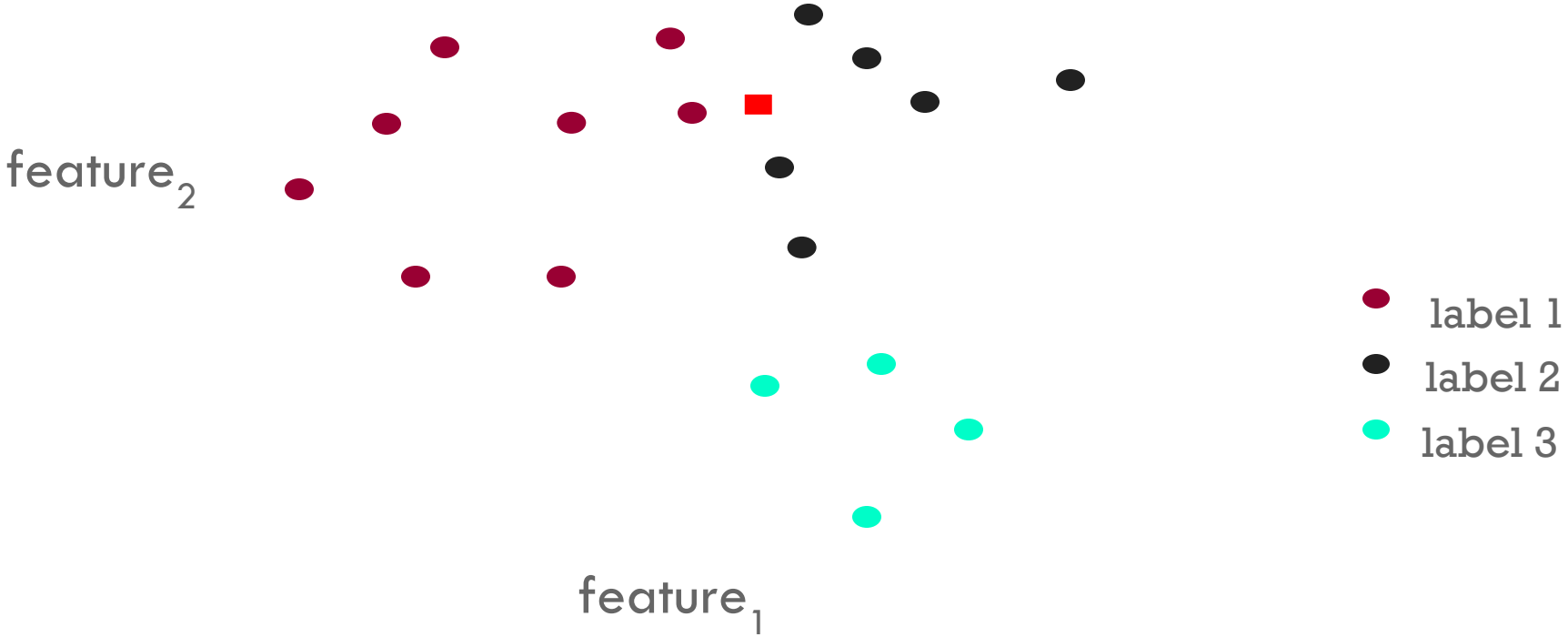
Decision boundaries

- k-NN algorithm does not explicitly compute decision boundaries.
- The decision boundaries form a subset of the Voronoi diagram for the training data.
- The more examples that are stored, the more complex the decision boundaries can become



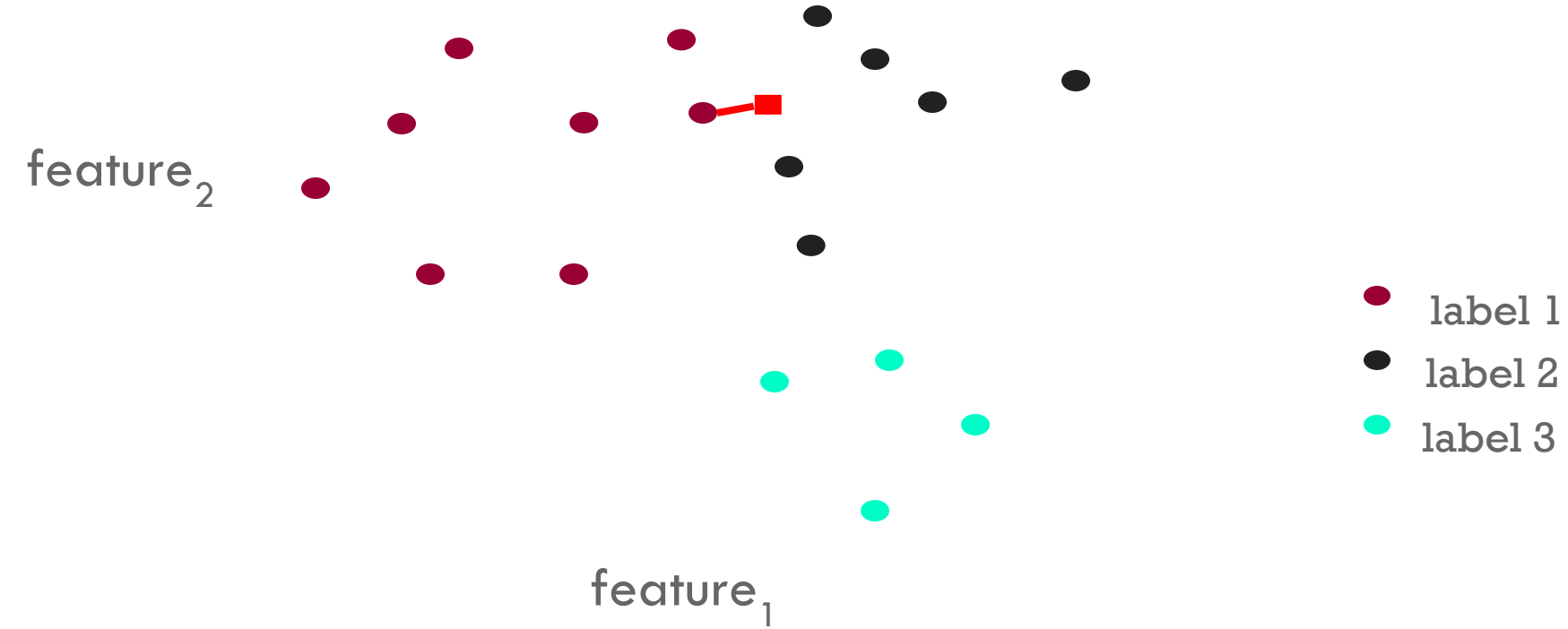
Choosing k

What is the label with k = 1?



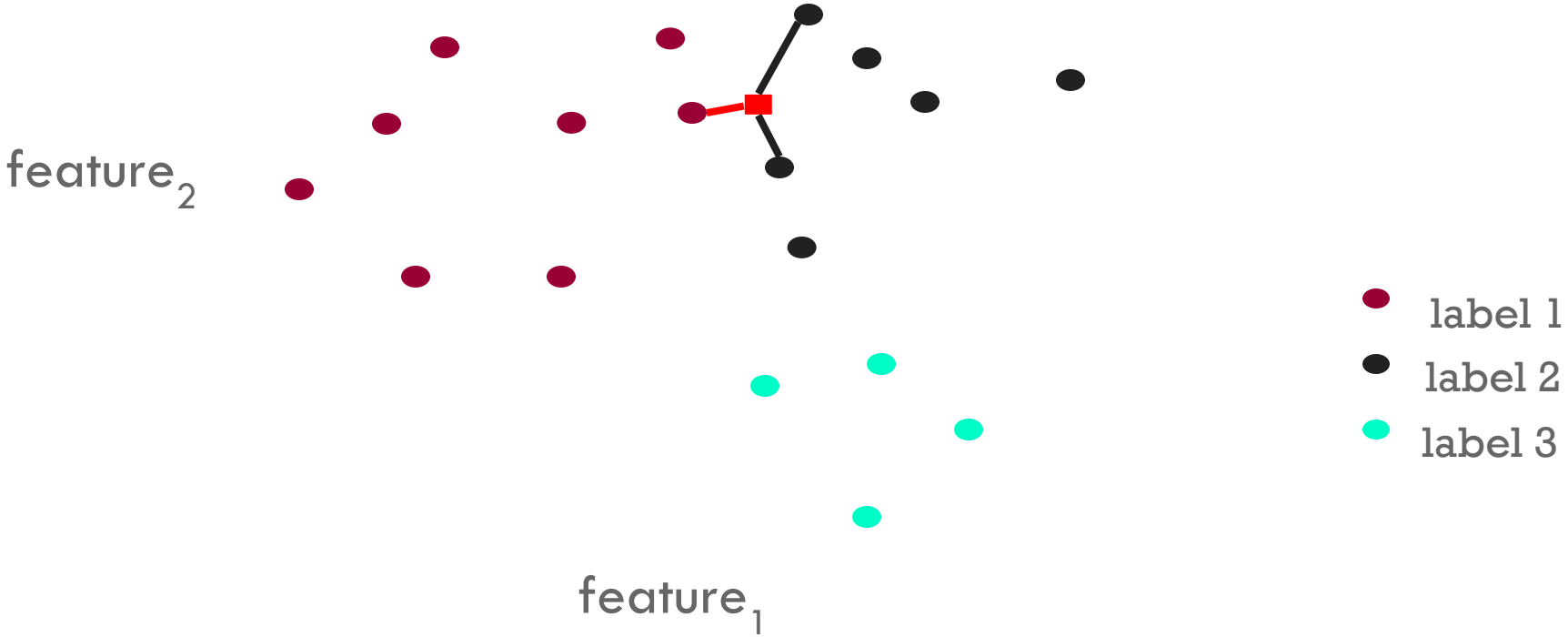
Choosing K

We choose red. Do you agree?



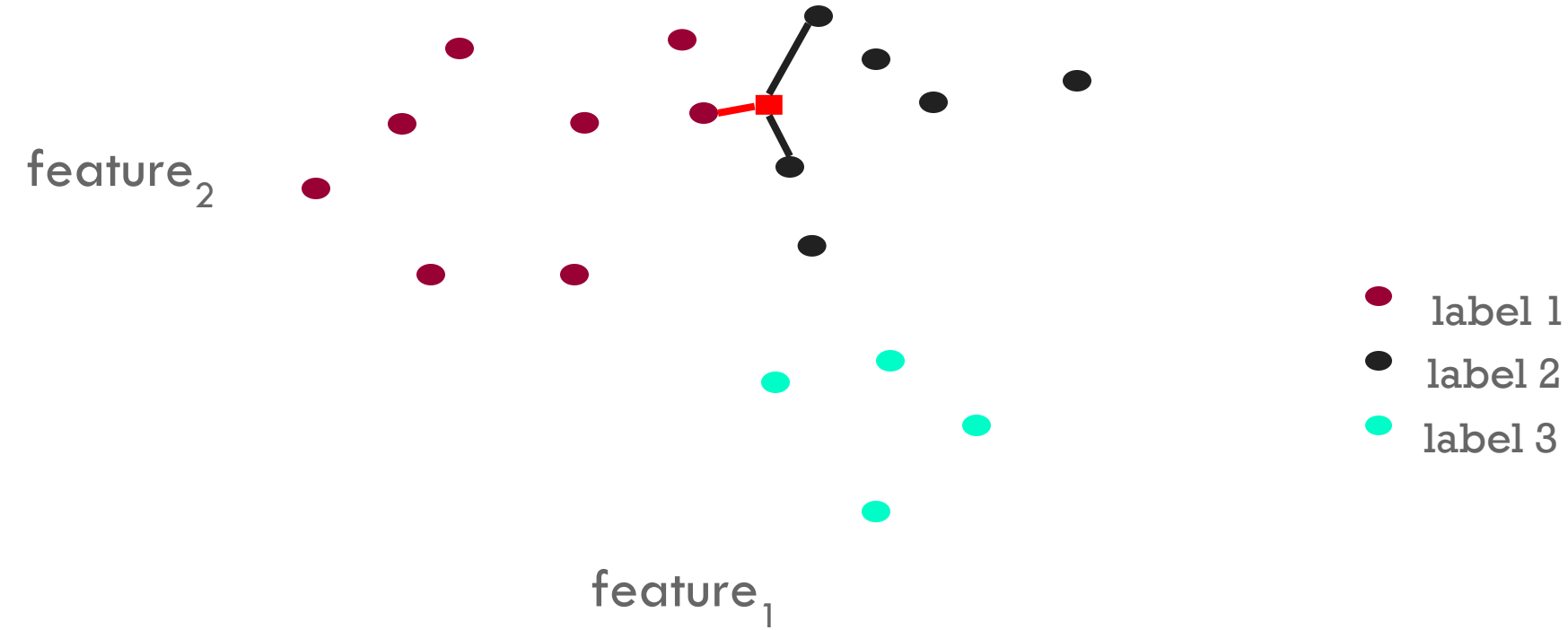
Choosing k

What is the label with k = 3?



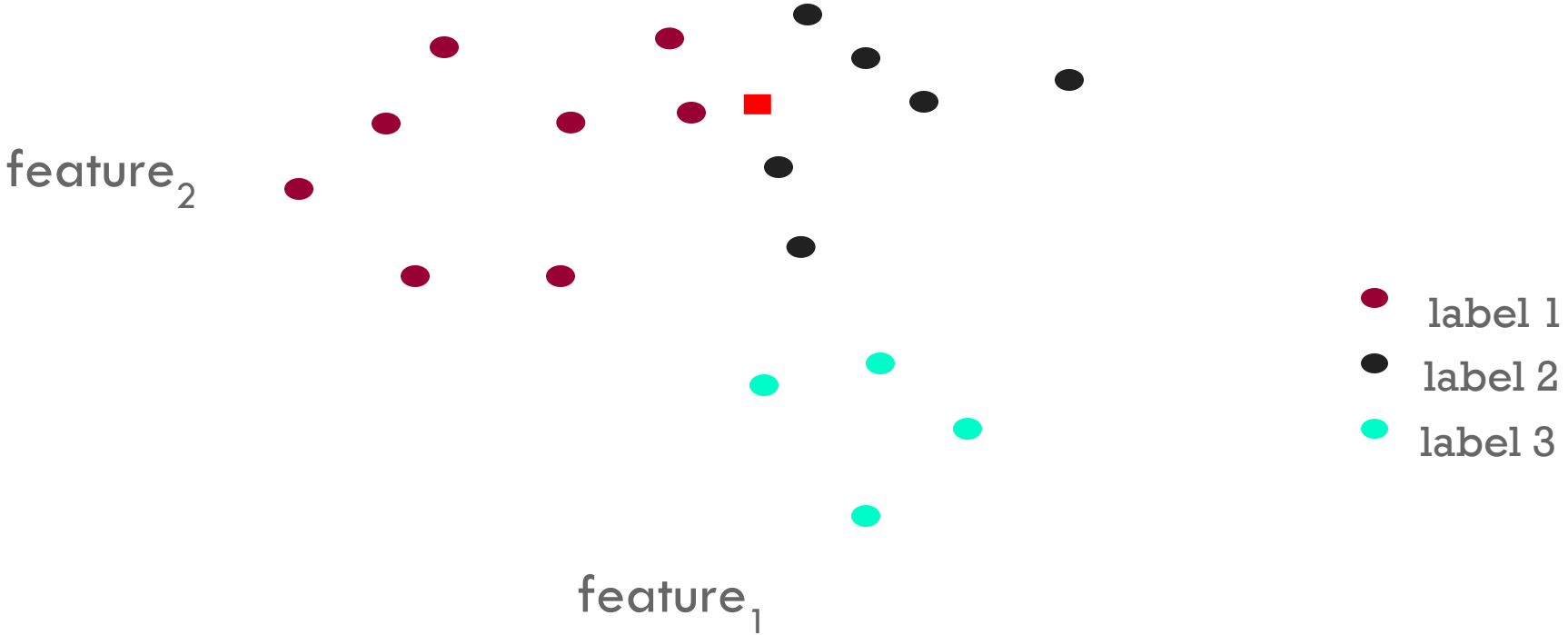
Choosing k

We choose black. Do you agree?



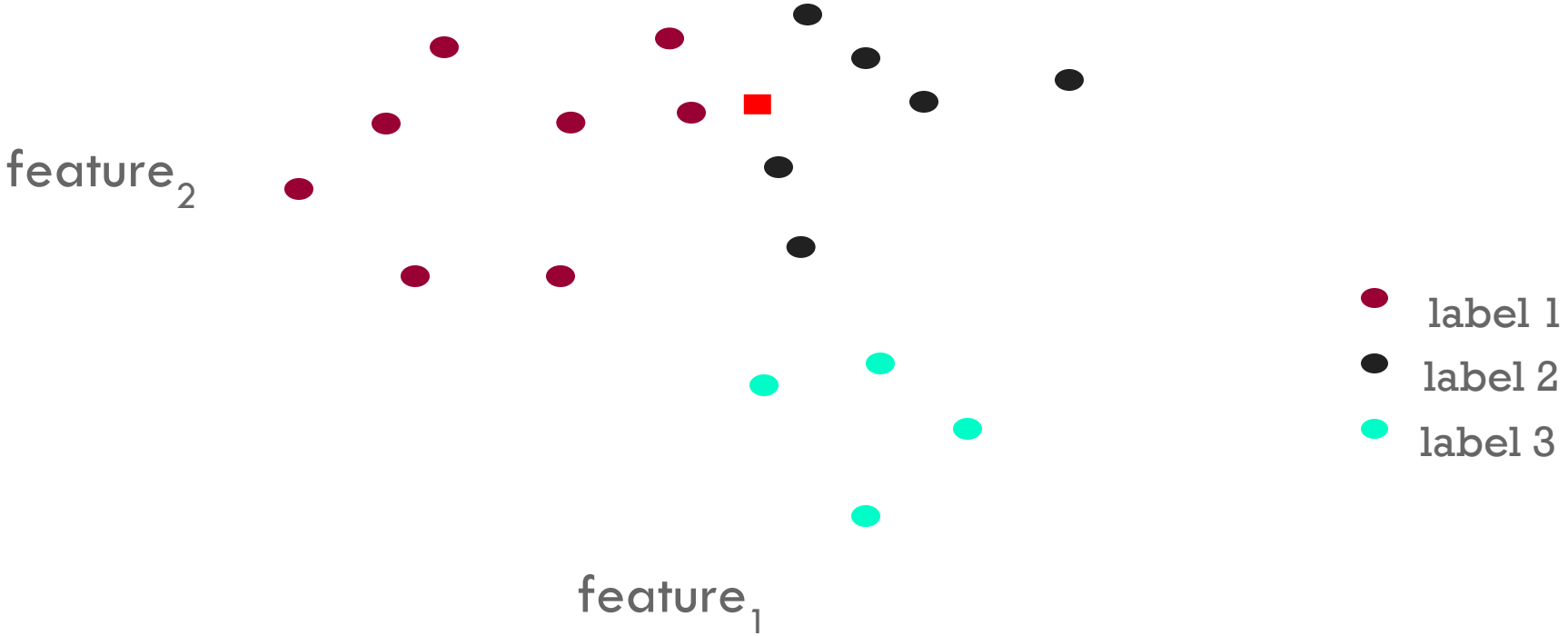
Choosing k

What is the label with k = 20?

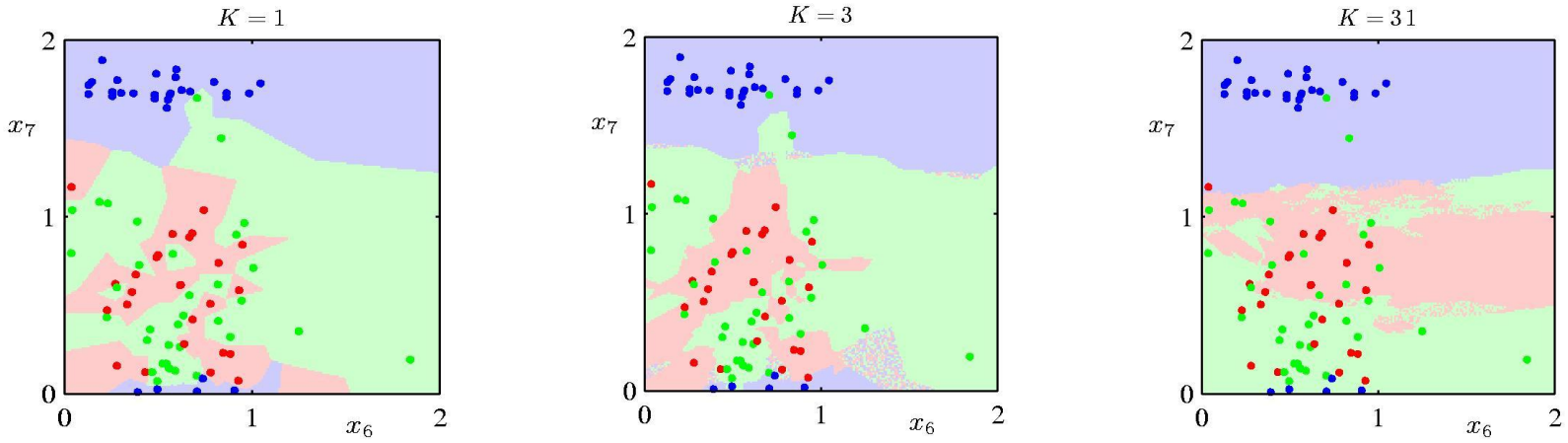


Choosing k

What is the label with k = 20? Red! (class with max number of datapoints, weird)



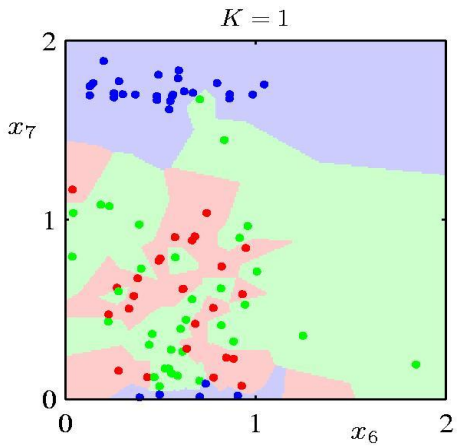
The impact of K

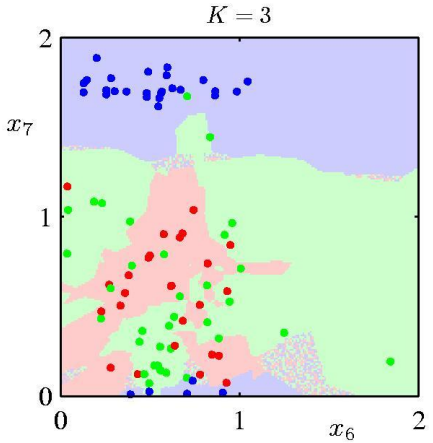


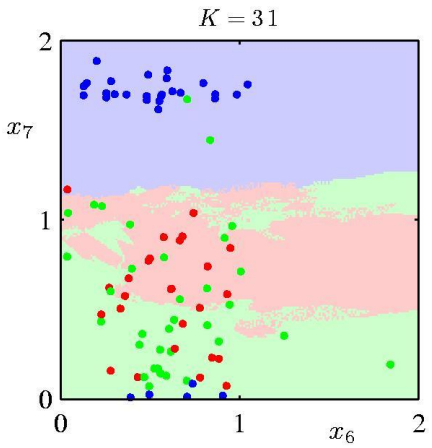
What is the role of k?

How does it relate to overfitting and underfitting?

The impact of K







Larger k produces smoother boundary effect

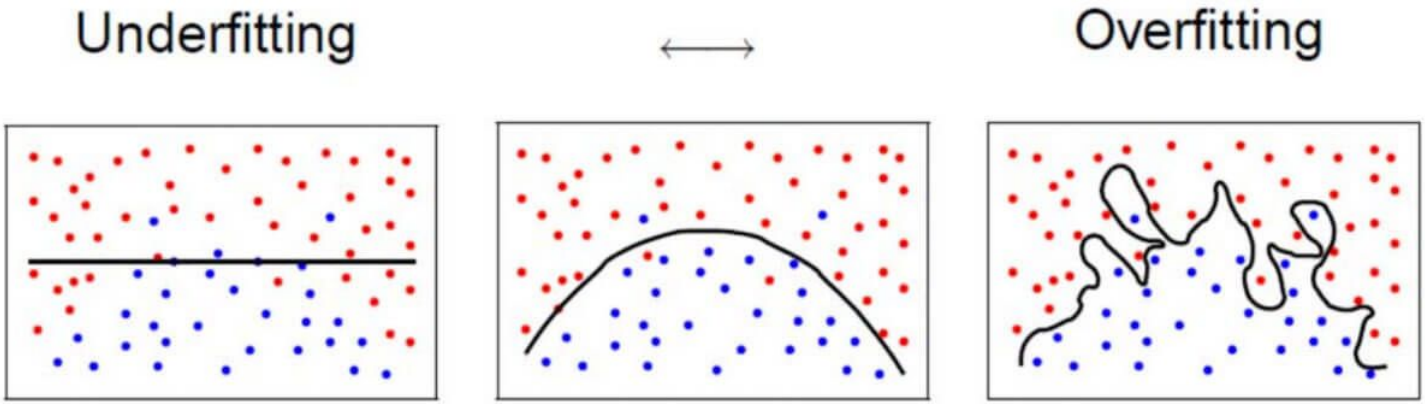
When k=N, always predict the majority class

RECAP: UNDERFITTING OVERFITTING

- The factors determining how well a machine learning algorithm will perform are its ability to:
  - Make the **training error small**.
  - Make the **gap between training and test error small**.
- These two factors correspond to the cases of **underfitting** and **overfitting**.
- **Underfitting** occurs when the model is not able to obtain a sufficiently low error value on the training set.
- **Overfitting** occurs when the gap between the training error and test error is too large.

RECAP: UNDERFITTING OVERFITTING

- Classification



K-Nearest Neighbor (K-NN)

To classify an example ***d***:

- Find ***k*** nearest neighbors of ***d***
- Choose as the class the majority class within the ***k*** nearest neighbors

How do we choose *k*?

How to pick k

- Common heuristics:
  - often 3, 5, 7
  - choose an odd number to avoid ties
- Use validation set
- Use cross-validation
- Rule of thumb is k < sqrt(n), where n is the number of training examples

K-Nearest Neighbor (K-NN)

To classify an example ***d***:

- Find ***k*** nearest neighbors of ***d***
- Choose as the class the majority class within the ***k*** nearest neighbors

Any other idea?

K-NN VARIATIONS

Instead of *k* nearest neighbors, count majority from all examples within a fixed distance

Weighted *k*-NN:

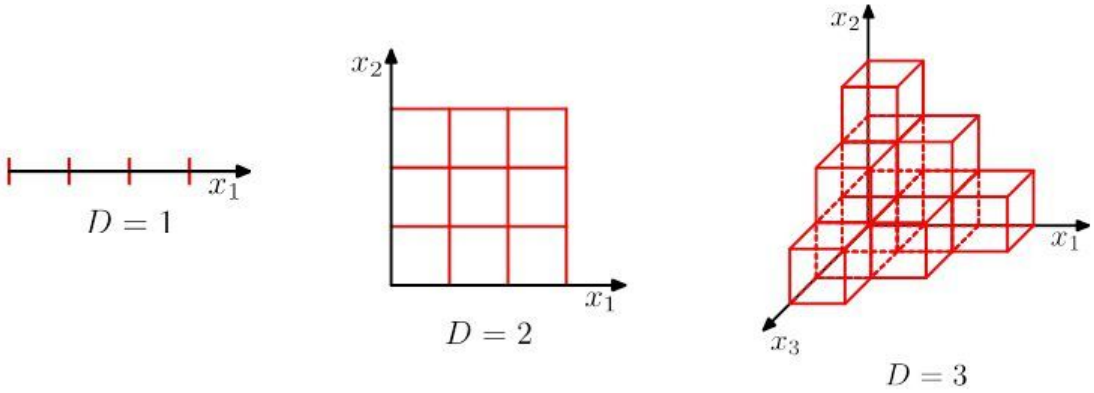
- Right now, all examples are treated equally
- Weight the "vote" of the examples, so that closer examples have more vote/weight
- Often use some sort of exponential decay

Lazy Learner VS Eager Learner

- k-NN is belongs to the class of **lazy learning** algorithms
- **Lazy learning**: Simply stores training data (or perform limited processing) and operates when it is given a test example
- **Eager learning** (e.g. Decision Trees, SVMs): Given a training set, constructs a classification model before receiving new test data to classify
- **Lazy learners**: less time in training but more time in predicting

Curse of Dimensionality

- **Curse of dimensionality:** In high dimensions almost all points are far away from each other
- The size of the data space grows exponentially with the number of dimensions.
- This means that the size of the data set must also grow exponentially in order to keep the same density.



Curse of Dimensionality

- The success of k-NN is very dependent on having a **dense data set.**
- Every machine learning algorithm needs a dense data set for accurate prediction
- What makes k-nearest neighbors special?
- k-NN requires a point to be close in **every single dimension**.
- Some algorithms can create models based on single dimensions, and only need points to be close together along that axis.
- k-NN doesn't work that way. It needs all points to be close along every axis in the data space.

Curse of Dimensionality: Summary

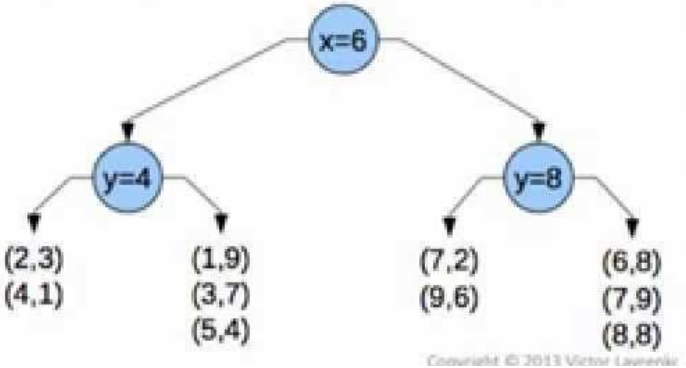
- The problem is fundamentally that there isn't enough data available for the number of dimensions.
- As the number of dimensions increases the size of the data space increases, and the amount of data needed to maintain density also increases.
- Without dramatic increases in the size of the data set, k-NN loses all predictive power.

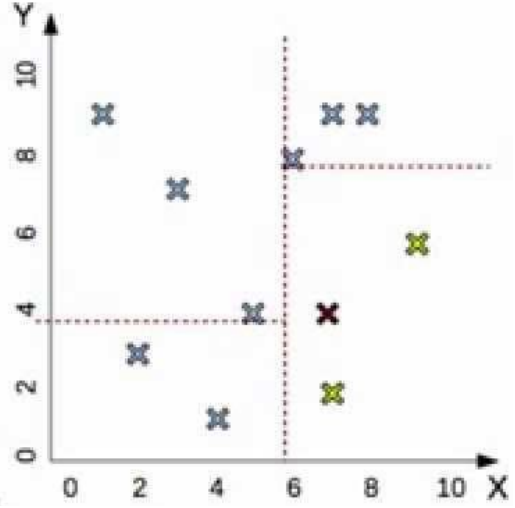
Computational cost

- Linear algorithm (no pre-processing):
  - Compute distance for all N datapoints
  - Complexity of distance computation: $O(kN)$
  - No additional space needed
- Tree-based **data structures**: pre-processing
  - Often used in applications: k-d trees (k-dimensional trees).

K-D Tree

- Building a K-D tree from training data:
  - {(1,9), (2,3), (4,1), (3,7), (5,4), (6,8), (7,2), (8,8), (7,9), (9,6)}
  - pick random dimension, find median, split data, repeat
- Find NNs for new point (7,4)
  - find region containing (7,4)
  - compare to all points in region





k-Nearest Neighbor: Summary

- Non parametric model
- When to consider
  - Instance map to points in R^N
  - Few (e.g. less than 20) features per instance
  - Lots of training data
- Advantages
  - Training is very fast (no training)
  - Learn complex target functions
- Disadvantages
  - Slow at query time
  - Easily fooled by irrelevant attributes

k-Nearest Neighbor: Advantages

- Easy to program
- No optimization or training required
- Classification accuracy can be very good, it can outperform more complex models

k-Nearest Neighbor: Issues

- Choose distance measure
  - Most common: Euclidean
- Choosing k
- Curse of Dimensionality
- Memory based technique.
  - Must make a pass through the data for each classification. This can be prohibitive for large data sets.

An Aside: Parametric vs non-parametric models

- Parametric models we have a finite number of parameters
    - Linear regression, logistic regression, and linear Support Vector Machines
- Nonparametric models: the number of parameters is (potentially) infinite. The complexity of the model grows with the number of training data.
    - K-nearest neighbor, decision trees, or RBF kernel SVMs are considered as non-parametric learning algorithms since the number of parameters grows with the size of the training set.

Example

Decent performance when large training set

- Yann LeCunn – MNIST Digit Recognition
  - Handwritten digits
  - 28x28 pixel images: $d = 784$
  - 60,000 training samples
  - 10,000 test samples
- Nearest neighbour is competitive

	Test Error Rate (%)
Linear classifier (1-layer NN)	12.0
K-nearest-neighbors, Euclidean	5.0
K-nearest-neighbors, Euclidean, deskewed	2.4
K-NN, Tangent Distance, 16x16	1.1
K-NN, shape context matching	0.67
1000 RBF + linear classifier	3.6
SVM deg 4 polynomial	1.1
2-layer NN, 300 hidden units	4.7
2-layer NN, 300 HU, [deskewing]	1.6
LeNet-5, [distortions]	0.8
Boosted LeNet-4, [distortions]	0.7

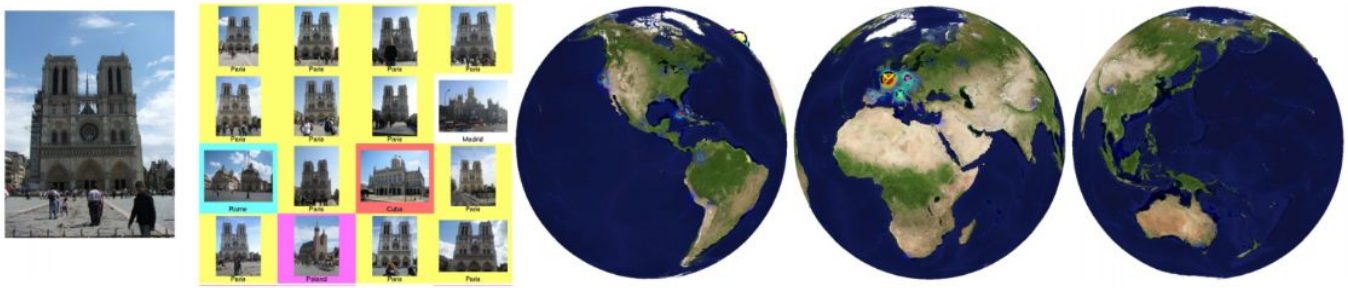
Example

Problem: Where (e.g., which country or GPS location) was this picture taken?

[Paper: James Hays, Alexei A. Efros. im2gps: estimating geographic information from a single image. CVPR'08. Project page: http://graphics.cs.cmu.edu/projects/im2gps/]

Example

- Get 6M images from Flickr with gps info (dense sampling across world)
- Represent each image with meaningful features
- Do kNN (large k better, they use k = 120)



http://graphics.cs.cmu.edu/projects/im2gps/
http://graphics.cs.cmu.edu/projects/im2gps/results.html
https://www.youtube.com/watch?v=dgif39IKT9A

QUESTIONS?